Masih Haseli

Curriculum Vitae

Department of Computing and Mathematical Sciences California Institute of Technology		□ mhaseli@caltech.edu □ mhaseli.github.id	
RESEARCH	• Dynamical Systems and Control Theory		
	• Operator Theoretic Approaches in Dynamical Systems		
	Machine Learning		
	• Robotics		
Employment	Postdoctoral Scholar Research Associate Department of Computing and Mathematical Sciences California Institute of Technology Advisor: Prof. Joel W. Burdick	Jul. 2025 - present	t
	Postdoctoral Scholar Department of Mechanical and Aerospace Engineering University of California, San Diego Advisor: Prof. Jorge Cortés	Sep. 2022 - Jun. 2025	5
EDUCATION	Ph.D. in Engineering Sciences (Mechanical Engineering) University of California, San Diego Advisor: Prof. Jorge Cortés	Sep. 2017 - Aug. 2022	2
	M.Sc. in Electrical Engineering – Control Amirkabir University of Technology, Tehran	Sep. 2013 - Oct. 2015	5
	B.Sc. in Electrical Engineering – Control Amirkabir University of Technology, Tehran	Sep. 2009 - Sep. 2013	3
Honors & Awards	• Robert Skelton Systems and Control Dissertation Award UCSD Center for Control Systems and Dynamics	2023	3
	• Best Student Paper Award The 2021 American Control Conference, New Orleans, Louisiana	2021	1
	• Bronze Medal Iran's National Mathematics Competition	2014	1
	• Silver Medal Iran's National Physics Olympiad	2008	3

(J1) Modeling nonlinear control systems via Koopman control family: universal forms and

Publications Journal Articles

subspace invariance proximity

M. Haseli, J. Cortés Automatica, *To appear* (J2) Two roads to Koopman operator theory for control: infinite input sequences and operator families

M. Haseli, I. Mezić, J. Cortés

IEEE Transactions on Automatic Control, submitted

(J3) Koopman operators in robot learning

L. Shi, M. Haseli, G. Mamakoukas, D. Bruder, I. Abraham, T. Murphey, J. Cortés, K. Karydis

IEEE Transactions on Robotics, submitted

(J4) Recursive forward-backward EDMD: guaranteed algebraic search for Koopman invariant subspaces

M. Haseli, J. Cortés

IEEE Access 13 (2025), 61006-61025

(J5) Invariance proximity: closed-form error bounds for finite-dimensional Koopman-based models

M. Haseli, J. Cortés

Systems and Control Letters, submitted

(J6) Generalizing dynamic mode decomposition: balancing accuracy and expressiveness in Koopman approximations

M. Haseli, J. Cortés

Automatica 153 (2023), 111001

(J7) Temporal forward-backward consistency, not residual error, measures the prediction accuracy of extended dynamic mode decomposition

M. Haseli, J. Cortés

IEEE Control Systems Letters 7 (2023), 649-654

(J8) Parallel learning of Koopman eigenfunctions and invariant subspaces for accurate long-term prediction

M. Haseli, J. Cortés

IEEE Transactions on Control of Network Systems 8 (4) (2021), 1833-18458

(J9) Learning Koopman eigenfunctions and invariant subspaces from data: Symmetric Subspace Decomposition

M. Haseli, J. Cortés

IEEE Transactions on Automatic Control 67 (7) (2022), 3442-3457

Conference Proceedings

(C1) Koopman operator extensions for control: bridging infinite input sequences and operator families

M. Haseli, I. Mezić, J. Cortés

Proceedings of the IEEE Conference on Decision and Control, Rio de Janeiro, Brazil, 2025, to appear

(C2) Real-time learning of predictive dynamic obstacle models for robotic motion planning S. B. Kombo, M. Haseli, J. W. Burdick Proceedings of the IEEE International Conference on Robotics and Automation, 2026, submitted

(C3) Temporal forward-backward consistency, not residual error, measures the prediction accuracy of extended dynamic mode decomposition

M. Haseli, J. Cortés

Proceedings of the American Control Conference, San Diego, 2023

(C5) Data-driven approximation of Koopman-invariant subspaces with tunable accuracy M. Haseli, J. Cortés

Proceedings of the American Control Conference, New Orleans, Louisiana, 2021, pp.

Best Student Paper Award Winner

(C6) Fast identification of Koopman-invariant subspaces: parallel symmetric subspace decomposition

M. Haseli, J. Cortés

Proceedings of the American Control Conference, Denver, Colorado, 2020, pp. 4545-4550

(C7) Efficient identification of linear evolutions in nonlinear vector fields: Koopman invariant subspaces

M. Haseli, J. Cortés

Proceedings of the IEEE Conference on Decision and Control, Nice, France, 2019, pp. 1746-1751

(C8) Approximating the Koopman operator using noisy data: noise-resilient extended dynamic mode decomposition

M. Haseli, J. Cortés

Proceedings of the American Control Conference, Philadelphia, PA, 2019, pp. 5499-5504

Spring 2021

Teaching EXPERIENCE

• Nonlinear Control (UCSD MAE 281B) Graduate Teaching Assistant

Instructor: Prof. Jorge Cortés

INVITED Talks

- SIAM Conference on Applications of Dynamical Systems, Denver, Colorado May 2025 Talk Title: Koopman Control Family and Universal Finite-Dimensional Forms
- U.S. Association for Computational Mechanics, Student Chapter Seminars Mar. 2024 Online: YouTube
- Jan. 2024 • Safe Autonomous Systems Lab Seminars Department of Mechanical and Aerospace Engineering, University of California, San Diego
- Scalable Optimization and Control Lab Seminars Sep. 2023 Department of Electrical and Computer Engineering, University of California, San Diego
- 2022 International Symposium on Nonlinear Theory and Its Applications Dec. 2022
- Data-Driven Reduced-Order Methods for System Control Mini-symposium Sep. 2021 Mechanistic Machine Learning and Digital Twins for Computational Science, Engineering & Technology Conference
- 37th Southern California Control Workshop, University of California, San Diego Jan. 2020

SERVICE

PROFESSIONAL Reviewer for: Automatica, IEEE Open Journal of Control Systems, IEEE Access, IEEE Control Systems Letters, Physica D: Nonlinear Phenomena, Journal of Dynamic Systems Measurement & Control, IEEE Conference on Decision and Control (CDC), American Control Conference (ACC), International Symposium on Mathematical Theory of Networks and Systems (MTNS), Resilience Week Symposium, Indian Control Conference, IFAC World Congress, International Conference on Robotics and Automation (ICRA), The Journal of Supercomputing, Mathematics of Control, Signals, and Systems