# Higher-Order DGFEM Transport Calculations on Polytope Meshes for Massively-Parallel Architectures

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## Outline

- Overview
  - The DGFEM  $S_N$  Transport Equation
  - Motivation for this Work
- Polytope Finite Element Basis Functions
  - Linear Basis Functions on 2D Polygons
  - Quadratic Serendipity Basis Functions on 2D Polygons
  - Linear Basis Functions on 3D Polyhedra
- Oiffusion Synthetic Acceleration on Polytopes
  - Theory
  - MIP Diffusion Form
- Proposed Work and Current Status
- Work Summary

## Transport Equation

## $\left[\mathbf{\Omega}\cdot\nabla+\sigma_{\mathsf{t}}(\mathbf{r},E)\right]\psi(\mathbf{r},E,\mathbf{\Omega})=\int_{0}^{\infty}\,\sigma_{\mathsf{s}}(\mathbf{r},E',E,\mathbf{\Omega}',\mathbf{\Omega})\psi(\mathbf{r},E',\mathbf{\Omega}')dE'd\mathbf{\Omega}'+Q(\mathbf{r},E,\mathbf{\Omega})$

#### **Boundary Conditions**

$$\psi(\mathbf{r}, E, \Omega) = \psi^{inc}(\mathbf{r}, E, \Omega) + \int_{4\pi} \int_0^\infty \beta(\mathbf{r}, E', E, \Omega', \Omega) \psi(\mathbf{r}, E', \Omega') dE' d\Omega'$$

#### Term Definitions

r - neutron position

E - neutron energy

 $\Omega$  - neutron solid angle

 $\psi(\mathbf{r}, E, \mathbf{\Omega})$  - angular flux

 $Q(\mathbf{r}, E, \Omega)$  - distributed neutron source

 $\sigma_t(\mathbf{r}, E)$  - total macroscopic cross section

 $\sigma_s(\mathbf{r}, E', E, \mathbf{\Omega}', \mathbf{\Omega})$  - total macroscopic scattering cross section

 $\beta(\mathbf{r}, E', E, \Omega', \Omega)$  - boundary albedo

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## Energy and Angular Discretization

## The multigroup $S_N$ equations

$$\left(\boldsymbol{\Omega}_{\textit{m}} \cdot \nabla + \sigma_{\textit{t,g}}\right) \psi_{\textit{m,g}} = \sum_{\textit{g'}=1}^{\textit{G}} \sum_{\textit{p}=0}^{\textit{Np}} \frac{2\textit{p}+1}{4\pi} \sigma_{\textit{s,p}}^{\textit{g'} \rightarrow \textit{g}} \sum_{\textit{n}=-\textit{p}}^{\textit{p}} \phi_{\textit{p,n,g'}} Y_{\textit{p,n}}(\boldsymbol{\Omega}_{\textit{m}}) + Q_{\textit{m,g}}$$

#### Multigroup Method

$$\psi_{\mathsf{g}} = \int_{\mathsf{E}_{\mathsf{g}}}^{\mathsf{E}_{\mathsf{g}-1}} \psi(\mathsf{E}) \, \mathsf{d}\mathsf{E}$$

cross sections goes here...

#### $S_N$ Discretization

$$egin{aligned} \phi_{
ho,n} &\equiv \int_{4\pi} d\Omega \, \psi(\Omega) \, Y_{
ho,n}(\Omega), \ \sigma_{s,
ho} &\equiv \int_{-1}^1 \, d\mu \, \sigma_s(\mu_0) P_
ho(\mu_0) \end{aligned}$$

$$\mu_0 \equiv \mathbf{\Omega}' \cdot \mathbf{\Omega}$$

$$\sigma_s(\mathbf{\Omega}'\cdot\mathbf{\Omega})\equivrac{1}{2\pi}\sigma_s(\mu)$$

