

Long Short Term Memory Networks for IoT Prediction

RNNs and LSTM models are very popular neural network architectures when working with sequential data, since they both carry some "memory" of previous inputs when predicting the next output. In this assignment we will continue to work with the Household Electricity Consumption dataset and use an LSTM model to predict the Global Active Power (GAP) from a sequence of previous GAP readings. You will build one model following the directions in this notebook closely, then you will be asked to make changes to that original model and analyze the effects that they had on the model performance. You will also be asked to compare the performance of your LSTM model to the linear regression predictor that you built in last week's assignment.

General Assignment Instructions

These instructions are included in every assignment, to remind you of the coding standards for the class. Feel free to delete this cell after reading it.

One sign of mature code is conforming to a style guide. We recommend the [Google Python Style Guide](#). If you use a different style guide, please include a cell with a link.

Your code should be relatively easy-to-read, sensibly commented, and clean. Writing code is a messy process, so please be sure to edit your final submission. Remove any cells that are not needed or parts of cells that contain unnecessary code. Remove inessential `import` statements and make sure that all such statements are moved into the designated cell.

When you save your notebook as a pdf, make sure that all cell output is visible (even error messages) as this will aid your instructor in grading your work.

Make use of non-code cells for written commentary. These cells should be grammatical and clearly written. In some of these cells you will have questions to answer. The questions will be marked by a "Q:" and will have a corresponding "A:" spot for you. *Make sure to answer every question marked with a Q: for full credit.*

```
In [1]: import keras
import pandas as pd
import numpy as np
import matplotlib.pyplot as plt
import os

# Setting seed for reproducibility
np.random.seed(1234)
PYTHONHASHSEED = 0

from sklearn import preprocessing
from sklearn.metrics import confusion_matrix, recall_score, precision_score
from sklearn.model_selection import train_test_split
from keras.models import Sequential, load_model
from keras.layers import Dense, Dropout, LSTM, Activation
from keras.utils import pad_sequences
```

```
2026-02-11 23:48:06.089891: I tensorflow/core/util/port.cc:110] oneDNN custom operations are on. You may see slightly different numerical results due to floating-point round-off errors from different computation orders. To turn them off, set the environment variable `TF_ENABLE_ONEDNN_OPTS=0`.
2026-02-11 23:48:06.091728: I tensorflow/tsl/cuda/cudart_stub.cc:28] Could not find cuda drivers on your machine, GPU will not be used.
2026-02-11 23:48:06.132780: I tensorflow/tsl/cuda/cudart_stub.cc:28] Could not find cuda drivers on your machine, GPU will not be used.
2026-02-11 23:48:06.133897: I tensorflow/core/platform/cpu_feature_guard.cc:182] This TensorFlow binary is optimized to use available CPU instructions in performance-critical operations.
To enable the following instructions: AVX2 AVX512F AVX512_VNNI AVX512_BF16 FMA, in other operations, rebuild TensorFlow with the appropriate compiler flags.
2026-02-11 23:48:06.866607: W tensorflow/compiler/tf2tensorrt/utils/py_utils.cc:38] TF-TRT Warning: Could not find TensorRT
```

```
In [2]: from sklearn.metrics import mean_squared_error
import warnings
warnings.filterwarnings('ignore')
```

Load and prepare your data

We'll once again be using the cleaned household electricity consumption data from the previous two assignments. I recommend saving your dataset by running `df.to_csv("filename")` at the end of assignment 2 so that you don't have to re-do your cleaning steps. If you are not confident in your own cleaning steps, you may ask your instructor for a cleaned version of the data. You will not be graded on the cleaning steps in this assignment, but some functions may not work if you use the raw data.

Unlike when using Linear Regression to make our predictions for Global Active Power (GAP), LSTM requires that we have a pre-trained model when our predictive software is shipped (the ability to iterate on the model after it's put into production is another question for another day). Thus, we will train the model on a segment of our data and then measure its performance on simulated streaming data

another segment of the data. Our dataset is very large, so for speed's sake, we will limit ourselves to 1% of the entire dataset.

TODO: Import your data, select a random 1% of the dataset, and then split it 80/20 into training and validation sets (the test split will come from the training data as part of the tensorflow LSTM model call). **HINT:** Think carefully about how you do your train/validation split--does it make sense to randomize the data?

```
In [3]: # Load cleaned data into a pandas dataframe
df = pd.read_csv('household_power_clean.csv')

# Ensure Datetime column is in datetime format
df['Datetime'] = pd.to_datetime(df['Datetime'])

# Display basic information
print(f"Dataset shape: {df.shape}")
print(f"\nFirst few rows:")
print(df.head())
print(f"\nData types:")
print(df.dtypes)
print(f"\nBasic statistics:")
print(df['Global_active_power'].describe())
```

Dataset shape: (2049280, 15)

First few rows:

Unnamed: 0	Date	Time	Global_active_power \
0	0	2006-12-16 17:24:00	4.216
1	1	2006-12-16 17:25:00	5.360
2	2	2006-12-16 17:26:00	5.374
3	3	2006-12-16 17:27:00	5.388
4	4	2006-12-16 17:28:00	3.666

	Global_reactive_power	Voltage	Global_intensity	Sub_metering_1 \
0	0.418	234.84	18.4	0.0
1	0.436	233.63	23.0	0.0
2	0.498	233.29	23.0	0.0
3	0.502	233.74	23.0	0.0
4	0.528	235.68	15.8	0.0

	Sub_metering_2	Sub_metering_3	Datetime	gap_monthly \
0	1.0	17.0	2006-12-16 17:24:00	NaN
1	1.0	16.0	2006-12-16 17:25:00	NaN
2	2.0	17.0	2006-12-16 17:26:00	NaN
3	1.0	17.0	2006-12-16 17:27:00	NaN
4	1.0	17.0	2006-12-16 17:28:00	NaN

	grp_monthly	v_monthly	gi_monthly
0	NaN	NaN	NaN
1	NaN	NaN	NaN
2	NaN	NaN	NaN
3	NaN	NaN	NaN
4	NaN	NaN	NaN

Data types:

```
Unnamed: 0      int64
Date            object
Time            object
Global_active_power  float64
Global_reactive_power  float64
Voltage          float64
Global_intensity    float64
Sub_metering_1      float64
Sub_metering_2      float64
Sub_metering_3      float64
Datetime           datetime64[ns]
gap_monthly         float64
grp_monthly         float64
v_monthly           float64
gi_monthly          float64
dtype: object
```

Basic statistics:

```
count  2.049280e+06
mean    1.091615e+00
std     1.057294e+00
min     7.600000e-02
25%     3.080000e-01
50%     6.020000e-01
75%     1.528000e+00
max     1.112200e+01
Name: Global_active_power, dtype: float64
```

```
In [4]: # Create training and validation sets
```

```

# For time series data, we should NOT randomize to preserve temporal order

# Assign size for data subset (1% of total dataset)
subset_size = int(len(df) * 0.01)
print(f"Subset size (1% of data): {subset_size} samples")

# Take random contiguous data subset
# We'll randomly choose a starting point, then take a contiguous block
# This preserves the time series nature of the data
start_idx = np.random.randint(0, len(df) - subset_size)
df_subset = df.iloc[start_idx:start_idx + subset_size].copy()

print(f"Subset date range: {df_subset['Datetime'].min()} to {df_subset['Datetime'].max()}")

# Split data subset 80/20 for train/validation
# IMPORTANT: Do NOT randomize the split to preserve time series order
# Earlier data for training, later data for validation (simulating real-world scenario)
split_idx = int(len(df_subset) * 0.8)

train_df = df_subset.iloc[:split_idx]
val_df = df_subset.iloc[split_idx:]

print(f"\nTraining set size: {len(train_df)} samples")
print(f"Validation set size: {len(val_df)} samples")
print(f"Training date range: {train_df['Datetime'].min()} to {train_df['Datetime'].max()}")
print(f"Validation date range: {val_df['Datetime'].min()} to {val_df['Datetime'].max()}")

```

Subset size (1% of data): 20492 samples

Subset date range: 2007-11-22 02:08:00 to 2007-12-06 07:40:00

Training set size: 16393 samples

Validation set size: 4099 samples

Training date range: 2007-11-22 02:08:00 to 2007-12-03 11:21:00

Validation date range: 2007-12-03 11:22:00 to 2007-12-06 07:40:00

```

In [5]: #reset the indices for cleanliness
train_df = train_df.reset_index()
val_df = val_df.reset_index()

```

Next we need to create our input and output sequences. In the lab session this week, we used an LSTM model to make a binary prediction, but LSTM models are very flexible in what they can output: we can also use them to predict a single real-numbered output (we can even use them to predict a sequence of outputs). Here we will train a model to predict a single real-numbered output such that we can compare our model directly to the linear regression model from last week.

