

## Programming Problems

- 2.24 In Section 2.3, we described a program that copies the contents of one file to a destination file. This program works by first prompting the user for the name of the source and destination files. Write this program using either the POSIX or Windows API. Be sure to include all necessary error checking, including ensuring that the source file exists.

Once you have correctly designed and tested the program, if you used a system that supports it, run the program using a utility that traces system calls. Linux systems provide the `strace` utility, and macOS systems use the `dtruss` command. (The `dtruss` command, which actually is a front end to `dtrace`, requires admin privileges, so it must be run using `sudo`.) These tools can be used as follows (assume that the name of the executable file is `FileCopy`):

**Linux:**

```
strace ./FileCopy
```

**macOS:**

```
sudo dtruss ./FileCopy
```

Since Windows systems do not provide such a tool, you will have to trace through the Windows version of this program using a debugger.

## Programming Projects

### Introduction to Linux Kernel Modules

In this project, you will learn how to create a kernel module and load it into the Linux kernel. You will then modify the kernel module so that it creates an entry in the `/proc` file system. The project can be completed using the Linux virtual machine that is available with this text. Although you may use any text editor to write these C programs, you will have to use the *terminal* application to compile the programs, and you will have to enter commands on the command line to manage the modules in the kernel.

As you'll discover, the advantage of developing kernel modules is that it is a relatively easy method of interacting with the kernel, thus allowing you to write programs that directly invoke kernel functions. It is important for you to keep in mind that you are indeed writing *kernel code* that directly interacts with the kernel. That normally means that any errors in the code could crash the system! However, since you will be using a virtual machine, any failures will at worst only require rebooting the system.

## I. Kernel Modules Overview

The first part of this project involves following a series of steps for creating and inserting a module into the Linux kernel.

You can list all kernel modules that are currently loaded by entering the command

```
lsmod
```

This command will list the current kernel modules in three columns: name, size, and where the module is being used.

---

```
#include <linux/init.h>
#include <linux/kernel.h>
#include <linux/module.h>

/* This function is called when the module is loaded. */
int simple_init(void)
{
    printk(KERN_INFO "Loading Kernel Module\n");

    return 0;
}

/* This function is called when the module is removed. */
void simple_exit(void)
{
    printk(KERN_INFO "Removing Kernel Module\n");
}

/* Macros for registering module entry and exit points. */
module_init(simple_init);
module_exit(simple_exit);

MODULE_LICENSE("GPL");
MODULE_DESCRIPTION("Simple Module");
MODULE_AUTHOR("SGG");
```

---

**Figure 2.21** Kernel module `simple.c`.

The program in Figure 2.21 (named `simple.c` and available with the source code for this text) illustrates a very basic kernel module that prints appropriate messages when it is loaded and unloaded.

The function `simple_init()` is the **module entry point**, which represents the function that is invoked when the module is loaded into the kernel. Similarly, the `simple_exit()` function is the **module exit point**—the function that is called when the module is removed from the kernel.

The module entry point function must return an integer value, with 0 representing success and any other value representing failure. The module exit point function returns void. Neither the module entry point nor the module exit point is passed any parameters. The two following macros are used for registering the module entry and exit points with the kernel:

```
module_init(simple_init)
```

```
module_exit(simple_exit)
```

Notice in the figure how the module entry and exit point functions make calls to the `printk()` function. `printk()` is the kernel equivalent of `printf()`, but its output is sent to a kernel log buffer whose contents can be read by the `dmesg` command. One difference between `printf()` and `printk()` is that `printk()` allows us to specify a priority flag, whose values are given in the `<linux/printk.h>` include file. In this instance, the priority is `KERN_INFO`, which is defined as an *informational* message.

The final lines—`MODULE_LICENSE()`, `MODULE_DESCRIPTION()`, and `MODULE_AUTHOR()`—represent details regarding the software license, description of the module, and author. For our purposes, we do not require this information, but we include it because it is standard practice in developing kernel modules.

This kernel module `simple.c` is compiled using the Makefile accompanying the source code with this project. To compile the module, enter the following on the command line:

```
make
```

The compilation produces several files. The file `simple.ko` represents the compiled kernel module. The following step illustrates inserting this module into the Linux kernel.

## II. Loading and Removing Kernel Modules

Kernel modules are loaded using the `insmod` command, which is run as follows:

```
sudo insmod simple.ko
```

To check whether the module has loaded, enter the `lsmod` command and search for the module `simple`. Recall that the module entry point is invoked when the module is inserted into the kernel. To check the contents of this message in the kernel log buffer, enter the command

```
dmesg
```

You should see the message "Loading Module."

Removing the kernel module involves invoking the `rmmod` command (notice that the `.ko` suffix is unnecessary):

```
sudo rmmod simple
```

Be sure to check with the `dmesg` command to ensure the module has been removed.

Because the kernel log buffer can fill up quickly, it often makes sense to clear the buffer periodically. This can be accomplished as follows:

```
sudo dmesg -c
```

Proceed through the steps described above to create the kernel module and to load and unload the module. Be sure to check the contents of the kernel log buffer using `dmesg` to ensure that you have followed the steps properly.

As kernel modules are running within the kernel, it is possible to obtain values and call functions that are available only in the kernel and not to regular user applications. For example, the Linux include file `<linux/hash.h>` defines several hashing functions for use within the kernel. This file also defines the constant value `GOLDEN_RATIO_PRIME` (which is defined as an unsigned long). This value can be printed out as follows:

```
printk(KERN_INFO "%lu\n", GOLDEN_RATIO_PRIME);
```

As another example, the include file `<linux/gcd.h>` defines the following function

```
unsigned long gcd(unsigned long a, unsigned b);
```

which returns the greatest common divisor of the parameters `a` and `b`.

