Autoencoder Tuning with PCA Principles

According to (1), "Autoencoders are directly related to Principal Component Analysis (PCA)," and an Autoencoder "extends PCA to a nonlinear space." Mathematically correct autoencoders are "well-posed," meaning they inherit the following properties of PCA:

- Tied Weights
 - Weights are equal for encoder and corresponding decoder layer (1)
 - Decoder weights are the transpose of the encoder weights, and this reduces the number of parameters for the model (2)
- Orthogonal Weights
 - Each weight vector is independent of others (1)
- Uncorrelated Features
 - Output of encoding layer is not correlated (1)
- Unit Norm
 - Weights on a layer have unit norm (1)

Furthermore, (1) explains how incorporating these properties provides regularization, addresses "exploding and vanishing gradient," and creates a smaller network for edge computing.

I am still exploring how to properly implement orthogonal weights and uncorrelated features.

Unit Norm

Tied Weights

```
==Encoder weights===
Hidden layer
[[ 0.223 -0.353 -0.272  0.392  0.133  0.229 -0.168 -0.244  0.449  0.01
  -0.488]
 [-0.362 0.22 0.25 -0.384 -0.055 0.184 -0.358 -0.195 0.2
                                                                -0.222
   0.564]
 [ 0.262 0.206 -0.237 -0.333 0.231 0.367 0.317 0.336 0.158 0.135
  -0.527]
 [ 0.166 -0.029  0.496  0.379  0.132  0.451  0.171  0.416  0.127  0.086
   0.368]
 [ 0.925  0.265  0.01
                       0.253 0.045 -0.007 0.043 -0.013 0.027 -0.064
  -0.038]
 [ 0.235  0.168 -0.274  0.102 -0.012 -0.136  0.042 -0.005  0.668  0.074
   0.6 ]
 [-0.592 0.
                0.487 -0.14
                              0.436 -0.082 0.313 0.213 0.015 -0.107
   0.201]
 [-0.546 -0.463 -0.469 -0.183 -0.153 0.03 -0.302 0.055 -0.164 -0.288
   0.076]
 [ 0.369 -0.14 -0.293 -0.086 0.087 0.221 0.154 -0.035 -0.726 0.123
   0.358]
 [ 0.25
         0.413 -0.326  0.301 -0.339 -0.017 -0.417 -0.01 -0.082  0.314
   0.42 ]]
Latent layer
[[ 0.102  0.005  0.301  0.268  0.499  0.064  0.022 -0.538 -0.162 -0.507]
   0.156 0.02
                                            0.207 0.123 -0.514 -0.367]
                0.385 0.188 -0.339 -0.468
 [-0.292 -0.196  0.134 -0.367 -0.183 -0.669 -0.153  0.371  0.105  0.265]
 [ 0.055 0.167 0.236 0.45 -0.329 0.54 0.032 0.201 0.224 -0.469]
 [ 0.202  0.46  -0.278  -0.24  -0.012  0.204  -0.397  0.02
                                                          0.365 0.529]
 [-0.264 0.201 -0.328 0.117 -0.187 -0.01
                                            0.43 -0.093 0.621 -0.393]
===Decoder weights===
Hidden layer 2
[[ 0.102 0.005 0.301 0.268 0.499 0.064 0.022 -0.538 -0.162 -0.507]
 [ 0.156  0.02  0.385  0.188 -0.339 -0.468  0.207  0.123 -0.514 -0.367]
 [-0.292 -0.196  0.134 -0.367 -0.183 -0.669 -0.153
                                                   0.371 0.105 0.265]
 [ 0.055  0.167  0.236  0.45  -0.329  0.54  0.032  [ 0.202  0.46  -0.278  -0.24  -0.012  0.204  -0.397
                                                   0.201 0.224 -0.469]
                                                          0.365 0.529
                                                   0.02
 [-0.264 0.201 -0.328 0.117 -0.187 -0.01 0.43 -0.093 0.621 -0.393]
Output layer
[[ 0.223 -0.353 -0.272  0.392  0.133  0.229 -0.168 -0.244  0.449  0.01
  -0.4881
 [-0.362 0.22
               0.25 -0.384 -0.055 0.184 -0.358 -0.195 0.2
  0.564]
 [ 0.262  0.206 -0.237 -0.333  0.231  0.367  0.317  0.336  0.158  0.135
  -0.527]
 [ 0.166 -0.029  0.496  0.379  0.132  0.451  0.171  0.416  0.127  0.086
   0.368]
 [ 0.925  0.265  0.01
                        0.253 0.045 -0.007 0.043 -0.013 0.027 -0.064
  -0.038]
 [ 0.235  0.168 -0.274  0.102 -0.012 -0.136  0.042 -0.005  0.668  0.074
   0.6 ]
 [-0.592 0.
                 0.487 -0.14
                               0.436 -0.082 0.313 0.213 0.015 -0.107
   0.201]
 [-0.546 -0.463 -0.469 -0.183 -0.153 0.03 -0.302 0.055 -0.164 -0.288
   0.076]
 [ 0.369 -0.14 -0.293 -0.086 0.087 0.221 0.154 -0.035 -0.726 0.123
