

An introduction to Tensorflow 2.0

Names

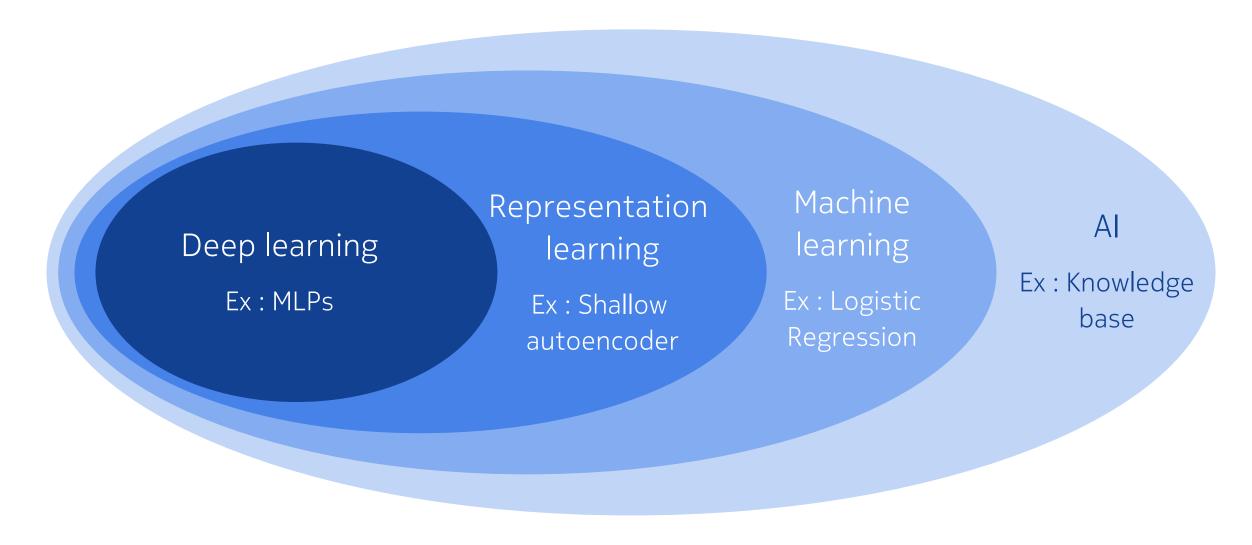
Training school

Date



An introduction to Tensorflow 2.0

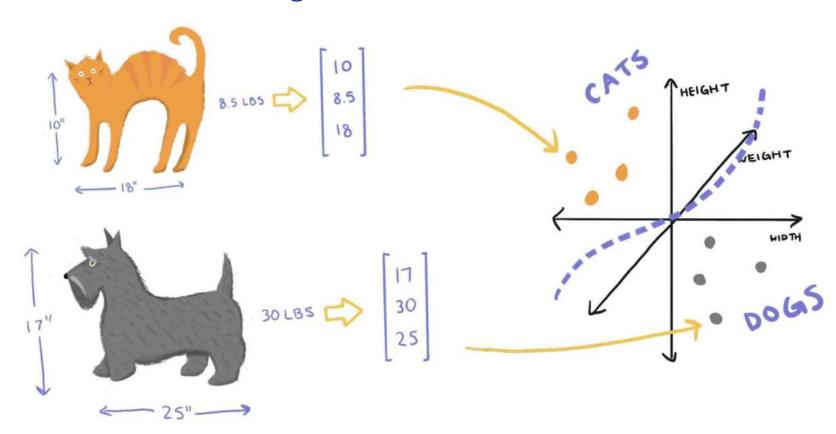
- Introduction to Deep Learning
- Tensorflow for beginners
- Tensorflow for experts
- Building a custom training loop





