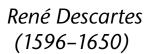
Generalized Barycentric Coordinates

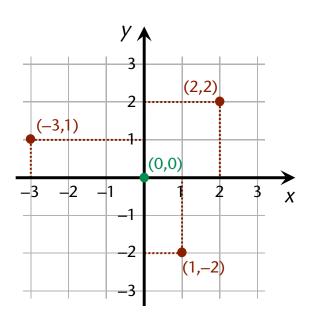
Kai Hormann

Faculty of Informatics Università della Svizzera italiana, Lugano

Cartesian coordinates







point (2,2) with

• *x*-coordinate: 2

y-coordinate: 2

mathematically:

$$(2,2) = 2 \cdot (1,0) + 2 \cdot (0,1)$$

in general:

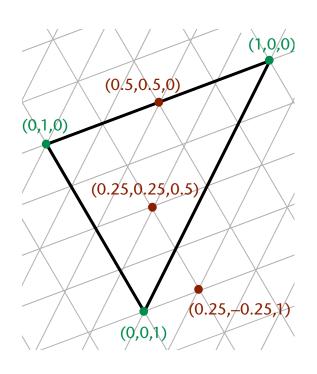
$$(x,y) = x \cdot (1,0) + y \cdot (0,1)$$

x- and y-coordinates w.r.t. base points (1,0) and (0,1)

Barycentric coordinates



August Ferdinand Möbius (1790–1868)



point (a,b,c) with 3 coordinates w.r.t. base points A, B, C

mathematically:

$$(a,b,c) = a \cdot A + b \cdot B + c \cdot C$$

where

$$A = (1,0,0)$$

 $B = (0,1,0)$

$$C = (0,0,1)$$

and

$$a + b + c = 1$$

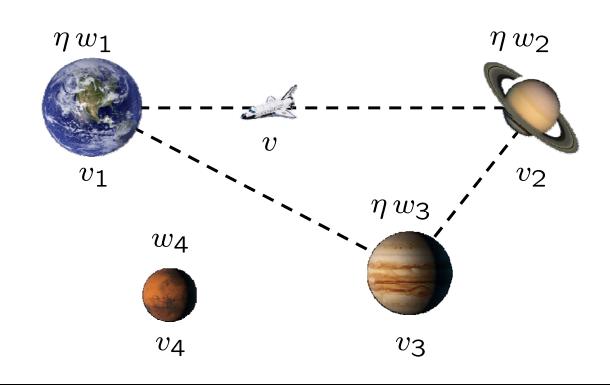
italiana

Barycentric coordinates

- lacksquare system of masses w_i at positions v_i
- position of the system's barycentre:
- w_i are the *barycentric coordinates* of v

$$v = \frac{\sum_{i} w_i v_i}{\sum_{i} w_i}$$

- not unique
- at least d+1 points needed to span \mathbb{R}^d



Barycentric coordinates

Theorem [Möbius, 1827]:

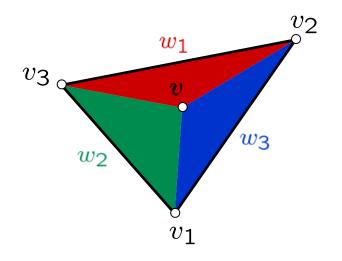
The barycentric coordinates w_1, \ldots, w_{d+1} of $v \in \mathbb{R}^d$ with respect to v_1, \ldots, v_{d+1} are unique up to a common factor

• example: d = 2

$$v = \frac{w_1v_1 + w_2v_2 + w_3v_3}{w_1 + w_2 + w_3}$$

$$\iff$$

$$w_i = \eta A(v, v_{i+1}, v_{i+2})$$



Barycentric coordinates for triangles

normalized barycentric coordinates

$$b_i(v) = \frac{w_i(v)}{w_1(v) + w_2(v) + w_3(v)}$$



partition of unity

 $\sum_{i} b_i(v) = 1$

reproduction

 $\sum_{i} b_i(v) v_i = v$

positivity

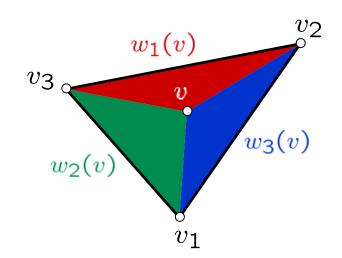
 $b_i(v) > 0, \quad v \in \overset{\circ}{\triangle}$

