## Matthew Hausknecht

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(512) 767-2465

https://mhauskn.github.io/

RESEARCH FOCUS Development of autonomous systems capable of adapting and learning in complex en-

vironments.

CITIZENSHIP USA

EMPLOYMENT DataRobot 2025 - Present

Principal AI Scientist responsible for directing DataRobot's research team.

Latitude AI / Argo AI 2022 - 2025

Staff Scientist improving the autonomy of self-driving vehicles.

Microsoft Research 2017 - 2022

Redmond, WA

Senior Researcher and founder of the reinforcement learning group.

EDUCATION The University of Texas at Austin, Austin, TX 2009 - 2016

Ph.D., Department of Computer Sciences

Advised by Peter Stone

Thesis: Cooperation and communication in multiagent deep reinforcement learning

Emory University, Atlanta, GA 2005 - 2009

B.S. Computer Science, Summa Cum Laude

Advised by Li Xiong, Eugene Agichtein, and Phillip Wolff

PUBLICATIONS syftr: Pareto-Optimal Generative AI

Alexander Conway, Debadeepta Dey, Stefan Hackmann, Matthew Hausknecht, Michael

Schmidt, Mark Steadman, Nick Volynets

International Conference on Automated Machine Learning (AutoML) 2025

Uni[Mask]: Unified Inference in Sequential Decision Problems

M Carroll, O Paradise, J Lin, R Georgescu, M Sun, D Bignell, S Milani, K Hofmann,

M Hausknecht, A Dragan, S Devlin

Conference on Neural Information Processing Systems (NeurIPS Oral) 2022

MoCapAct: A Multi-Task Dataset for Simulated Humanoid Control

N Wagener, A Kolobov, F Frujeri, R Loynd, C Cheng, M Hausknecht

Conference on Neural Information Processing Systems: Datasets and Benchmarks Track (NeurIPS) 2022

Reading and Acting while Blindfolded: The Need for Semantics in Text Game Agents S Yao, K Narasimhan, M Hausknecht

Annual Conference of the North American Chapter of the Association for Computational Linguistics (NAACL) 2021

ALFWorld: Aligning Text and Embodied Environments for Interactive Learning

| M Shridhar, X Yuan, M Côté, Y Bisk, A Trischler, M Hausknecht<br>International Conference on Learning Representations (ICLR) 2021  |  |  |
|--|--|--|
| Keep CALM and Explore: Language Models for Action Generation in Text-based Games S Yao, R Rao, M Hausknecht, K Narasimhan  |  |  |
| Empirical Methods in Natural Language Processing (EMNLP) 2020  |  |  |
| Working Memory Graphs R Loynd, R Fernandez, A Celikyilmaz, A Swaminathan, M Hausknecht International Conference on Machine Learning (ICML)   |  |  |
| Learning Calibratable Policies using Programmatic Style-Consistency E Zhan, A Tseng, Y Yue, A Swaminathan, M Hausknecht International Conference on Machine Learning (ICML)  |  |  |
| Graph constrained reinforcement learning for natural language action spaces P Ammanabrolu, M Hausknecht International Conference on Learning Representations (ICLR)  |  |  |
| Interactive Fiction Games: A Colossal Adventure  MJ Hausknecht, P Ammanabrolu, MA Côté, X Yuan  Association for the Advancement of Artificial Intelligence (AAAI)  |  |  |
| Scriptnet: Neural static analysis for malicious javascript detection JW Stokes, R Agrawal, G McDonald, M Hausknecht IEEE Military Communications Conference (MILCOM)   |  |  |
| Nail: A general interactive fiction agent  M Hausknecht, R Loynd, G Yang, A Swaminathan, JD Williams  Technical Report   |  |  |
| Counting to Explore and Generalize in Text-based Games 2018<br>Xingdi Yuan, Marc-Alexandre Côté, Alessandro Sordoni, Romain Laroche, Remi Tachet<br>des Combes, Matthew Hausknecht, Adam Trischler<br>European Workshop on Reinforcement Learning (EWRL)                                   |  |  |
| TextWorld: A Learning Environment for Text-based Games 2018<br>Marc-Alexandre Côté, Ákos Kádár, Xingdi Yuan, Ben Kybartas, Tavian Barnes, Emery<br>Fine, James Moore, Matthew Hausknecht, Layla El Asri, Mahmoud Adada, Wendy Tay,<br>Adam Trischler<br>IJCAI/ICML Computer Games Workshop |  |  |
| Leveraging grammar and reinforcement learning for neural program synthesis 2018 Rudy Bunel, Matthew Hausknecht, Jacob Devlin, Rishabh Singh, Pushmeet Kohli International Conference on Learning Representations (ICLR)  |  |  |
| Revisiting the arcade learning environment: Evaluation protocols and open problems for general agents  2017  MC Machado, MG Bellemare, E Talvitie, J Veness, M Hausknecht, Michael Bowling  International Joint Conferences on Artificial Intelligence (IJCAI)                             |  |  |