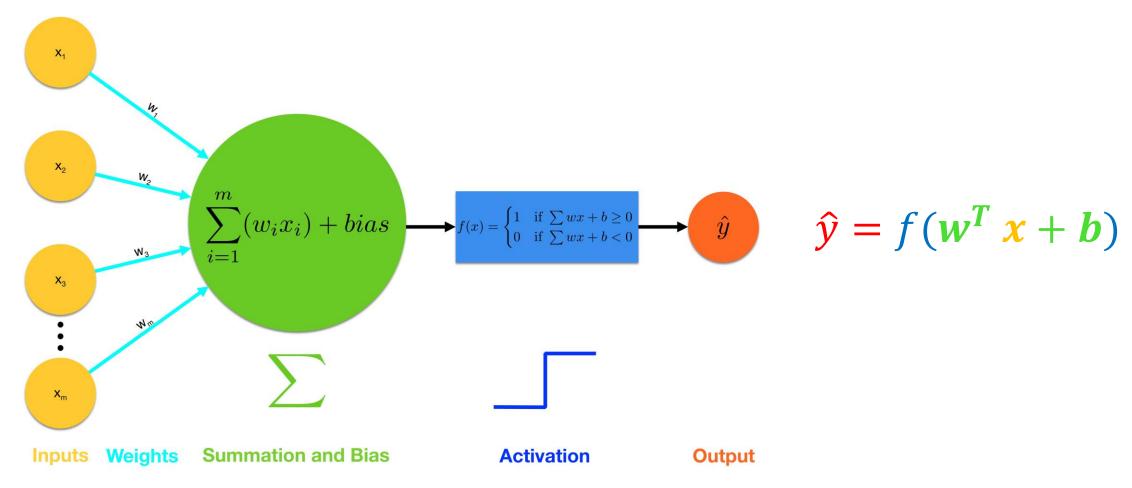
We usually have:

- A set of **Features**: height, weight, width
- A set of **Labels**: Cats, Dogs



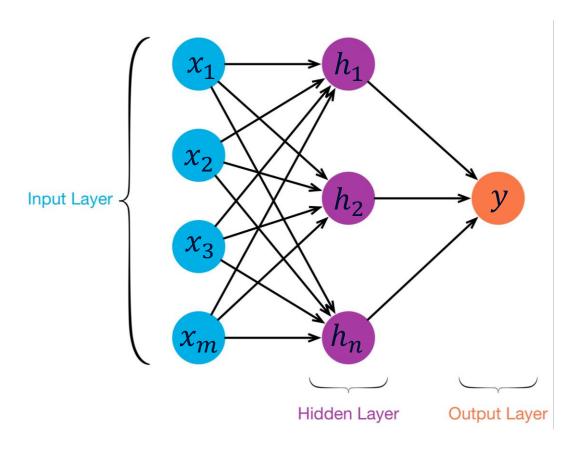


The basic element is a **Neuron**





Neural Network with 1 hidden dense layer



$$y = f(\mathbf{W_o}(f(\mathbf{W_h}\mathbf{x} + \mathbf{b_h}) + \mathbf{b_o})$$



Other types of layers:

2D Convolutional:

Multiplies the 2D inputs by N kernels creating N 2D outputs Parameters : # of kernels N, kernel size, ...

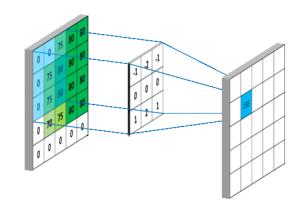
2D Max Pooling:

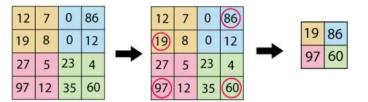
Down-sample the inputs by taking the maximum of sub-regions Parameters : sub-regions sizes, ...

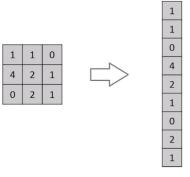
Flatten:

Converts the inputs into a dimension [batch_size, -1]

