

# Problem 1

$$P \propto H^a Q^b W^c \rightarrow P = K H^a Q^b W^c$$

$$ML^2T^{-3} = K (L)^a (L^3T^{-1})^b (ML^{-2}T^{-2})^c$$

$$M: 1 = c$$

$$L: 2 = a + 3b - 2c \rightarrow 4 = a + 3b$$

$$T: -3 = -b - 2c \rightarrow b = 1$$

$$\therefore a = 1$$

$$\therefore P = K H Q W$$

# Problem 2

$H \rightarrow$  Geometric Property

$V \rightarrow$  Kinematic property

$\rho \rightarrow$  dynamic property

$$\pi_1 = H^{a_1} V^{b_1} \rho^{c_1} D$$

$$\pi_2 = H^{a_2} V^{b_2} \rho^{c_2} \mu$$

$$\pi_3 = H^{a_3} V^{b_3} \rho^{c_3} g$$

For  $\pi_1$ :

$$1 = (L)^{a_1} (LT^{-1})^{b_1} (ML^{-3})^{c_1} L$$

$$L: 0 = a_1 + b_1 - 3c_1 + 1$$

$$M: 0 = c_1$$

$$T: 0 = -b_1$$

$$\therefore a_1 = -1$$

$$\therefore \pi_1 = \frac{D}{H}$$

## Problem 2 cont.

For  $\pi_2$ :

$$1 = (L)^{a_2} (LT^{-1})^{b_2} (ML^{-3})^{c_2} (ML^{-1}T^{-1})$$

$$L: 0 = a_2 + b_2 - 3c_2 - 1$$

$$M: 0 = c_2 + 1 \rightarrow c_2 = -1$$

$$T: 0 = -b_2 - 1 \rightarrow b_2 = -1$$

$$\therefore a_2 = -1$$

$$\therefore \pi_2 = \frac{\mu}{H V \phi}$$

For  $\pi_3$ :

$$1 = (L)^{a_3} (LT^{-1})^{b_3} (ML^{-3})^{c_3} (LT^2)$$

$$M: 0 = c_3$$

$$T: 0 = -b_3 - 2 \rightarrow b_3 = -2$$

$$L: 0 = a_3 + b_3 - 3c_3 + 1 \rightarrow a_3 = 1$$

$$\therefore \pi_3 = \frac{g H}{V^2}$$

$$\therefore \phi = f(\pi_1, \pi_2, \pi_3)$$

$$\therefore \phi = f\left(\frac{D}{H}, \frac{\mu}{g V H}, \frac{g H}{V^2}\right)$$

$$V = \sqrt{g H} \phi\left[\frac{D}{H}, \frac{\mu}{g V H}\right]$$

## Problem 3

$D \rightarrow$  geometric property

$V \rightarrow$  kinematic property

$\rho \rightarrow$  dynamic property

$$\pi_1 = D^{a_1} V^{b_1} \rho^{c_1} \Delta P, \quad \pi_2 = D^{a_2} V^{b_2} \rho^{c_2} L$$

$$\pi_3 = D^{a_3} V^{b_3} \rho^{c_3} m, \quad \pi_4 = D^{a_4} V^{b_4} \rho^{c_4} K$$

For  $\pi_1$ :

$$1 = (L)^{a_1} (LT^{-1})^{b_1} (ML^{-3})^{c_1} (ML^{-1}T^{-2})$$

$$M: 0 = c_1 + 1 \rightarrow c_1 = -1$$

$$T: 0 = -b_1 - 2 \rightarrow b_1 = -2$$

$$L: 0 = a_1 + b_1 - 3c_1 - 1 \rightarrow a_1 = 0$$

$$\therefore \pi_1 = \frac{\Delta P}{V^2 \rho}$$

For  $\pi_2$ :

$$1 = (L)^{a_2} (LT^{-1})^{b_2} (ML^{-3})^{c_2} L$$

$$M: 0 = c_2$$

$$T: 0 = -b_2 \rightarrow b_2 = 0$$

$$L: 0 = a_2 + b_2 - 3c_2 + 1 \rightarrow a_2 = -1$$

$$\therefore \pi_2 = \frac{L}{D}$$

## Problem 3 Cont.

For  $\pi_3$ .

