



Istituto Nazionale di Fisica Nucleare
LABORATORI NAZIONALI DI LEGNARO



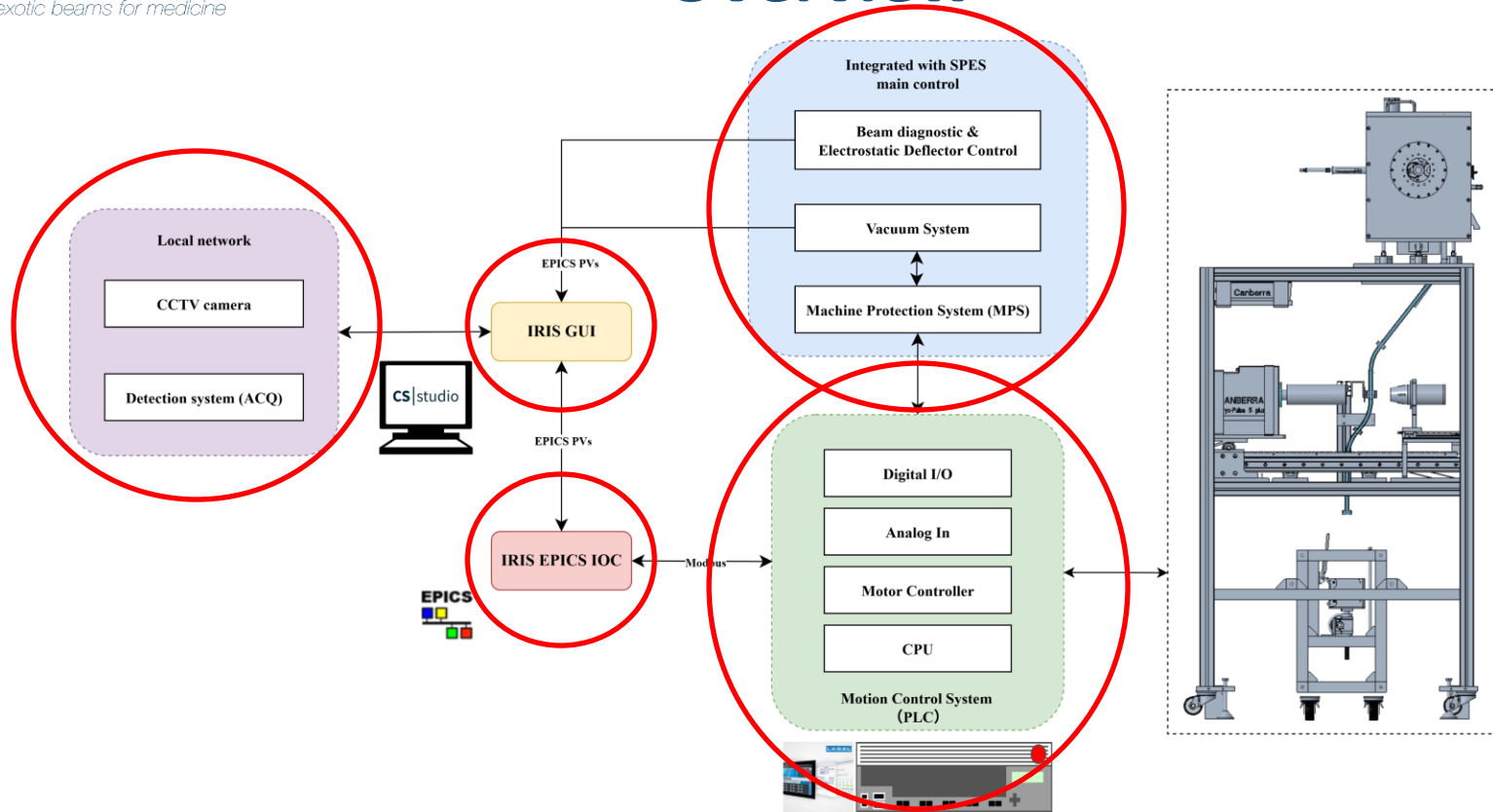
Laboratori Nazionali di Legnaro – INFN

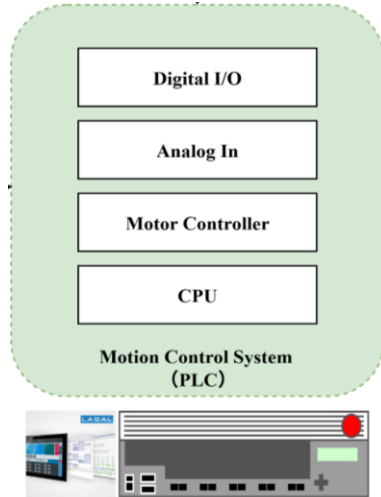
IRIS Control System and GUI – Overview

M. Martello and D.Chen on behalf of IRIS group

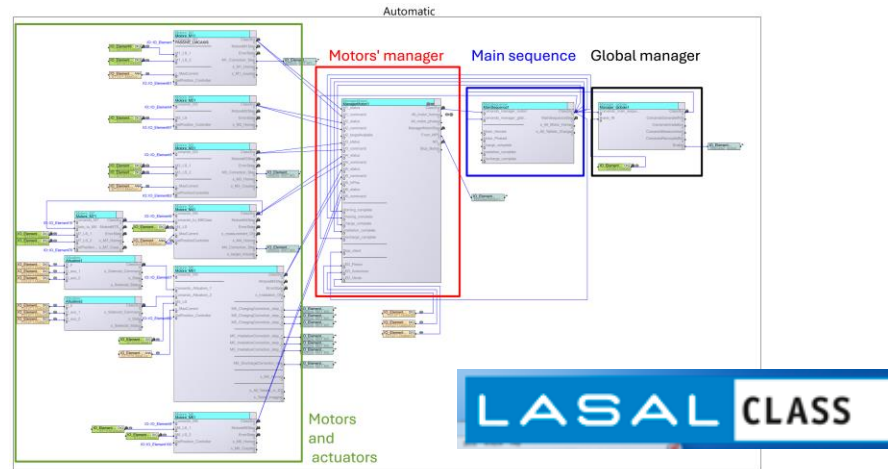
September 17th, 2025

Overview





- Sigmatek **PLC modules**: CPU, Motion controllers, Digital/Analog I/O
- **Finite State Machine (FSM)**
 - Management and segmentation of the system's various operational states and control logics.
 - System designed for easy scalability