$$P_{
ho}(\mathbf{\Omega}'\cdot\mathbf{\Omega})\equivrac{1}{2\pi}P_{
ho}(\mu)$$

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## Spatial Discretization

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## Iterative Procedure

#### Classic Source Iteration

$$egin{aligned} \psi^{(\ell+1)} &= \mathbf{L}^{-1} \left( \mathsf{M} \mathbf{\Sigma} \phi^{(\ell)} + \mathbf{Q} 
ight) \ \phi^{(\ell+1)} &= \mathbf{D} \mathbf{L}^{-1} \left( \mathsf{M} \mathbf{\Sigma} \phi^{(\ell)} + \mathbf{Q} 
ight) \ \phi &= \mathbf{D} \psi \end{aligned}$$

#### **Operator Terms**

L - streaming + collision operator

M - moment-to-discrete operator

D - discrete-to-moment operator

Σ - scattering operator

#### Transport Sweep

The operation  $\mathbf{L}^{-1}$  can be performed in different ways. For this work, we will use the matrix-free, full-domain transport sweep.



#### Optically thick problems can cause slow convergence rates

## Source Iteration Approximate Spectral Radius

$$\rho^{(k+1)} \approx \frac{||\phi^{(k+1)} - \phi^{(k)}||}{||\phi^{(k)} - \phi^{(k-1)}||}$$

## Optically Thick Cases - leakage/absorption does not dominate

- 1-group sense:  $\frac{\sigma_s}{\sigma_t} \approx 1$  and  $(\sigma_t \cdot \text{diam}(\mathcal{D})) \gg 1$
- MG sense:

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- Thermal upscattering into higher energy groups is significant
- Single group iteration, g, with  $\frac{\sigma_s^{g o g}}{\sigma_{t,g}} pprox 1$  and  $(\sigma_{t,g} \cdot \operatorname{diam}(\mathcal{D})) \gg 1$
- TRT problem:
  - heat capacities tend to zero
  - time steps tend to infinity

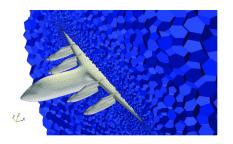


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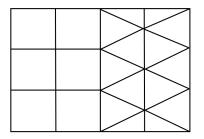


- Other physics communities are now employing polytope grids due to decreased cell/face counts (CFD in particular)



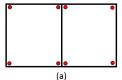


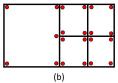
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- They allow for transition elements between different domain regions



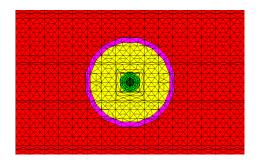


- Other physics communities are now employing polytope grids due to decreased cell/face counts (CFD in particular)
- They allow for transition elements between different domain regions
- Hanging nodes from non-conforming meshes are not necessary
- Independently-generated simplicial grids (i.e. created in parallel) can be stitched together





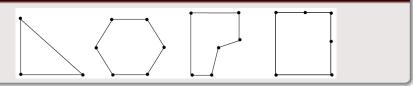
- Other physics communities are now employing polytope grids due to decreased cell/face counts (CFD in particular)
- They allow for transition elements between different domain regions
- Hanging nodes from non-conforming meshes are not necessary
- Independently-generated simplicial grids (i.e. created in parallel) can be stitched together with polytopes without communicating the whole mesh across processors



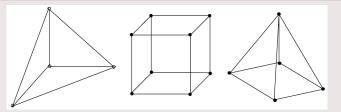


## Polytope Finite Elements

## 2D arbitrary convex/concave polygons

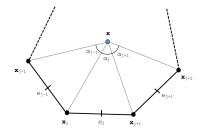


## 3D convex polyhedra





## Linear Basis Functions on 2D Polygons

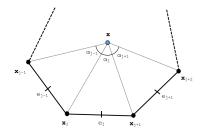


## Basis Function Properties - Barycentric Coordinates

- $0 \lambda_i \geq 0$
- $2 \sum_{i} \lambda_{i} = 1$
- $\lambda_i(\mathbf{x}_j) = \delta_{ij}$