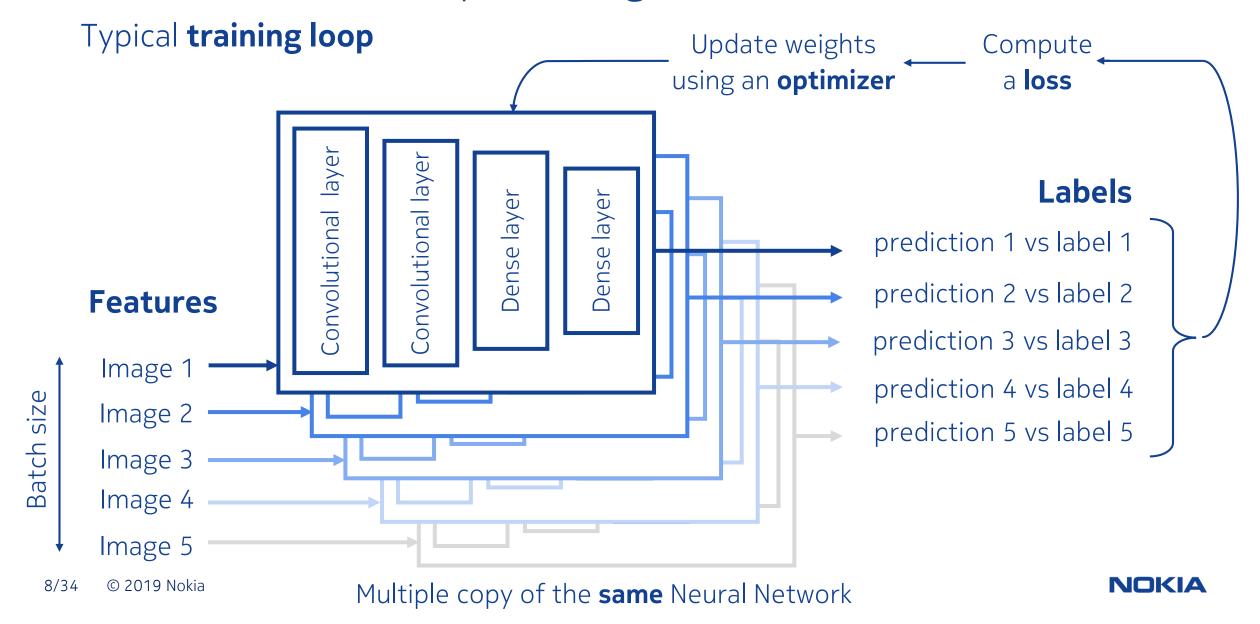
Etc.











The **loss function** depends on the task

(for a batch: compute forward path \rightarrow compute **loss** & gradients \rightarrow apply optimizer)

- For a regression problem: Mean Squared Error, etc.
- For a classification problem: Cross Entropy, etc.

MSE =
$$\frac{1}{B_S} \sum_{i=1}^{B_S} (y_i - \hat{y}_i)^2$$

$$CE = \frac{1}{B_S} \sum_{i=1}^{B_S} \sum_{j=1}^{C} -p_{ij} \log(\hat{p}_{ij})$$

Regularization adds a penalty terms depending on the weights:

L1 regularization increase sparsity

$$Loss = \frac{1}{B_S} \sum_{i=1}^{B_S} (y_i - \hat{y}_i)^2 + \lambda \sum_{j=1}^{\#\theta} |\theta_j|$$

$$MSE \qquad L1$$

$$Tuning parameter$$

L2 regularization avoids overfitting

$$Loss = \frac{1}{B_S} \sum_{i=1}^{B_S} (y_i - \hat{y}_i)^2 + \lambda \sum_{j=1}^{\#\theta} \theta_j^2$$
MSE

L2

Tuning parameter

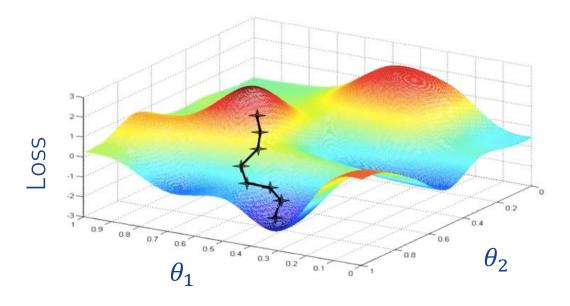
Tuning parameter

Training is done by Stochastic Gradient Descent (SGD) or a variant

(for a batch: compute forward path → compute loss & gradients → apply **optimizer**)

SGD updates the weights in the negative gradient direction

$$\theta_{t+1} = \theta_t - \eta \nabla L(\theta_t; \hat{y}, y)$$
Learning rate
Predictions
Gradient of the
Loss function