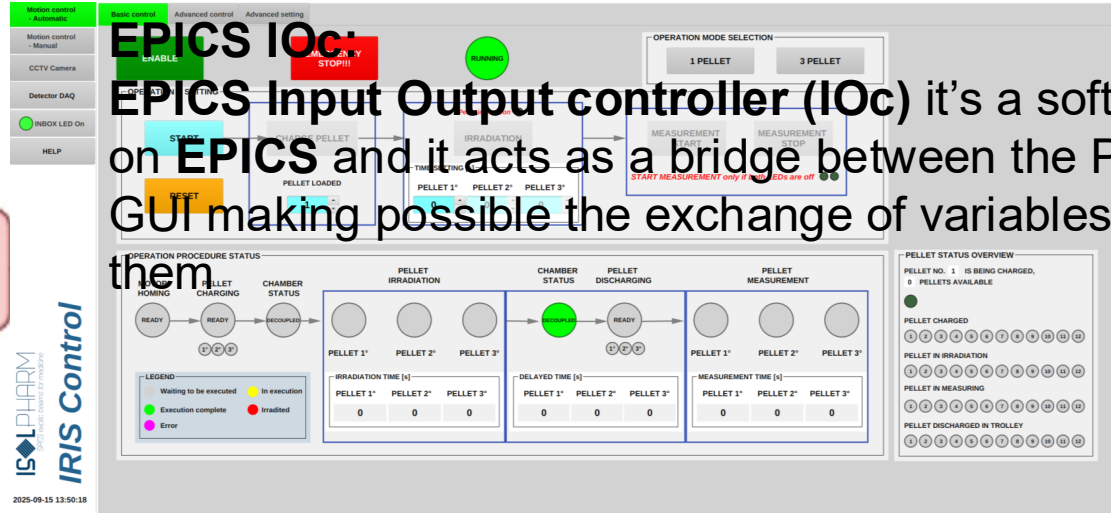


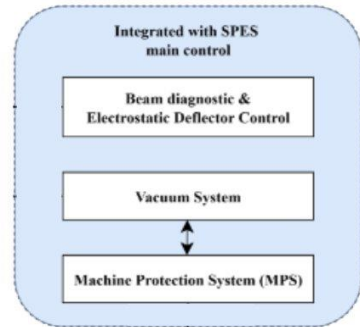
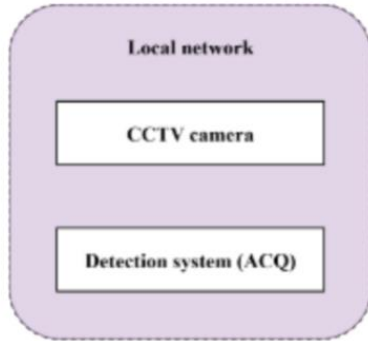
IRIS GUI:

IRIS Graphical User Interfaces (GUI) is based on **CS-Studio** a suite of tools designed for **interacting** with control systems.

EPICS IOc:

EPICS Input Output controller (IOc) it's a software based on **EPICS** and it acts as a bridge between the PLC and the GUI making possible the exchange of variables between them.





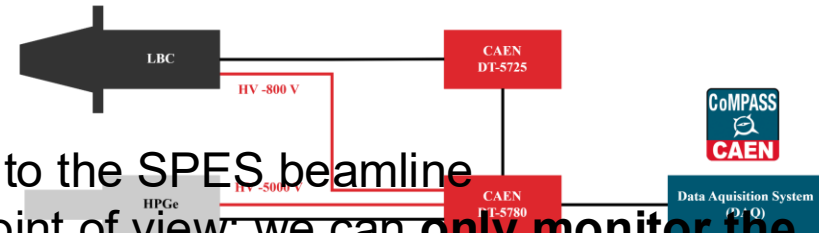
Local Network

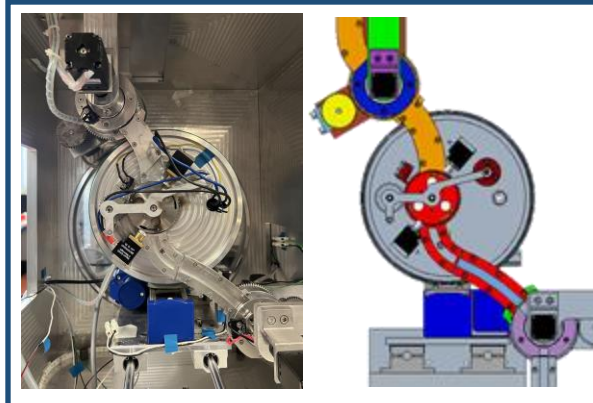
- **CCTV cameras:** Used to monitor the process.
- **Detection system (ACQ):** A data acquisition system based on detectors (CoMPASS).



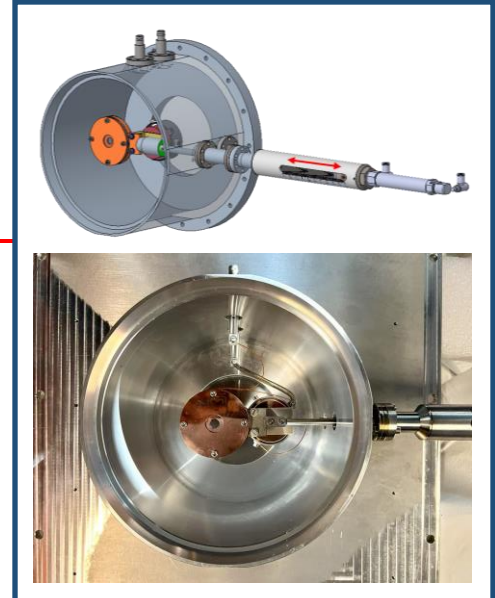
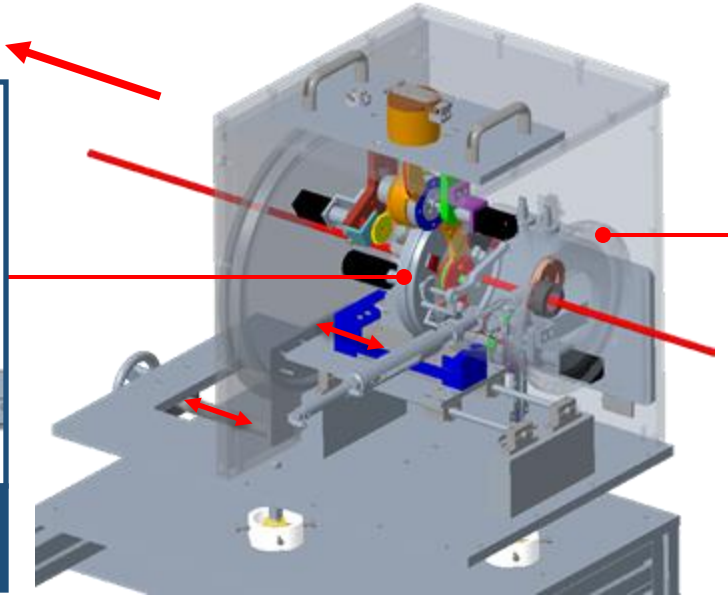
SPES main control

- It allows **Integration** into the SPES beamline
- From an operational point of view: we can **only monitor the variables** provided by the system, without the ability to send commands or modify its behavior.