## Wachspress Rational Functions

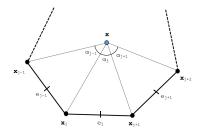


$$\lambda_i^W(\mathbf{x}) = \frac{w_i(\mathbf{x})}{\sum_i w_j(\mathbf{x})}, \qquad w_j(\mathbf{x}) = \frac{A(\mathbf{x}_{j-1}, \mathbf{x}_j, \mathbf{x}_{j+1})}{A(\mathbf{x}, \mathbf{x}_{j-1}, \mathbf{x}_j) A(\mathbf{x}, \mathbf{x}_j, \mathbf{x}_{j+1})}$$

$$A(\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3) = \frac{1}{2} \begin{vmatrix} 1 & 1 & 1 \\ x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \end{vmatrix}$$



## Piecewise Linear (PWL) Functions



$$\lambda_i^{PWL}(\mathbf{x}) = t_i(\mathbf{x}) + \alpha_i t_c(\mathbf{x})$$

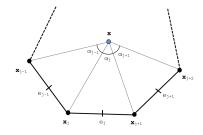
 $t_i$  - standard 2D linear function for a triangle  $(i, i+1, K_c)$ ; 1 at vertex i that linearly decreases to 0 to the cell center and the adjoining vertices

 $t_c$  - 2D tent function; 1 at cell center and linearly decreases to 0 to each cell vertex

 $\alpha_i = \frac{1}{N_V}$  - weight parameter for vertex i

 $N_V$  - number of cell vertices

#### Mean Value Coordinates



$$\lambda_i^{MV}(\mathbf{x}) = \frac{w_i(\mathbf{x})}{\sum_j w_j(\mathbf{x})}, \qquad w_j(\mathbf{x}) = \frac{\tan(\alpha_{j-1}/2) + \tan(\alpha_j/2)}{|\mathbf{x}_j - \mathbf{x}|}$$

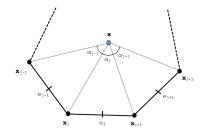
## Limit as $\mathbf{x} \to \mathbf{x}_i$

$$\lim_{\mathbf{x}\to\mathbf{x}_j}\tan(\alpha_{j-1}/2)+\tan(\alpha_j/2)=0 \qquad \qquad \lim_{\mathbf{x}\to\mathbf{x}_j}w_j(\mathbf{x})=1$$





## Maximum Entropy Coordinates



$$\lambda_i^{ME}(\mathbf{x}) = \frac{w_i(\mathbf{x})}{\sum_i w_i(\mathbf{x})}, \qquad w_j(\mathbf{x}) = m_j(\mathbf{x}) \exp(-\omega^* \cdot (\mathbf{x}_j - \mathbf{x}))$$

$$\omega^* = \operatorname{argmin} F(\omega, \mathbf{x}) \qquad F(\omega, \mathbf{x}) = \operatorname{In} \left( \sum_j w_j(\mathbf{x}) \right)$$



## Summary of the 2D Linear Basis Functions

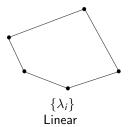
Basis Function	Dimension	Polytope Types	Analytical/Numerical	Direct/Iterative
Wachspress	2D/3D	Convex*	Numerical	Direct
PWL	1D/2D/3D	Convex/Concave	Analytical	Direct
Mean Value	2D**	Convex/Concave	Numerical	Direct
Max Entropy	1D/2D/3D	Convex/Concave	Numerical	Iterative***

- \* weak convexity for Wachspress coordinates does not cause blow up
- \*\* mean value 3D analogue only applicable to tetrahedron
- \*\*\* maximum entropy minimization solved via Newton's Method



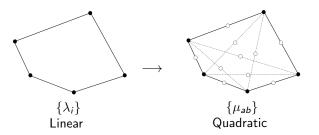
## Quadratic Serendipity Basis Functions on 2D Polygons

