

# Chapter 14

## Deep Learning in Diagnosis of Brain Disorders

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**Abstract** In this chapter, we introduce our recent work on neuroimaging-based AD diagnosis with machine learning techniques, especially deep learning. Specifically, we focus on the problems of feature representation and complementary information fusion from different modalities, e.g., MRI and PET. In our experimental results on the publicly available ADNI dataset, we could validate the effectiveness of the deep learning-based feature representation and its superiority to the competing methods. We also present the importance of collaborating communities of machine learning and clinical neuroscience for clinical interpretation of the learned feature representations.

**Keywords** Alzheimer's disease (AD) • Mild cognitive impairment (MCI) • Deep learning • Stacked auto-encoder • Deep Boltzmann machine

### 14.1 Introduction

As the population becomes older, the world is now facing an epidemic of dementia. Among various causes of dementia, Alzheimer's Disease (AD) is the most prevalent in elderly people, which rises significantly every year in terms of the proportion of

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\*Data used in preparation of this article were obtained from the Alzheimer's Disease Neuroimaging Initiative (ADNI) database (<http://www.loni.ucla.edu/ADNI>). As such, the investigators within the ADNI contributed to the design and implementation of ADNI and/or provided data but did not participate in analysis or writing of this report. A complete list of ADNI investigators is available at [http://adni.loni.ucla.edu/wpcontent/uploads/how\\_to\\_apply/ADNI\\_Authorship\\_List.pdf](http://adni.loni.ucla.edu/wpcontent/uploads/how_to_apply/ADNI_Authorship_List.pdf).

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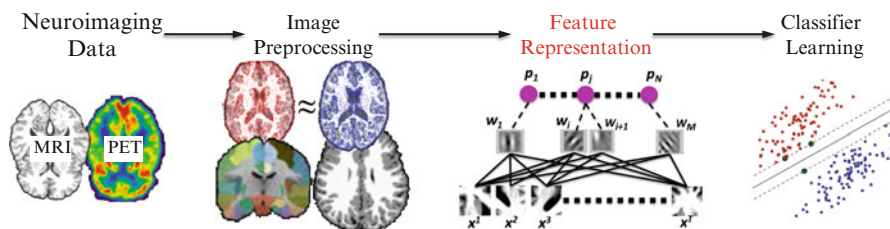
cause of death. A recent study by Alzheimer's Association reported that 10~20 % of people aged 65 or older have Mild Cognitive Impairment (MCI), a prodromal stage of AD [1]. But there is no treatment to halt its progression to AD yet. In this regard, it has been one of the major issues to understand the underlying mechanisms that develop such devastating neurodegenerative disease in the fields of neuroscience, neuropsychiatry, etc.

The current scientific technologies of medical imaging, such as Magnetic Resonance Imaging (MRI) and Positron Emission Topography (PET), provide paths to investigate the structure and function of the brain in vivo. With the help of such tools, researchers have made a great leap in understanding the disease. However, the group-level analysis prevalently used for investigation and understanding of the disease is not clinically applicable for individual diagnosis. In the meantime, machine learning techniques, which can efficiently analyze the complex patterns in observations, help pave the way for a computer-aided AD diagnosis system by building computational models that can discriminate patients with the disease from healthy normal subjects.

The conventional computer-aided diagnostic systems mostly considered neuroimaging features such as voxel intensities of predefined regions, gray matter volumes, cortical thickness, to name a few, all of which can be considered as simple low-level features. From a machine learning point of view, it is beneficiary to exploit the latent high-level features inherent in data to enhance the diagnostic performance. Deep learning [3], which has already proved its effectiveness by showing promising results in various fields including speech/object recognition [9, 23] and medical imaging analysis [14, 26], can discover latent or abstract high-level information in neuroimaging data, and thus be useful for the disease diagnosis. In this chapter, we introduce our recent work on neuroimaging-based AD diagnosis with deep learning.