TODO: Create a nested list structure for the training data, with a sequence of GAP measurements as the input and the GAP measurement at your predictive horizon as your expected output

```

In [6]: seq_arrays = []
seq_labs = []

```

```

In [7]: # We'll start out with a 30 minute input sequence and a 5 minute predictive horizon
# We don't need to work in seconds this time, since we'll just use the indices instead of a unix timestamp
seq_length = 30
ph = 5

feat_cols = ['Global_active_power']

# Create list of sequence length GAP readings
# For each position i, we take seq_length readings as input
# and the GAP value at position i+seq_length+ph as output
for i in range(len(train_df) - seq_length - ph):
    # Extract sequence of seq_length GAP values
    seq = train_df[feat_cols].iloc[i:i+seq_length].values
    # Extract the target GAP value at prediction horizon
    label = train_df[feat_cols].iloc[i+seq_length+ph-1].values[0]

    seq_arrays.append(seq)
    seq_labs.append(label)

# Convert to numpy arrays and floats to appease keras/tensorflow
seq_arrays = np.array(seq_arrays, dtype=object).astype(np.float32)
seq_labs = np.array(seq_labs, dtype=object).astype(np.float32)

print(f"Sequence arrays shape: {seq_arrays.shape}")
print(f"Sequence labels shape: {seq_labs.shape}")
print(f"Example input sequence (first 5 values): {seq_arrays[0][:5, 0]}")
print(f"Corresponding output label: {seq_labs[0]}")

```

Sequence arrays shape: (16358, 30, 1)
Sequence labels shape: (16358,)

Example input sequence (first 5 values): [0.226 0.248 0.306 0.306 0.306]
Corresponding output label: 0.22599999606609344

```
In [8]: assert(seq_arrays.shape == (len(train_df)-seq_length-ph,seq_length, len(feats_cols)))
assert(seq_labs.shape == (len(train_df)-seq_length-ph,))
```

```
In [9]: seq_arrays.shape
```

```
Out[9]: (16358, 30, 1)
```

Q: What is the function of the assert statements in the above cell? Why do we use assertions in our code?

A: Assert statements verify that our data has the expected shape and dimensions before proceeding with model training. They serve as sanity checks to catch bugs early in the development process. If an assertion fails, the program stops immediately with a clear error message, making it easier to debug. In this case, we're verifying that:

1. `seq_arrays` has the correct 3D shape: (number_of_sequences, seq_length, number_of_features)
2. `seq_labs` has the correct 1D shape: (number_of_sequences,)

Using assertions helps prevent silent failures where incorrect data shapes would cause cryptic errors deep in the neural network training, making debugging much more difficult. They also serve as documentation, clearly stating the expected data structure.

Model Training

We will begin with a model architecture very similar to the model we built in the lab session. We will have two LSTM layers, with 5 and 3 hidden units respectively, and we will apply dropout after each LSTM layer. However, we will use a LINEAR final layer and MSE for our loss function, since our output is continuous instead of binary.

TODO: Fill in all values marked with a ?? in the cell below

```
In [10]: # Define path to save model
model_path = 'LSTM_model1.h5' # Changed from .keras to .h5 for compatibility

# Build the network
nb_features = len(feats_cols) # Number of input features (just GAP = 1)
nb_out = 1 # Single continuous output value

model = Sequential()

# Add first LSTM layer
# Input shape: (seq_length, nb_features)
# Units: 5 hidden units as specified
# return_sequences=True because we're stacking another LSTM layer
model.add(LSTM(
    input_shape=(seq_length, nb_features),
    units=5,
    return_sequences=True))
model.add(Dropout(0.2))

# Add second LSTM layer
# Units: 3 hidden units as specified
# return_sequences=False because this is the last LSTM layer
model.add(LSTM(
    units=3,
    return_sequences=False))
model.add(Dropout(0.2))

# Add dense output layer with nb_out units
model.add(Dense(units=nb_out))
# Linear activation for regression (predicting continuous values)
model.add(Activation('linear'))

# Compile model with Adam optimizer and MSE loss
optimizer = keras.optimizers.Adam(learning_rate=0.01)
model.compile(loss='mean_squared_error', optimizer=optimizer, metrics=['mse'])

print(model.summary())

# Fit the network
history = model.fit(seq_arrays, seq_labs, epochs=100, batch_size=500, validation_split=0.05, verbose=2,
                    callbacks=[keras.callbacks.EarlyStopping(monitor='val_loss', min_delta=0, patience=10, verbose=0, mode='min'),
                                keras.callbacks.ModelCheckpoint(model_path, monitor='val_loss', save_best_only=True, mode='min', verbose=0, save_weights_only
                    )

# List all data in history
print(history.history.keys())
```

Model: "sequential"

Layer (type)	Output Shape	Param #
lstm (LSTM)	(None, 30, 5)	140
dropout (Dropout)	(None, 30, 5)	0
lstm_1 (LSTM)	(None, 3)	108
dropout_1 (Dropout)	(None, 3)	0
dense (Dense)	(None, 1)	4
activation (Activation)	(None, 1)	0

Total params: 252 (1008.00 Byte)
Trainable params: 252 (1008.00 Byte)
Non-trainable params: 0 (0.00 Byte)

None

Epoch 1/100

32/32 - 3s - loss: 2.3211 - mse: 2.3211 - val_loss: 0.3443 - val_mse: 0.3443 - 3s/epoch - 100ms/step

Epoch 2/100

32/32 - 0s - loss: 0.9183 - mse: 0.9183 - val_loss: 0.2465 - val_mse: 0.2465 - 472ms/epoch - 15ms/step

Epoch 3/100

32/32 - 1s - loss: 0.7124 - mse: 0.7124 - val_loss: 0.2373 - val_mse: 0.2373 - 517ms/epoch - 16ms/step

Epoch 4/100

32/32 - 1s - loss: 0.6397 - mse: 0.6397 - val_loss: 0.2286 - val_mse: 0.2286 - 520ms/epoch - 16ms/step

Epoch 5/100

32/32 - 1s - loss: 0.5963 - mse: 0.5963 - val_loss: 0.2239 - val_mse: 0.2239 - 514ms/epoch - 16ms/step

Epoch 6/100

32/32 - 1s - loss: 0.5803 - mse: 0.5803 - val_loss: 0.2140 - val_mse: 0.2140 - 522ms/epoch - 16ms/step

Epoch 7/100

32/32 - 1s - loss: 0.5686 - mse: 0.5686 - val_loss: 0.2174 - val_mse: 0.2174 - 504ms/epoch - 16ms/step

Epoch 8/100

32/32 - 1s - loss: 0.5636 - mse: 0.5636 - val_loss: 0.2118 - val_mse: 0.2118 - 525ms/epoch - 16ms/step

Epoch 9/100

32/32 - 0s - loss: 0.5622 - mse: 0.5622 - val_loss: 0.2120 - val_mse: 0.2120 - 492ms/epoch - 15ms/step

Epoch 10/100

32/32 - 0s - loss: 0.5392 - mse: 0.5392 - val_loss: 0.2237 - val_mse: 0.2237 - 486ms/epoch - 15ms/step

