

Networks 4:

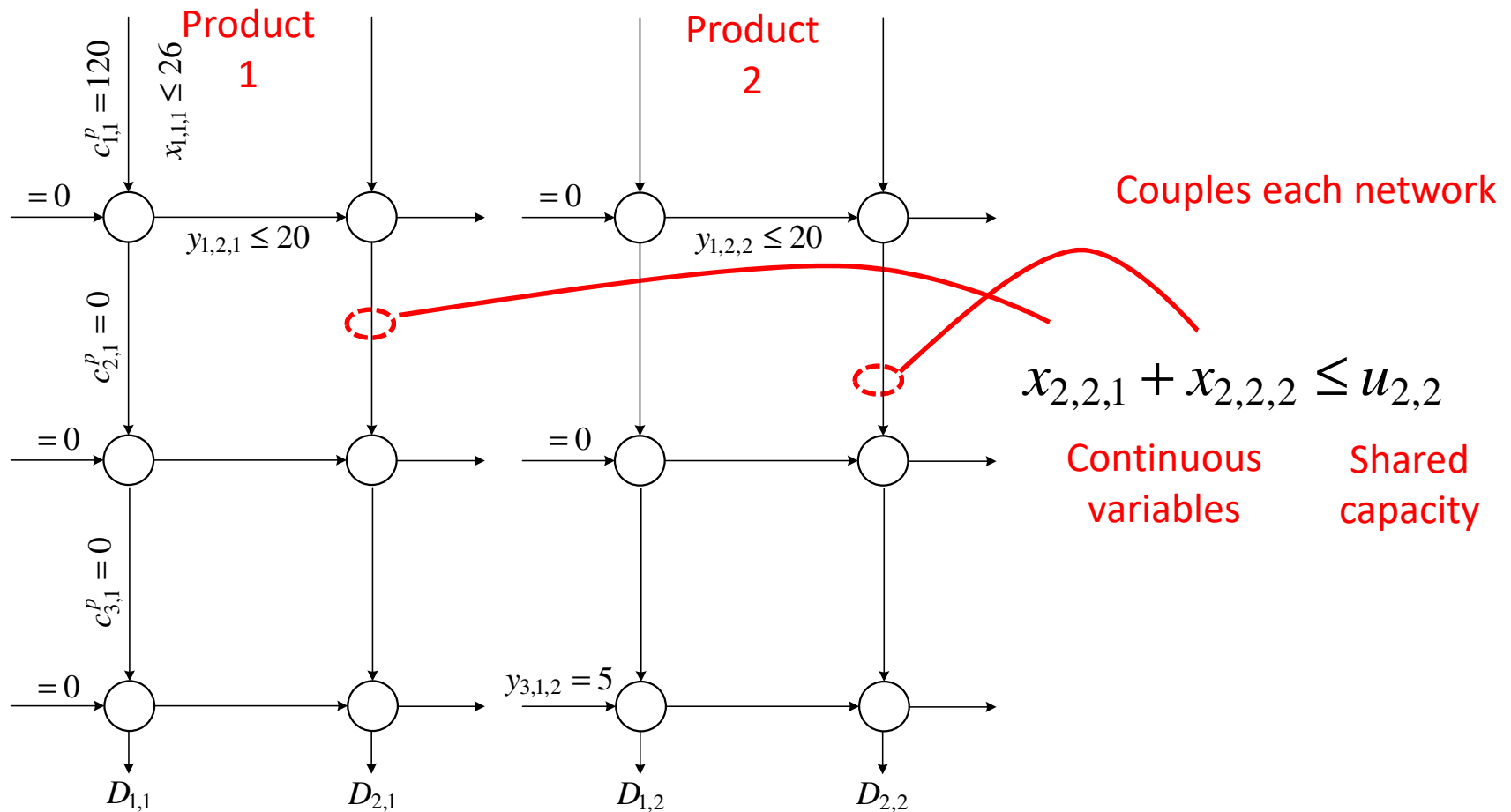
Production-Inventory Planning:

Multiple Products

- Adding constraints to a math program can never improve a solution
- Can ignore situations that would make a solution worse
 - Makes it easier to add constraints to implement a decision
 - Cf. setup constraints

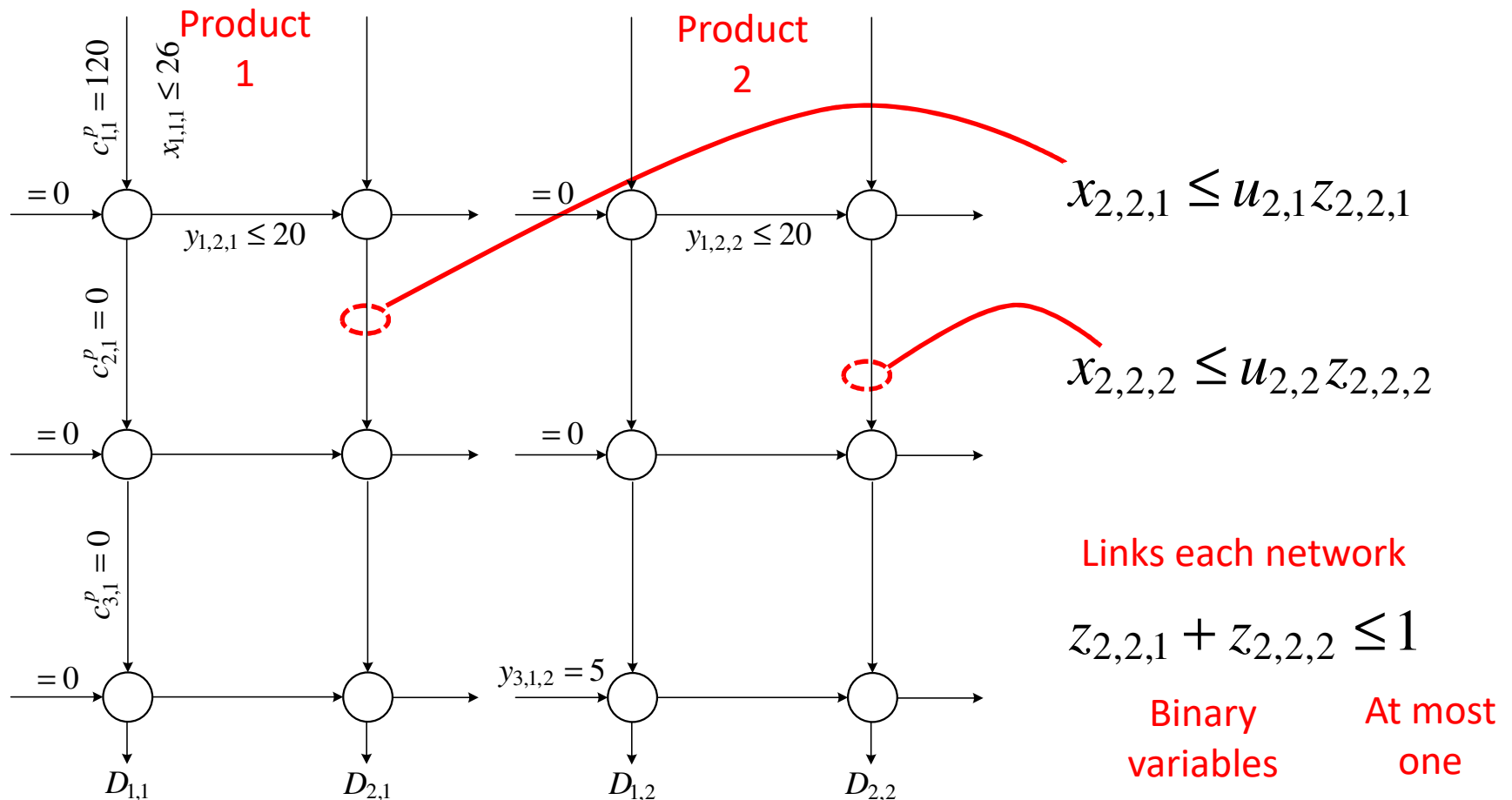
Coupling Constraints

- Otherwise separate product networks connected via sharing the **combined** use of a resource's capacity