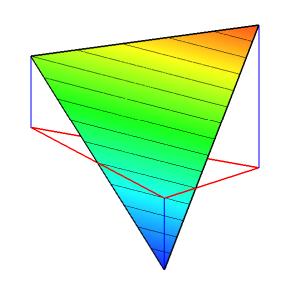
Lagrange property

 $b_i(v_j) = \delta_{ij}$

application

• linear interpolation of data $F(v) = \sum_{i=1}^{3} b_i(v) f_i$





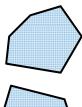
Generalized barycentric coordinates

finite-element-method with polygonal elements

convex [Wachspress 1975]

weakly convex [Malsch & Dasgupta 2004]

arbitrary [Sukumar & Malsch 2006]





interpolation of scattered data

natural neighbour interpolants [Sibson 1980]



– " – of higher order

[Hiyoshi & Sugihara 2000]

Dirichlet tessellations

[Farin 1990]

Generalized barycentric coordinates

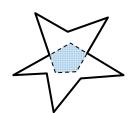
- parameterization of piecewise linear surfaces
 - shape preserving coordinates

[Floater 1997]

discrete harmonic (DH) coordinates [Eck et al. 1995]

mean value (MV) coordinates

[Floater 2003]



other applications

discrete minimal surfaces

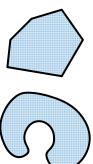
[Pinkall & Polthier 1993]

colour interpolation

[Meyer et al. 2002]

boundary value problems

[Belyaev 2006]



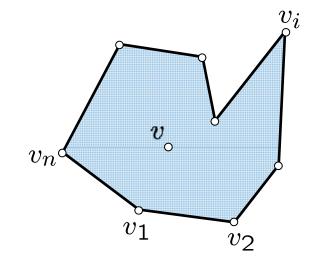
Arbitrary polygons

barycentric coordinates $w_1(v), \ldots, w_n(v)$

$$v = \frac{\sum_{i=1}^{n} w_i(v) v_i}{\sum_{j=1}^{n} w_j(v)}$$

normalized coordinates

$$b_i(v) = \frac{w_i(v)}{\sum_{j=1}^n w_j(v)}$$



- properties
 - partition of unity
 - reproduction

$$\sum_{i=1}^{n} b_i(v) = 1$$

$$\sum_{i=1}^{n} b_i(v) v_i = v$$

linear precision

$$\left. \begin{array}{l} \sum_{i=1}^{n} b_i(v) = 1\\ \sum_{i=1}^{n} b_i(v) v_i = v \end{array} \right\} \Rightarrow \sum_{i=1}^{n} b_i(v) \phi(v_i) = \phi(v)$$

for all $\phi \in \pi_1$

Convex polygons

[Floater, H. & Kós 2006]

• Theorem: If all $w_i(v) > 0$, then

positivity

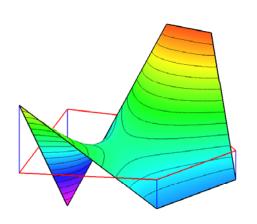
$$b_i(v) > 0$$

Lagrange property

$$b_i(v_j) = \delta_{ij}$$

linear along boundary

$$b_i|_{[v_i,v_{i+1}]} \in \pi_1$$



application

interpolation of data given at the vertices

$$F(v) = \sum_{i=1}^{n} b_i(v) f_i$$

- F(v) inside the convex hull of the f_i
- direct and efficient evaluation

Examples

Wachspress (WP) coordinates

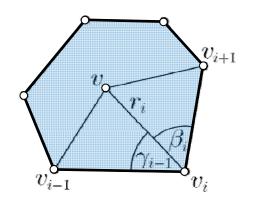
$$w_i = \frac{\cot \gamma_{i-1} + \cot \beta_i}{r_i^2}$$