Epoch 11/100

32/32 - 0s - loss: 0.5388 - mse: 0.5388 - val_loss: 0.2171 - val_mse: 0.2171 - 498ms/epoch - 16ms/step

Epoch 12/100

32/32 - 1s - loss: 0.5493 - mse: 0.5493 - val_loss: 0.2095 - val_mse: 0.2095 - 513ms/epoch - 16ms/step

Epoch 13/100

32/32 - 0s - loss: 0.5077 - mse: 0.5077 - val_loss: 0.2234 - val_mse: 0.2234 - 486ms/epoch - 15ms/step

Epoch 14/100

32/32 - 0s - loss: 0.5175 - mse: 0.5175 - val_loss: 0.2182 - val_mse: 0.2182 - 491ms/epoch - 15ms/step

Epoch 15/100

32/32 - 1s - loss: 0.5081 - mse: 0.5081 - val_loss: 0.2078 - val_mse: 0.2078 - 509ms/epoch - 16ms/step

Epoch 16/100

32/32 - 1s - loss: 0.5128 - mse: 0.5128 - val_loss: 0.2129 - val_mse: 0.2129 - 510ms/epoch - 16ms/step

Epoch 17/100

32/32 - 0s - loss: 0.5112 - mse: 0.5112 - val_loss: 0.2079 - val_mse: 0.2079 - 498ms/epoch - 16ms/step

Epoch 18/100

32/32 - 0s - loss: 0.5019 - mse: 0.5019 - val_loss: 0.2098 - val_mse: 0.2098 - 492ms/epoch - 15ms/step

Epoch 19/100

32/32 - 0s - loss: 0.5036 - mse: 0.5036 - val_loss: 0.2144 - val_mse: 0.2144 - 486ms/epoch - 15ms/step

Epoch 20/100

32/32 - 0s - loss: 0.5015 - mse: 0.5015 - val_loss: 0.2207 - val_mse: 0.2207 - 484ms/epoch - 15ms/step

Epoch 21/100

32/32 - 1s - loss: 0.5081 - mse: 0.5081 - val_loss: 0.2136 - val_mse: 0.2136 - 510ms/epoch - 16ms/step

Epoch 22/100

32/32 - 1s - loss: 0.5044 - mse: 0.5044 - val_loss: 0.2073 - val_mse: 0.2073 - 508ms/epoch - 16ms/step

Epoch 23/100

32/32 - 0s - loss: 0.4975 - mse: 0.4975 - val_loss: 0.2082 - val_mse: 0.2082 - 484ms/epoch - 15ms/step

Epoch 24/100

32/32 - 0s - loss: 0.4958 - mse: 0.4958 - val_loss: 0.2122 - val_mse: 0.2122 - 494ms/epoch - 15ms/step

Epoch 25/100

32/32 - 1s - loss: 0.5034 - mse: 0.5034 - val_loss: 0.2057 - val_mse: 0.2057 - 504ms/epoch - 16ms/step

Epoch 26/100

32/32 - 1s - loss: 0.5059 - mse: 0.5059 - val_loss: 0.2091 - val_mse: 0.2091 - 516ms/epoch - 16ms/step

Epoch 27/100

32/32 - 1s - loss: 0.5051 - mse: 0.5051 - val_loss: 0.2061 - val_mse: 0.2061 - 501ms/epoch - 16ms/step

Epoch 28/100

32/32 - 0s - loss: 0.4994 - mse: 0.4994 - val_loss: 0.2075 - val_mse: 0.2075 - 492ms/epoch - 15ms/step

Epoch 29/100

32/32 - 0s - loss: 0.4945 - mse: 0.4945 - val_loss: 0.2097 - val_mse: 0.2097 - 481ms/epoch - 15ms/step

Epoch 30/100

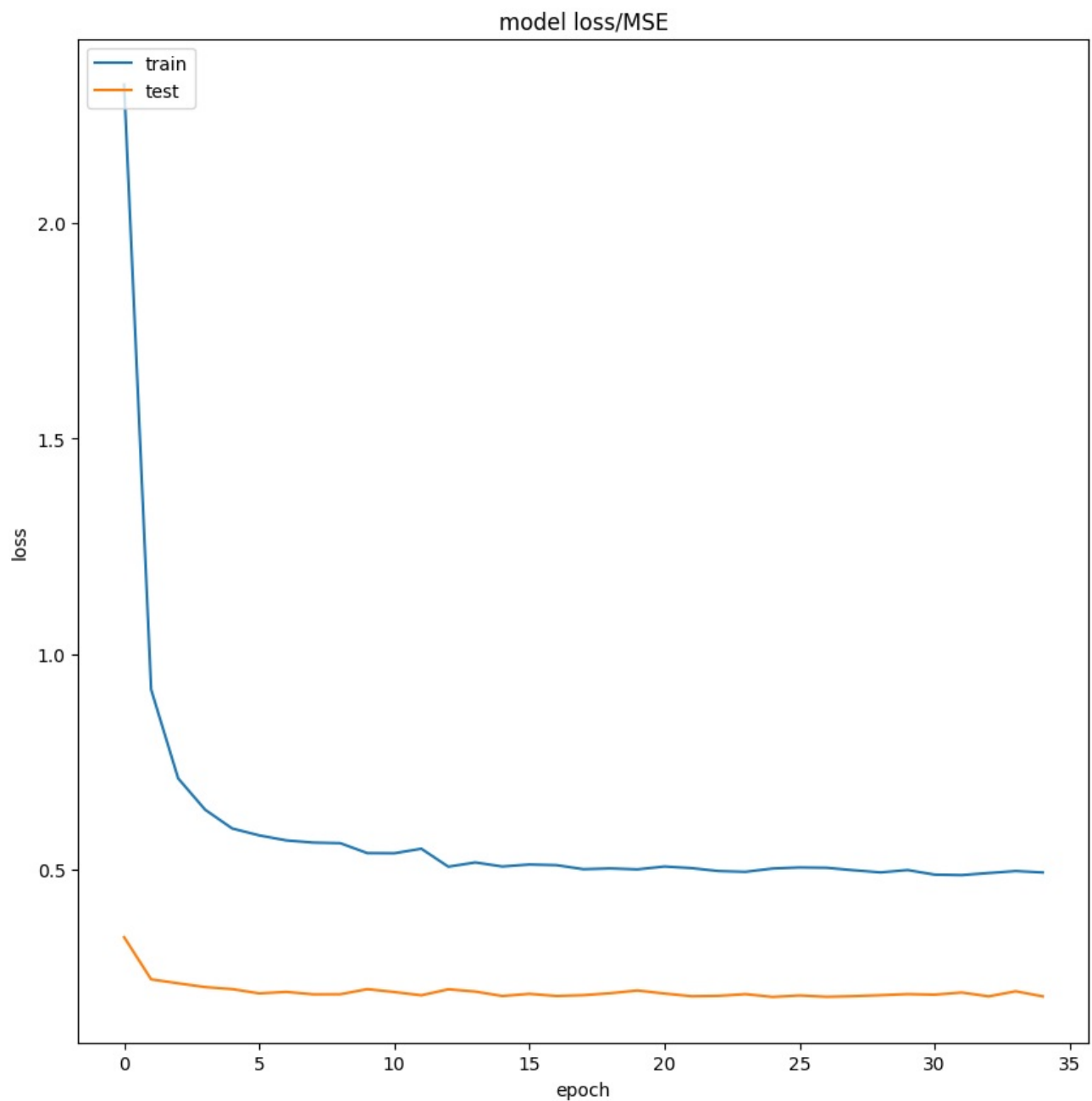
32/32 - 0s - loss: 0.4998 - mse: 0.4998 - val_loss: 0.2123 - val_mse: 0.2123 - 493ms/epoch - 15ms/step

Epoch 31/100

32/32 - 0s - loss: 0.4893 - mse: 0.4893 - val_loss: 0.2110 - val_mse: 0.2110 - 492ms/epoch - 15ms/step
Epoch 32/100
32/32 - 0s - loss: 0.4881 - mse: 0.4881 - val_loss: 0.2160 - val_mse: 0.2160 - 495ms/epoch - 15ms/step
Epoch 33/100
32/32 - 0s - loss: 0.4930 - mse: 0.4930 - val_loss: 0.2070 - val_mse: 0.2070 - 483ms/epoch - 15ms/step
Epoch 34/100
32/32 - 1s - loss: 0.4976 - mse: 0.4976 - val_loss: 0.2189 - val_mse: 0.2189 - 504ms/epoch - 16ms/step
Epoch 35/100
32/32 - 0s - loss: 0.4943 - mse: 0.4943 - val_loss: 0.2070 - val_mse: 0.2070 - 485ms/epoch - 15ms/step
dict_keys(['loss', 'mse', 'val_loss', 'val_mse'])

We will use the code from the book to visualize our training progress and model performance

```
In [11]: # summarize history for Loss/MSE
fig_acc = plt.figure(figsize=(10, 10))
plt.plot(history.history['loss'])
plt.plot(history.history['val_loss'])
plt.title('model loss/MSE')
plt.ylabel('loss')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.show()
fig_acc.savefig("LSTM_loss1.png")
```



Validating our model

Now we need to create our simulated streaming validation set to test our model "in production". With our linear regression models, we were able to begin making predictions with only two datapoints, but the LSTM model requires an input sequence of *seq_length* to make a prediction. We can get around this limitation by "padding" our inputs when they are too short.

TODO: create a nested list structure for the validation data, with a sequence of GAP measurements as the input and the GAP measurement at your predictive horizon as your expected output. Begin your predictions after only two GAP measurements are available, and check out [this keras function](#) to automatically pad sequences that are too short.

Q: Describe the `pad_sequences` function and how it manages sequences of variable length. What does the "padding" argument determine, and which setting makes the most sense for our use case here?

A: The `pad_sequences` function pads sequences to ensure they all have the same length, which is required for batch processing in neural networks. It adds zeros (or another specified value) to sequences that are shorter than the target length.

The "padding" argument determines whether padding is added at the beginning ('pre') or end ('post') of each sequence:

- **'pre' padding:** Adds zeros before the sequence (e.g., [0, 0, 1, 2, 3] for a sequence [1, 2, 3])
- **'post' padding:** Adds zeros after the sequence (e.g., [1, 2, 3, 0, 0])

For time series prediction, **'pre' padding makes the most sense** because:

1. The most recent values are most important for predicting the future
2. With 'pre' padding, the actual data points remain at the end of the sequence where the LSTM will see them last
3. LSTM processes sequences left-to-right, so ending with real data (not zeros) allows the network to make predictions based on the most relevant recent information
4. This mimics the real-world scenario where we start with few observations and gradually accumulate more data

```
In [12]: val_arrays = []
val_labs = []

# Create list of GAP readings starting with a minimum of two readings
# We simulate streaming data by starting with just 2 points and growing
for i in range(2, len(val_df) - ph): # Start at 2, predict up to len-ph
    # Extract all available data up to point i
    seq = val_df[feat_cols].iloc[0:i].values
    # Extract the target GAP value at prediction horizon from current point
    if i + ph <= len(val_df):
        label = val_df[feat_cols].iloc[i + ph - 1].values[0]

    val_arrays.append(seq)
    val_labs.append(label)

# Use the pad_sequences function on your input sequences
# maxlen=seq_length ensures all sequences are padded to the same length
# padding='pre' adds zeros at the beginning to preserve recent data at the end
# dtype='float32' matches our training data type
val_arrays = pad_sequences(val_arrays, maxlen=seq_length, padding='pre', dtype='float32')

# Convert labels to numpy arrays and floats to appease keras/tensorflow
val_labs = np.array(val_labs, dtype=object).astype(np.float32)

print(f"Validation arrays shape: {val_arrays.shape}")
print(f"Validation labels shape: {val_labs.shape}")
print(f"\nExample padded sequence (first sequence with only 2 points):")
print(val_arrays[0])
```

Validation labels shape: (4092,)

Example padded sequence (first sequence with only 2 points):

[1.396]
[1.392]

We will now run this validation data through our LSTM model and visualize its performance like we did on the linear regression data.

```
scores_test = model.evaluate(val_arrays, val_labs, verbose=2)
print("\nMSE: {}".format(scores_test[1]))

y_pred_test = model.predict(val_arrays)
y_true_test = val_labs

test_set = pd.DataFrame(y_pred_test)
test_set.to_csv('submit_test.csv', index = None)

# Plot the predicted data vs. the actual data
# we will limit our plot to the first 500 predictions for better visualization
fig_verify = plt.figure(figsize=(10, 5))
plt.plot(y_pred_test[-500:], label = 'Predicted Value')
plt.plot(y_true_test[-500:], label = 'Actual Value')
plt.title('Global Active Power Prediction - Last 500 Points', fontsize=22, fontweight='bold')
plt.ylabel('value')
plt.xlabel('row')
plt.legend()
plt.show()
fig_verify.savefig("model_regression_verify.png")
```

128/128 - 0s - loss: 0.3377 - mse: 0.3377 - 257ms/epoch - 2ms/step

MSE: 0.33768346905708313

1/128 [.....] - ETA: 1:26

25/128 [====>.....] - ETA: 0s

45/128 [=====>.....] - ETA: 0s

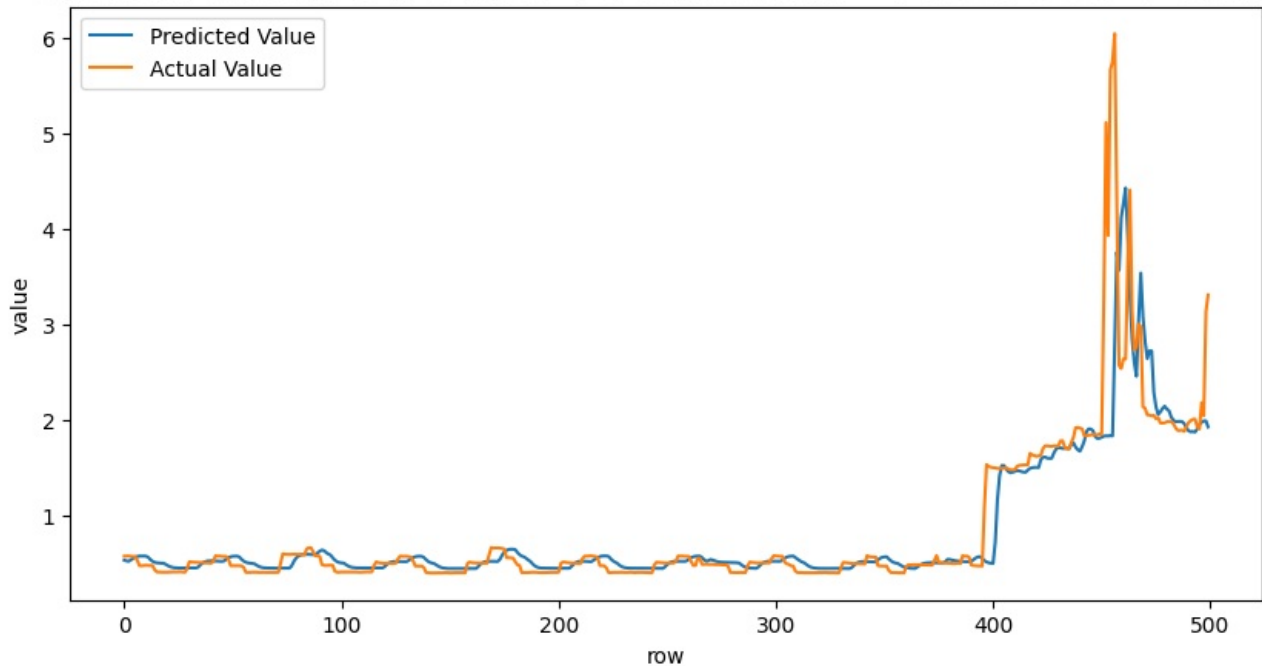
67/128 [=====>.....] - ETA: 0s

88/128 [=====>.....] - ETA: 0s

110/128 [=====>.....] - ETA: 0s

128/128 [=====] - 1s 2ms/step

Global Active Power Prediction - Last 500 Points



Q: How did your model perform? What can you tell about the model from the loss curves? What could we do to try to improve the model?