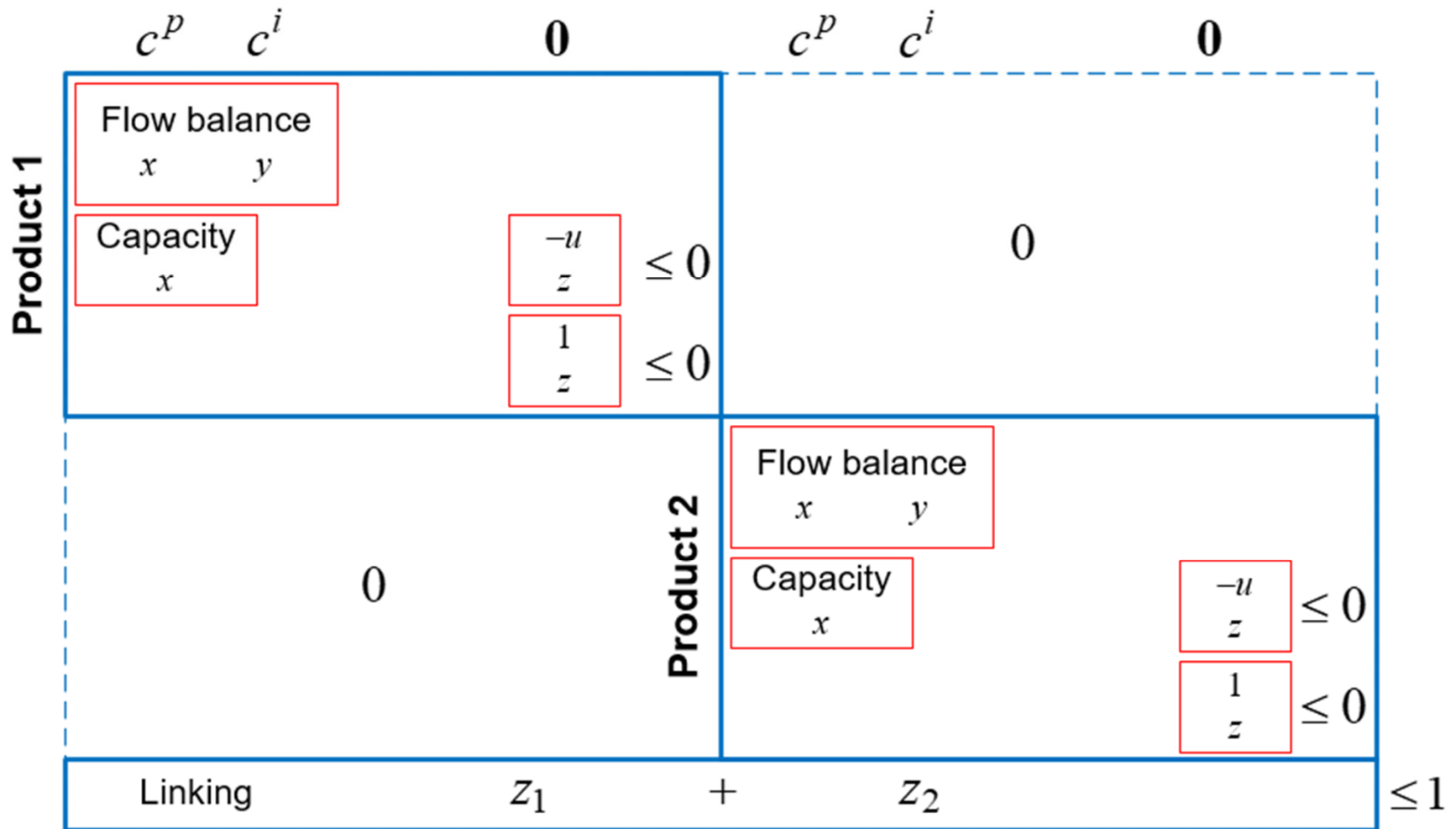


Linking Constraints

- Otherwise separate product networks connected via sharing the **exclusive** use of a resource's capacity



Multiple Products with Exclusive Shared Resources



Multiple Products with Exclusive Shared Resources

$$\begin{aligned}
 &\text{Minimize} \quad \sum_{i=1}^m \sum_{j=1}^t \sum_{k=1}^g c_{ik}^p x_{ijk} + \sum_{i=1}^m \sum_{j=2}^{t+1} \sum_{k=1}^g c_{ik}^i y_{ijk} \\
 &\text{subject to} \quad -x_{ijk} + x_{(i+1)jk} - y_{ijk} + y_{i(j+1)k} = 0, \quad i = 1, \dots, m-1; j = 1, \dots, t; k = 1, \dots, g \quad (a) \\
 &\quad \quad \quad -x_{mjk} - y_{mjk} + y_{m(j+1)k} = d_{jk}, \quad j = 1, \dots, t; k = 1, \dots, g \quad (b) \\
 &\quad \quad \quad x_{ijk} \leq u_{ik} z_{ijk}, \quad i = 1, \dots, m; j = 1, \dots, t; k = 1, \dots, g \quad (c) \\
 &\quad \quad \quad \sum_{k=1}^g z_{ijk} \leq 1, \quad i = 1, \dots, m; j = 1, \dots, t \quad (d) \\
 &\quad \quad \quad y_{i1k} = y_i^0, \quad i = 1, \dots, m; k = 1, \dots, g \\
 &\quad \quad \quad y_{i(t+1)k} = y_{ik}^{t+1}, \quad i = 1, \dots, m; k = 1, \dots, g \\
 &\quad \quad \quad x, y \geq 0; z \in \{0, 1\},
 \end{aligned}$$