- **①** Form the linear barycentric functions  $\{\lambda_i\}$
- ② Construct the pairwise products  $\{\mu_{ab}\}$
- **③** Eliminate the interior nodes to form a serendipity basis  $\{\xi_{ij}\}$



## Quadratic Serendipity Basis Functions on 2D Polygons

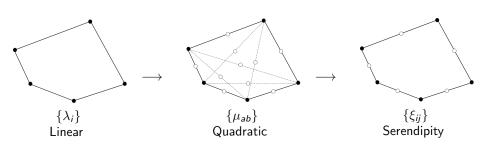
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- **①** Form the linear barycentric functions  $\{\lambda_i\}$
- **②** Construct the pairwise products  $\{\mu_{ab}\}$
- **3** Eliminate the interior nodes to form a serendipity basis  $\{\xi_{ii}\}$



#### Pairwise products of the barycentric basis functions

## **Necessary Precision Properties**

$$\sum_{\mathit{aa} \in \mathit{V}} \mu_{\mathit{aa}} + \sum_{\mathit{ab} \in \mathit{E} \cup \mathit{D}} 2\mu_{\mathit{ab}} = 1$$

$$\sum_{\mathsf{aa} \in V} \mathbf{x}_{\mathsf{aa}} \mu_{\mathsf{aa}} + \sum_{\mathsf{ab} \in E \cup D} 2\mathbf{x}_{\mathsf{ab}} \mu_{\mathsf{ab}} = \mathbf{x}$$

$$\sum_{aa \in V} \mathbf{x}_a \mathbf{x}_a^T \mu_{aa} + \sum_{ab \in F \cup D} \left( \mathbf{x}_a \mathbf{x}_b^T + \mathbf{x}_b \mathbf{x}_a^T \right) \mu_{ab} = \mathbf{x} \mathbf{x}^T$$

V - vertex nodes

E - face midpoint nodes

D - interior diagonal nodes

## Further Notation/Notes

$$\mathbf{x}_{ab} = \frac{\mathbf{x}_a + \mathbf{x}_b}{2}, \qquad \mu_{ab} = \lambda_a \lambda_b$$

$$\mu_{ab}^{K}(\mathbf{r}) = 0, \quad \{ab \in D, \, \mathbf{r} \in \partial K\}$$



#### Eliminate interior nodes to form serendipity basis

## Reduction Problem - $[\xi] := \mathbb{A}[\mu]$

$$\mathbb{A} = \left[ \begin{array}{cccc} c_{11}^{11} & \dots & c_{ab}^{11} & \dots & c_{(n-2)n}^{11} \\ \dots & \ddots & \vdots & \ddots & \vdots \\ c_{11}^{ij} & \dots & c_{ab}^{ij} & \dots & c_{(n-2)n}^{ij} \\ \dots & \ddots & \vdots & \ddots & \vdots \\ c_{11}^{n(n+1)} & \dots & c_{ab}^{n(n+1)} & \dots & c_{(n-2)n}^{n(n+1)} \end{array} \right]$$

## Serendipity Precision Properties

$$\begin{split} \sum_{ii \in V} \xi_{ii} + \sum_{i(i+1) \in E} 2\xi_{i(i+1)} &= 1 \\ \sum_{ii \in V} \mathbf{x}_{ii} \xi_{ii} + \sum_{i(i+1) \in E} 2\mathbf{x}_{i(i+1)} \xi_{i(i+1)} &= \mathbf{x} \\ \sum_{ii \in V} \mathbf{x}_{i} \mathbf{x}_{i}^{T} \xi_{ii} + \sum_{i(i+1) \in E} \left(\mathbf{x}_{i} \mathbf{x}_{i+1}^{T} + \mathbf{x}_{i+1} \mathbf{x}_{i}^{T}\right) \xi_{i(i+1)} &= \mathbf{x} \mathbf{x}^{T} \end{split}$$

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## Special case - bilinear coordinates on the unit square