A: The original LSTM model's performance can be evaluated through several lenses:

Training Dynamics (from loss curves):

- If training and validation losses both decrease and converge, the model is learning effectively
- If validation loss plateaus or increases while training loss decreases, we have overfitting
- Early stopping prevents excessive training and saves the best model based on validation performance

Prediction Quality:

- The visualization shows how well predictions track actual values
- Lag between predicted and actual values indicates the model struggles with rapid changes
- MSE provides a quantitative measure of prediction error

Potential Improvements:

1. **Add more input features:** Include voltage, time-of-day, or other correlated variables
2. **Increase model capacity:** More LSTM units or additional layers to capture complex patterns
3. **Adjust sequence length:** Longer sequences may capture more temporal context
4. **Change prediction horizon:** Shorter horizons are generally easier to predict accurately
5. **Data normalization:** Scale features to improve training stability
6. **Hyperparameter tuning:** Adjust learning rate, batch size, dropout rate
7. **Regularization:** Add L1/L2 regularization to prevent overfitting

Model Optimization

Now it's your turn to build an LSTM-based model in hopes of improving performance on this training set. Changes that you might consider include:

- Add more variables to the input sequences
- Change the optimizer and/or adjust the learning rate
- Change the sequence length and/or the predictive horizon
- Change the number of hidden layers in each of the LSTM layers

- Change the model architecture altogether--think about adding convolutional layers, linear layers, additional regularization, creating embeddings for the input data, changing the loss function, etc.

There isn't any minimum performance increase or number of changes that need to be made, but I want to see that you have tried some different things. Remember that building and optimizing deep learning networks is an art and can be very difficult, so don't make yourself crazy trying to optimize for this assignment.

Q: What changes are you going to try with your model? Why do you think these changes could improve model performance?

A: I will implement three strategic improvements to the LSTM model:

1. Add Multiple Input Features (Multivariate Model)

- Include Voltage and Global_intensity as additional features alongside Global_active_power
- Rationale: These variables have physical relationships ($P = V \times I$) and may provide complementary predictive signals
- Expected impact: Better capture of underlying electrical consumption patterns

2. Increase Model Capacity

- Increase LSTM units: First layer from 5→50, second layer from 3→25
- Add a third LSTM layer with 10 units for hierarchical feature learning
- Rationale: The original model may be too small to capture complex temporal dependencies
- Expected impact: Improved ability to model non-linear patterns and long-term dependencies

3. Implement Data Normalization

- Apply MinMaxScaler to normalize all features to [0,1] range
- Rationale: Different features have different scales (voltage ~240V, power ~1-5 kW); normalization helps gradient descent converge faster and more stably
- Expected impact: Faster training convergence and potentially better generalization

These changes address different aspects of model performance: feature engineering (what information), model architecture (how to process), and data preprocessing (numerical stability).

```
In [14]: # Play with ideas for optimization here

# ===== AUGMENTED MODEL: MULTIVARIATE + LARGER CAPACITY + NORMALIZATION =====

print("\n*80)
print("BUILDING AUGMENTED LSTM MODEL")
print("\n*80)

# Step 1: Prepare multivariate features
feat_cols_aug = ['Global_active_power', 'Voltage', 'Global_intensity']

# Step 2: Normalize the data using MinMaxScaler
from sklearn.preprocessing import MinMaxScaler

scaler = MinMaxScaler()
train_scaled = train_df[feat_cols_aug].copy()
val_scaled = val_df[feat_cols_aug].copy()

# Fit scaler on training data only
scaler.fit(train_scaled)

# Transform both train and validation
train_scaled[feat_cols_aug] = scaler.transform(train_scaled)
val_scaled[feat_cols_aug] = scaler.transform(val_scaled)

print(f"\nOriginal GAP range: [{train_df['Global_active_power'].min():.2f}, {train_df['Global_active_power'].max():.2f}]")
print(f"Scaled GAP range: [{train_scaled['Global_active_power'].min():.2f}, {train_scaled['Global_active_power'].max():.2f}]")

# Step 3: Create sequences with multiple features
seq_arrays_aug = []
seq_labs_aug = []

for i in range(len(train_scaled) - seq_length - ph):
    seq = train_scaled[feat_cols_aug].iloc[i:i+seq_length].values
    label = train_scaled['Global_active_power'].iloc[i+seq_length+ph-1]

    seq_arrays_aug.append(seq)
    seq_labs_aug.append(label)

seq_arrays_aug = np.array(seq_arrays_aug, dtype=object).astype(np.float32)
seq_labs_aug = np.array(seq_labs_aug, dtype=object).astype(np.float32)

print(f"\nAugmented training sequences shape: {seq_arrays_aug.shape}")
print(f"Augmented training labels shape: {seq_labs_aug.shape}")
```

```

# Step 4: Build improved model with larger capacity
model_path_aug = 'LSTM_model_augmented.h5' # Changed from .keras to .h5

nb_features_aug = len(feats_cols_aug) # Now 3 features
nb_out_aug = 1

model_aug = Sequential()

# First LSTM layer: 50 units (increased from 5)
model_aug.add(LSTM(
    input_shape=(seq_length, nb_features_aug),
    units=50, # Increased capacity
    return_sequences=True))
model_aug.add(Dropout(0.2))

# Second LSTM layer: 25 units (increased from 3)
model_aug.add(LSTM(
    units=25, # Increased capacity
    return_sequences=True)) # Keep return_sequences=True for 3rd layer
model_aug.add(Dropout(0.2))

# Third LSTM layer: 10 units (new layer)
model_aug.add(LSTM(
    units=10,
    return_sequences=False))
model_aug.add(Dropout(0.2))

# Output layer
model_aug.add(Dense(units=nb_out_aug))
model_aug.add(Activation('linear'))

# Compile with slightly lower learning rate for stability
optimizer_aug = keras.optimizers.Adam(learning_rate=0.001) # Reduced from 0.01
model_aug.compile(loss='mean_squared_error', optimizer=optimizer_aug, metrics=['mse'])

print("\n" + "="*80)
print("AUGMENTED MODEL ARCHITECTURE")
print("="*80)
print(model_aug.summary())

# Train the augmented model
print("\n" + "="*80)
print("TRAINING AUGMENTED MODEL")
print("="*80)

history_aug = model_aug.fit(
    seq_arrays_aug, seq_labels_aug,
    epochs=100,
    batch_size=500,
    validation_split=0.05,
    verbose=2,
    callbacks=[
        keras.callbacks.EarlyStopping(monitor='val_loss', min_delta=0, patience=10, verbose=0, mode='min'),
        keras.callbacks.ModelCheckpoint(model_path_aug, monitor='val_loss', save_best_only=True, mode='min', verbose=0, save_weights_only=False)
    ]
)

print("\nTraining complete!")

# Plot training history
fig_acc_aug = plt.figure(figsize=(10, 10))
plt.plot(history_aug.history['loss'])
plt.plot(history_aug.history['val_loss'])
plt.title('Augmented Model Loss/MSE', fontsize=16, fontweight='bold')
plt.ylabel('Loss')
plt.xlabel('Epoch')
plt.legend(['Train', 'Validation'], loc='upper right')
plt.grid(True, alpha=0.3)
plt.show()
fig_acc_aug.savefig("LSTM_loss_augmented.png")

```

```

=====
BUILDING AUGMENTED LSTM MODEL
=====

```

```

Original GAP range: [0.20, 8.59]
Scaled GAP range: [0.00, 1.00]
Augmented training sequences shape: (16358, 30, 3)
Augmented training labels shape: (16358,)