   0.358]
 [ 0.25
         0.413 -0.326 0.301 -0.339 -0.017 -0.417 -0.01 -0.082 0.314
   0.42 ]]
```

```
Encoder weights dot products
[[ 1.
       -0.42 0.23 -0.07 0.24 0.08 -0.48 0.01 -0.28 -0.1 ]
 [-0.42]
       1.
             -0.4
                    0.06 -0.39
                               0.26 0.34 0.23 -0.19
                                                     0.12]
 [ 0.23 -0.4
              1.
                    0.02 0.24 -0.12 -0.1 -0.27
                                                 0.02 -0.28]
 [-0.07 0.06 0.02
                   1.
                          0.24 0.19 0.32 -0.43 0.06
                                                      0.03]
 [ 0.24 -0.39 0.24
                    0.24
                         1.
                                0.28 -0.55 -0.69 0.25
                         0.28
                               1.
 [ 0.08 0.26 -0.12 0.19
                                     -0.15 -0.2
                                                -0.15
                    0.32 -0.55 -0.15
 [-0.48 0.34 -0.1
                                           0.01 -0.24 -0.58]
                                    1.
 [ 0.01 0.23 -0.27 -0.43 -0.69 -0.2
                                     0.01
                                          1.
                                                 0.07 - 0.1 
                                                 1.
 [-0.28 -0.19 0.02 0.06 0.25 -0.15 -0.24 0.07
                                                       0.25]
        0.12 -0.28 0.03 0.34 0.46 -0.58 -0.1
                                                 0.25
 [-0.1
        0.19 -0.58 0.16 -0.47 -0.03]
[[ 1.
        1.
 [ 0.19
              0.17 0.13 -0.67 -0.17]
 [-0.58 0.17 1.
                   -0.51 0.01 -0.15]
 [ 0.16 0.13 -0.51 1.
                         -0.15 0.37]
 [-0.47 -0.67 0.01 -0.15 1.
                               -0.05]
 [-0.03 -0.17 -0.15 0.37 -0.05 1. ]]
Decoder weights dot product
[[ 1.
        0.19 -0.58 0.16 -0.47 -0.03]
              0.17 0.13 -0.67 -0.17]
 [ 0.19 1.
 [-0.58 0.17 1.
                   -0.51 0.01 -0.15]
 [ 0.16 0.13 -0.51 1.
                         -0.15 0.37]
 [-0.47 -0.67 0.01 -0.15 1.
                               -0.05]
 [-0.03 -0.17 -0.15 0.37 -0.05 1. ]]
        -0.42 0.23 -0.07 0.24 0.08 -0.48 0.01 -0.28 -0.1 ]
[[ 1.
             -0.4
                    0.06 -0.39
                                                     0.121
 [-0.42
        1.
                               0.26
                                     0.34 0.23 -0.19
 [ 0.23 -0.4
              1.
                    0.02 0.24 -0.12 -0.1 -0.27
                                                 0.02 -0.28]
 [-0.07 0.06 0.02
                          0.24 0.19 0.32 -0.43 0.06
                    1.
                                                      0.03]
 [ 0.24 -0.39 0.24
                   0.24
                         1.
                                0.28 -0.55 -0.69 0.25
 [ 0.08 0.26 -0.12
                    0.19
                         0.28
                                     -0.15 -0.2 -0.15
                               1.
                                                     0.46]
                    0.32 -0.55 -0.15
 [-0.48 0.34 -0.1
                                     1.
                                           0.01 -0.24 -0.58]
 [ 0.01 0.23 -0.27 -0.43 -0.69 -0.2
                                     0.01
                                           1.
                                                 0.07 - 0.1 
 [-0.28 -0.19 0.02
                    0.06 0.25 -0.15 -0.24 0.07
                                                 1.
                                                       0.25]
        0.12 -0.28 0.03 0.34 0.46 -0.58 -0.1
                                                 0.25
```

Sources

- https://towardsdatascience.com/build-the-right-autoencoder-tune-and-optimize-using-pcaprinciples-part-ii-24b9cca69bd6
- https://medium.com/@lmayrandprovencher/building-an-autoencoder-with-tied-weights-inkeras-c4a559c529a2