## Bilinear coordinates and quadratic extension

$$\lambda_{1} = (1-x)(1-y)$$

$$\lambda_{2} = x(1-y)$$

$$\lambda_{3} = xy$$

$$\lambda_{4} = (1-x)y$$

$$\mu_{11} = (1-x)^{2}(1-y)^{2}$$

$$\mu_{12} = (1-x)x(1-y)^{2}$$

$$\mu_{23} = x^{2}y(1-y)$$

$$\mu_{33} = x^{2}y^{2}$$

$$\mu_{44} = (1-x)^{2}y^{2}$$

$$\mu_{41} = (1-x)^{2}y(1-y)$$

$$\mu_{13} = (1-x)x(1-y)y$$

$$\mu_{24} = (1-x)x(1-y)y$$

#### Reduction matrix

## Serendipity coordinates

$$\xi_{11} = (1 - x)(1 - y)(1 - x - y)$$

$$\xi_{22} = x(1 - y)(x - y)$$

$$\xi_{33} = xy(-1 + x + y)$$

$$\xi_{44} = (1 - x)y(y - x)$$

$$\xi_{12} = (1 - x)x(1 - y)$$

$$\xi_{23} = xy(1 - y)$$

$$\xi_{34} = (1 - x)xy$$

$$\xi_{41} = (1 - x)y(1 - y)$$



## Linear Basis Functions on 3D Polyhedra

## Linear basis functions and convex polyhedra only for 3D

- The 2D quadratic serendipity formulation is more arduous in 3D
- Intercell coupling is not straightforward for concave polyhedra
- Focus on 3D PWL functions MAXENT only other function for arbitrary polyhedra
- Focus on 3D parallelepipeds and extruded convex polygons (convex prisms)

#### 3D PWL basis functions

$$b_i(\mathbf{x}) = t_i(\mathbf{x}) + \sum_{f=1}^{F_i} \beta_f^i t_f(\mathbf{x}) + \alpha_i t_c(\mathbf{x})$$

 $t_i$  - standard 3D linear function for a tet  $(i, i+1, f_c, K_c)$ ; 1 at vertex i, linearly decreases to 0 to the cell center, each adjoining face center, and each adjoining vertex

 $t_c$  - 3D tent function; 1 at cell center, linearly decreases to 0 at all vertices and face centers t<sub>f</sub> - face tent function; 1 at face center, linearly decreases to 0 at each face vertex and cell center

 $\alpha_i = \frac{1}{N_V}$  - weight parameter for vertex i

 $\beta_f^i = \frac{1}{N_c}$  - weight parameter for face f touching vertex i



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#### The diffusion equation is used as our low-order operator

## The Diffusion Equation

$$-
abla \cdot D
abla \Phi(\mathbf{r}) + \sigma \Phi(\mathbf{r}) = q(\mathbf{r}), \qquad \mathbf{r} \in \mathcal{D}$$

#### General Boundary Conditions

$$\begin{split} \Phi(\textbf{r}) &= \Phi_0(\textbf{r}), \qquad \textbf{r} \in \partial \mathcal{D}^d \\ - D \partial_n \Phi(\textbf{r}) &= J_0(\textbf{r}), \qquad \textbf{r} \in \partial \mathcal{D}^n \\ \frac{1}{4} \Phi(\textbf{r}) + \frac{1}{2} D \partial_n \Phi(\textbf{r}) &= J^{inc}(\textbf{r}), \qquad \textbf{r} \in \partial \mathcal{D}^r \end{split}$$

#### Desirable diffusion form properties

- Can handle concave and degenerate polytope cells
- Symmetric Positive-Definite (SPD)
- Availability of suitable preconditioners
- Agnostic of directionality of interior faces