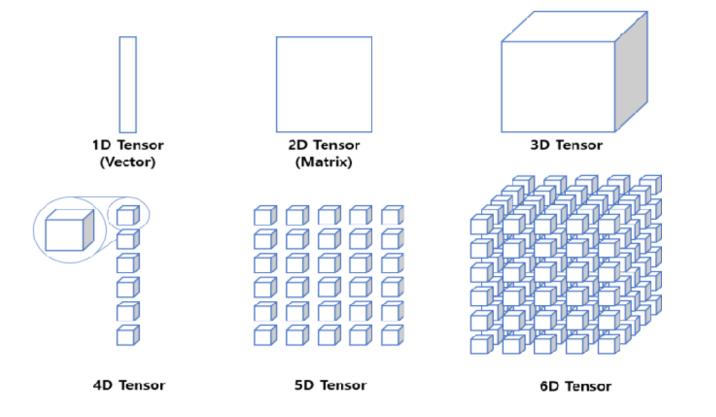


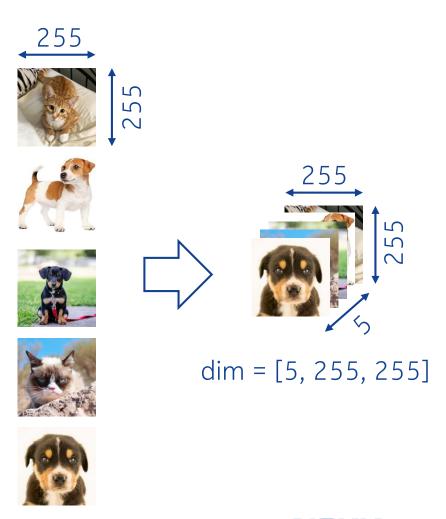
The most used variant is **Adam**:

- Individual adaptive learning rate for each parameters
- Exponential moving average of gradients
- Computationally efficient



A **Tensor** is a N-dimensional Matrix The first dimension is usually the batch size







Tensorflow 2.0 is **very pythonic**Lots of equivalent functions between Numpy & Tensorflow

Numpy

```
import numpy as np

a = np.array([[2, 2], [2, 2]], dtype=np.int32)
b = np.array([[3, 3], [4, 4]], dtype=np.int32)
c = a*b

print(c)

[[6 6]
```

Tensorflow

```
import tensorflow as tf

a = tf.constant([[2, 2], [2, 2]], dtype=tf.int32)
b = tf.constant([[3, 3], [4, 4]], dtype=tf.int32)
c = a*b

print(c)

tf.Tensor(
[[6 6]
[8 8]], shape=(2, 2), dtype=int32)
```

Supported TF data types: bool, string, int8/16/32/64, float32/64, complex64/128, etc.



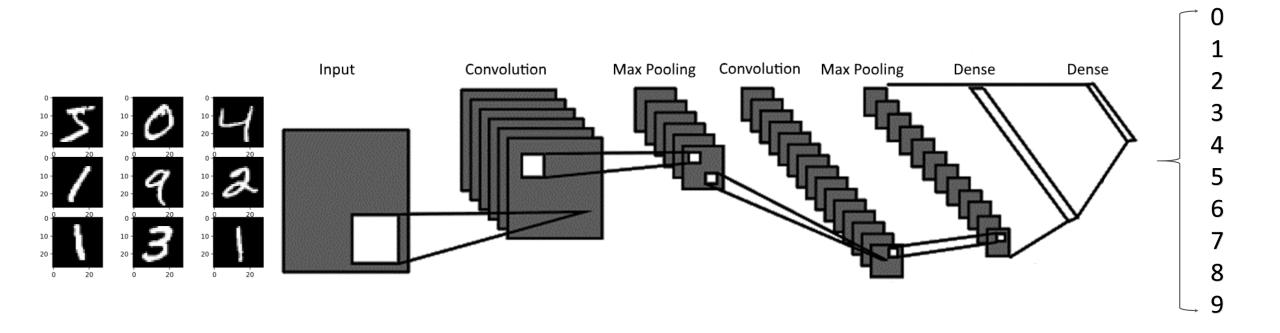
[8 8]]

The parameters of a NN are created as Variables

```
cst = tf.constant([[2, 2], [2, 2]]) # cst is a fixed Tensor
var = tf.Variable([[2, 2], [2, 2]]) # var will be updated during training
print('cst:', cst, '\n')
print('var:', var, '\n')
cst: tf.Tensor(
[[2 2]
 [2 2]], shape=(2, 2), dtype=int32)
var: <tf.Variable 'Variable:0' shape=(2, 2) dtype=int32, numpy=</pre>
array([[2, 2],
       [2, 2]], dtype=int32)>
```

