

## Matthew Hausknecht

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| CONTACT        | <a href="mailto:matthew.hausknecht@gmail.com">matthew.hausknecht@gmail.com</a><br><a href="https://mhauskn.github.io/">https://mhauskn.github.io/</a>   | (512) 703-0857 |
| RESEARCH FOCUS | I work at the intersection of Deep Learning and Reinforcement Learning to develop autonomy capable of adapting and learning in complex environments.  |                |
| CITIZENSHIP    | USA   |                |
| EMPLOYMENT     | <b>Argo AI</b><br><i>Staff Scientist</i> improving autonomy of self-driving vehicles.   | 2022           |
|                | <b>Microsoft Research</b><br>Redmond, WA<br><i>Senior Researcher</i> and founder of the reinforcement learning group.   | 2017 - 2022    |
|                | <b>Google</b><br><i>Research Intern</i><br>Developed recurrent deep neural network architectures for large scale video classification. Advised by George Toderici.  | 2014           |
| EDUCATION      | <b>The University of Texas at Austin</b> , Austin, TX<br><i>Ph.D., Department of Computer Sciences</i><br>Advised by Peter Stone<br>Thesis: <i>Cooperation and communication in multiagent deep reinforcement learning</i>                                      | 2009 - 2016    |
|                | <b>Emory University</b> , Atlanta, GA<br><i>B.S. Computer Science, Summa Cum Laude</i><br>Advised by Li Xiong, Eugene Agichtein, and Phillip Wolff  | 2005 - 2009    |
| PUBLICATIONS   | Uni[Mask]: Unified Inference in Sequential Decision Problems<br>M Carroll, O Paradise, J Lin, R Georgescu, M Sun, D Bignell, S Milani, K Hofmann, M Hausknecht, A Dragan, S Devlin<br><i>Conference on Neural Information Processing Systems (NeurIPS Oral)</i> | 2022           |
|                | MoCapAct: A Multi-Task Dataset for Simulated Humanoid Control<br>N Wagener, A Kolobov, F Frujeri, R Loynd, C Cheng, M Hausknecht<br><i>Conference on Neural Information Processing Systems: Datasets and Benchmarks Track (NeurIPS)</i>                         | 2022           |
|                | Reading and Acting while Blindfolded: The Need for Semantics in Text Game Agents<br>S Yao, K Narasimhan, M Hausknecht<br><i>Annual Conference of the North American Chapter of the Association for Computational Linguistics (NAACL)</i>                        | 2021           |
|                | ALFWorld: Aligning Text and Embodied Environments for Interactive Learning<br>M Shridhar, X Yuan, M Côté, Y Bisk, A Trischler, M Hausknecht<br><i>International Conference on Learning Representations (ICLR)</i>   | 2021           |

Keep CALM and Explore: Language Models for Action Generation in Text-based Games  
S Yao, R Rao, M Hausknecht, K Narasimhan  
*Empirical Methods in Natural Language Processing (EMNLP)* 2020

Working Memory Graphs 2020  
R Loynd, R Fernandez, A Celikyilmaz, A Swaminathan, M Hausknecht  
*International Conference on Machine Learning (ICML)*

Learning Calibratable Policies using Programmatic Style-Consistency 2020  
E Zhan, A Tseng, Y Yue, A Swaminathan, M Hausknecht  
*International Conference on Machine Learning (ICML)*

Graph constrained reinforcement learning for natural language action spaces 2020  
P Ammanabrolu, M Hausknecht  
*International Conference on Learning Representations (ICLR)*

Interactive Fiction Games: A Colossal Adventure 2020  
MJ Hausknecht, P Ammanabrolu, MA Côté, X Yuan  
*Association for the Advancement of Artificial Intelligence (AAAI)*

Scriptnet: Neural static analysis for malicious javascript detection 2019  
JW Stokes, R Agrawal, G McDonald, M Hausknecht  
*IEEE Military Communications Conference (MILCOM)*

Nail: A general interactive fiction agent 2018  
M Hausknecht, R Loynd, G Yang, A Swaminathan, JD Williams  
*Technical Report*

Counting to Explore and Generalize in Text-based Games 2018  
Xingdi Yuan, Marc-Alexandre Côté, Alessandro Sordoni, Romain Laroché, Remi Tachet des Combes, Matthew Hausknecht, Adam Trischler  
*European Workshop on Reinforcement Learning (EWRL)*

TextWorld: A Learning Environment for Text-based Games 2018  
Marc-Alexandre Côté, Ákos Kádár, Xingdi Yuan, Ben Kybartas, Tavian Barnes, Emery Fine, James Moore, Matthew Hausknecht, Layla El Asri, Mahmoud Adada, Wendy Tay, Adam Trischler  
*IJCAI/ICML Computer Games Workshop*

Leveraging grammar and reinforcement learning for neural program synthesis 2018  
Rudy Bunel, Matthew Hausknecht, Jacob Devlin, Rishabh Singh, Pushmeet Kohli  
*International Conference on Learning Representations (ICLR)*

Revisiting the arcade learning environment: Evaluation protocols and open problems for general agents 2017  
MC Machado, MG Bellemare, E Talvitie, J Veness, M Hausknecht, Michael Bowling  
*International Joint Conferences on Artificial Intelligence (IJCAI)*

