library(tidyverse) library(modelr) options(na.action = na.warn) # setting a random seed ensures that randomly generated numbers are the same everytime you run the notebook # ensures reproducible results set.seed(2021) - Attaching packages tidyverse 1.3.0 — ✓ ggplot2 3.3.3 ✓ purrr 0.3.4 ✓ tibble 3.0.6 ✓ dplyr 1.0.4 ✓ tidyr 1.1.2 ✓ stringr 1.4.0 ✓ readr 1.4.0 ✓ forcats 0.5.1 - Conflicts tidyverse conflicts() — * dplyr::filter() masks stats::filter() * dplyr::lag() masks stats::lag() Let's look at how we can create a Train/Validation/Test split of our tibble to develop a linear model for a dataset In [2]: ggplot(mpg) + geom_point(aes(cty, hwy)) 40 -30 hwy 20 -• Too late! Data Leakage has already occurred. • We can no longer effectively evaluate an answer to the question: Is a linear model a good predictive model? • Let's still use the mpg dataset to see how different train/validation/test splits may affect our thinking. ■ 60%/20%/20% split In [3]: # add a row id to each row of mpg mpg_id <- mpg %>% mutate(id = row_number()) %>% select(id, everything()) %>% print() # A tibble: 234 x 12 id manufacturer model cyl trans hwy fl displ year drv <dbl> <int> <int> <chr> <int> <chr> <chr> <chr> <int> <int> <chr> 1.8 <u>1</u>999 4 auto(1... f 1 audi a4 29 p 1.8 <u>1</u>999 4 manual... f 2 audi 29 p <u>2</u>008 3 audi a4 4 manual... f 31 p <u>2</u>008 30 p 4 audi 4 auto(a... f 2.8 <u>1</u>999 5 audi a4 6 auto(l... f 26 p 6 audi 2.8 <u>1</u>999 6 manual... f a4 26 p 7 audi 3.1 <u>2</u>008 27 p a4 6 auto(a... f 18 1.8 <u>1</u>999 26 p 8 audi a4 quat... 4 manual... 4 9 1.8 <u>1</u>999 9 audi a4 quat... 4 auto(1... 4 16 25 p 10 audi a4 quat... 2 <u>2</u>008 10 4 manual... 4 28 p # ... with 224 more rows, and 1 more variable: class <chr> In [4]: # take a random sample of 60% of the data train <- mpg_id %>% sample_frac(.60) %>% print() # A tibble: 140 x 12 id manufacturer model displ year hwy fl cyl trans drv cty <int> <chr> <chr> <dbl> <int> <int> <chr> <int> <int> <chr> 135 lincoln navigato... 5.4 <u>1</u>999 17 r 8 auto(... r 11 166 subaru impreza ... 2.2 <u>1</u>999 4 auto(... 4 21 26 r 174 toyota 4runner ... 2.7 <u>1</u>999 4 manua... 4 15 20 r 186 toyota camry $3.5 \quad \underline{2008}$ 6 auto(... f 19 28 r 140 mercury 4.6 <u>2</u>008 8 auto(... 4 13 19 r mountain... 4.7 <u>2</u>008 70 dodge ram 1500... 8 manua... 4 9 12 e 192 toyota camry so... <u>1</u>999 6 manua... f 18 26 r 3 passat 2.8 <u>1</u>999 233 volkswagen 6 manua... f 18 26 p 32 r 102 honda civic 1.6 <u>1</u>999 4 manua... f 25 2.4 <u>1</u>999 110 hyundai 4 manua... f 27 r 10 sonata # ... with 130 more rows, and 1 more variable: class <chr> In [6]: # recall what an anti-join does! valid_test <- anti_join(mpg_id, train, by = "id") %>% print() # A tibble: 94 x 12 id manufacturer model displ year cyl trans drv hwy fl cty <int> <chr> <chr> <dbl> <int> <int> <chr> <int> <int> <chr> 2 audi a4 1.8 <u>1</u>999 4 manua... f 21 29 p 3 audi <u>2</u>008 4 manua... f 31 p a4 5 audi 2.8 <u>1</u>999 6 auto(... f 16 26 p a4 2.8 <u>1</u>999 6 audi 6 manua... f a4 quatt... 1.8 <u>1</u>999 26 p 8 audi 4 manua... 4 9 audi a4 quatt... 1.8 <u>1</u>999 4 auto(... 4 25 p <u>2</u>008 10 audi a4 quatt... 2 4 manua... 4 20 28 p 12 audi a4 quatt... 2.8 <u>1</u>999 15 25 p 6 auto(... 4 25 p 14 audi a4 quatt... $3.1 \quad \underline{2008}$ 6 auto(... 