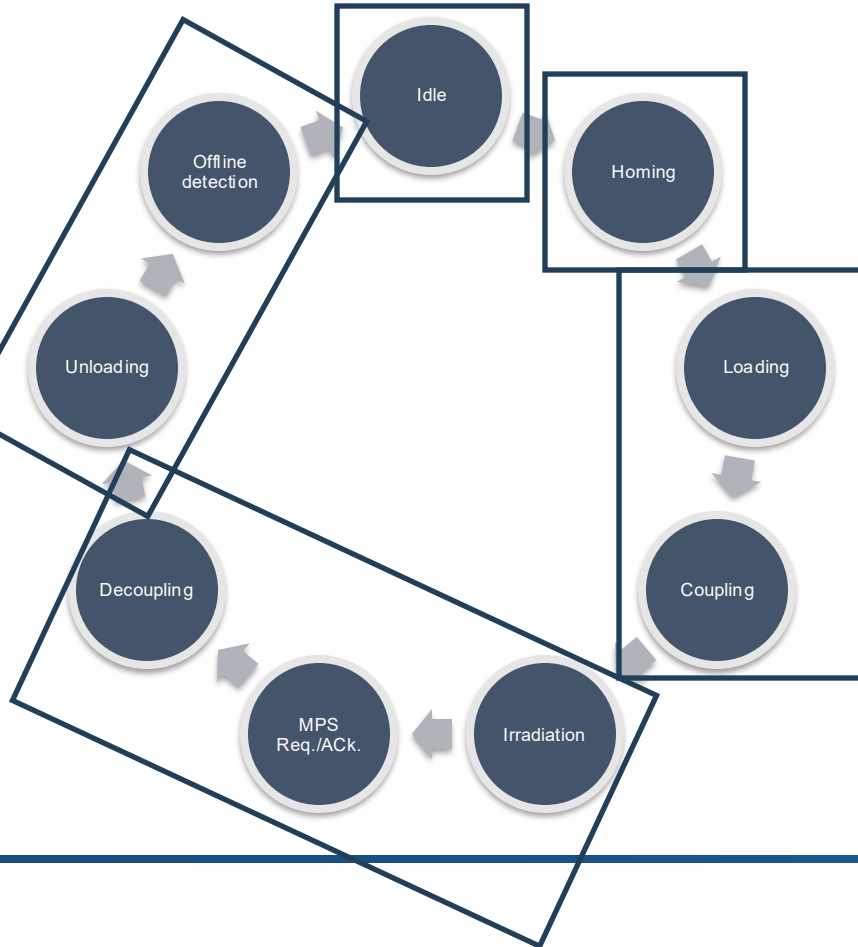




Motion system
- Loading, Alignment, Unloading



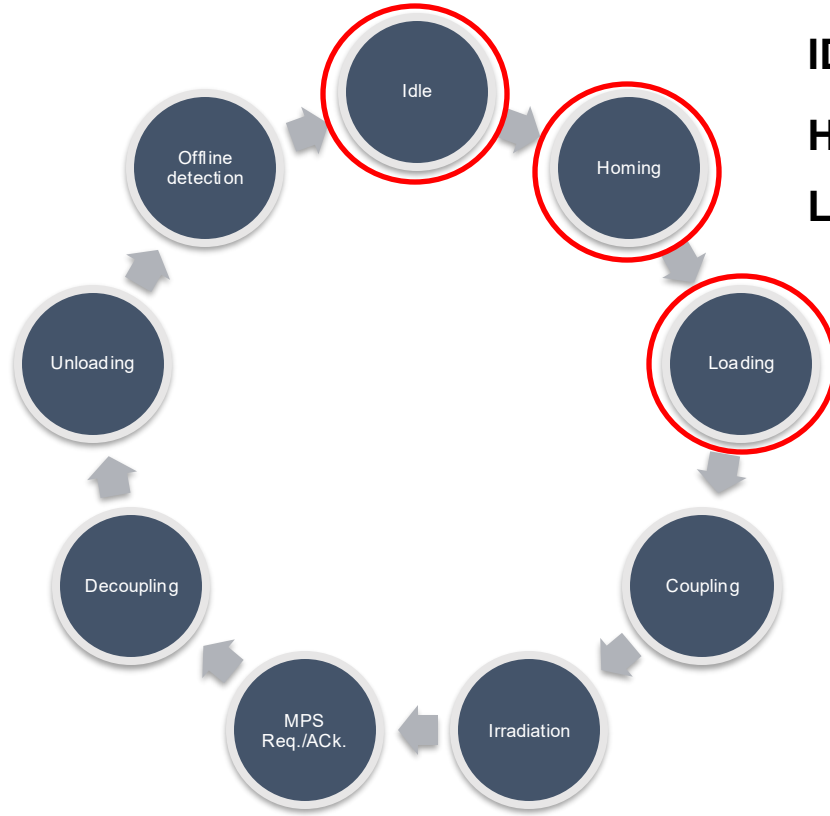
Implantation Chamber



The process is structured in 5 different phases:

- **Idle**
- **Homing**
- **Charge:**
 - Loading
 - Coupling
- **Irradiation:**
 - Irradiation
 - MPS Req./ACK
 - Decoupling
- **Discharge:**
 - Unloading
 - Offline detection

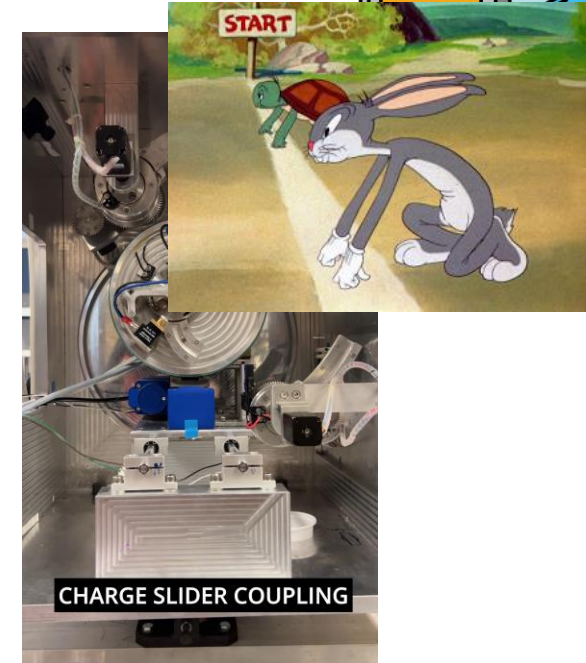
Workflow



IDLE: waiting for external command.