Let's play with MNIST: A large database of handwritten digits

Goal: predict the digit given an image





Preparing the dataset

```
# Load dataset, contains 4 Numpy arrays
(x train, y train), (x test, y test) = tf.keras.datasets.mnist.load data()
# Convert Numpy arrays to Tensors
x_train = tf.convert_to_tensor(x_train, dtype=tf.float32) # [60000, 28, 28]
y train = tf.convert to tensor(y train, dtype=tf.int32) # [60000]
x_test = tf.convert_to_tensor(x_test, dtype=tf.float32) # [10000, 28, 28]
y test = tf.convert to tensor(y test, dtype=tf.int32) # [10000]
# Scale the dataset and add a channel dimension
x_{train} = x_{train}/255.0
x_{train} = tf.expand_dims(x_{train}, axis=-1) # [60000, 28, 28, 1]
x \text{ test} = x \text{ test/}255.0
x_{\text{test}} = \text{tf.expand\_dims}(x_{\text{test}}, \text{axis}=-1) # [10000, 28, 28, 1]
```

Keras is a high-level neural networks API Give access to pre-made Layers

```
from tensorflow import keras
from tensorflow.keras.layers import Conv2D, MaxPooling2D, Flatten, Dense
```





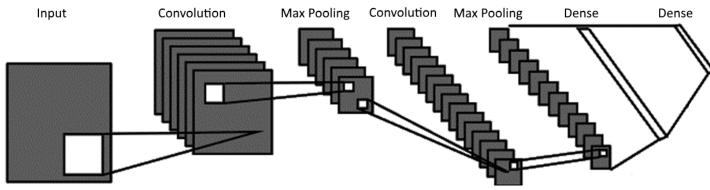
The **Sequential API**: Easily define models

```
my_model = tf.keras.models.Sequential([

Conv2D(filters=6, kernel_size=8, activation='relu'),
    MaxPooling2D(pool_size=(2, 2)),
    Conv2D(filters=15, kernel_size=4, activation='relu'),
    MaxPooling2D(pool_size=(2, 2)),

Flatten(),

Dense(128, activation='relu'),
    Dense(10, activation='softmax') # Outputs a probability distribution
])
```



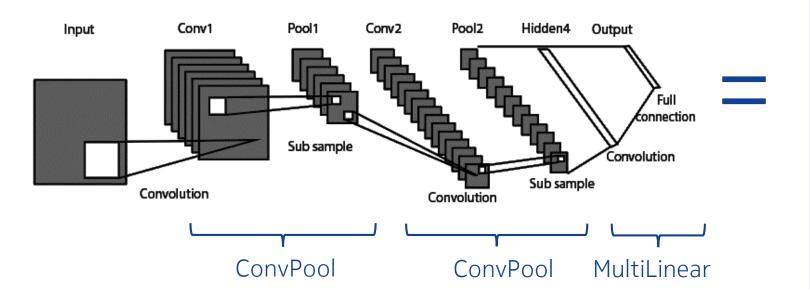


Keras gives access to pre-made training functions

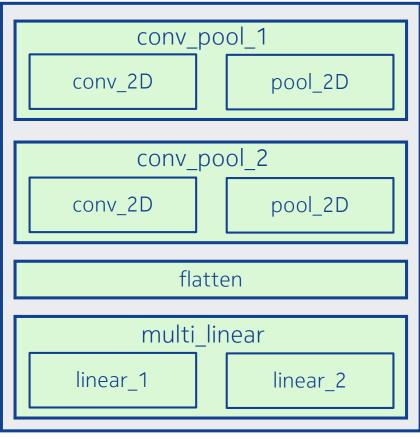
```
my_model.compile(optimizer='adam',
        loss='sparse categorical crossentropy', # Only one correct class
        metrics=['accuracy']) # Percentage of good predictions
my model.fit(x train, y train, epochs=3, batch size=1024)
my model.evaluate(x test, y test, verbose=2)
Train on 60000 samples
Epoch 1/3
Epoch 2/3
Epoch 3/3
[0.1858606786608696, 0.9435]
Final loss Final accuracy
```