## 14.2 Background

Figure 14.1 illustrates the general framework of machine learning-based AD diagnosis, composed of four main steps, namely, (1) neuroimaging data acquisition, (2) image preprocessing (including registration, tissue segmentation, Regions-



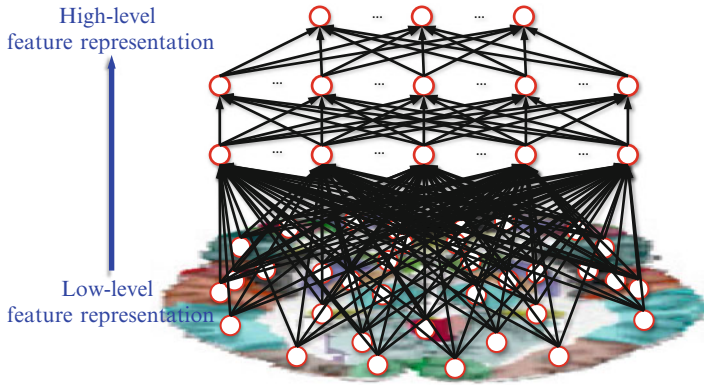
**Fig. 14.1** A general framework for machine learning-based AD diagnosis using neuroimaging data

Of-Interest (ROIs) parcellation, etc.), (3) feature extraction/representation, and (4) classifier learning. Although machine learning techniques can be involved in all of these steps [11, 24], in this chapter, we focus on the step of feature representation.

As for feature extraction or representation, the existing methods can be categorized into voxel-based approach, ROI-based approach, and patch-based approach. A voxel-based approach directly uses the voxel intensities of MRI or PET as features in classification [2, 10]. Although the voxel-based approach can reflect small changes in structure or function and it is easy to interpret the results, its main limitation comes from the high-dimensionality of feature vectors and also no consideration of the inter-region relation information. On the other hand, the ROI-based approach can handle the issue of high-dimensionality by extracting representative features from the structurally or functionally parcellated brain regions. Thanks to the relatively low feature-dimension and the whole brain coverage, this approach has been most widely used in the literature [6, 12, 20, 29, 32, 34]. However, the features extracted from ROIs are very coarse in the sense that they cannot reflect small or subtle changes involved in the brain diseases. In the meantime, a patch-based approach dissects a brain into small 3D patches from which it extracts features and trains a classifier for each patch location, and then combines classifiers' outputs in a hierarchical manner [15, 31]. The patch-based approach has the advantages of (1) reflecting subtle changes by using voxel-wise features as the voxel-based approach does and (2) also considering a whole brain information as the ROI-based approach does by hierarchically integrating regional information.

### 14.3 Deep Learning for AD Diagnosis

Although the existing methods described in Sect. 14.2 have shown their effectiveness for AD diagnosis in the literature, they mostly used the simple low-level features without considering the high-level information latent in those features. Inspired from the biological model of the human visual cortex [7, 25], recent studies in machine learning have shown that a deep architecture composed of multiple non-linear transformations is useful to find highly non-linear and complex patterns in the data [3, 18]. This motivated us to apply deep learning techniques to neuroimaging-based AD diagnosis in [30, 31], where we used Stacked Auto-Encoder (SAE) and Deep Boltzmann Machine (DBM), respectively. In the following, we introduce these studies and further discuss the future research issues that should be tackled for clinical interpretation.



**Fig. 14.2** Stacked auto-encoder that discovers the latent high-level information inherent in ROI-based features

### 14.3.1 Stacked Auto-Encoder (SAE)

As a pioneering study of the application of deep learning for AD diagnosis, we used an SAE [4] to discover a latent feature representation in neuroimaging or biological data. Specifically, as the name says, we stacked auto-encoders, one after another by taking the outputs from the hidden units of the lower layer as the input to the upper layer's input units, and so on. Figure 14.2 shows the network structure of our SAE model with three auto-encoders stacked. As illustrated in Fig. 14.2, in this study, we took an ROI-based approach by extracting representative features from ROIs, which set the values of the input units in the bottom layer of our SAE.

Thanks to the hierarchical nature in structure, one of the most important characteristics of the SAE is to learn or discover highly non-linear and complicated patterns such as the relations among input features. Another important characteristic of the SAE is that the latent representation can be learned directly from the data. Utilizing its representational and self-taught learning properties, we could find a latent representation of the original low-level features, directly extracted from neuroimaging data. When an input sample is presented to an SAE model, the different layers of the network represent different levels of information. That is, the lower the layer in the network, the simpler patterns (e.g., linear relations of features); the higher the layer, the more complicated or abstract patterns inherent in the input feature vector (e.g., non-linear relations among features) [17].