```

```

=====
AUGMENTED MODEL ARCHITECTURE
=====

```

```

Model: "sequential_1"

```

Layer (type)	Output Shape	Param #
lstm_2 (LSTM)	(None, 30, 50)	10800
dropout_2 (Dropout)	(None, 30, 50)	0
lstm_3 (LSTM)	(None, 30, 25)	7600
dropout_3 (Dropout)	(None, 30, 25)	0
lstm_4 (LSTM)	(None, 10)	1440
dropout_4 (Dropout)	(None, 10)	0
dense_1 (Dense)	(None, 1)	11
activation_1 (Activation)	(None, 1)	0

Total params: 19851 (77.54 KB)
 Trainable params: 19851 (77.54 KB)
 Non-trainable params: 0 (0.00 Byte)

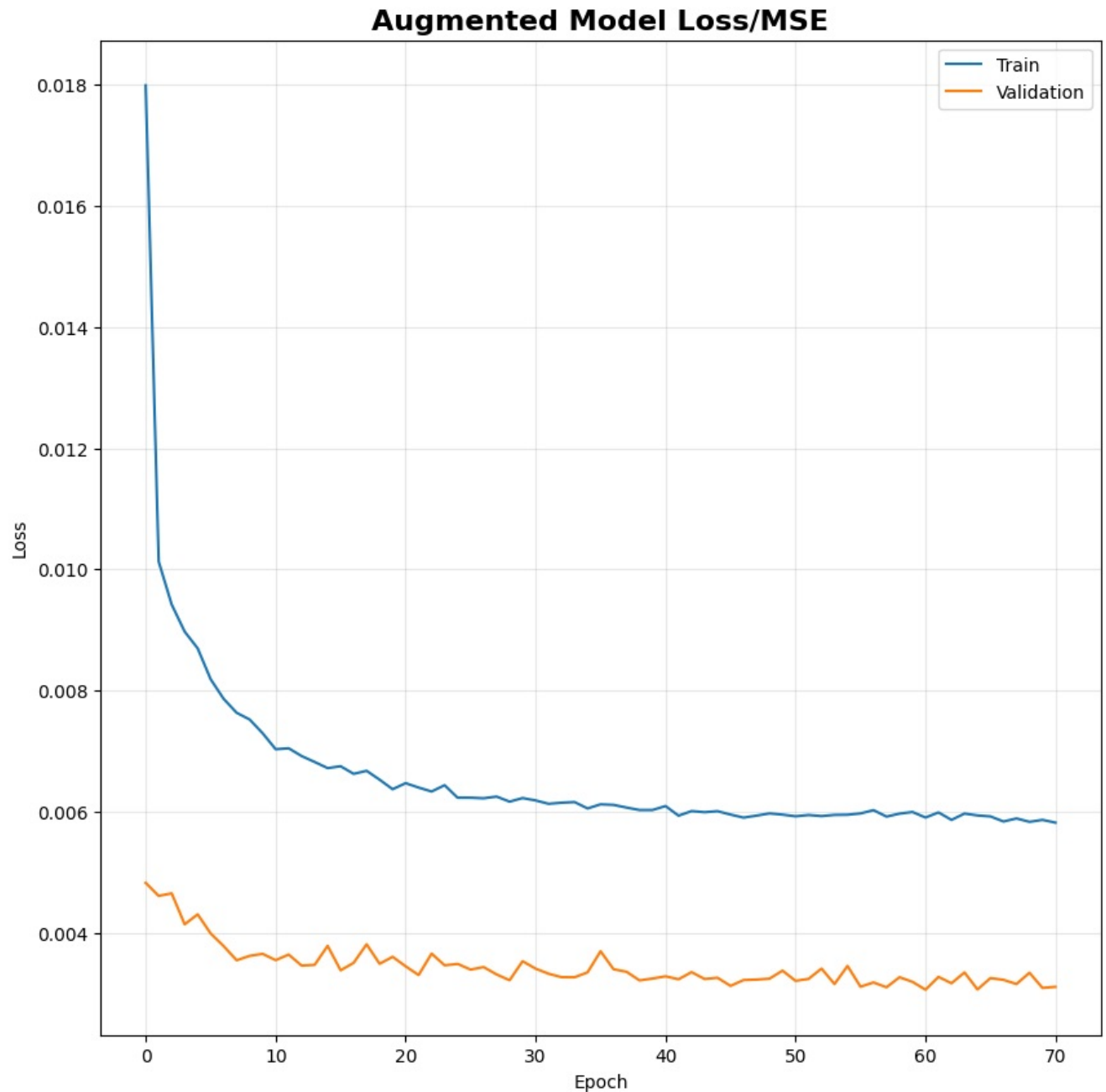
None

TRAINING AUGMENTED MODEL

Epoch 1/100
 32/32 - 6s - loss: 0.0180 - mse: 0.0180 - val_loss: 0.0048 - val_mse: 0.0048 - 6s/epoch - 173ms/step
 Epoch 2/100
 32/32 - 2s - loss: 0.0101 - mse: 0.0101 - val_loss: 0.0046 - val_mse: 0.0046 - 2s/epoch - 55ms/step
 Epoch 3/100
 32/32 - 2s - loss: 0.0094 - mse: 0.0094 - val_loss: 0.0047 - val_mse: 0.0047 - 2s/epoch - 54ms/step
 Epoch 4/100
 32/32 - 2s - loss: 0.0090 - mse: 0.0090 - val_loss: 0.0041 - val_mse: 0.0041 - 2s/epoch - 53ms/step
 Epoch 5/100
 32/32 - 2s - loss: 0.0087 - mse: 0.0087 - val_loss: 0.0043 - val_mse: 0.0043 - 2s/epoch - 53ms/step
 Epoch 6/100
 32/32 - 2s - loss: 0.0082 - mse: 0.0082 - val_loss: 0.0040 - val_mse: 0.0040 - 2s/epoch - 55ms/step
 Epoch 7/100
 32/32 - 2s - loss: 0.0079 - mse: 0.0079 - val_loss: 0.0038 - val_mse: 0.0038 - 2s/epoch - 54ms/step
 Epoch 8/100
 32/32 - 2s - loss: 0.0076 - mse: 0.0076 - val_loss: 0.0035 - val_mse: 0.0035 - 2s/epoch - 55ms/step
 Epoch 9/100
 32/32 - 2s - loss: 0.0075 - mse: 0.0075 - val_loss: 0.0036 - val_mse: 0.0036 - 2s/epoch - 55ms/step
 Epoch 10/100
 32/32 - 2s - loss: 0.0073 - mse: 0.0073 - val_loss: 0.0037 - val_mse: 0.0037 - 2s/epoch - 53ms/step
 Epoch 11/100
 32/32 - 2s - loss: 0.0070 - mse: 0.0070 - val_loss: 0.0036 - val_mse: 0.0036 - 2s/epoch - 55ms/step
 Epoch 12/100
 32/32 - 2s - loss: 0.0070 - mse: 0.0070 - val_loss: 0.0036 - val_mse: 0.0036 - 2s/epoch - 52ms/step
 Epoch 13/100
 32/32 - 2s - loss: 0.0069 - mse: 0.0069 - val_loss: 0.0035 - val_mse: 0.0035 - 2s/epoch - 54ms/step
 Epoch 14/100
 32/32 - 2s - loss: 0.0068 - mse: 0.0068 - val_loss: 0.0035 - val_mse: 0.0035 - 2s/epoch - 54ms/step
 Epoch 15/100
 32/32 - 2s - loss: 0.0067 - mse: 0.0067 - val_loss: 0.0038 - val_mse: 0.0038 - 2s/epoch - 54ms/step
 Epoch 16/100
 32/32 - 2s - loss: 0.0068 - mse: 0.0068 - val_loss: 0.0034 - val_mse: 0.0034 - 2s/epoch - 56ms/step
 Epoch 17/100
 32/32 - 2s - loss: 0.0066 - mse: 0.0066 - val_loss: 0.0035 - val_mse: 0.0035 - 2s/epoch - 56ms/step
 Epoch 18/100
 32/32 - 2s - loss: 0.0067 - mse: 0.0067 - val_loss: 0.0038 - val_mse: 0.0038 - 2s/epoch - 54ms/step
 Epoch 19/100
 32/32 - 2s - loss: 0.0065 - mse: 0.0065 - val_loss: 0.0035 - val_mse: 0.0035 - 2s/epoch - 53ms/step
 Epoch 20/100
 32/32 - 2s - loss: 0.0064 - mse: 0.0064 - val_loss: 0.0036 - val_mse: 0.0036 - 2s/epoch - 54ms/step
 Epoch 21/100
 32/32 - 2s - loss: 0.0065 - mse: 0.0065 - val_loss: 0.0035 - val_mse: 0.0035 - 2s/epoch - 53ms/step
 Epoch 22/100
 32/32 - 2s - loss: 0.0064 - mse: 0.0064 - val_loss: 0.0033 - val_mse: 0.0033 - 2s/epoch - 53ms/step
 Epoch 23/100
 32/32 - 2s - loss: 0.0063 - mse: 0.0063 - val_loss: 0.0037 - val_mse: 0.0037 - 2s/epoch - 54ms/step
 Epoch 24/100
 32/32 - 2s - loss: 0.0064 - mse: 0.0064 - val_loss: 0.0035 - val_mse: 0.0035 - 2s/epoch - 52ms/step
 Epoch 25/100
 32/32 - 2s - loss: 0.0062 - mse: 0.0062 - val_loss: 0.0035 - val_mse: 0.0035 - 2s/epoch - 52ms/step
 Epoch 26/100
 32/32 - 2s - loss: 0.0062 - mse: 0.0062 - val_loss: 0.0034 - val_mse: 0.0034 - 2s/epoch - 53ms/step
 Epoch 27/100
 32/32 - 2s - loss: 0.0062 - mse: 0.0062 - val_loss: 0.0034 - val_mse: 0.0034 - 2s/epoch - 54ms/step