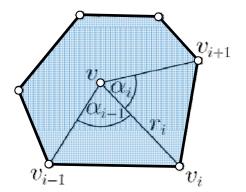


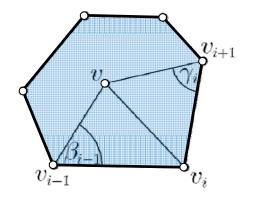
$$w_i = \frac{\tan(\alpha_{i-1}/2) + \tan(\alpha_i/2)}{r_i}$$

discrete harmonic (DH) coordinates

$$w_i = \cot \beta_{i-1} + \cot \gamma_i$$







Normal form

[Floater, H. & Kós 2006]

Theorem: All barycentric coordinates can be written as

$$w_i = \frac{c_{i+1}A_{i-1} - c_iB_i + c_{i-1}A_i}{A_{i-1}A_i}$$

with certain real functions c_i

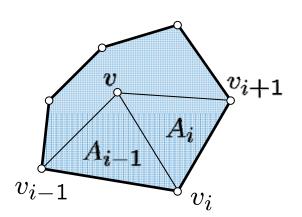


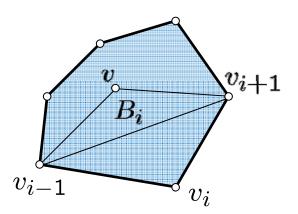
•
$$c_i = f(r_i)$$
 with $r_i = ||v - v_i||$



$$f: \mathbb{R}^+ \to \mathbb{R}$$

exists for all three-point coordinates





Three-point coordinates

Theorem: $w_i(v) > 0$ if and only if f is

positive

monotonic

$$f'(r) \ge 0$$

convex

$$f''(r) \ge 0$$

sub-linear

$$f'(r) \le f(r)/r$$

examples

WP coordinates

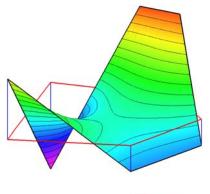
$$f(r) = 1$$

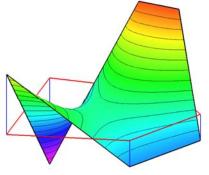
MV coordinates

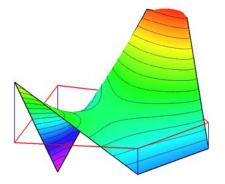
$$f(r) = r$$

DH coordinates

$$f(r) = r^2$$

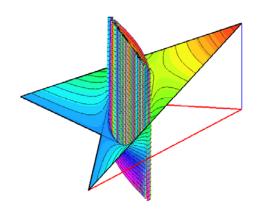






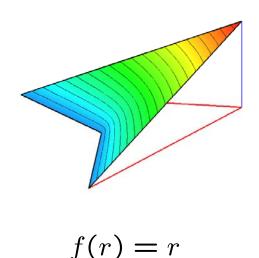
Non-convex polygons

Wachspress

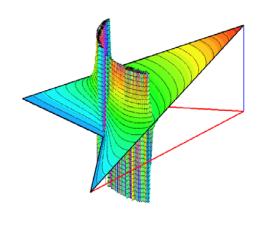


f(r) = 1

mean value



discrete harmonic



$$f(r) = r^2$$

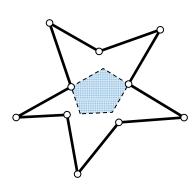
poles, if
$$W(v) = \sum_{j=1}^{n} w_j(v) = 0$$
, because $b_i(v) = \frac{w_i(v)}{W(v)}$

italiana

- **Theorem:** $W(v) \neq 0$ if and only if f is
 - positive

super-linear

$$f'(r) \ge f(r)/r$$

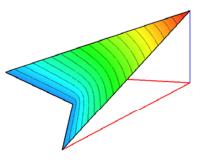


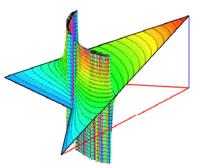
- examples
 - MV coordinates

$$f(r) = r$$

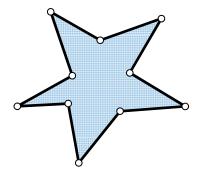
DH coordinates

$$f(r) = r^2$$





- **Theorem:** W(v) = 0 for some v if f is
 - strictly super-linear f'(r) > f(r)/r

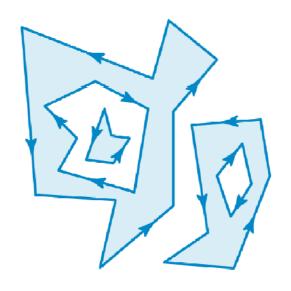


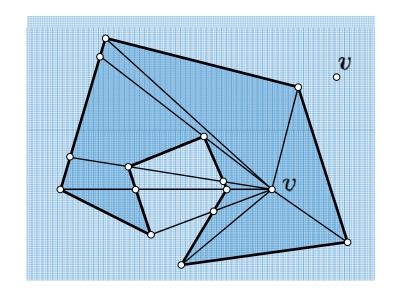
Mean value coordinates

[H. & Floater 2006]

Theorem: MV coordinates have no poles in \mathbb{R}^2

$$W(v) = \sum w_j(v) = \sum \kappa_i(v) \neq 0$$





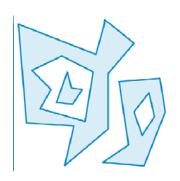
Mean value coordinates

properties

- well-defined everywhere in \mathbb{R}^2
- Lagrange property $b_i(v_j) = \delta_{ij}$
- linear along boundary $b_i|_{[v_i,v_{i+1}]} \in \pi_1$
- Inear precision $\sum_i b_i(v)\phi(v_i) = \phi(v)$ for $\phi \in \pi_1$
- smoothness C^0 at v_i , otherwise C^∞
- similarity invariance $b_i = \hat{b}_i \circ \psi$ for $\widehat{\Omega} = \psi(\Omega)$

application

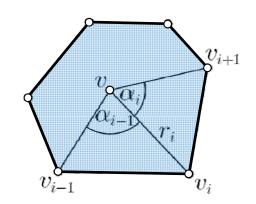
• direct interpolation of data $F(v) = \sum_{i=1}^{n} b_i(v) f_i$



Implementation

Mean Value coordinates

$$w_i = \frac{\tan(\alpha_{i-1}/2) + \tan(\alpha_i/2)}{r_i}$$



$$\tan(\alpha_{i}/2) = \frac{\sin \alpha_{i}}{1 + \cos \alpha_{i}} = \frac{r_{i}r_{i+1}\sin \alpha_{i}}{r_{i}r_{i+1} + r_{i}r_{i+1}\cos \alpha_{i}}$$
$$= \frac{\det(s_{i}, s_{i+1})}{r_{i}r_{i+1} + \langle s_{i}, s_{i+1} \rangle} = t_{i}$$

$$s_i = v_i - v$$

$$w_i = \frac{t_{i-1} + t_i}{r_i}$$

italiana

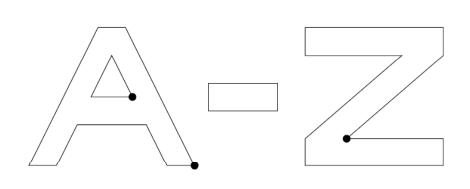
Implementation

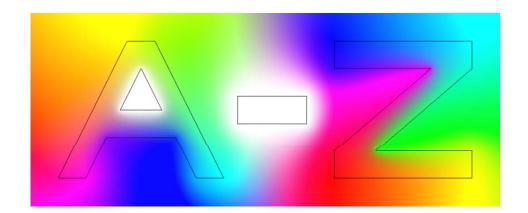
```
function F(v)
```

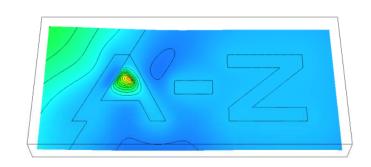
```
for i = 1 to n do
01
02
                                                  11 for i = 1 to n do
    s_i := v_i - v
03 r_i := ||s_i||
                                                  12 t_i := A_i/(r_i r_{i+1} + D_i)
04 if r_i = 0 then
                                    //v = v_i 13 f := 0
05
        return f_i
                                                  14 W := 0
    for i = 1 to n do
                                                  15 for i = 1 to n do
06
     A_i := \det(s_i, s_{i+1})
                                                  16 w := (t_{i-1} + t_i)/r_i
07
   D_i := \langle s_i, s_{i+1} \rangle
                                                  17 f := f + w f_i
80
    if A_i = 0 and D_i < 0 then //v \in e_i
                                                 18 W := W + w
09
         return (r_{i+1}f_i + r_if_{i+1})/(r_i + r_{i+1}) 19 return f/W
10
```

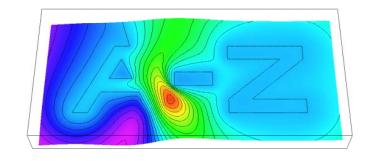
efficient and robust evaluation of the function F(v)

Colour interpolation



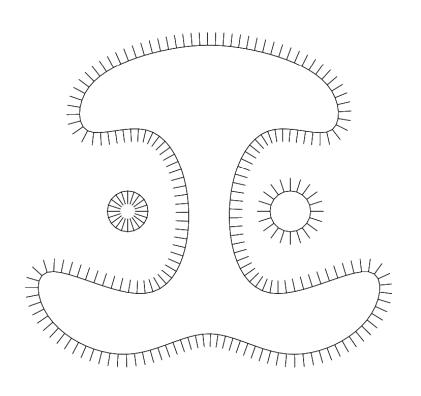


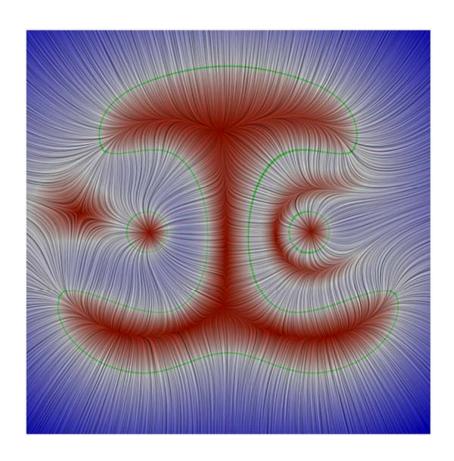




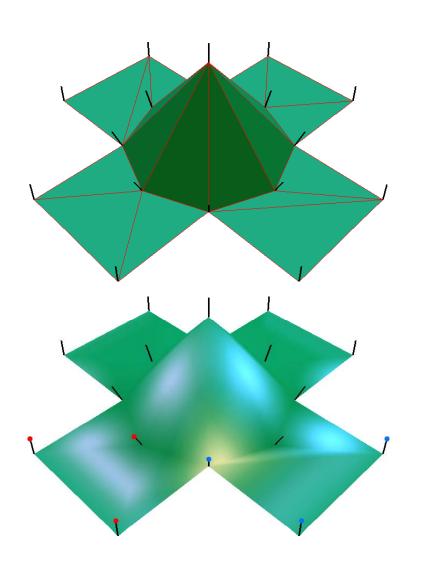


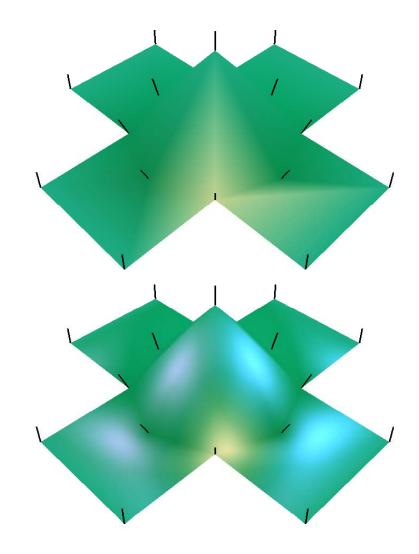
Vector fields





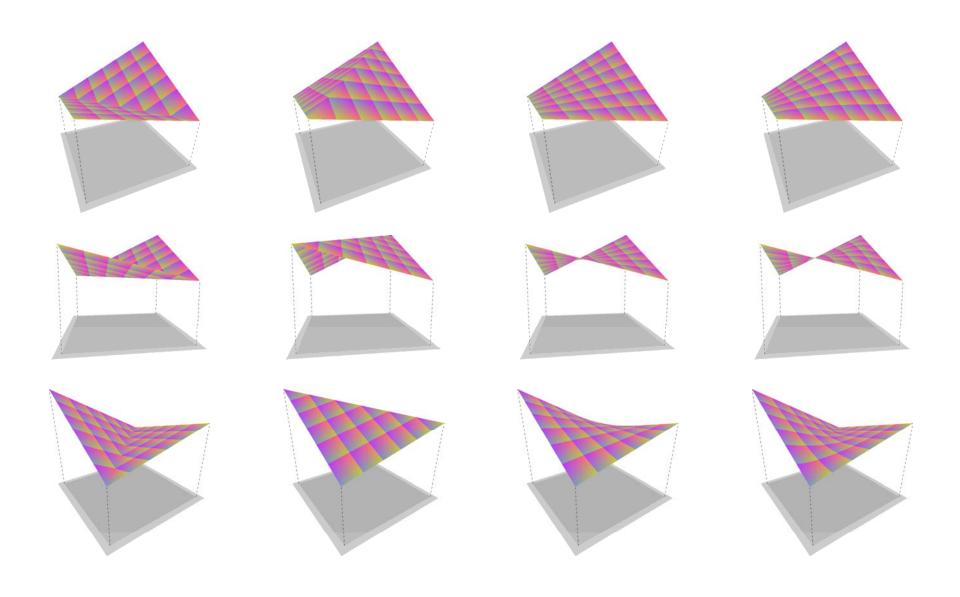
Smooth shading



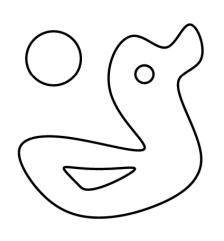


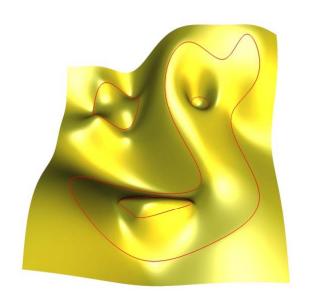
italiana

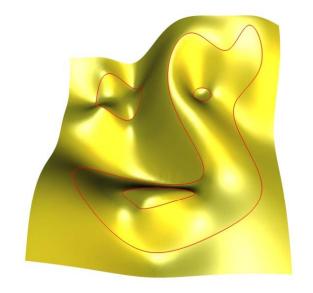
Rendering of quadrilateral elements



Transfinite interpolation



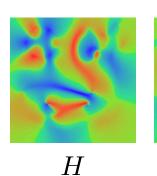


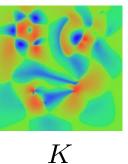


radial basis functions

mean value coordinates

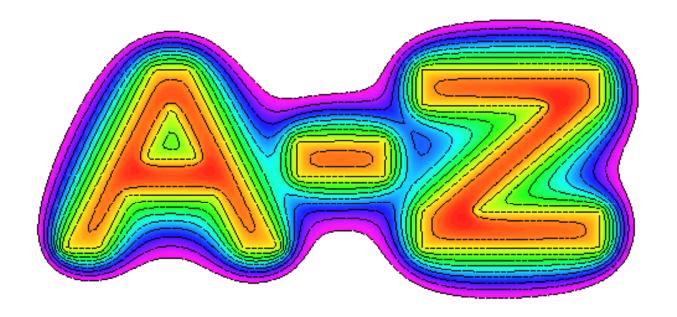
H K





Smooth distance function

- Function D = 1/W approximates the distance function
 - D(v) = 0 and $\|\nabla D(v)\| = 1/2$ along the boundary
 - smooth, except at the vertices