#### Symmetric Interior Penalty (SIP) Form

#### Bilinear Form

$$\begin{split} a(\Phi,b) &= \left\langle D \nabla \Phi, \nabla b \right\rangle_{\mathcal{D}} + \left\langle \sigma \Phi, b \right\rangle_{\mathcal{D}} \\ &+ \left\{ \kappa_e^{\textit{SIP}} \llbracket \Phi \rrbracket, \llbracket b \rrbracket \right\}_{E_h^i} - \left\{ \llbracket \Phi \rrbracket, \{\{D \partial_n b\}\} \right\}_{E_h^i} - \left\{ \{\{D \partial_n \Phi\}\}, \llbracket b \rrbracket \right\}_{E_h^i} \\ &+ \left\{ \kappa_e^{\textit{SIP}} \Phi, b \right\}_{\partial \mathcal{D}^d} - \left\{ \Phi, D \partial_n b \right\}_{\partial \mathcal{D}^d} - \left\{ D \partial_n \Phi, b \right\}_{\partial \mathcal{D}^d} + \frac{1}{2} \left\{ \Phi, b \right\}_{\partial \mathcal{D}^r} \end{split}$$

#### Linear Form

$$egin{aligned} \ell(b) &= \left\langle q, b 
ight
angle_{\mathcal{D}} - \left\{ J_{0}, b 
ight\}_{\partial \mathcal{D}^{n}} + 2 \Big\{ J_{inc}, b \Big\}_{\partial \mathcal{D}^{r}} \ &+ \Big\{ \kappa_{e}^{SIP} \Phi_{0}, b \Big\}_{\partial \mathcal{D}^{d}} - \Big\{ \Phi_{0}, D \partial_{n} b \Big\}_{\partial \mathcal{D}^{d}} \end{aligned}$$



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## SIP Penalty Coefficient

$$\kappa_e^{SIP} \equiv egin{cases} rac{C_B}{2} \left(rac{D^+}{h^+} + rac{D^-}{h^-}
ight) &, e \in E_h^i \ C_B rac{D^-}{h^-} &, e \in \partial \mathcal{D} \end{cases}$$
 $\mathcal{C}_B = cp(p+1)$ 

c - user defined constant ( $c \geq 1$ ) p - polynomial order of the finite element basis (1,2,3,...)  $D^{(+/-)}$  - diffusion coefficient defined on the positive/negative side of a face  $h^{(+/-)}$  - orthogonal projection defined on the positive/negative side of a face

$$u^{\pm} = \lim_{s \to 0^{\pm}} u(\mathbf{r} + s\mathbf{n})$$



## Modified Interior Penalty (MIP) Form

## Diffusion Form

$$\begin{split} \left\langle D\nabla\Phi,\nabla b\right\rangle_{\mathcal{D}} + \left\langle \sigma\Phi,b\right\rangle_{\mathcal{D}} \\ + \left\{\kappa_{e}^{MIP}\llbracket\Phi\rrbracket,\llbracket b\rrbracket\right\}_{E_{h}^{i}} - \left\{\llbracket\Phi\rrbracket,\{\{D\partial_{n}b\}\}\right\}_{E_{h}^{i}} - \left\{\{\{D\partial_{n}\Phi\}\},\llbracket b\rrbracket\right\}_{E_{h}^{i}} \\ + \left\{\kappa_{e}^{MIP}\Phi,b\right\}_{\partial\mathcal{D}^{vac}} - \frac{1}{2}\left\{\Phi,D\partial_{n}b\right\}_{\partial\mathcal{D}^{vac}} - \frac{1}{2}\left\{D\partial_{n}\Phi,b\right\}_{\partial\mathcal{D}^{vac}} \\ = \left\langle q,b\right\rangle_{\mathcal{D}} \end{split}$$

#### MIP Penalty Term

$$\kappa_e^{MIP} = \max(rac{1}{4}, \kappa_e^{SIP})$$



#### Proposed Work

#### **POLYFEM**

- Analyze the different 2D linear polygonal basis functions for use in DGFEM transport calculations
- Perform the same analysis with the quadratic serendipity basis functions