4 17 21 chevrolet c1500 su... 5.3 <u>2</u>008 14 20 r 8 auto(… r # ... with 84 more rows, and 1 more variable: class <chr> In [7]: # split the non-training data in half for a 60/20/20 split valid <- valid test %>% sample_frac(.50) test <- anti_join(valid_test, valid, by = "id")</pre> In [8]: # drop id columns from each train <- select(train, -id)</pre> valid <- select(valid, -id)</pre> test <- select(test, -id)</pre> In [9]: ggplot(train) + geom_point(aes(cty, hwy)) hwy 20 -In [10]: ggplot(valid) + geom_point(aes(cty, hwy)) 30 hwy In [11]: ggplot(test) + geom_point(aes(cty, hwy)) 40 -Do you notice any differences between the three datasets? In [12]: # we create an RMSE (Root Mean Squared Error) which finds the error for a linear model that predicts hwy from cty RMSE <- function(a, data) {</pre> preds <- a[1] + data\$x * a[2]</pre> diffs <- data\$y - preds</pre> sqrt(mean(diffs^2)) (best <- optim(c(0, 0), RMSE, data = mutate(train, x = cty, y = hwy))) 1.01610178769046 · 1.32986710523856 \$par 1.57898762587647 \$value function: 79 gradient: <NA> \$counts \$convergence NULL \$message In [13]: a <- best\$par ggplot() + geom_point(data = train, aes(cty,hwy)) + # the data geom_abline(aes(intercept = a[1], slope = a[2])) 40 -30 hwy 20 -How well does this generalize to the validation set? In [14]: RMSE(a, mutate(valid, x=cty, y=hwy)) ggplot() + geom_point(data = valid, aes(cty,hwy)) + # the data geom_abline(aes(intercept = a[1], slope = a[2])) 2.21540849389388 40 -30 hwy 20 -• Why is the error larger on the validation set than the training set? • Let's try a different model before finishing with our test set. In [15]: # we'll use a different error function to find a good linear model avg_abs_diff <- function(a, data) {</pre> preds <- a[1] + data\$x * a[2]</pre> diffs <- data\$y - preds</pre> mean(abs(diffs)) (best2 <- optim(c(0, 0), avg_abs_diff, data = mutate(train, x = cty, y = hwy))) \$par 0.999618183964959 · 1.33335152279893 \$value 1.26666680821588 function: 137 gradient: <NA> \$counts \$convergence NULL \$message In [16]: RMSE(best2\$par, mutate(valid, x=cty, y=hwy)) ggplot() + geom_point(data = valid, aes(cty,hwy)) + # the data geom_abline(aes(intercept = a[1], slope = a[2])) 2.21270026031954 40 -30 hwy 20 -15 • Although we computed the second model using a different **loss function**, we still have to use the same **metric** to compare models. • A loss function is the error term you want to minimize using an optimization procedure. • A **metric** is the score you use for evaluating a model. • Sometimes you can use your metric as a loss function, but not always! • A loss function has to satisfy certain mathematical properties so you can use various optimization algorithms. At this point we might say we are done with model development. Our best model is given by the line: $y = 1.333 \times + .999$ • The final step: Evaluate the model on the test set. In [17]: RMSE(best2\$par, mutate(test, x=cty, y=hwy)) 1.68427675709087 In data science competitions, often there is a publicly available dataset and a private test dataset. Data scientists/enthusiasts will take the publicly available data, split into train and validation and go into model development. Each will submit their model for evaluation on the test set. The test set determines the "best" model or the "winner." Attempt: • Does it make sense to create a separate linear model for each specific class of car? • What steps would you take to answer this question? • Pick a class of car, split it into training and validation and fit a linear model to this class of car. In [18]: ggplot(mpg) + geom point(aes(cty, hwy, color=class)) 40 class hwy subcompact In [19]: mpg_suv <- filter(mpg, class == "suv")</pre> In []: