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## Poor Mans Parallelism

### Intruduction

The problem is solved using C#.

Two applications are created, a server application accept request over TCP network, and a client application wich devide the work load and spread it to the servers.

The servers in this case are all the locla machines and they are listening from different ports.

### The solution:

#### The client application

To establish communications, TCP synchronized sockets are implemented, a Class Connect that has the method to perform the send operation.

#### The main program

1.The system prompt for specification of the problem, the user enter the values of C,sizes x, y, max number of iterations max\_n, number of servers, the addresses and port numbers,

this is stored in a string.

2. Extract values from the string using the split method and store the values in a string array data\_str;

3. Convert string obtained to integers and doubles.

4. Devide the work.

This is done in th following steps:

- determine the optimal division of servers such as each server get a workload, such that we get a  $a \times b$

division (a horizontally and b vertically), that is  $\text{divs} = a \times b$ .

In the case  $\text{divs}$  is a prime number, the total number of servers  $\text{divs}$  is a prime number then we take  $a = \text{divs}$  and  $b=1$ .

In the case it is not,  $a$  is determined to be the first prime number that divide the total number  $\text{divs}$ .

- determine the work load, each server get the amount of data specified as  $xloc$  and  $yloc$ . Then  $xloc = x/a$ ,  $yloc = y/b$ .

- set the byte array where the global picture is stored as `Entire_pic`.

- set the byte array where local picture is stored as `part`.

- Prepare connections.

The client should send requests to servers synchronically, that is no send-receive operation should be first terminated to connect for the other server.

To implement this, thread are used. Threads take delegates as objects, these delegates perform the send operation by calling the method `SendWork` of a Class `Connect`.

To begin the operation, the thread are started by the method `Start()`:

The class `Connect` is a class which has the constructor `getwork`, the constructor take the values of `min` and `max` of `C`, local part  $xloc$  and  $yloc$ , `max_n`, host address of the server and port, and `i`, `j` which determine the where in the global picture the local part is situated.

The class `Connect` has a private member `part`, where the result from the server is stored, when the receive operation is terminated.

For example for  $i=0, j=0$  the part is located in the upper left corner of the global picture, for  $i=0, j=1$  the part is the upper second part horizontally.

- To send the work loads, we iterate on `i` and `j`.

- different servers take different times to perform the calculations. The class `Connect` has a private boolean member `status` which is set to true when the data is received.

- when all servers have finished the send back operation, the message "all servers responded." is displayed.

- Iterate on all obtained parts and store the data in the global picture variable `entire-pic`.

- Convert the `entire_pic` variable to a 2-dimensional array of integers.

- Store the result in a PGM file.

`SendWork()` method in the class `Connect`:

This method sends the information using a socket.

- establish the remote endpoint for the socket.

The IP address is obtained by parsing the host, using the method Parse.

The remote endpoint is obtained by the IP address and the port number.

Create the TCP/IP socket sender.

Connect the socket to the remote endpoint by the operation `send.Connect(remoteEP)`.

A string that contains all information to send is constructed by converting the values to string values and then by the method `Concat` join them all together, the string work is obtained.

Convert the string to bytes and store it as a variable `msg`.

Send the data to the socket by the operation `sender.send(msg)` and then receive the response from the server by the operation `send.receive(bytes)`, where `bytes` is a byte buffer.

Close the socket and set the boolean variable `status` to `true`.

Catch error by throwing exceptions, and display the errors when caught.

## **The server application**

The server application uses sockets to listen for incoming communications from the client.

### **The main program**

Preparation of servers for listening, this is done by the following steps:

1. Create instances of the Class `Connect`, that is connections, the class has a constructor `serverspec`, which take the host address and the port number as arguments.
2. Create threads, as the listening operation is performed by each server independently, threads are used, they take delegates as `ThreadStart` and these delegates take a method of the class which is `listen()` to begin listening for incoming connections.
3. Threads are started, the method `listen()` are called.

The method `listen()` of the class `Connect`:

The method obtain the IP address by parsing the host, then establish a local endpoint for the socket, then create the TCP/IP socket listener.

Bind the socket to the local endpoint and begin listening, this is done by the operations:

```
listener.Bind(localEndPoint);  
listener.Listen(10);
```

Extract the first pending connection request from the connection request queue of the listening socket, and then creates and return a new socket handler:

```
socket handler = listener(accept);
```

The connections is processed, bytes are received by the operation

```
int bytesRec = handler.Receive(bytes);
```

Convert the bytes received to a string data,

Get the substring data\_new which contains the values of C and xloc,yloc, max\_n and the position i,j.

Convert the string values extracted as integers and doubles.

Iterate by values of x and y that varies of the partial region horizontally and vertically. Iterate by value of C, from minC\_re to maxC\_re and from minC\_im to maxC\_im.

For each pixel Z0 with coordinates (x,y) in in the partial region we have the initial values:

```
// initial values  
double tx = x + cx;  
double ty = y + cy;
```

That is Z1 with coordinates (tx,ty)  $Z_1 = Z_0 + C$ .

We calculate the absolute value as the following:

```
double znewx = tx * tx - ty * ty + tx;    The power  
double znewy = ty + 2 * tx * ty;  
double absZ = Math.Sqrt(znewx * znewx - znewy*znewy); The square root.
```

That is to check if the absolute value is greater then the absolute value of C, as the following:

```
if (absZ > Math.Sqrt(cx * cx - cy * cy))
```

If this is true, then stop the iteration and n is the number of iterations performed modulo 256, convert then to bytes and store in the partial array part\_pic as the following:

```
byte px1 = (byte)(n % 256);  
part_pic[(x - i * xloc) + y * (yloc - j * yloc)] = px1;  
break;
```

Otherwise, continue the iteration, and the new initial values are

```
else n++;  
tx = znewx;  
ty = znewy;
```

That is  $Z_2 = Z_1 + C$ .

The iteration continues in this manner until n reaches the maximum number of iterations allowed, max\_n.

we set this as the following:

```
while (n < max_n);
```

When the iteration is performed over all points in the partial region, we obtain a byte array that contains the number of iterations performed foreach pixel.

The data part\_pic is sent back to client, and socked is closed. Catch exceptions and display errors if any exists.