HOMING: All motors are set to their 2

LOADING:





MPS REQ/ACK

Communications with
Machine Protection
System for a safe
decoupling

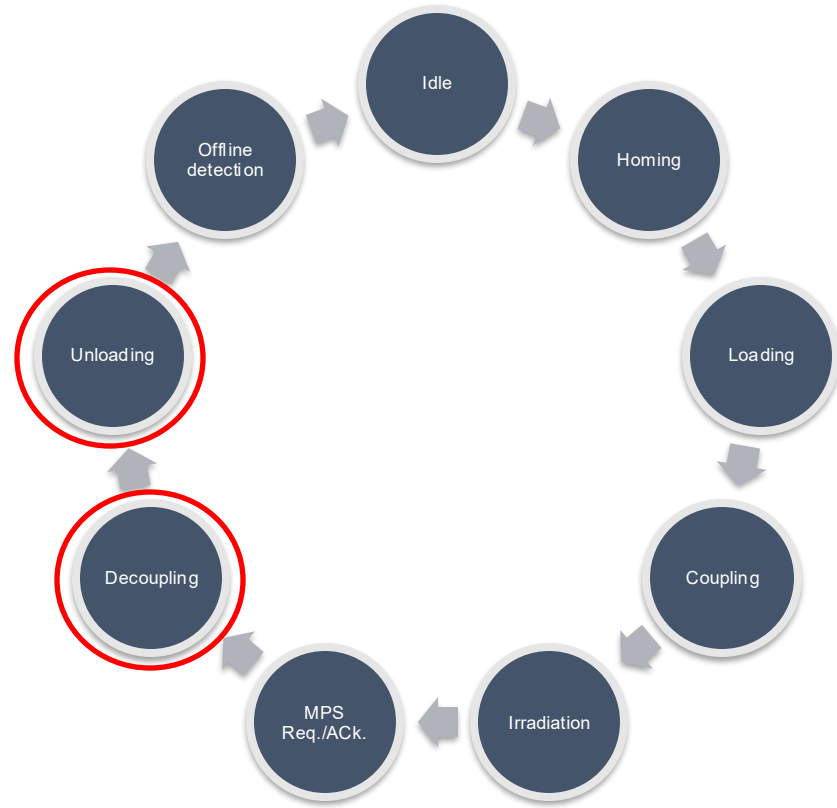


IRRADIATION

If the operational
conditions are
reached



Pellets are
transported to the
irradiation position
one at a time and
remain there for
the required time.

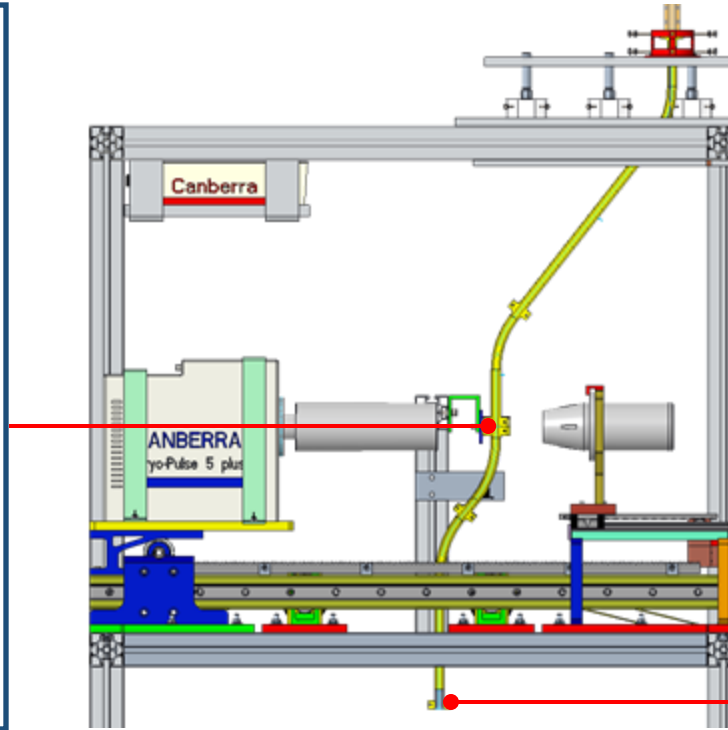
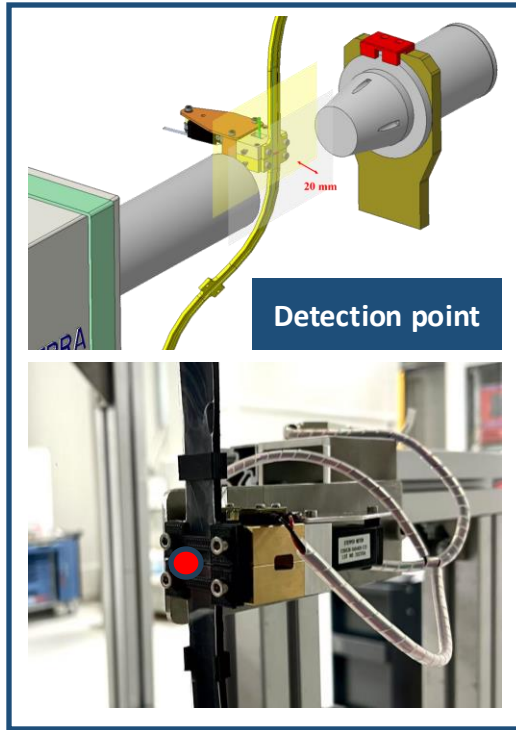


DECOUPLING

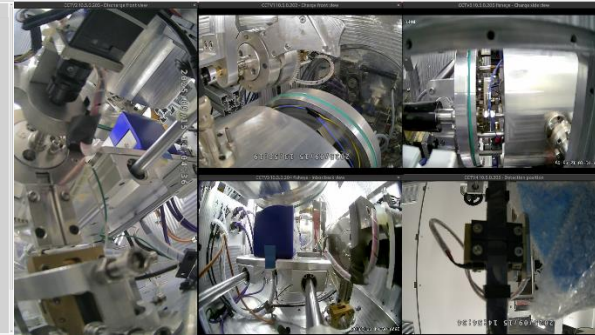
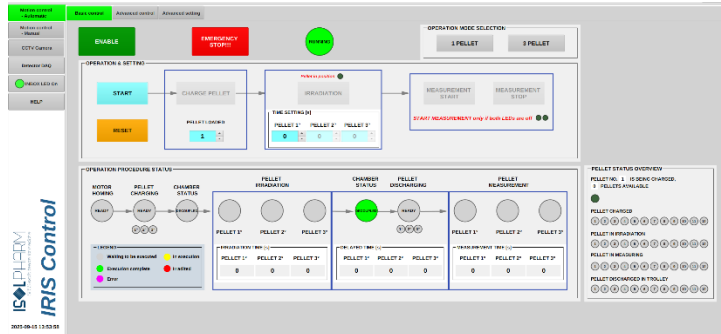