Neural Program Meta-Induction J Devlin, RR Bunel, R Singh, M Hausknecht, P Kohli Advances in Neural Information Processing Systems (NIPS)

International Joint Conferences on Artificial Intelligence (IJCAI)

2017

| Matthew Hausknecht  Ph.D. Thesis  | 2017           |
|---|----------------|
| Half field offense: An environment for multiagent learning and ad hoc teamwork Matthew Hausknecht, P Mupparaju, S Subramanian, S Kalyanakrishnan, P Ston AAMAS Adaptive Learning Agents (ALA) Workshop        |                |
| On-policy vs. off-policy updates for deep reinforcement learning Matthew Hausknecht, Peter Stone  Deep Reinforcement Learning: Frontiers and Challenges, IJCAI 2016 Workshop                                  | 2016           |
| Deep Reinforcement Learning in Parameterized Action Space<br>Matthew Hausknecht, Peter Stone<br>Proceedings of the International Conference on Learning Representations (ICLR)                                | 2016           |
| Machine Learning Capabilities of a Simulated Cerebellum<br>Matthew Hausknecht, Wen-Ke Li, Michael Mauk, and Peter Stone<br>IEEE Transactions on Neural Networks and Learning Systems                          | 2016           |
| Deep Recurrent Q-Learning for Partially Observable MDPs<br>Matthew Hausknecht, Peter Stone<br>AAAI Fall Symposium on Sequential Decision Making for Intelligent Agents  | 2015           |
| Beyond Short Snippets: Deep Networks for Video Classification<br>Joe Yue-Hei Ng, Matthew Hausknecht, Sudheendra Vijayanarasimhan, Oriol Vir<br>Rajat Monga, George Toderici<br>CVPR 2015                      | 2015<br>nyals, |
| A Neuroevolution Approach to General Atari Game Playing<br>Matthew Hausknecht, Joel Lehman, Risto Miikkulainen, and Peter Stone<br>IEEE Transactions on Computational Intelligence and AI in Games            | 2013           |
| Using a million cell simulation of the cerebellum: Network scaling and task generality Wen-Ke Li, Matthew J. Hausknecht, Peter Stone, and Michael D. Mauk Neural Networks                                     | 2012           |
| HyperNEAT-GGP: A HyperNEAT-based Atari General Game Player<br>Matthew Hausknecht, Piyush Khandelwal, Risto Miikkulainen, and Peter Stone<br>Proceedings of Genetic and Evolutionary Computation Conference    | 2012           |
| Dynamic Lane Reversal in Traffic Management<br>Matthew Hausknecht, Tsz-Chiu Au, Peter Stone, David Fajardo, and Travis Wall<br>Proceedings of IEEE Intelligent Transportation Systems Conference              | 2011<br>ler    |
| Autonomous Intersection Management: Multi-Intersection Optimization Matthew Hausknecht, Tsz-Chiu Au, and Peter Stone  Proceedings of IROS 2011-IEEE/RSJ International Conference on Intelligent Early Systems | 2011<br>Robots |
| Vision Calibration and Processing on a Humanoid Soccer Robot  | 2010           |

Piyush Khandelwal, Matthew Hausknecht, Juhyun Lee, Aibo Tian and Peter Stone

Fifth Workshop on Humanoid Soccer Robots

Learning Powerful Kicks on the Aibo ERS-7: The Quest for a Striker.

Hausknecht, M. and Stone, P.

Proceedings of the RoboCup International Symposium

For want of a nail: How absences cause events. 2009

2010

Wolff, P., Barbey, A., Hausknecht, M.

Journal of Experimental Psychology: General

Heuristic Based Extraction of Causal Relations from Annotated Causal 2009

Cue Phrases Hausknecht, M.

 $Undergraduate\ Dissertation$ 

Additional

EXPERIENCE Google Research 2014

Intern

Developed recurrent neural network architectures for large scale video classification.

University of Texas at Austin

Teaching Assistant Discrete Math for Computer Science: Honors Fall 2013

**Emory University** 

Teaching Assistant Introduction to Computer Science Fall 2007

OPEN SOURCE SOFTWARE Jericho (Python, C) - A lightweight python-based interface connecting learning agents with interactive fiction games. Additional text-based reinforcement agent implementations using Pytorch.

Half-field Offense (Python, C++) - Simulator to interface learning agents with the RoboCup 2D soccer simulator. Continuous action agent implementation using Caffe.

Arcade Learning Environment (Python, C++) - Created the first interfaces which allowed external agents to use ALE as a library. Additionally investigated the first uses of recurrent networks for deep reinforcement learning.

Languages Python, C/C++, Pytorch

Honors & Phi Kappa Phi, 2010

AWARDS NSF Graduate Research Fellowship, 2009

MCD Fellowship, The University of Texas at Austin, 2009

Trevor Evans Award, Emory University, 2009 Dean's List, Emory University, 2005-2008

Phi Beta Kappa, 2007