## **Active-capture** $v_{\rm C} \approx v_{\rm R}$ Searching $v_c >> 0$ Handling Time h Detection Pursuit, Attack, Capture, Subjugation, Ingestion $v_{\rm R} >> 0$ Sit-and-wait Grazing $\nu_{\rm C} >> \nu_{\rm R}$ $v_c << v_p$ $v_{\rm c} >> 0$