UNLOADING





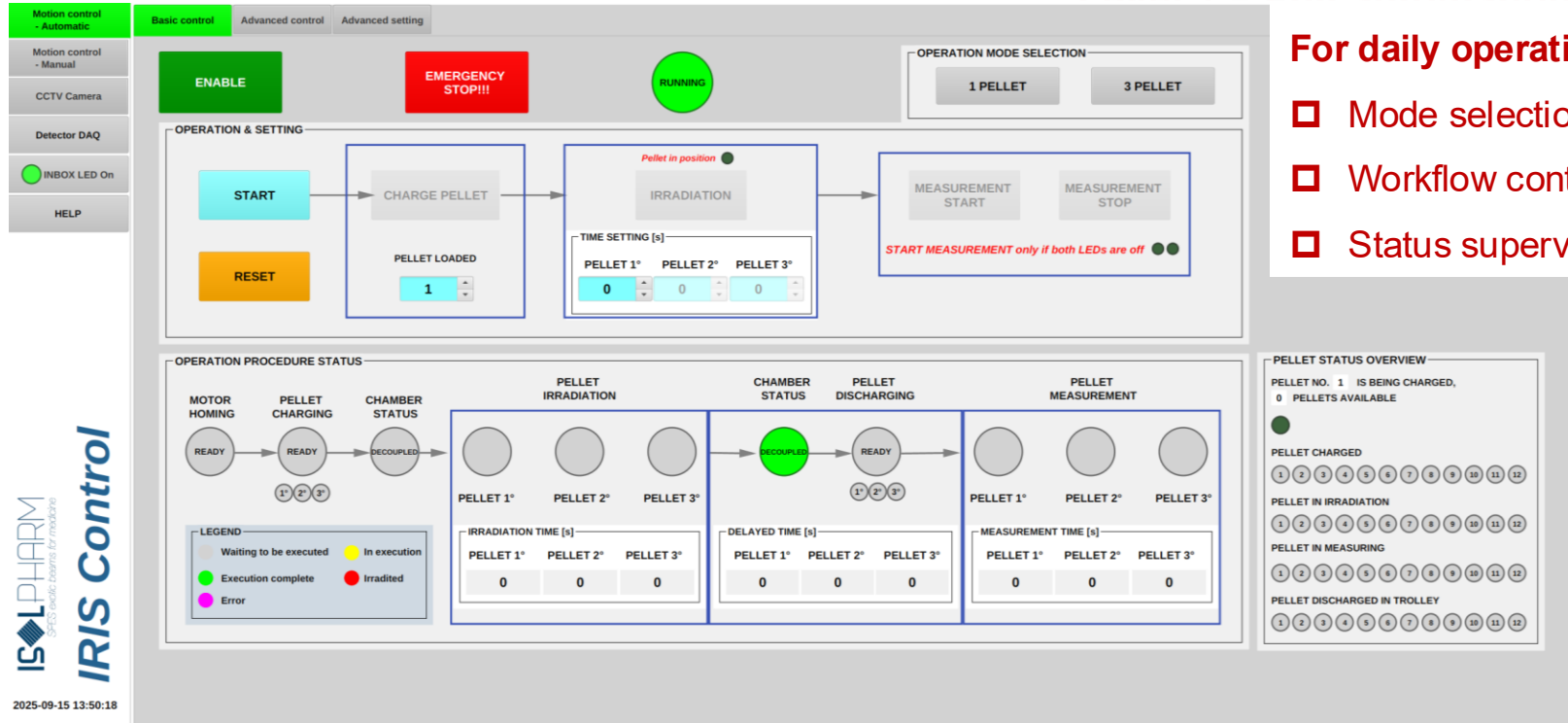
- ❑ **Multi-tab configuration** - Integrated, Intuitive, User-friendly, Constrained
- ❑ **Responsibility** - Control and Supervision
- ❑ **User-oriented GUI design**
 - Three motion control modes for various operational requirements
 - Constraints for preventing misoperation
 - Instant manual