m = number of production stages

t = number of periods of production

g = number of products

c_{ik}^p = production cost (dollar/ton) in stage i for product k

x_{ijk} = production (ton) at stage i in period j for product k

c_{ik}^i = inventory cost (dollar/ton) in stage i for product k

y_{ijk} = stage- i inventory (ton) from period $j-1$ to j for product k

z_{ijk} = production indicator at stage i in period j for product k

d_{jk} = demand (ton) in period j for product k

u_{ik} = production capacity (ton) of stage i in period j for product k

y_{ik}^0 = initial inventory (ton) of stage i for product k

y_{ik}^{t+1} = final inventory (ton) of stage i for product k .

Multiple Products with Setup Costs

	c^p	c^i	c^s	0		c^p	c^i	c^s	0
Product 1	Flow balance x y								
	Capacity x			$-u$ z	≤ 0	0			
			Setup v	1 z	≤ 0				
Product 2	0					Flow balance x y			
						Capacity x		$-u$ z	≤ 0
						Setup v		1 z	≤ 0
Linking				z_1	+	z_2			≤ 1

Setup Constraints

$z_{mtg} \in \{0,1\}$, production indicator

z_{mtg}	1	2	3	4	5	6	7
1	0	1	1	0	1	1	1
2	0	0	0	1	0	0	0

$v_{mtg} \in \{0,1\}$, setup indicator

v_{mtg}	1	2	3	4	5	6	7
1	0	1	0	0	1	0	0
2	0	0	0	1	0	0	0

	$-v_t$	+	z_t	-	z_{t-1}	\leq	0
	0		0		0		0
	0		0		1		-1
Don't want (not feasible)	0		1		0		1
	0		1		1		0
	1		0		0		-1
	1		0		1		-2
Want (feasible)	1		1		0		0
	1		1		1		-1

Feasible, but not min cost

Multiple Products with Setup Costs

$$\begin{aligned}
 \text{Minimize} \quad & \sum_{i=1}^m \sum_{j=1}^t \sum_{k=1}^g c_{ik}^p x_{ijk} + \sum_{i=1}^m \sum_{j=2}^{t+1} \sum_{k=1}^g c_{ik}^i y_{ijk} + \sum_{i=1}^m \sum_{j=1}^t \sum_{k=1}^g c_{ik}^s v_{ijk} \\
 \text{subject to} \quad & -x_{ijk} + x_{(i+1)jk} - y_{ijk} + y_{i(j+1)k} = 0, & i = 1, \dots, m-1; j = 1, \dots, t; k = 1, \dots, g \quad (a) \\
 & -x_{mjk} - y_{mjk} + y_{m(j+1)k} = d_{jk}, & j = 1, \dots, t; k = 1, \dots, g \quad (b) \\
 & x_{ijk} \leq u_{ik} z_{ijk}, & i = 1, \dots, m; j = 1, \dots, t; k = 1, \dots, g \quad (c) \\
 & -v_{i1k} + z_{i1k} \leq z_{ik}^0, & i = 1, \dots, m; k = 1, \dots, g \quad (d) \\
 & -v_{ijk} + z_{ijk} - z_{i(j-1)k} \leq 0, & i = 1, \dots, m; j = 2, \dots, t; k = 1, \dots, g \quad (e) \\
 & \sum_{k=1}^g z_{ijk} \leq 1, & i = 1, \dots, m; j = 1, \dots, t \quad (f) \\
 & y_{i1k} = y_i^0, & i = 1, \dots, m; k = 1, \dots, g \\
 & y_{i(t+1)k} = y_{ik}^{t+1}, & i = 1, \dots, m; k = 1, \dots, g \\
 & x, y \geq 0; v, z \in \{0, 1\},
 \end{aligned}$$