To find the optimal parameters, we performed unsupervised layer-wise pre-training [8] and supervised fine-tuning during the auto-encoding task via back-propagation [5, 13] sequentially. It is noteworthy that, in order to obtain the complicated non-linear relations among neuroimaging features, we considered a number of hidden units larger than the number of input features, from which we can

still find an interesting structure by imposing a sparsity constraint via a Kullback-Leibler (KL) divergence. Specifically, in our pre-training step, we optimized the following objective function:

$$E(\mathbf{Y}_{h-1}, \hat{\mathbf{Y}}_{h-1}) + \gamma \sum_{j=1}^{D_h} KL(\rho || \hat{\rho}_j) \quad (14.1)$$

where  $E(\mathbf{Y}_{h-1}, \hat{\mathbf{Y}}_{h-1})$  denotes an error between the input  $\mathbf{Y}_{h-1}$  (i.e., the output from  $(h-1)$ -th layer) and its reconstruction  $\hat{\mathbf{Y}}_{h-1}$ ,  $D_h$  is the number of units in the  $h$ -th hidden layer, and  $\gamma$  is a control parameter. In Eq. (14.1), KL divergence controls the sparseness of the hidden units based on the average activation  $\hat{\rho}_j$  of the  $j$ -th hidden unit over the training samples and the target average activation  $\rho$ .

#### 14.3.1.1 Experiments and Performance Comparison

To validate the effectiveness of the SAE-based feature representation, we conducted experiments with ADNI dataset (available at '<http://www.loni.ucla.edu/ADNI>'). Specifically, we considered the baseline MRI, 18-fluoro-deoxyglucose PET, and CerebroSpinalFluid (CSF) data acquired from 51 subjects with AD, 99 subjects with MCI (including 43 progressive MCI (pMCI) and 56 stable MCI (sMCI))<sup>1</sup>, and 52 Healthy normal Controls (HC). Along with the neuroimaging and biological data, two types of clinical scores, Mini-Mental State Examination (MMSE) and Alzheimer's Disease Assessment Scale-Cognitive subscale (ADAS-Cog), were also provided for each subject.

We built one SAE model<sup>2</sup> per modality and concatenated the original Low-Level Features (LLF) and the SAE-learned Features (SAEF) to construct an augmented feature vector (LLF+SAEF), which thus includes both low-level and high-level information. To fuse the complementary information from multiple modalities, we used a multi-kernel Support Vector Machine (SVM) [27], preceded by feature selection with a sparse regression method [33]. We considered three binary classification problems: AD vs. HC, MCI vs. HC, and pMCI vs. sMCI. In the classification of MCI vs. HC, both pMCI and sMCI data were used as the MCI class. Due to a limited small number of training samples, we applied a 10-fold cross validation technique.

We summarized the classification accuracies in Table 14.1. In AD vs. HC, compared to the accuracy of 0.970 with an LLF-based method, the proposed method improved the accuracy by 0.009. In the classification of MCI and HC, the

<sup>1</sup>In our work, 'progressive' and 'stable' denote whether the subjects with MCI progressed to AD in 18 months.

<sup>2</sup>The number of hidden units were manually determined proportional to the input dimension. As for the sparsity target and the weighting parameter of the sparsity penalty in Eq. (14.1), we set to  $\rho = 0.05$  and  $\gamma = 0.01$ .

**Table 14.1** Performance comparison in an ROI-based feature representation. As for statistical significance, a paired  $t$ -test was performed (LLF: Low-Level Features; SAEF: SAE-learned Feature representations; pMCI: progressive MCI; sMCI: stable MCI)

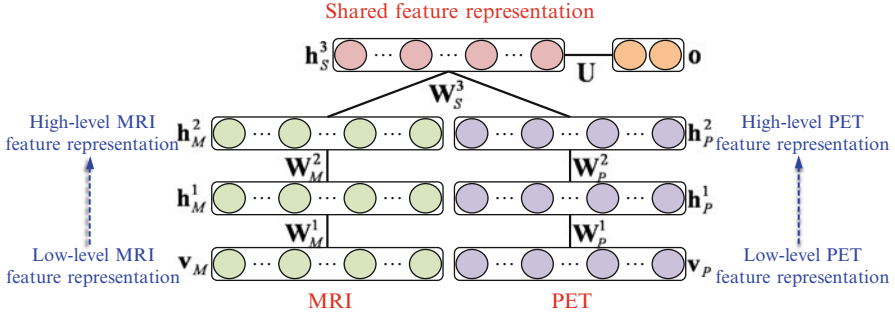
Method	AD/HC	MCI/HC	pMCI/sMCI
LLF	0.970 $\pm$ 0.010	0.848 $\pm$ 0.014	0.760 $\pm$ 0.020
LLF+SAEF	<b>0.979<math>\pm</math>0.007</b>	<b>0.888<math>\pm</math>0.012</b>	<b>0.779<math>\pm</math>0.027</b>
$p$ -value	0.0432	2.2693e-06	0.0904