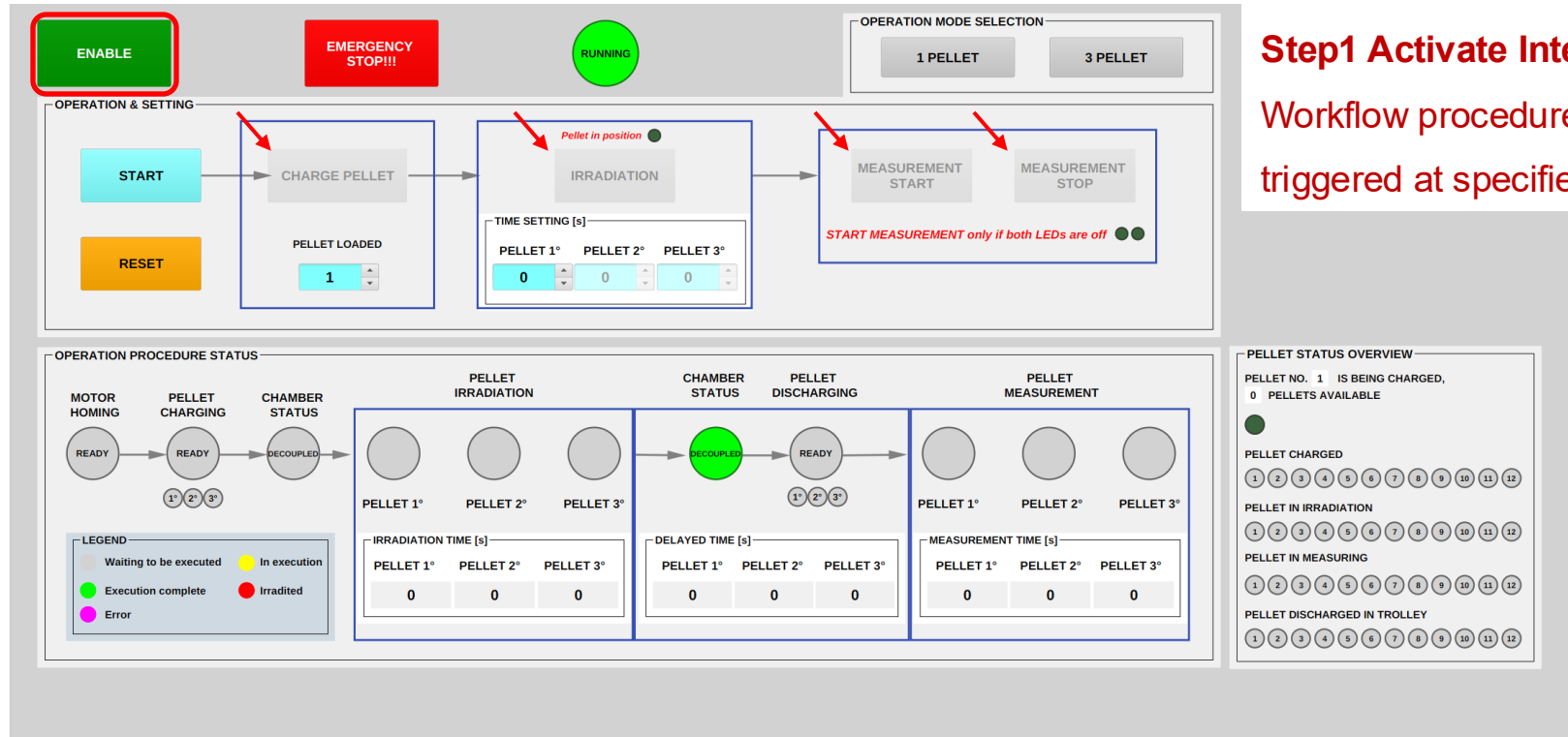


Level 1 – Full automation

For daily operation

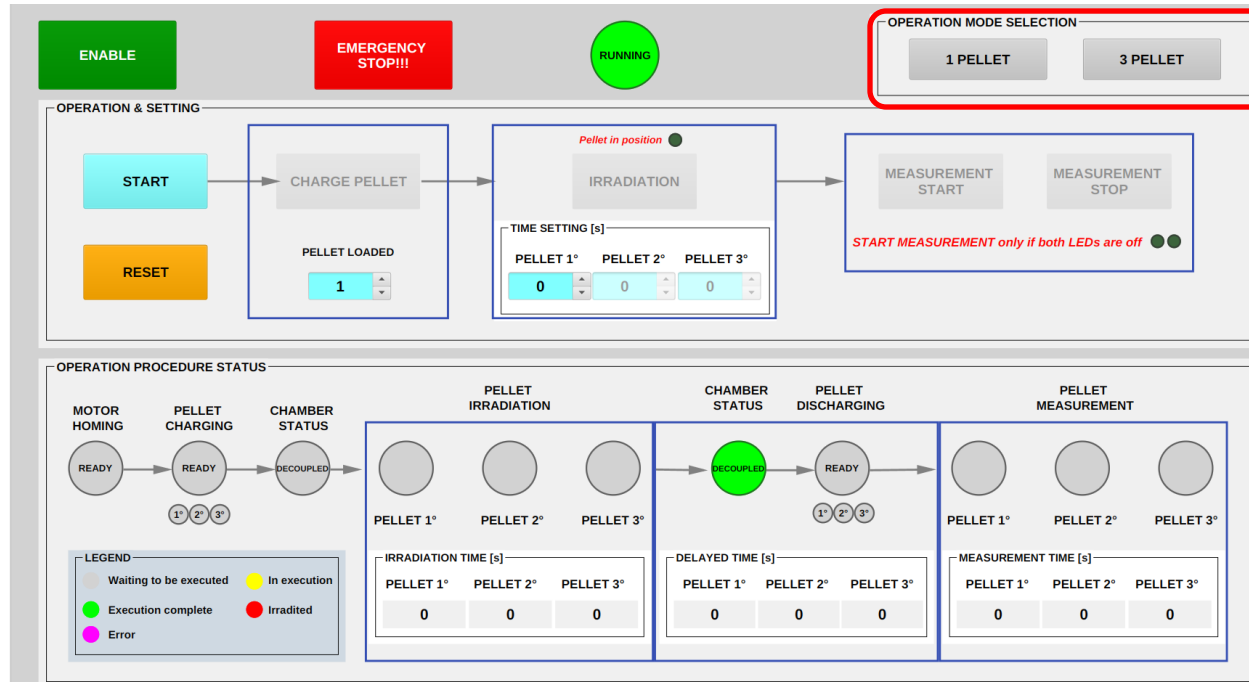
- ❑ Mode selection
- ❑ Workflow control
- ❑ Status supervision





Step1 Activate Interface

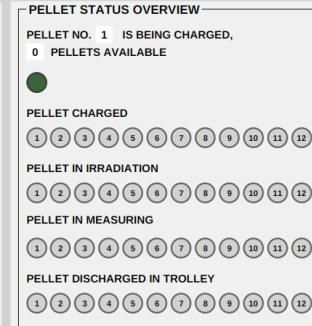
Workflow procedures deactivated,
triggered at specified conditions