$$1 = (L)^{a_3} (LT^{-1})^{b_3} (ML^{-3})^{c_3} (ML^{-4}T^{-1})$$

$$M: 0 = c_3 + 1 \rightarrow c_3 = -1$$

$$T: 0 = -b_3 - 1 \rightarrow b_3 = -1$$

$$L: 0 = a_3 + b_3 - 3c_3 - 1 \rightarrow a_3 = -1$$

$$\therefore \pi_3 = \frac{\mu}{\rho V D}$$

For  $\pi_4$ :

$$1 = (L)^{a_4} (LT^{-1})^{b_4} (ML^{-3})^{c_4} L$$

(as solved in  $\pi_2$ )

$$a_4 = -1, b_4 = c_4 = 0$$

$$\therefore \pi_4 = \frac{k}{D}$$

$$0 = F(\pi_1, \pi_2, \pi_3, \pi_4)$$

$$\therefore 0 = F\left(\frac{\Delta P}{\rho V^2}, \frac{L}{D}, \frac{\mu}{\rho V D}, \frac{k}{D}\right)$$

$$\therefore \frac{\Delta P}{\rho V^2} = \phi\left(\frac{L}{D}, Re, \frac{k}{D}\right) \text{ where } Re = \frac{\rho V D}{\mu}$$

$$\therefore \Delta P = \rho V^2 \phi\left(\frac{L}{D}, Re, \frac{k}{D}\right)$$

## Problem 4

Prototype:  $D_p = 1.5 \text{ m}$ 

$$\mu_p = 3 \times 10^{-2} \text{ Poise}$$

(specific gravity)  $\rho = 0.9$ 

$$Q_p = 3.0 \text{ m}^3/\text{s}$$

Model:

$$D_m = 0.15 \text{ m}$$

$$\mu_m = 0.01 \text{ Poise}$$

$$(\text{sg})_m = 1$$

$$V_p = \frac{Q_p}{A_p} = \frac{4 Q_p}{\pi D_p^2} = \frac{4 \times 3}{\pi (1.5)^2} \approx 1.698 \text{ m/s}$$

By equating Reynolds numbers

$$Re_m = Re_p$$

$$V_m = \frac{\rho_p}{\rho_m} \frac{D_p}{D_m} \frac{\mu_m}{\mu_p} V_p = 0.9 \times 10 \times 0.3 \times 1.698 \approx 5.093 \text{ m/s}$$

$$Q_m = A_m V_m = \frac{1}{4} \pi D_m^2 V_m \approx 0.09 \text{ m}^3/\text{s} \\ = 90 \text{ Liters/s}$$

Problem 5

$$\lambda = \frac{L_m}{L_p} = \frac{1}{40}$$

By equating Froude number

$$\frac{V_m}{\sqrt{g L_m}} = \frac{V_p}{\sqrt{g L_p}} \rightarrow V_p = \sqrt{\frac{L_p}{L_m}} V_m$$

$$= \sqrt{40} \times 2 \text{ m/s}$$

$$\approx 12.65 \text{ m/s}$$

$$\frac{Q_p}{Q_m} = \frac{A_p V_p}{A_m V_m} = (\lambda)^{-2} (\lambda)^{-\frac{1}{2}} = \lambda^{-\frac{5}{2}}$$

$$\therefore Q_p = \lambda^{-\frac{5}{2}} Q_m = 40^{\frac{5}{2}} \times 2.5 \text{ m}^3/\text{s} \approx 25298 \text{ m}^3/\text{s}$$

## Problem 6

$$\lambda = \frac{L_m}{L_p} = \frac{1}{20}$$

$$\frac{H_p}{H_m} = \frac{1}{\lambda} \rightarrow H_p = \frac{1}{\lambda} H_m = 20 \times 0.2 \text{ m} = 4 \text{ m}$$

Since  $\frac{Q_p}{Q_m} = \left(\frac{1}{\lambda}\right)^{\frac{5}{2}}$  as calculated P5

$$\frac{E_p}{E_m} = \frac{\rho g Q_p H_p}{\rho g Q_m H_m} = \frac{Q_p H_p}{Q_m H_m} = \left(\frac{1}{\lambda}\right)^{\frac{7}{2}}$$

$$\therefore E_p = 20^{\frac{7}{2}} \times \frac{1}{10} \text{ kW} = 3578 \text{ kW}$$