Mesh animation

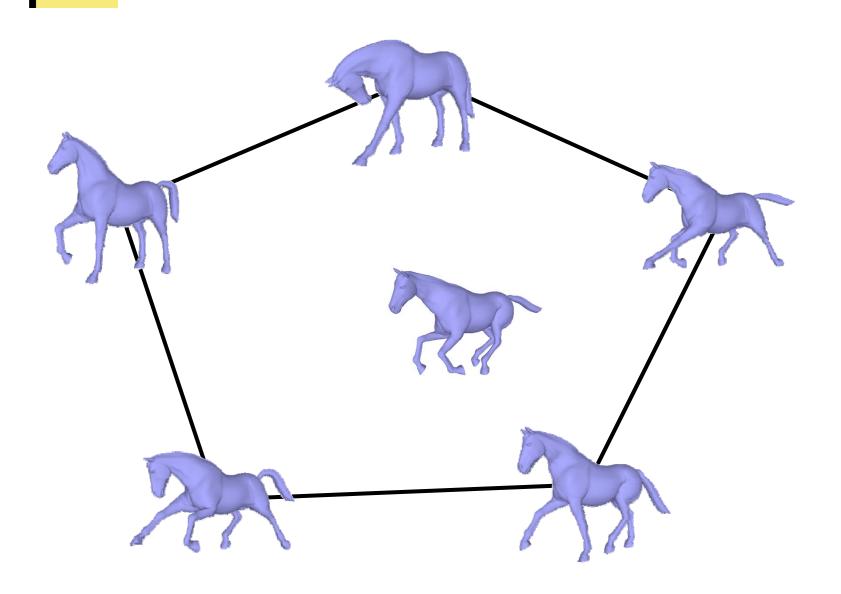
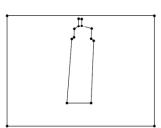
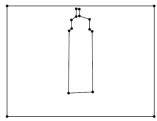


Image warping









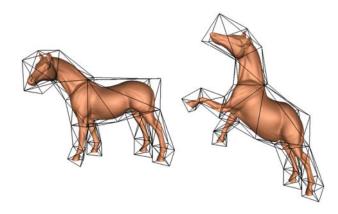
original image

mask

warped image

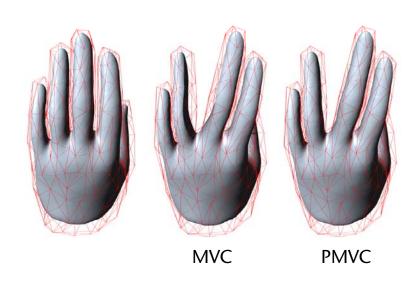
Mesh warping

MV coordinates in 3D



- negative inside the domain
- positive MV coordinates
 - only C⁰-continuous
 - no closed form

[Ju et al. 2005]



[Lipman et al. 2007]







MVC

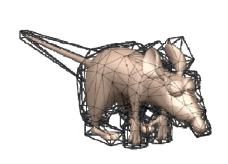
PMVC

Harmonic coordinates

- define normalized coordinate b_i as solution of PDE

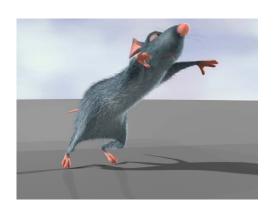
$$\Delta b_i = 0$$
 subject to $b_i(v_j) = \delta_{ij}, \quad b_i|_{[v_i,v_{i+1}]} \in \pi_1$

- Lagrange property ✓ well-defined ✓ smooth ✓
- linear precision ✓ positivity ✓ efficient *
- animation for Ratatouille



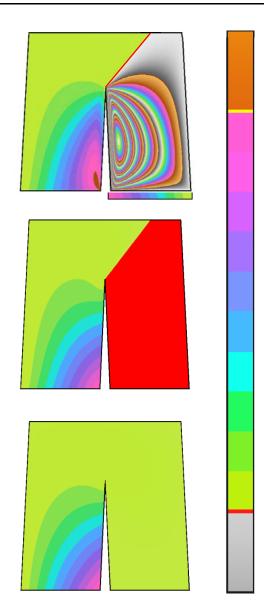


[Joshi et al. 2007]



Positive barycentric coordinates

- drawbacks so far ...
- mean value coordinates
 - negative
- positive mean value coordinates
 - not smooth (only C⁰)
- harmonic coordinates
 - rather expensive to compute
 - not smooth in practice



Maximum entropy coordinates

[H. & Sukumar 2008]

- based on maximizing the Shannon-Jaynes entropy
- Lagrange property ✓ well-defined ✓ smooth (✓)
- Iinear precision ✓ positivity ✓ efficient (✓)

