

Michael I. Gosselin

Last Updated February 15, 2014

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SKILLS	<p>Computer Skills:</p> <ul style="list-style-type: none">• Eagle, MATLAB, NX 6.0 (beginner) SolidWorks 2013 (intermediate), Simulink, L^AT_EX, LabVIEW, Mac OSX, Microsoft Windows, AVR Studio (C, C++) <p>Electronics Skills:</p> <ul style="list-style-type: none">• 2-layer PCB design, prototyping, & fabrication (through hole & surface mount), Mixed-signal design, Linear & PWM motor drives, Analog filters & signal conditioning, Power amplification, MAEVARM M2 (uses ATMEL 32U4) <p>Machine Skills:</p> <ul style="list-style-type: none">• Waterjet cutter, Laser cutter, Vertical mill, Lathe, MIG welder, Drill press, Band saw	
RELEVANT COURSEWORK & PROJECTS	<p>University of Pennsylvania, Philadelphia, PA</p> <p>Electronic Hardware Independent Study Project January 2013 - Present</p> <ul style="list-style-type: none">• Conceptualized methods for adding high-performance stereo audio output capability to an ARM Cortex M4 microcontroller.• Designed a circuit and PCB to implement the design; developed Eagle models, manufactured, populated, tested 4 iterations.• Evaluated 3 stereo DAC integrated circuits and evaluated serial protocols for suitability for audio output (selected Philips I2S standard)• Used focused physical prototyping to evaluate analog circuits for filtering and buffering audio. <p><i>PennApps Hackathon</i> January 2013 Student Hacker</p> <ul style="list-style-type: none">• Collaborated with 3 engineering students (ME, EE, CS) to create 2 mobile robots controllable over the internet, designed to shoot darts at one another.• Over a 48-hour period: conceptualized, designed, tested and debugged motor drive electronics, RF wireless system and dart-shooting mechanical hardware.• Worked with teammates to implement the TalkBox API on Android Jellybean OS to capture video using mobile phones (affixed to each of the robots), giving each of the robot's users a live video stream (over the internet).• Presented the project to a panel of Judges and advanced to the finalist group of the top 20 teams (out of 500 competitors). <p>University of British Columbia, Vancouver, BC, Canada</p> <p><i>Senior Mechanical Design Project</i> September 2011 to April 2012</p> <ul style="list-style-type: none">• Collaborated with 4 engineering students (ME, BE) to conceptualize, prototype and refine (3 iterations) a surgical retractor for minimally invasive surgeries.• Manufactured and tested focused and comprehensive physical prototypes of near-micro scale linkages for deployment and actuation of retractor concepts.• Interviewed experts and stakeholders (surgeons, administrators, biomedical engineers, reprocessing personnel) to develop a broader understanding of current surgical retraction needs.	

- Validated tool performance quantitatively in laparoscopic ‘trainer’ apparatus and animal lab (porcine) trials, with participation of urology residents and physicians.

RESEARCH EXPERIENCE

University of Pennsylvania, Philadelphia, PA

GRASP Laboratory - Haptics Research Group

September 2012 to Present

Research Assistant

- Trained 4th-year medical students on SAGES curriculum for peg transfer training task on an Intuitive Surgical daVinci robotic surgery system.
- Implemented automatic capture of force, vibration, and time data using DAC hardware and MATLAB to determine quantitative skills metrics for test subjects.
- Analysed data for 16 subjects, plotted key relationships for surgical skill between groups of subjects.
- Contributed to draft sections of journal article, containing key outcomes from comparisons between groups of subjects.

Lazer Zentrum Hannover e.V., Hannover, Niedersachsen, Germany

Laser Microtechnology Group

September 2009 to December 2009

Manufacturing Research Intern

- Experimentally determined optimal laser marking parameters for batch-fabrication of novel thin metal film resistive strain gauges. [1]
- Selected range and scope of experiments to permit sufficient statistical power in analysis of laser marked samples.
- Used nonlinear regression and error analysis of surface measurements of laser markings to build an energy model for marking behavior thin metal films.
- Collaborated with a thin-film deposition company, a professor and a PhD student to apply the thin metal film strain gauge technology to a diesel engine connecting rod for further validation.

COMMUNITY CONTRIBUTIONS

Association de Volontarios para el Servicio en Areas Protegidas (ASVO)

Volunteer

May 2012

- Worked with a team of 20 UBC undergraduates through UBC GoGlobal International Service Learning (ISL) Program. Work included relocating leatherback sea turtle eggs along Costa Rica’s Caribbean coast, and construction of demonstration farms for introducing novel farming methods to a developing community.

EDUCATION

University of Pennsylvania, Philadelphia, PA, USA

Master of Science in Engineering, Mechanical Engineering and Applied Mechanics

Specialization in Mechatronics

December 2013

University of British Columbia, Vancouver, BC, Canada

Bachelor of Applied Science, Mechanical Engineering

Engineering Co-op Program

May 2011

PEER- REVIEWED PAPERS

- [1] Oliver Suttman, Michael Gosselin, Ulrich Klug and Rainer Kling, “Picosecond laser patterning of NiCr thin film strain gages”, Proc. SPIE 7589, 758914 (2010); doi:10.1117/12.840842

AWARDS & RECOGNITION

PennApps Hackathon: Top 20 Finalist

January 2013

GoGlobal International Service Learning Award

March 2012

UBC Dean’s Honor List

December 2010