Neural Program Meta-Induction 2017  
J Devlin, RR Bunel, R Singh, M Hausknecht, P Kohli  
*Advances in Neural Information Processing Systems (NIPS)*

Cooperation and communication in multiagent deep reinforcement learning 2017  
Matthew Hausknecht

*Ph.D. Thesis*

- Half field offense: An environment for multiagent learning and ad hoc teamwork 2016  
Matthew Hausknecht, P Mupparaju, S Subramanian, S Kalyanakrishnan, P Stone  
*AAMAS Adaptive Learning Agents (ALA) Workshop*
- On-policy vs. off-policy updates for deep reinforcement learning 2016  
Matthew Hausknecht, Peter Stone  
*Deep Reinforcement Learning: Frontiers and Challenges, IJCAI 2016 Workshop*
- Deep Reinforcement Learning in Parameterized Action Space 2016  
Matthew Hausknecht, Peter Stone  
*Proceedings of the International Conference on Learning Representations (ICLR)*
- Machine Learning Capabilities of a Simulated Cerebellum 2016  
Matthew Hausknecht, Wen-Ke Li, Michael Mauk, and Peter Stone  
*IEEE Transactions on Neural Networks and Learning Systems*
- Deep Recurrent Q-Learning for Partially Observable MDPs 2015  
Matthew Hausknecht, Peter Stone  
*AAAI Fall Symposium on Sequential Decision Making for Intelligent Agents*
- Beyond Short Snippets: Deep Networks for Video Classification 2015  
Joe Yue-Hei Ng, Matthew Hausknecht, Sudheendra Vijayanarasimhan, Oriol Vinyals, Rajat Monga, George Toderici  
*CVPR 2015*
- A Neuroevolution Approach to General Atari Game Playing 2013  
Matthew Hausknecht, Joel Lehman, Risto Miikkulainen, and Peter Stone  
*IEEE Transactions on Computational Intelligence and AI in Games*
- Using a million cell simulation of the cerebellum: Network scaling and task generality 2012  
Wen-Ke Li, Matthew J. Hausknecht, Peter Stone, and Michael D. Mauk  
*Neural Networks*
- HyperNEAT-GGP: A HyperNEAT-based Atari General Game Player 2012  
Matthew Hausknecht, Piyush Khandelwal, Risto Miikkulainen, and Peter Stone  
*Proceedings of Genetic and Evolutionary Computation Conference*
- Dynamic Lane Reversal in Traffic Management 2011  
Matthew Hausknecht, Tsz-Chiu Au, Peter Stone, David Fajardo, and Travis Waller  
*Proceedings of IEEE Intelligent Transportation Systems Conference*
- Autonomous Intersection Management: Multi-Intersection Optimization 2011  
Matthew Hausknecht, Tsz-Chiu Au, and Peter Stone  
*Proceedings of IROS 2011-IEEE/RSJ International Conference on Intelligent Robots and Systems*
- Vision Calibration and Processing on a Humanoid Soccer Robot 2010  
Piyush Khandelwal, Matthew Hausknecht, Juhyun Lee, Aibo Tian and Peter Stone  
*Fifth Workshop on Humanoid Soccer Robots*
- Learning Powerful Kicks on the Aibo ERS-7: The Quest for a Striker. 2010

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|--------------------------|---|-----------|
|                          | Hausknecht, M. and Stone, P.<br><i>Proceedings of the RoboCup International Symposium</i>   |           |
|                          | For want of a nail: How absences cause events.<br>Wolff, P., Barbey, A., Hausknecht, M.<br><i>Journal of Experimental Psychology: General</i>   | 2009      |
|                          | Heuristic Based Extraction of Causal Relations from Annotated Causal<br>Cue Phrases<br>Hausknecht, M.<br><i>Undergraduate Dissertation</i>  | 2009      |
| ADDITIONAL<br>EXPERIENCE | <b>University of Texas at Austin</b><br><i>Teaching Assistant</i> Discrete Math for Computer Science: Honors  | Fall 2013 |
|                          | <b>Emory University</b><br><i>Teaching Assistant</i> Introduction to Computer Science   | Fall 2007 |
| OPEN SOURCE<br>SOFTWARE  | <a href="#">Jericho</a> (Python, C) - A lightweight python-based interface connecting learning agents with interactive fiction games. Additional text-based reinforcement <a href="#">agent implementations</a> using Pytorch.<br><br><a href="#">Half-field Offense</a> (Python, C++) - Simulator to interface learning agents with the RoboCup 2D soccer simulator. Continuous action <a href="#">agent implementation</a> using Caffe.<br><br><a href="#">Arcade Learning Environment</a> (Python, C++) - Created the first interfaces which allowed external agents to use ALE as a library. Additionally investigated the first uses of <a href="#">recurrent networks for deep reinforcement learning</a> . |           |
| LANGUAGES                | Python, C/C++, Pytorch  |           |
| HONORS &<br>AWARDS       | Phi Kappa Phi, 2010<br>NSF Graduate Research Fellowship, 2009<br>MCD Fellowship, The University of Texas at Austin, 2009<br>Trevor Evans Award, Emory University, 2009<br>Dean's List, Emory University, 2005-2008<br>Phi Beta Kappa, 2007  |           |