where,

m = number of production stages

t = number of periods of production

g = number of products

c_{ik}^p = production cost (dollar/ton) in stage i for product k

x_{ijk} = production (ton) at stage i in period j for product k

c_{ik}^i = inventory cost (dollar/ton) in stage i for product k

y_{ijk} = stage- i inventory (ton) from period $j-1$ to j for product k

c_{ik}^s = setup cost (dollar) in stage i for product k

v_{ijk} = setup indicator at stage i in period j for product k

z_{ijk} = production indicator at stage i in period j for product k

d_{jk} = demand (ton) in period j for product k

u_{ik} = production capacity (ton) of stage i in period j for product k

z_{ik}^0 = initial setup at stage i for product k

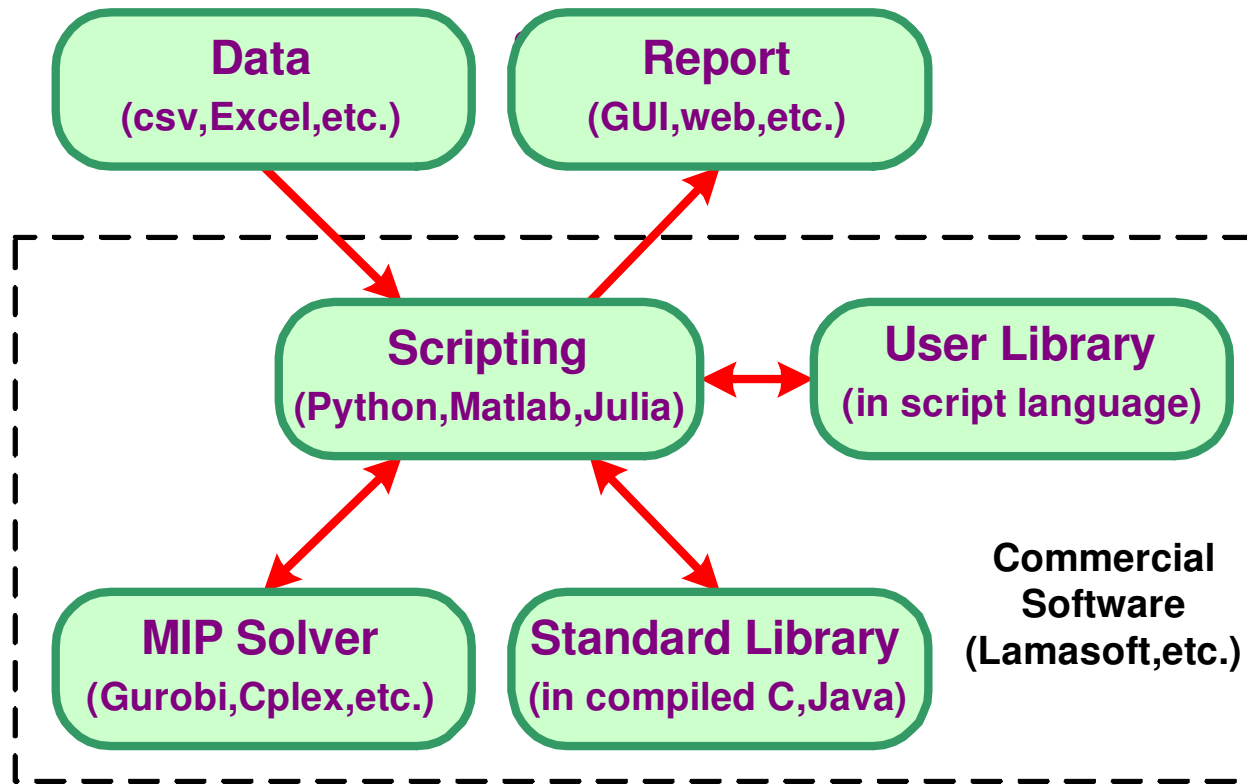
y_{ik}^0 = initial inventory (ton) of stage i for product k

y_{ik}^{t+1} = final inventory (ton) of stage i for product k .

Discussion

1. Indicator variables require MILP instead of LP:
2. Lumpy resources require indicator variables to include fixed costs (setup, prod scale economies, etc)
3. Shared resources:
 - Coupling constraints used to ensures total output doesn't exceed available capacity (can still be LP)
 - Linking constraints used to ensure only one activity per period
4. Demand over planning horizon can be a mix of firm and forecasted orders from MPS/MRP/ERP
5. What is a realistic or typical number of demand periods?
 - Length should include all significant planning decisions (e.g., scheduled maintenance)
6. How is safety stock taken into consideration?

Work Flow of Logistics Software Stack



- **Flow:** *Data* → *Model* → *Solver* → *Output* → *Report*
 - reports are run on a regular period-to-period, *rolling-horizon* basis as part of normal operations management
 - model only changed when logistics network changes