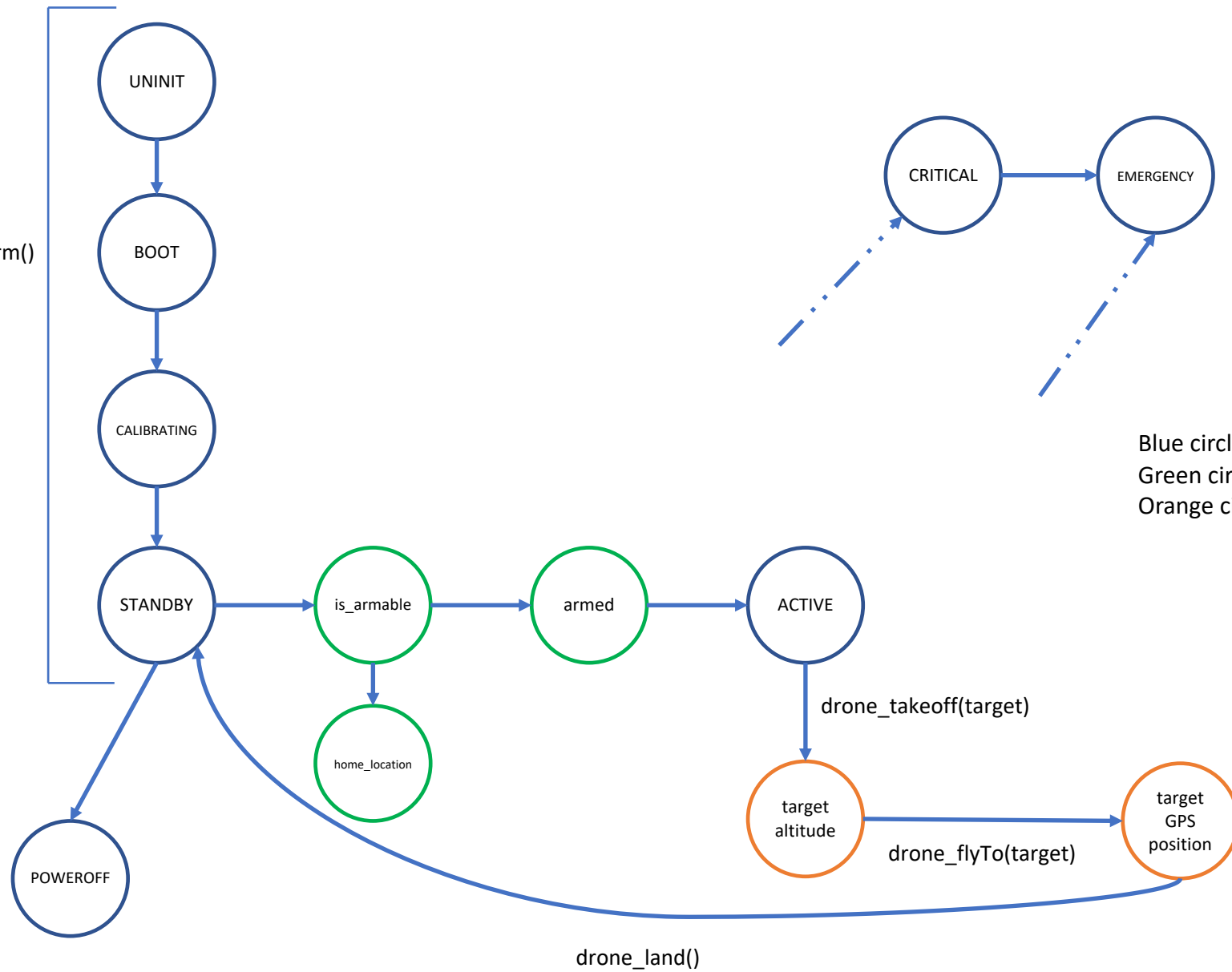


drone\_arm()



Blue circles = states described by system\_status.state  
Green circles = other attributes exposed by DroneKit API  
Orange circles = user-defined values