proposed method showed the best classification accuracy of 0.888. The performance improvement compared to the classification accuracy of 0.848 with the LLF-based method was 0.04. In discriminating pMCI from sMCI, our method also outperformed the LLF-based method. While the LLF-based method showed the classification accuracy of 0.760, our method achieved the classification accuracy of 0.779. Based on these results, we argue that the SAE-based feature representation helped enhance the diagnostic accuracies, justifying the importance of using high-level information latent in the observation.

### 14.3.2 Deep Boltzmann Machine (DBM)

While an ROI-based approach helps alleviate the high-dimensionality problem in neuroimaging pattern analysis, it fails to handle subtle changes within an ROI or across ROIs. In this regard, Liu et al. proposed a patch-based approach that can efficiently handle both the high-dimensionality problem and subtle changes in an image and gradually integrated a number of local patches of a Gray Matter (GM) density map hierarchically [15]. Although they showed the efficacy of their method for AD/MCI diagnosis, it is well known that the structural or functional images are susceptible to acquisition noise, intensity inhomogeneity, artifacts, etc. Furthermore, the raw voxel density or intensity values in a patch can be considered as low-level features that do not efficiently capture more informative high-level features. To this end, we proposed a deep learning-based high-level structural and functional feature representation from MRI and PET, respectively, for AD/MCI classification. Furthermore, for multiple modalities fusion, unlike the existing methods that first extracted features from each modality independently and then mostly combined heterogeneous features via either simple feature concatenation or kernel machines, we designed a multi-modal deep learning architecture using DBM.

A DBM is structured by stacking multiple Restricted Boltzmann Machines (RBMs) in a hierarchical manner. The rationale of using DBM for feature representation is as follows: It can learn the internal latent representations that capture non-linear complicated patterns and/or statistical relations in a hierarchical manner [3, 16]. However, unlike many other deep network models such as deep belief network [8] and SAE [26], the approximate inference procedure after the initial bottom-up



**Fig. 14.3** Multimodal deep Boltzmann machine that integrates the structural and functional information and finds the shared feature representations

pass incorporates top-down feedback, which allows DBM to use higher-level knowledge to resolve uncertainty about intermediate-level features, thus creating better data-dependent representations and statistics [22]. Thanks to this two-way dependencies, i.e., bottom-up and top-down, it was shown that DBMs achieved the state-of-the-art performance in computer vision [21, 28]. To this end, we used a DBM to discover hierarchical feature representations from neuroimaging in our work.

Regarding multiple modalities fusion, different modalities will have different statistical properties. Thus, simple concatenation of the features of multiple modalities in a shallow architecture can cause strong connections among the variables of an individual modality, but failed to find inter-modality relations [19]. In order to tackle this problem, we devised a discriminative Multi-Modal DBM (MM-DBM), in which the top hidden layer had multiple entries of the lower hidden layers and the label layer, to extract a shared feature representation by fusing neuroimaging information of MRI and PET. Figure 14.3 presents a network of our MM-DBM, where one pathway represents the statistical properties of MRI and the other pathway represents those of PET, and the top shared hidden layer finally discovers the shared properties of the modalities in a supervised manner. The joint distribution over the multimodal inputs of MRI ( $\mathbf{v}_M$ ) and PET ( $\mathbf{v}_P$ ) and the output label ( $\mathbf{o}$ ) can be estimated as follows:

$$P(\mathbf{v}_M, \mathbf{v}_P, \mathbf{o}; \Theta) = \sum_{\mathbf{h}_M^2, \mathbf{h}_P^2, \mathbf{h}_S^3} P(\mathbf{h}_M^2, \mathbf{h}_P^2, \mathbf{h}_S^3, \mathbf{o}) \left( \sum_{\mathbf{h}_M^1} P(\mathbf{v}_M, \mathbf{h}_M^1, \mathbf{h}_M^2) \right) \left( \sum_{\mathbf{h}_P^1} P(\mathbf{v}_P, \mathbf{h}_P^1, \mathbf{h}_P^2) \right) \quad (14.2)$$

where  $\Theta = \{\mathbf{W}_M^1, \mathbf{W}_M^2, \mathbf{W}_P^1, \mathbf{W}_P^2, \mathbf{W}_S^3, \mathbf{U}\}$ ,  $\mathbf{h}$  denotes a hidden layer, the subscripts  $M$ ,  $P$ , and  $S$  denote, respectively, units of the MRI path, the PET path, and the shared hidden layer. For the parameters learning, we performed two consecutive steps: (1)