Creating a Tensorflow dataset

Creating custom models and layers











The **subclassing API**: defining new layers

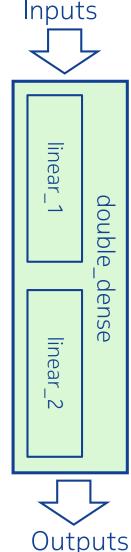
```
from tensorflow.keras.layers import Layer
class Linear(Layer):
    """y = Wx + b"""
   def init (self, units=32): # Called when creating the Layer
        super(Linear, self). init ()
        self.units = units # units = number of neurons = output shape
   def build(self, input_shape): # Called the first time the layer is used
        self.W = self.add_weight(shape=(input_shape[-1], self.units),
                               initializer='random normal', trainable=True)
        self.b = self.add weight(shape=(self.units,),
                               initializer='random normal', trainable=True)
   def | call(self, inputs): # What the layer actually does
        return tf.matmul(inputs, self.W) + self.b
```





Layers are recursively composable with custom Layers

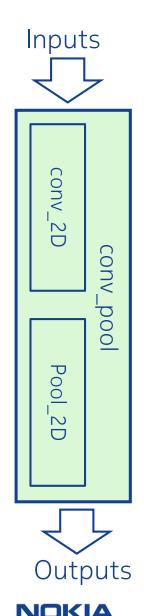
```
class DoubleDense(Layer):
    """ Linear-relu + Linear-Softmax """
   def __init__(self, nb_classes): # Called when creating the layer
        super(DoubleDense, self).__init__()
        self.nb classes = nb classes
   def build(self, input_shape): # Called the first time the layer is used
        self.linear 1 = Linear(units=128)
        self.linear 2 = Linear(units=self.nb classes)
   def call(self, inputs): # What the layer actually does
       x = tf.nn.relu(self.linear_1(inputs))
       x = tf.nn.softmax(self.linear_2(x)) # Outputs a probability distribution
       return x
```





Layers are recursively composable with Keras layers

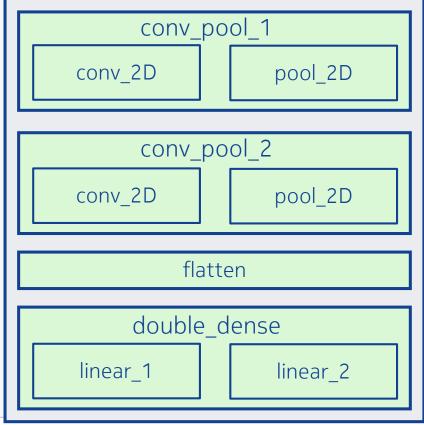
```
class ConvPool2D(Layer):
    """ Conv2D-relu + MaxPooling2D
   def __init__(self, nb_kernels, kernel_size): # Called at layer creation
        super(ConvPool2D, self). init ()
        self.nb_kernels = nb_kernels
        self.kernel size = kernel size
   def build(self, input shape): # Called the first time the layer is used
        self.conv_2D = Conv2D(filters=self.nb_kernels,
                              kernel size=self.kernel size,
                              activation='relu')
        self.pool 2D = MaxPooling2D(pool size=(2, 2))
   def call(self, inputs): # What the layer actually does
       x = self.conv_2D(inputs)
       x = self.pool 2D(x)
        return x
```



The **subclassing API**: defining new Models



```
from tensorflow.keras import Model
class MyModel(Model):
    def init (self, nb classes): # Called when creating the model
        super(MyModel, self). init ()
        self.nb classes = nb classes
   def build(self, input shape): # Called the first time the layer is used
        self.conv pool 1 = ConvPool2D(nb kernels=6, kernel size=8)
        self.conv pool 2 = ConvPool2D(nb kernels=15, kernel size=4)
        self.flatten = Flatten()
        self.double dense = DoubleDense(nb classes=self.nb classes)
   def call(self, inputs): # What the model actually does
        self.x 0 = self.conv pool 1(inputs)
        self.x 1 = self.conv pool 2(self.x 0)
        self.x 2 = self.flatten(self.x 1)
        self.predictions = self.double dense(self.x 2)
        return self.predictions
```



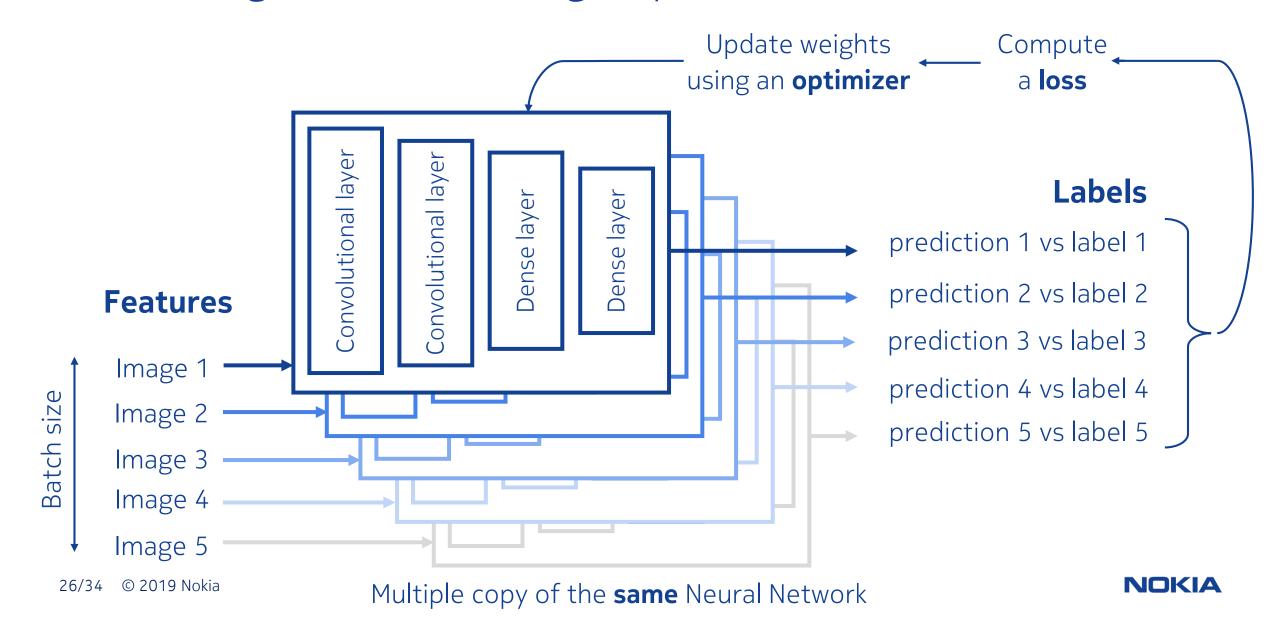


Creating the model using pre-made functions

```
loss_function = tf.keras.losses.SparseCategoricalCrossentropy()
optimizer = tf.keras.optimizers.Adam()

my_model = MyModel(nb_classes=10)
my_model.compile(optimizer, loss_function)
```

| <pre>my_model.summary()</pre> | | |
|---|---|---------|
| Model: "my_model_13" | | |
| Layer (type) | Output Shape | Param # |
| conv_pool2d_8 (ConvPool2D) | multiple | 390 |
| conv_pool2d_9 (ConvPool2D) | multiple | 1455 |
| flatten_4 (Flatten) | multiple | 0 |
| multi_linear_4 (MultiLinear) | multiple | 18698 |
| Total params: 20,543 Trainable params: 20,543 Non-trainable params: 0 | ======================================= | ======= |



Important **metrics** can be logged

```
# Define the loss function
loss_function = tf.keras.losses.SparseCategoricalCrossentropy()

# Define the optimizer
optimizer = tf.keras.optimizers.Adam()

# Define the metrics
train_loss = tf.keras.metrics.Mean(name='train_loss')
train_accuracy = tf.keras.metrics.SparseCategoricalAccuracy(name='train_accuracy')

test_loss = tf.keras.metrics.Mean(name='test_loss')
test_accuracy = tf.keras.metrics.SparseCategoricalAccuracy(name='test_accuracy')
```



The **tf.GradientTape API** provides automatic differentiation. All operations executed inside a gradient tape are recorded.

```
x = 3
y = x^{2}
\frac{dy}{dx} = 2x = 6
```

```
x = tf.Variable(3.0)
with tf.GradientTape() as tape:
    y = tf.square(x)
dy_dx = tape.gradient(y, x)
print(dy_dx)
```

tf.Tensor(6.0, shape=(), dtype=float32)