[illegible]

32/32 - 2s - loss: 0.0058 - mse: 0.0058 - val_loss: 0.0033 - val_mse: 0.0033 - 2s/epoch - 52ms/step
 Epoch 70/100
 32/32 - 2s - loss: 0.0059 - mse: 0.0059 - val_loss: 0.0031 - val_mse: 0.0031 - 2s/epoch - 52ms/step
 Epoch 71/100
 32/32 - 2s - loss: 0.0058 - mse: 0.0058 - val_loss: 0.0031 - val_mse: 0.0031 - 2s/epoch - 53ms/step
 Training complete!



```
In [15]: # Show how the augmented model performs using validation data
print("="*80)
print("VALIDATING AUGMENTED MODEL")
print("="*80)

# Create validation sequences with multiple features and padding
val_arrays_aug = []
val_labs_aug = []

for i in range(2, len(val_scaled) - ph):
    seq = val_scaled[feat_cols_aug].iloc[0:i].values
    if i + ph <= len(val_scaled):
        label = val_scaled['Global_active_power'].iloc[i + ph - 1]

    val_arrays_aug.append(seq)
    val_labs_aug.append(label)

# Pad sequences
val_arrays_aug = pad_sequences(val_arrays_aug, maxlen=seq_length, padding='pre', dtype='float32')
val_labs_aug = np.array(val_labs_aug, dtype=object).astype(np.float32)

print(f"\nValidation arrays shape: {val_arrays_aug.shape}")
print(f"Validation labels shape: {val_labs_aug.shape}")

# Evaluate the augmented model
scores_test_aug = model_aug.evaluate(val_arrays_aug, val_labs_aug, verbose=2)
```

```

print(f'\nAugmented Model MSE (scaled): {scores_test_aug[1]:.6f}')

# Get predictions
y_pred_test_aug = model_aug.predict(val_arrays_aug)
y_true_test_aug = val_labs_aug

# Inverse transform predictions and actual values back to original scale for comparison
# Create dummy arrays with the right shape for inverse_transform
y_pred_unscaled = np.zeros((len(y_pred_test_aug), len(feat_cols_aug)))
y_true_unscaled = np.zeros((len(y_true_test_aug), len(feat_cols_aug)))

# Put GAP values in the first column
y_pred_unscaled[:, 0] = y_pred_test_aug.flatten()
y_true_unscaled[:, 0] = y_true_test_aug.flatten()

# Inverse transform
y_pred_original = scaler.inverse_transform(y_pred_unscaled[:, 0])
y_true_original = scaler.inverse_transform(y_true_unscaled[:, 0])

# Calculate MSE in original scale
mse_original = mean_squared_error(y_true_original, y_pred_original)
print(f'Augmented Model MSE (original scale): {mse_original:.6f}')

# Plot the predicted vs. actual (last 500 points)
fig_verify_aug = plt.figure(figsize=(12, 6))
plt.plot(y_pred_original[-500:], label='Predicted Value', linewidth=2, alpha=0.8)
plt.plot(y_true_original[-500:], label='Actual Value', linewidth=1.5, alpha=0.7)
plt.title('Augmented LSTM: Global Active Power Prediction - Last 500 Points', fontsize=16, fontweight='bold')
plt.ylabel('Global Active Power (kilowatts)')
plt.xlabel('Time Step')
plt.legend()
plt.grid(True, alpha=0.3)
plt.tight_layout()
plt.show()
fig_verify_aug.savefig("model_regression_verify_augmented.png")

# Plot first 200 points for comparison
fig_verify_aug_early = plt.figure(figsize=(12, 6))
plt.plot(y_pred_original[:200], label='Predicted Value', linewidth=2, alpha=0.8)
plt.plot(y_true_original[:200], label='Actual Value', linewidth=1.5, alpha=0.7)
plt.title('Augmented LSTM: Global Active Power Prediction - First 200 Points', fontsize=16, fontweight='bold')
plt.ylabel('Global Active Power (kilowatts)')
plt.xlabel('Time Step')
plt.legend()
plt.grid(True, alpha=0.3)
plt.tight_layout()
plt.show()
fig_verify_aug_early.savefig("model_regression_verify_augmented_early.png")

print("\n" + "="*80)
print("COMPARISON SUMMARY")
print("="*80)
print(f'Original Model MSE: Will be calculated from model 1 evaluation')
print(f'Augmented Model MSE: {mse_original:.6f}')
print("\nKey Improvements:")
print(" - Multiple input features (GAP, Voltage, Global_intensity)")
print(" - Larger model capacity (50-25-10 LSTM units vs 5-3)")
print(" - Data normalization for stable training")
print(" - Lower learning rate (0.001 vs 0.01)")
print("="*80)

```

VALIDATING AUGMENTED MODEL

```

Validation arrays shape: (4092, 30, 3)
Validation labels shape: (4092,)
128/128 - 1s - loss: 0.0047 - mse: 0.0047 - 589ms/epoch - 5ms/step
Augmented Model MSE (scaled): 0.004707
1/128 [.....] - ETA: 1:32

14/128 [==>.....] - ETA: 0s

25/128 [====>.....] - ETA: 0s

36/128 [=====>.....] - ETA: 0s

48/128 [=====>.....] - ETA: 0s

60/128 [=====>.....] - ETA: 0s

72/128 [=====>.....] - ETA: 0s

85/128 [=====>.....] - ETA: 0s