**Table 14.2** Performance comparison in a patch-based feature representation (pMCI: progressive MCI, sMCI: stable MCI)

Method	AD/HC	MCI/HC	pMCI/sMCI
Intensity [15]	0.903±0.070	0.839±0.006	0.733±0.125
MM-DBM	<b>0.954±0.052</b>	<b>0.857±0.052</b>	<b>0.759±0.154</b>

a greedy layer-wise pre-training for a good initial setup of the model parameters and (2) iterative alternation of variational mean-field approximation to estimate the posterior probabilities of hidden units and stochastic approximation to update model parameters [22].

**14.3.2.1 Experiments and Performance Comparison**

We used the baseline MRI and PET data of the ADNI dataset: 93 subjects with AD, 204 subjects with MCI including 76 pMCI and 128 sMCI, and 101 HC. After conducting the preprocessing of anterior commissure-posterior commissure correction, skull stripping, cerebellum removal, registration to a common space, and tissue segmentation, we obtained spatially normalized GM volumes (i.e., GM tissue densities) and the PET images rigidly aligned to the corresponding MR images. For computational efficiency, we further down-sampled images to  $64 \times 64 \times 64$  voxels. As for a patch size, we set it to  $11 \times 11 \times 11$  by following Liu et al.’s work [15] for fair comparison, and thus the input dimension of each modality patch in our MM-DBM was 1,331.

We applied a 10-fold cross validation technique. The outputs of the top shared layer were used as features, which represent the fused information of structural and functional images. In order to combine the distributed patch information over an image and to build an image-level classifier, we used a hierarchical classifier learning scheme, described in [15]. In our work, we used a linear SVM for classification.

As presented in Table 14.2, in the classification of AD and HC, our method showed the mean accuracy of 0.954. Compared to the intensity-based method [15] that showed the accuracy of 0.903, we improved by 0.051. In the discrimination of MCI from HC, the proposed method achieved the accuracy of 0.857. Meanwhile, the intensity-based method [15] achieved the accuracies of 0.839. Again, the proposed method outperformed the competing method by making performance improvements of 0.018. In the classification between pMCI and sMCI, which is the most important for early diagnosis and treatment, the intensity-based method achieved the accuracy of 0.733. Compared to this result, our method improved the accuracy by 0.026. Concisely, in our three binary classifications, based on the classification accuracy, our deep learning-based method clearly outperformed the competing method.



## 14.4 Discussions and Conclusions

We applied deep learning methods for high-level feature representations and validated their efficacy by showing their superiority to the competing methods in terms of the diagnostic performance. Specifically, in Sect. 14.3.1, we applied an SAE to discover latent relations among the ROI-based features and then combined multiple modalities via kernel machine. Although the SAE model can be considered as the conventional multi-layer neural network, by initializing our model parameters with a greedy layer-wise pre-training and then fine-tuning the whole model, we could learn parameters to represent the inherent information better. Meanwhile, in Sect. 14.3.2, we devised a systematic method for a joint feature representation with an MM-DBM. Unlike the SAE model that learns parameters in a top-down manner, the DBM finds the optimal parameters in a bi-directional (i.e., bottom-up and top-down) manner. We utilized this favorable characteristic and successfully applied to find the shared representation from MRI and PET.

However, from a neurophysiological perspective, it is still very hard or impossible to interpret the learned representations and to understand the trained model parameters. In other words, there is no general or intuitive way to interpret the latent feature representations or the trained models. The problem of effective interpretation of the latent feature representations is a big challenge that should be tackled by the communities of machine learning and clinical neuroscience collaboratively. Furthermore, to our best knowledge, the existing disease diagnosis systems including ours output simply the clinical status of a testing subject, e.g., AD, MCI, or HC, with no presentation of the basis that supports their decision. In other words, when a subject is identified by a diagnosis system as a patient with either AD or MCI, it is clinically important to present its basis for the decision, e.g., structurally abnormal brain regions or abnormal functional connectivities observed in the neuroimaging data. Thus, all these would be our forthcoming research issues.

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