## EEPROM MEMORY FW (PSoC 5 firmware - SoftHand Pro and Generic)

	BYTE 1 BYTE 2 BYTE 3 BYTE 4 BYTE 5 BYTE 6 BYTE 7 BYTE 8 BYTE 9 BYTE 10 BYTE 11 BYTE 12 BYTE 13 BYTE 14 BYTE 15 BYTE 16								STRUCT NAME
1	FLAG UNUSED BYTES (15)								
2	EMG ACTIVATION COUNTER 1	EMG ACTIVATION COUNTER 2		POSITION HISTOGRAM[0]		POSITION HISTOGRAM[1]			
3	POSITION HISTOGRAM[2] POSITION HIST		Λ[3]	POSITION HISTOGRAM[4]		POSITION HISTOGRAM[5]			
4	POSITION HISTOGRAM[6] POSITION HISTOG		Л[7]	7] POSITION HISTOGRAM[8]		POSITION HISTOGRAM[9]			CNT
5	CURRENT HISTOGRAM[0] CURRENT HIS		N[1]	CURRENT HISTOGRAM[2]		CURRENT HISTOGRAM[3]			CIVI
6	REST COUNTER WIRE DI			TOTAL RUNTIME		TIME REST			
7	POWER CYCLES EXCESSIVE SIGNAL ACTIVITY[0]		/ITY[0]	EXCESSIVE SIGNAL ACTIVITY[1]					
8			UNUSED E	/TES 1 (16)					
9	UNUSED BYTES 1 (16)								
10									
11	ID HW MAINT. HW MAINT. HW MAINT.	STATS PERIOD STATS PERIOD STATS PERIOD		RESET USE 2ND BAUDRATE	USER ID	DEV TYPE			DEV
	DAY MONTH YEAR  KP	BEGIN DAY BEGIN MONTH BEGIN YEA	К	COUNTERS MOTOR BAODINATE	I		_C		521
12	KI_C KD_C			KP_DL		KI_DL			
13	KD_DL		KP_CDL		KI_CDL		KD_CDL		
14	ACTIV PWM DRIVER MOTOR POSITION	POS_LIM_INF				MAX STEP NEG			MOTOR[0]
15	RESCALING TYPE LIMIT FLAG  MAX STEP POS			POS_LIM_SUP		CURRENT LOOKUP 2			ΙνίΟΤΟΚ[υ]
16		CURRENT LOOKUP_0		CURRENT LOOKUP_1					
17	CURRENT LOOKUP_3  ENCODER PWM RATE NOT REVERS.	CURRENT LOOKUP_4		CURRENT LOOKUP_5		CURR_LIMIT	INPUT CONTR		
18	LINE LIMITER FLAG					ı			
19	KP KI			KD		KP_C			
20	KI_C	KD_C	KD_C		KP_DL		KI_DL		
21	KD_DL	KP_CDL		KI_CDL		KD_CDL			
22	ACTIV PWM DRIVER MOTOR POSITION RESCALING TYPE LIMIT FLAG	POS_LIM_INF		POS_LIM_SUP		MAX STEP NEG			MOTOR[1]
23	MAX STEP POS CURRENT LOG		_0	CURRENT LOOKUP_1		CURRENT LOOKUP_2			
24	CURRENT LOOKUP_3 CURRENT LOOKUP_4			CURRENT LOOKUP_5		CURR_LIMIT INPUT CONTR			
25	ENCODER PWM RATE NOT REVERS.  LINE LIMITER FLAG								
26	ENCODER RAW READ CONF FLAGS	DER RAW READ CONF FLAGS (5) RESOLUTION (3)		OFFSET 0		OFFSET 1			
27	OFFSET 2	MULTIPLIER 0		MULTIPLIER 1		MULTIPLIER 2			ENC[0]
28	DOUBLE HANDLE ENCODER IDX USE FOR RATIO	ENCODER IDX USE FOR CONTROL GEARS PARAM GEARS PARAM N1 N2 II							
29	ENCODER RAW READ CONF FLAGS (5) RESOLUTION (3)			OFFSET 0		OFFSET 1			
30	OFFSET 2 MULTIPI			MULTIPLIER 1		MULTIPLIER 2			ENC[1]
31	DOUBLE HANDLE ENCODER IDX USE FOR								
32	EMG THRESHOLD 1 EMG THRESHOLD 2			EMG MAX VALUE 2		EMG SPEED 0 EMG SPEED 1 EMG CALIB. SWITCH			EMG
	READ IMU SPI READ IMU CONF FLAGS (5) - IMU 0			IMU CONF FLAGS (5) - IMU 1	IMU CONF FLA	STARTUP EMG AGS (4) - IMU 2			
33	IMU FLAG IMU CONF FLAGS (5) - IMU 3			DNF FLAGS (5) - IMU 4					IMU
34	CHECKED TIME (6) READ EXP READ AD			ADC CONF FLAGS (12) - CHANNEL [0,7]					
35	ADC CONF FLAGS (12) - CHANNEL [8,11]	DC CONF FLAGS (12) - CHANNEL [8 11] RECORD EMG						EXP	
36	USER CODE STRING			USER EMG STRUCT					
37	USER EMG STRUCT			OJEN EINIO JINOCI					USER[0]
38	USER CODE STRING			USER EMG STRUCT					
39				OSEK EINIG STRUCT					USER[1]
40	USER EMG STRUCT								
41	USER CODE STRING			USER EMG STRUCT					USER[2]
42	USER EMG STRUCT			PEST POSITION VEI REST					
43	REST POSITION	REST POSITION DEL	AY	REST POSITION VEL		POSITION POSITION			SH
44	JOYSTICK CLOSURE SPEED JOYSTICK THRESHOLD	JOYSTICK JOYSTICK GAIN 1 GAIN 2							JOY
45	SLAVE COMM ACTIVE SLAVE ID								MS
46	MAXIMUM RESIDUAL CURRENT MAXIMUM PRESSURE KPA			PROPORTIONAL ERROR FB GAIN					FB
47	WRIST ACT. THRESHOLD 1 FAST ACT. THRESHOLD 2 DIRECTION ASSOCIATION								WR
48									

Each struct size is multiple of 16 bytes (EEPROM row length)