Once you are able to correctly load and unload your module, complete the following additional steps:

1. Print out the value of `GOLDEN_RATIO_PRIME` in the `simple_init()` function.
2. Print out the greatest common divisor of 3,300 and 24 in the `simple_exit()` function.

As compiler errors are not often helpful when performing kernel development, it is important to compile your program often by running `make` regularly. Be sure to load and remove the kernel module and check the kernel log buffer using `dmesg` to ensure that your changes to `simple.c` are working properly.

In Section 1.4.3, we described the role of the timer as well as the timer interrupt handler. In Linux, the rate at which the timer ticks (the [tick rate](#)) is the value `HZ` defined in `<asm/param.h>`. The value of `HZ` determines the frequency of the timer interrupt, and its value varies by machine type and architecture. For example, if the value of `HZ` is 100, a timer interrupt occurs 100 times per second, or every 10 milliseconds. Additionally, the kernel keeps track of the global variable `jiffies`, which maintains the number of timer interrupts that have occurred since the system was booted. The `jiffies` variable is declared in the file `<linux/jiffies.h>`.

1. Print out the values of `jiffies` and `HZ` in the `simple_init()` function.
2. Print out the value of `jiffies` in the `simple_exit()` function.

Before proceeding to the next set of exercises, consider how you can use the different values of jiffies in `simple_init()` and `simple_exit()` to determine the number of seconds that have elapsed since the time the kernel module was loaded and then removed.

### III. The /proc File System

The /proc file system is a “pseudo” file system that exists only in kernel memory and is used primarily for querying various kernel and per-process statistics.

---

```
#include <linux/init.h>
#include <linux/kernel.h>
#include <linux/module.h>
#include <linux/proc_fs.h>
#include <asm/uaccess.h>

#define BUFFER_SIZE 128
#define PROC_NAME "hello"

ssize_t proc_read(struct file *file, char __user *usr_buf,
    size_t count, loff_t *pos);

static struct file_operations proc_ops = {
    .owner = THIS_MODULE,
    .read = proc_read,
};

/* This function is called when the module is loaded. */
int proc_init(void)
{
    /* creates the /proc/hello entry */
    proc_create(PROC_NAME, 0666, NULL, &proc_ops);

    return 0;
}

/* This function is called when the module is removed. */
void proc_exit(void)
{
    /* removes the /proc/hello entry */
    remove_proc_entry(PROC_NAME, NULL);
}
```

---

**Figure 2.22** The /proc file-system kernel module, Part 1

This exercise involves designing kernel modules that create additional entries in the /proc file system involving both kernel statistics and information related

to specific processes. The entire program is included in Figure 2.22 and Figure 2.23.

We begin by describing how to create a new entry in the /proc file system. The following program example (named `hello.c` and available with the source code for this text) creates a /proc entry named /proc/hello. If a user enters the command

```
cat /proc/hello
```

the infamous Hello World message is returned.

---

```
/* This function is called each time /proc/hello is read */
ssize_t proc_read(struct file *file, char __user *usr_buf,
    size_t count, loff_t *pos)
{
    int rv = 0;
    char buffer[BUFFER_SIZE];
    static int completed = 0;

    if (completed) {
        completed = 0;
        return 0;
    }

    completed = 1;

    rv = sprintf(buffer, "Hello World\n");

    /* copies kernel space buffer to user space usr_buf */
    copy_to_user(usr_buf, buffer, rv);

    return rv;
}
module_init(proc_init);
module_exit(proc_exit);

MODULE_LICENSE("GPL");
MODULE_DESCRIPTION("Hello Module");
MODULE_AUTHOR("SGG");
```

---

**Figure 2.23** The /proc file system kernel module, Part 2

In the module entry point `proc_init()`, we create the new /proc/hello entry using the `proc_create()` function. This function is passed `proc_ops`, which contains a reference to a struct `file_operations`. This struct initial-

izes the `.owner` and `.read` members. The value of `.read` is the name of the function `proc_read()` that is to be called whenever `/proc/hello` is read.

Examining this `proc_read()` function, we see that the string "Hello World\n" is written to the variable `buffer` where `buffer` exists in kernel memory. Since `/proc/hello` can be accessed from user space, we must copy the contents of `buffer` to user space using the kernel function `copy_to_user()`. This function copies the contents of kernel memory `buffer` to the variable `usr_buf`, which exists in user space.

Each time the `/proc/hello` file is read, the `proc_read()` function is called repeatedly until it returns 0, so there must be logic to ensure that this function returns 0 once it has collected the data (in this case, the string "Hello World\n") that is to go into the corresponding `/proc/hello` file.

Finally, notice that the `/proc/hello` file is removed in the module exit point `proc_exit()` using the function `remove_proc_entry()`.

## IV. Assignment

This assignment will involve designing two kernel modules:

1. Design a kernel module that creates a `/proc` file named `/proc/jiffies` that reports the current value of `jiffies` when the `/proc/jiffies` file is read, such as with the command

```
cat /proc/jiffies
```

Be sure to remove `/proc/jiffies` when the module is removed.

2. Design a kernel module that creates a `proc` file named `/proc/seconds` that reports the number of elapsed seconds since the kernel module was loaded. This will involve using the value of `jiffies` as well as the HZ rate. When a user enters the command

```
cat /proc/seconds
```

your kernel module will report the number of seconds that have elapsed since the kernel module was first loaded. Be sure to remove `/proc/seconds` when the module is removed.