Creating the training step

```
def test step(images, labels):
# One SGD step with a given batch
                                                                  # Forward pass
def train step(images, labels):
                                                                  predictions = my model(images)
                                                                  # Loss for this batch
    # Open a GradientTape
                                                                  t loss = loss function(labels, predictions)
    with tf.GradientTape() as tape:
                                                                  # Save Loss and accuracy
        #Forward pass
                                                                  test loss(t loss)
        predictions = my model(images)
                                                                  test_accuracy(labels, predictions)
        # Loss for this batch
        loss = loss function(labels, predictions)
    # Get gradients of loss w.r.t. the weights
    gradients = tape.gradient(loss, my_model.trainable_variables)
    # Update the weights according to our optimizer
    optimizer.apply gradients(zip(gradients, my model.trainable variables))
    # Save loss and accuracy
    train loss(loss)
    train accuracy(labels, predictions)
```

Test the model on a given batch

Creating the training loop

```
my model = MyModel(nb classes=10)
start = time.time()
# Iterate over 3 epochs
for epoch in range(3):
    # Train over every batch in the training dataset
    for images, labels in train ds:
        train step(images, labels)
    # Test over every batch in the testing dataset
    for test images, test labels in test ds:
        test step(test images, test labels)
    # Print result
    template = 'Epoch {:.0f}, Loss: {:.3f}, Accuracy: {:.3f} '+ \
               'Test Loss: {:.3f}, Test Accuracy: {:.3f}'
    print(template.format(epoch+1, train loss.result(), train accuracy.result()*100,
                          test loss.result(), test accuracy.result()*100))
    # Reset the metrics for the next epoch
    train loss.reset states()
    train accuracy.reset states()
    test loss.reset states()
    test accuracy.reset states()
# Display elapsed time
end = time.time()
print('TIME = ', end - start)
Epoch 1,
          Loss: 1.383, Accuracy: 59.863
                                           Test Loss: 0.500, Test Accuracy: 84.560
Epoch 2, Loss: 0.409, Accuracy: 87.717
                                           Test Loss: 0.296, Test Accuracy: 91.140
          Loss: 0.279, Accuracy: 91.637
                                           Test Loss: 0.219, Test Accuracy: 93.480
Epoch 3,
```

TIME = 6.866998195648193

Building a graph to speed up training

by adding @tf.function before the training and testing functions

```
# One SGD step with a given batch
@tf.function
def train_step(images, labels):
```

```
# Test the model on a given batch
@tf.function
def test_step(images, labels):
```

| | Without @tf.function | With @tf.function |
|---------------------------|----------------------|-------------------|
| Training time for 3 epoch | ~6.86s | ~3.46s |

But we loose access to the value of the model's attributes \otimes

```
# With @tf.function
my_model.x_2
```

```
<tf.Tensor 'my_model_9/flatten/Reshape: 0' shape=(784, 135) dtype=float32>
```



Adding **regularization** to the loss function

Using Keras layers' parameters :

And/or using custom layers' loss property:

```
def call(self, inputs): # What the layer actually does
    self.l1_reg = tf.reduce_sum(tf.abs(self.W)) + tf.reduce_sum(tf.abs(self.b))
    self.add_loss(self.l1_reg)
```

And adding those losses to the training loop :

```
predictions = my_model(images)
# Loss for this batch
loss = loss_function(labels, predictions)
# Add extra losses created during this forward pass:
loss += 1e-3 * sum(my_model.losses)
```



Building a custom loss function

Create a new class

```
from tensorflow.keras.losses import Loss

class CustomLoss(Loss):
    """ Custom Sparse Cross Entropy loss with L1 regularization """

def __init__(self, tuning_param): # Called when creating the layer
    super(CustomLoss, self).__init__()
    self.tuning_param = tuning_param
    self.SCE = tf.keras.losses.SparseCategoricalCrossentropy()

def call(self, y_true, y_pred): # What the loss function actually does
    return self.SCE(y_true, y_pred) + self.tuning_param * sum(my_model.losses)
```

Instantiate the class

```
cust_loss_function = CustomLoss(tuning_param=1e-3)
```

Change the loss in the training loop

```
predictions = my_model(images)
# Loss for this batch
loss = cust_loss_function(labels, predictions)
```





Find a working example at

https://mgoutay.github.io/tutorials/2019/11/14/tf2-tutorial.html

Any questions?