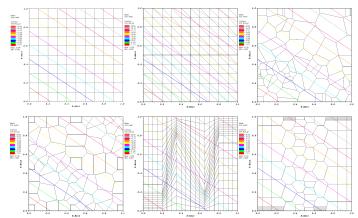
#### MIP DSA

- Analyze the 2D linear/quadratic basis functions with DSA preconditioning through Fourier/numerical analysis
- Extend the analysis of MIP DSA to arbitrary convex 3D polyhedra
- Implement MIP DSA in PDT using HYPRE
  - Analyze the scalability of the method to high process counts
  - Perform parametric studies on aggregation/partitioning factors to generate a performance model of MIP DSA with HYPRE
  - Implement and perform analysis of two-grid acceleration at scale
  - Question Run reactor-type problem (e.g., C5G7)
  - 6 Run real-world numerical experiments IM1



$$\mu \frac{\partial \psi}{\partial x} + \eta \frac{\partial \psi}{\partial y} + \sigma_t \psi = Q(x, y, \mu, \eta)$$

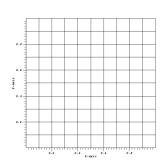
$$\psi(x, y, \mu, \eta) = ax + by + c\mu + d\eta + e, \qquad \phi(x, y) = 2\pi (ax + by + e)$$

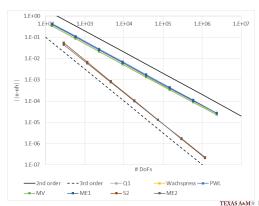




## Convergence rates using MMS for the 2D polygonal basis functions

$$\psi(x,y) = \sin(\nu \frac{\pi x}{L_x}) \sin(\nu \frac{\pi y}{L_y})$$
$$\phi(x,y) = 2\pi \sin(\nu \frac{\pi x}{L_x}) \sin(\nu \frac{\pi y}{L_y})$$

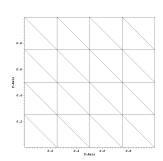


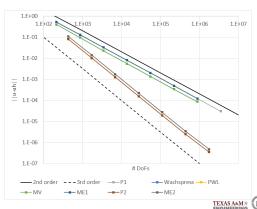




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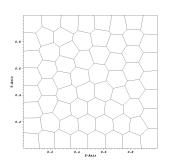


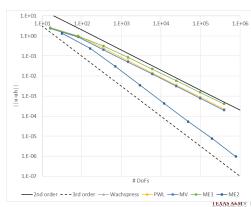




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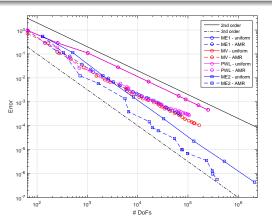
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### Convergence rates using MMS and AMR for the 2D polygonal basis functions

$$\psi(x,y) = x(L_x - x)y(L_y - y) \exp(-\frac{(x - x_0)^2 + (y - y_0)^2}{\gamma}),$$

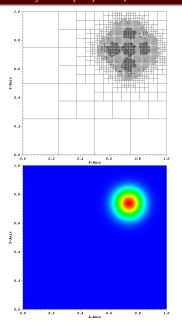
$$\phi(x,y) = 2\pi x(L_x - x)y(L_y - y) \exp(-\frac{(x - x_0)^2 + (y - y_0)^2}{\gamma})$$