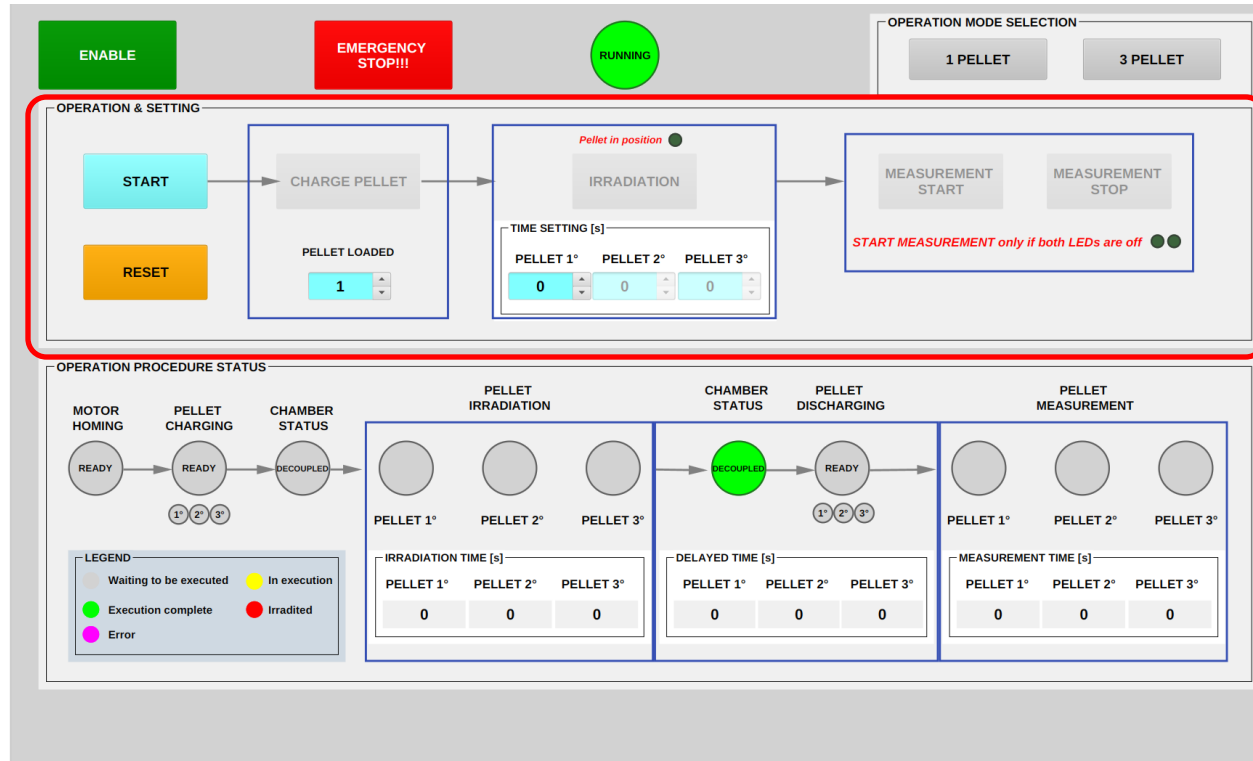


Step2 Select Operation Mode

1 pellet – system calibration tests

3 pellet – routine operation



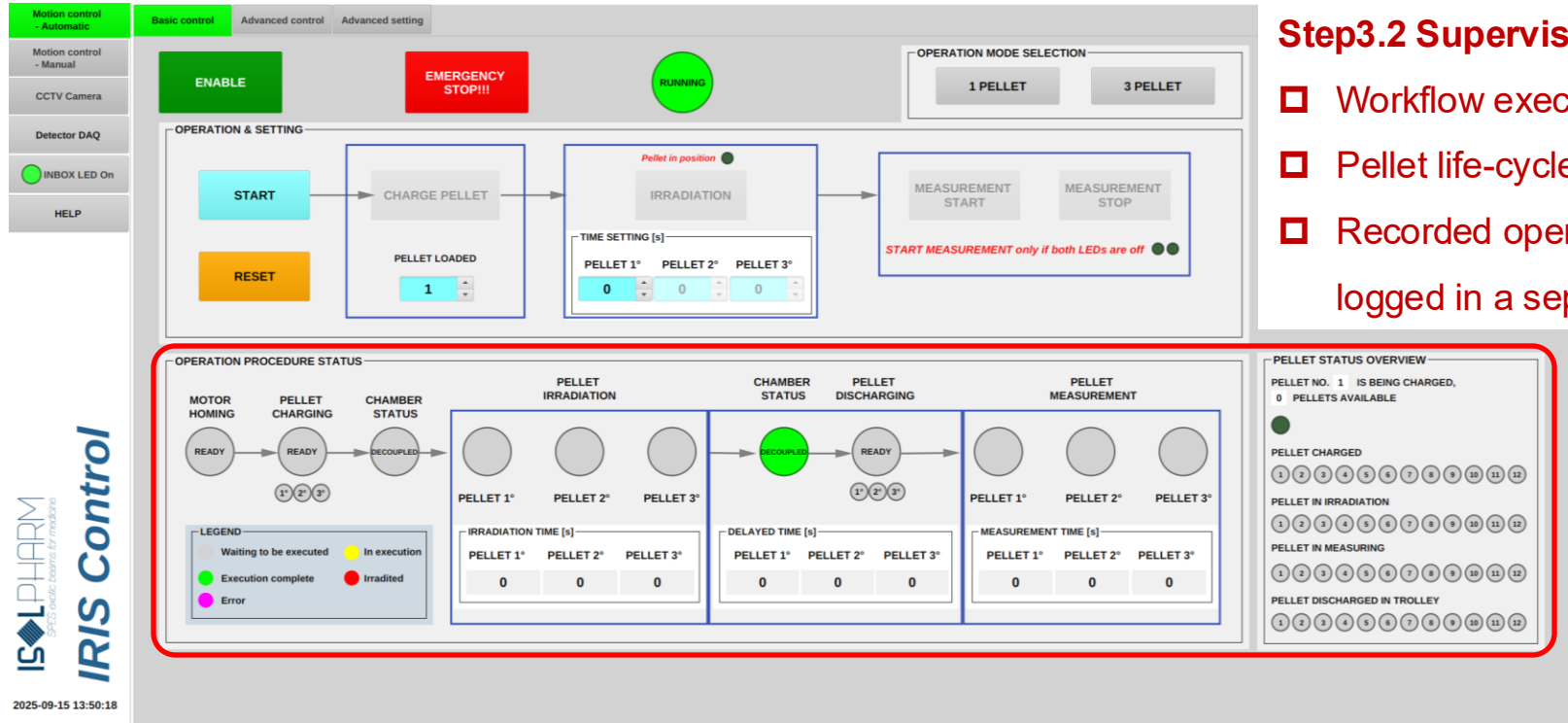


Step3.1

Proceed with assignments

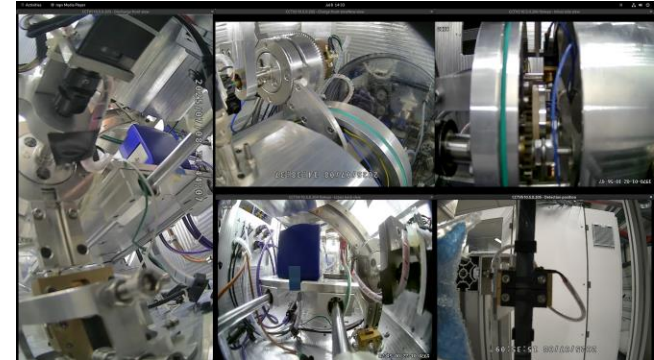
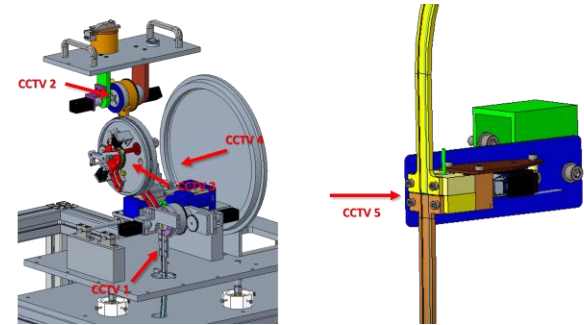
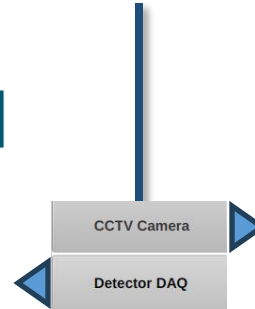
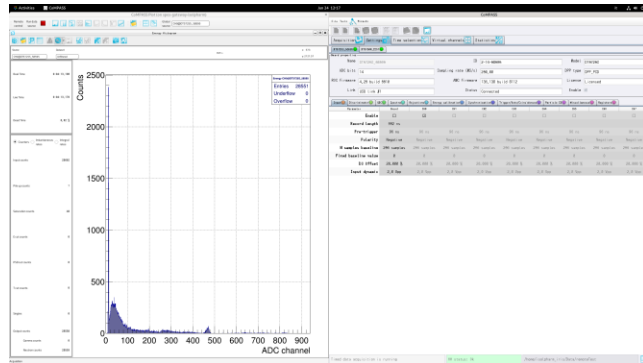
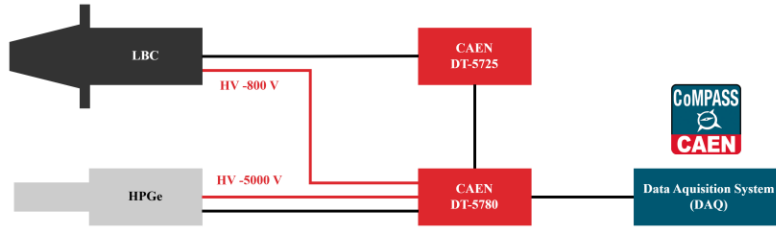
Customized parameters:

- ❑ Pellet loaded into the system
- ❑ Irradiation time for each pellet



Step3.2 Supervision

- ❑ Workflow execution
- ❑ Pellet life-cycle
- ❑ Recorded operation time, logged in a separate file



- ❑ Detection system DAQ and cameras are configured under local network with **separate systems**
- ❑ Integrated in the GUI as “one-click” calling up command, with executable scripts

Motion control - Automatic

Motion control - Manual

CCTV Camera

Detector DAQ

INBOX LED On

HELP

Basic control
Advanced control
Advanced setting

ENABLE

EMERGENCY STOP!!!