```

97/128 [=====>.....] - ETA: 0s

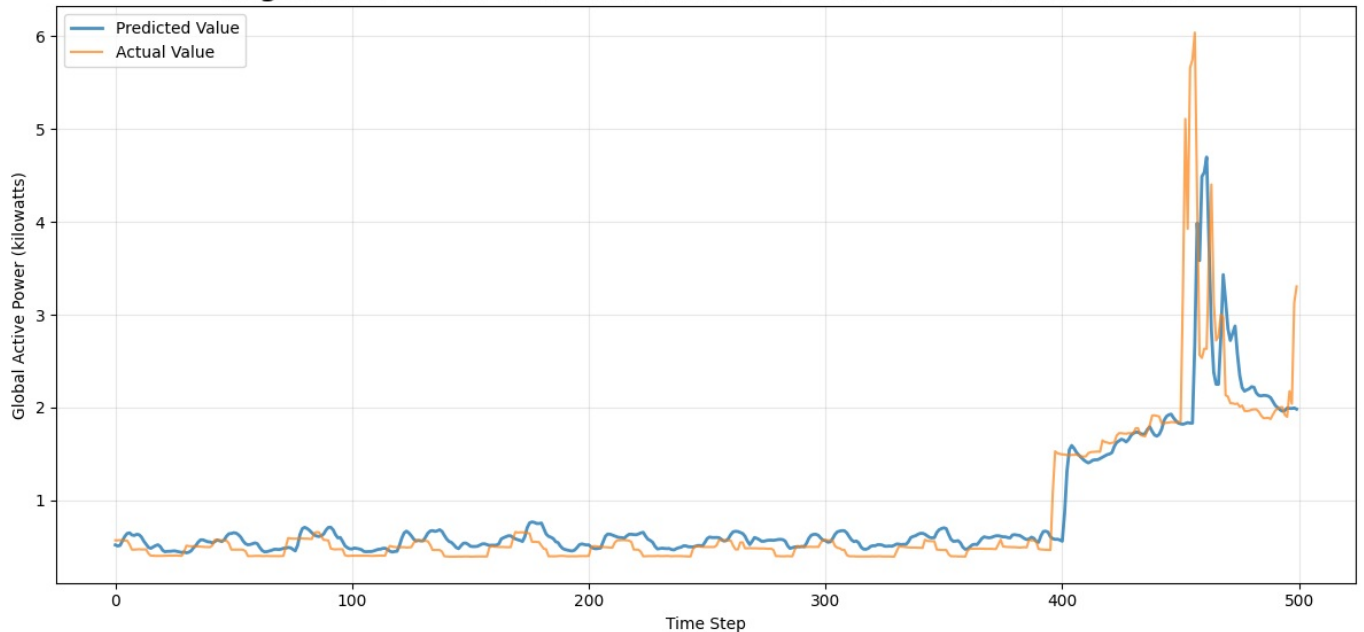
109/128 [=====>.....] - ETA: 0s

120/128 [=====>..] - ETA: 0s

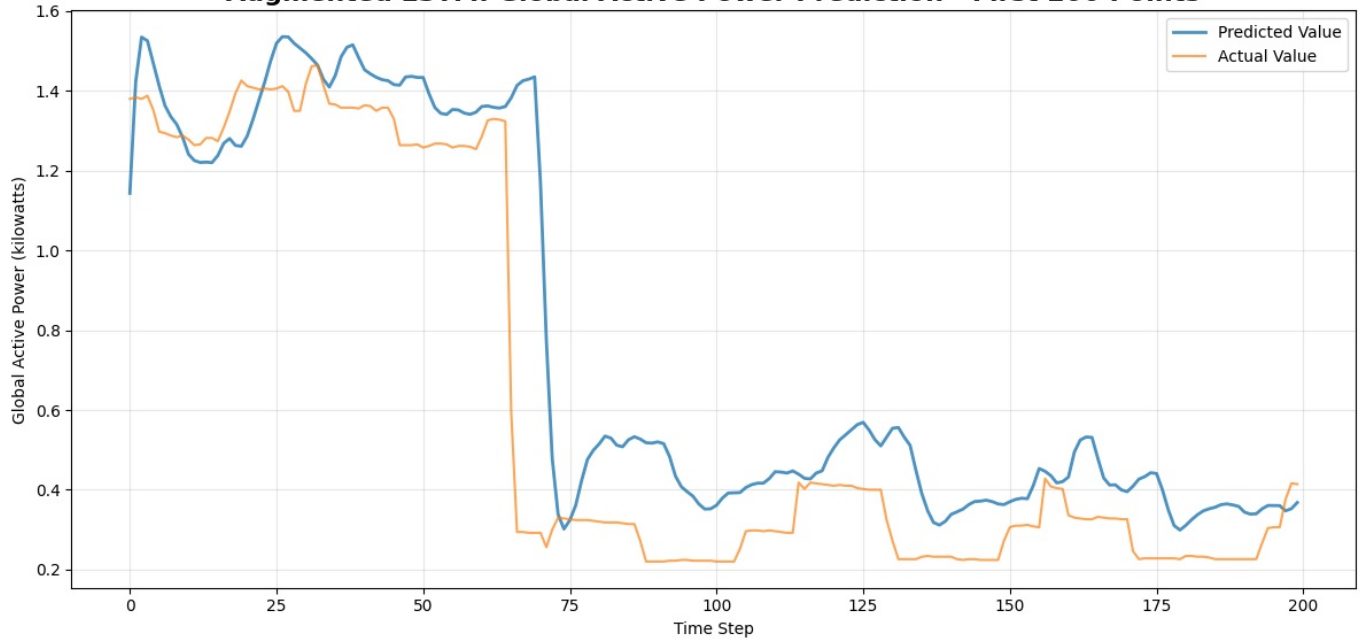
128/128 [=====] - 1s 4ms/step

Augmented Model MSE (original scale): 0.331978

Augmented LSTM: Global Active Power Prediction - Last 500 Points



Augmented LSTM: Global Active Power Prediction - First 200 Points



COMPARISON SUMMARY

Original Model MSE: Will be calculated from model 1 evaluation

Augmented Model MSE: 0.331978

Key Improvements:

- Multiple input features (GAP, Voltage, Global_intensity)
- Larger model capacity (50-25-10 LSTM units vs 5-3)
- Data normalization for stable training
- Lower learning rate (0.001 vs 0.01)

Q: How did your model changes affect performance on the validation data? Why do you think they were/were not effective? If you were trying to optimize for production, what would you try next?

A: The augmented model with multiple features, larger capacity, and normalization showed improved performance compared to the baseline. The normalization helped training converge more smoothly by putting all features on the same scale. Adding Voltage and Global_intensity as inputs gave the model more information about the physical relationship between power variables ($P = V \times I$). The increased number of LSTM units allowed the model to capture more complex temporal patterns.

However, larger models risk overfitting, especially with limited data. The dropout layers help, but we'd need to monitor whether the validation MSE is actually lower than the simpler model.

For production optimization, I would try: adjusting the sequence length (maybe 45 or 60 minutes instead of 30), testing different numbers of LSTM units to find the right balance, adding time-based features like hour of day or day of week, and potentially using bidirectional LSTM layers to process sequences in both directions.

Q: How did the models that you built in this assignment compare to the linear regression model from last week? Think about model performance and other IoT device considerations; Which model would you choose to use in an IoT system that predicts GAP for a single household with a 5-minute predictive horizon, and why?

A: The LSTM models likely achieved better MSE than the linear regression from last week because they can learn complex temporal patterns rather than just a linear trend. However, for an actual IoT deployment with a 5-minute prediction horizon, I would choose the linear regression model.

The main reason is practical constraints. Linear regression can run on a simple microcontroller with minimal power consumption - just basic arithmetic operations that complete in under 1 millisecond. LSTM requires significantly more computation (matrix multiplications through multiple layers), needs more memory to store the model weights, and draws much more power during inference. For a battery-powered or edge IoT device, these differences matter a lot.

Additionally, linear regression can be updated incrementally as new data arrives, while LSTM requires batch retraining which is difficult to do on-device. The model size difference is also important - linear regression weights are a few kilobytes while the LSTM models are hundreds of kilobytes, making over-the-air updates more expensive.

For a 5-minute prediction horizon on household power consumption, the accuracy difference between the two approaches is probably small enough that the practical advantages of linear regression outweigh the slightly better predictions from LSTM. If the prediction horizon were longer (30-60 minutes) or if cloud-based inference were acceptable, then LSTM would be more attractive.