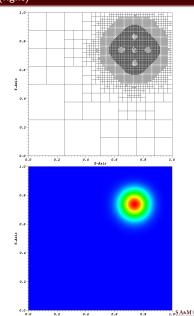
Proposed Work and Current Status



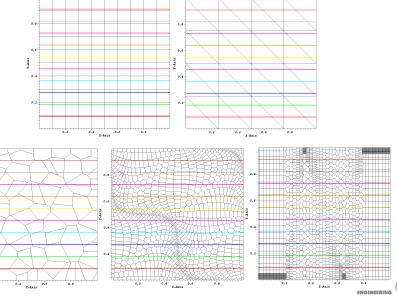


## Linear ME cycle 15 (left) and quadratic ME cycle 08 (right)





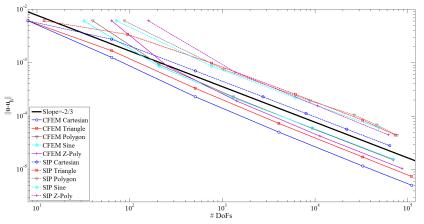




0.6

Proposed Work and Current Status 00000000000

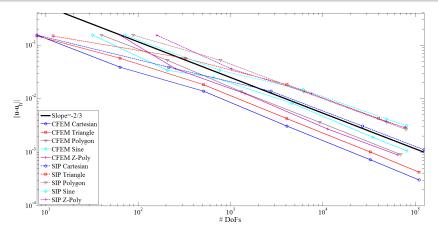
$$\Phi(x, y, z) = xyz(L_x - x)(L_y - y)(L_z - z)$$
  
 
$$L_x = L_x = L_x = 1.0$$





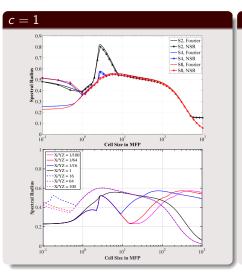
$$\Phi(x, y, z) = xyz(L_x - x)(L_y - y)(L_z - z) \exp(-(\mathbf{r} - \mathbf{r}_0) \cdot (\mathbf{r} - \mathbf{r}_0))$$
  

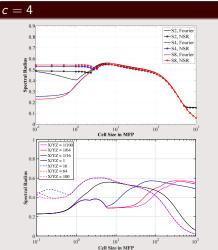
$$L_x = L_x = L_x = 1.0, \qquad \mathbf{r}_0 = (3/4, 3/4, 3/4)$$





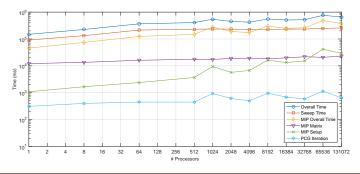
#### Fourier analysis - 3D PWL basis functions







#### MIP DSA Timing Data with PDT on Vulcan using HYPRE



### Problem Description

Overview

- Modified Zerr problem used optimal sweep aggregation parameters
  - homogeneous cube about 500 mfp and c=0.9999
  - 58 level-symmetric quadrature
- pointwise convergence tolerance of 1e-8
- SI precondition with MIP DSA using HYPRE PCG and AMG





## Two-grid acceleration implementation in PDT

- Successfully implemented and deugged
  - Includes non-orthogonal mesh configurations
  - Includes multi-material configurations
- Have tested the two-grid methodology on a homogeneous graphite block as well as a block with an air duct
- Iteration counts for a very large configuration (very optically thick) are similar to simple infinite medium calculations

l	Materials	Unaccelerated Iterations	Accelerated Iterations
	Graphite Only	2027	21
Ì	Graphite + Air Duct	2138	23



November 24, 2015

### POLYFEM Ongoing Work

- Finish quadratic serendipity extension for polygonal finite elements to Wachspress, PWL, and mean value.
- Determine the effects of numerical integration strategies on highly-distorted polygonal elements
- Perform analysis on benchmark cases using AMR
  - Searchlight problem (partially completed)
  - IAEA-EIR-2 problem

# MIP DSA Ongoing Work

- Finish the MIP DSA Fourier analysis for all the 2D polygonal basis functions (including the quadratic serendipity extension).
- Analyze the effects of AMR with polygonal basis functions on the MIP DSA PCG iteration counts (with and without bootstrapping)
- Remaining PDT work:
  - Complete parametric studies (a lot of the raw results have been compiled) of MIP DSA with HYPRE and generate a working performance model
  - Perform additional two-grid acceleration studies on simple geometries
  - Run IM1 problem with two-grid acceleration
  - Commit all acceleration additions to master for use in the CERT project



## Questions?

A special acknowledgment to the Department of Energy Rickover Fellowship Program in Nuclear Engineering, which provides strong support to its fellows and their professional development.