RUNNING

OPERATION MODE SELECTION

1 PELLET

3 PELLET

OPERATION & SETTING

START

CHARGE PELLET

RESET

PELLET LOADED

1

Pellet in position ●

IRRADIATION

TIME SETTING [s]

PELLET 1°	PELLET 2°	PELLET 3°
0	0	0

MEASUREMENT START

MEASUREMENT STOP

START MEASUREMENT only if both LEDs are off ●●

OPERATION PROCES

MOTOR HOMING

READY

irradiation time (s)

432000.00

432000.00

14400

delay time (s)

6.00E+02

6.00E+02

300

acquisition time (s)

21600

21600

172800

LEGEND

Waiting to be executed
In execution

Execution complete
Irradiated

Error

IRRADIATION TIME [s]

PELLET 1°	PELLET 2°	PELLET 3°
0	0	0

DELAYED TIME [s]

PELLET 1°	PELLET 2°	PELLET 3°
0	0	0

MEASUREMENT TIME [s]

PELLET 1°	PELLET 2°	PELLET 3°
0	0	0

PELLET IN MEASURING

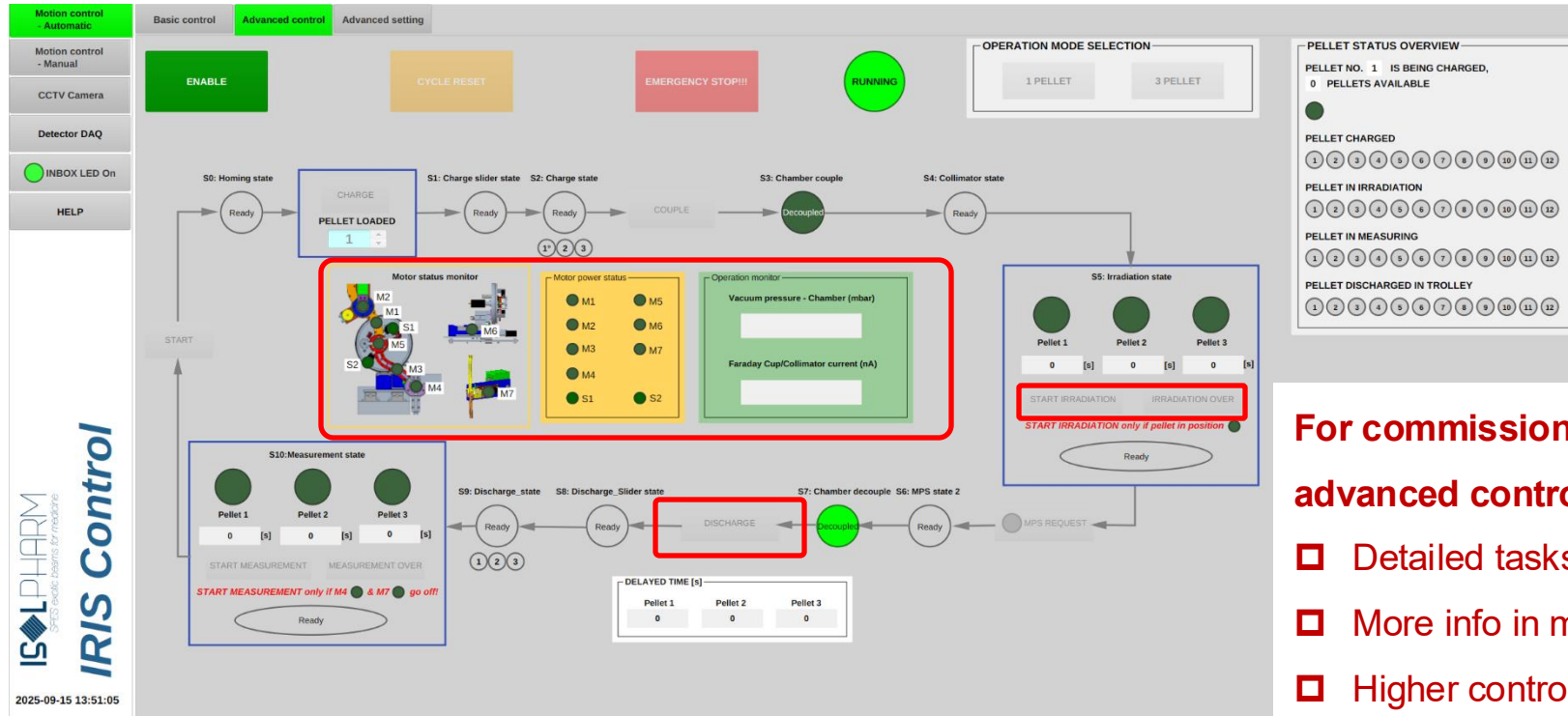
PELLET DISCHARGED IN TROLLEY

Step4 Data log and analysis

Physical quantities

- ❑ Radionuclide production
- ❑ Final yield

Level 2 – Semi-automation



For commissioning & advanced control

- ❑ Detailed tasks breakdown
- ❑ More info in monitoring
- ❑ Higher control freedom

Motion control - Automatic

Motion control - Manual

CCTV Camera

Detector DAQ

● INBOX LED On

HELP

Basic control
Advanced control
Advanced setting

M1 - Charge slider

● Power on

● Homed

● In movement

● In position

M2 - Charge buffer

● Power on

● Homed

● In movement

M3 - Discharge slider

● Power on

● Homed

● In movement

● In position

M4 - Discharge buffer

Exact steps

Correction steps

● Power on

● Homed

● In movement

M5 - Central movement

Charging

Exact steps 1	<input type="text" value="-237.000"/>	Correction steps 1	<input type="text" value="0.000"/>
Exact steps 2	<input type="text" value="-480.000"/>	Correction steps 2	<input type="text" value="0.000"/>
Exact steps 3	<input type="text" value="-712.000"/>	Correction steps 3	<input type="text" value="0.000"/>

Irradiation

Exact steps 1	<input type="text" value="45.000"/>	Correction steps 1	<input type="text" value="0.000"/>
Exact steps 2	<input type="text" value="92.000"/>	Correction steps 2	<input type="text" value="0.000"/>
Exact steps 3	<input type="text" value="143.000"/>	Correction steps 3	<input type="text" value="0.000"/>

Discharging

Exact steps	<input type="text" value="250.000"/>	Correction steps	<input type="text" value="0.000"/>
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● Power on ● Homed ● In movement

M6 - Longitudinal axis

● Power on

● Homed

● In movement

● In position

M7 - Tablet block

● Power on

● Homed

● In movement

● In position

You can even tune the exact motor axis steps here

Level 3 - Manual



**For commissioning,
fully customized movements**

- ☐ Motor movements and presets
- ☐ Motor status monitoring
- ☐ Solenoid movements

- IRIS control system have been built and commissioned regarding operational capabilities
- Further commissioning is expected in the first implantation experiments
- Functionality and GUI could be upgraded from the perspective of third-party utilization, comments and suggestions are welcome

