## Temperature-dependent viscosity

Common source of non-linearity is the variation of viscosity with temperature. Ice rheology is complex and depends on the microscopic deformation mechanism.

We consider "diffusion creep" which results in a Newtonian rheology.

$$\mu = \frac{R T d^2}{42 V_m D_{o,V}} exp\left(\frac{E_A}{R T}\right)$$

Parameters:  $d = grain diameter \sim 1 mm$  T = temperature  $V_m = molar volume 1.97 \cdot 10^{-5} \frac{m^3}{mol}$   $D_{0,V} = vol. diff. constant 9.1 \cdot 10^{-4} \frac{m^3}{s}$   $E_A = vol. diff. act. energy 59.4 \frac{kJ}{mol}$   $R = mol. gas constant 8.314 \frac{J}{K mol}$ Newtonian because  $\mu \neq \mu(\underline{v})$ ?

But µ has Arrhenius dependence on T

The temperature - dependence of the preexponential factor is aften neglected.

$$\mu = \mu_0 \exp\left(\frac{E_A}{RT}\right)$$

$$\mu_0 = \frac{RT_m d^2}{42 V_m D_{0,V}}$$

Example problem: Couette flow with T gradient Bondary layer forms

at the hot top boundary

where shear is localized.

To The shear is localized.

In the absence of heating by viscous dissipation the T-field is independent of velocity ⇒ one-way coupling: v=v(T) but T≠T(v) Viscous energy dissiportion leads to two-way roupl.

## Energy balance equation

Assumptions:

$$\Rightarrow \nabla \cdot \left[ \underline{\nabla} - \alpha \nabla T \right] = 0 \qquad \alpha = \frac{\kappa}{\rho c_{p}} \text{ therm.}$$

5, 
$$\underline{V} = \begin{bmatrix} V(z) \\ 0 \end{bmatrix}$$
 and  $\underline{T} = \underline{T}(z) \Rightarrow \nabla \underline{T} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ 

$$\nabla \cdot [\underline{V}T] = \underline{V} \cdot \nabla \underline{T} + \underline{T} (\nabla \underline{V})$$

$$= [V(z) \ 0] [0] = \underline{0}$$

$$\Rightarrow \quad -\nabla \cdot \alpha \nabla T = 0 \quad \Rightarrow \quad \frac{d^2T}{dz^2} = 0$$

Temperature field: AT= TT-TB

Integrating twice: T=TB+ ATZ

Velocity & pressure fields:

$$-\nabla \cdot \left[\mu \left(\nabla y + \nabla \overline{y}\right)\right] + \nabla \pi = 0$$

$$\nabla \cdot v = 0$$

deviatoric stress in component form:

$$\underline{\underline{\Gamma}} = \mu \left( \nabla_{\underline{V}} + \nabla_{\underline{V}}^{\underline{T}} \right) = \mu \begin{bmatrix} 2 \vee_{x_1 x} & \vee_{x_1 z} + \vee_{z_1 x} \\ \vee_{x_1 z} + \vee_{z_1 x} & 2 \vee_{z_1 z} \end{bmatrix}$$

From flow geometry: 
$$V_z = 0 \Rightarrow V_{z,z} = V_{z,x} = 0$$

$$V_{x,x} = 0 \quad \text{(from continuity)}$$

$$\nabla \pi = \begin{pmatrix} \pi_{,z} \\ \pi_{,z} \end{pmatrix} = \begin{pmatrix} \pi_{,x} \\ 0 \end{pmatrix}$$

=> all terms in z-momentum balance vanish

$$-\frac{3z}{3}\left[\frac{3z}{4}\right] + \frac{3x}{3\pi} = 0$$
  $\lambda = \lambda^{x}$ 

In Couette example the domain is infinite in x-dir, so that  $\frac{211}{2x} = 0$ .

$$\frac{\partial}{\partial z} \left[ \mu(T(z)) \frac{\partial v}{\partial z} \right] = 0$$

$$V(0) = 0 \qquad V(H) = 0$$

Solve following ODE: 
$$\frac{\partial}{\partial z} \left[ \mu(T(z)) \frac{\partial v}{\partial z} \right] = 0$$

$$v(0) = 0 \quad v(H) = u$$

$$\mu = \mu_0 \exp\left(\frac{E_q}{RT}\right)$$

$$T = T_g + \frac{\Delta T}{H} z$$

$$\Delta T = T_T - T_g > 0$$

lutegrate once:

 $\mu \frac{\partial v}{\partial z} = c_1$  here  $c_1 = T = \text{shear stress}$ 

T = M 2 is definition of m?

Integrale once more:

$$V(Z) = T \int_{0}^{Z} \frac{dz}{\mu(T(z))}$$

$$V(z) = T \int_{0}^{z} \frac{dz}{\mu_{0} \exp\left(\frac{E_{0}}{RT(z)}\right)} = \frac{\Gamma}{\mu_{0}} \int_{0}^{z} \exp\left(\frac{-E_{0}/P}{T(z)}\right) dz$$

$$V(z) = \frac{\Gamma}{H_{\bullet}} \int_{0}^{z} \exp\left(\frac{-E_{a}/R}{T_{g} + \Delta Tz/H}\right) dz$$

difficult integral, but if AT & To the

exponential factor can be approximated as

$$\int_{\Gamma(z)}^{\infty} (z) = -\frac{E_{\alpha}}{RT_{B}} \frac{1}{1 + \frac{\Delta T}{T_{R}} \frac{z}{H}} = \frac{-a}{1 + bz'} \qquad z' = \frac{z}{H} \quad \alpha = \frac{E_{\alpha}}{RT_{B}} \quad b = \frac{\Delta T}{T_{B}}$$

Taylor series expansion at z'= 0

$$\mathcal{L}_{o}f(z) = f(o) + \frac{df}{dz} \cdot z' = -a + abz = -a(1-bz')$$

where 
$$\frac{df}{dz} = \frac{ab}{(1+bz')^2}$$
 so that we have

$$f(z) = -\frac{E_a}{RT_B} \frac{l}{1 + \frac{\Delta T}{T_R} \frac{z}{H}} \approx -\frac{E_a}{RT_B} \left(1 - \frac{\Delta T}{T_B} \frac{z}{H}\right)$$

$$V(z) = \frac{T}{\mu_0} \tilde{e}^{\alpha} \int_{-\infty}^{z} e^{\alpha b z'} dz$$

$$V(Z') = \frac{TH}{\mu_0} e^{-\alpha} \int_0^{z'} e^{abz'} dz'' = \frac{TH}{\mu_0} \frac{e^{-\alpha}}{ab} \left( e^{abz'} - e^c \right)$$

$$V(Z') = \frac{TH}{\mu_0} \frac{e^{-a}}{ab} \left( e^{abz'} - 1 \right)$$

1, Set relocity of top plake and find shew strew T 3 Set shear stress to and find velocity of top plate

$$V(z'=1) = u = \frac{TH}{\mu_0} \frac{e^{-a}}{ab} (e^{ab} - 1)$$
  
=>  $\tau = \frac{u\mu_0}{H} \frac{ab}{e^{-a}} \frac{1}{e^{ab}-1}$ 

substitute

$$\frac{V(z')}{U} = \frac{e^{ab}z'-1}{e^{ab}-1} \quad \text{where } a = \frac{E_a}{RT_B} \quad b = \frac{\Delta T}{T_B} \quad z' = \frac{Z}{H}$$
so that  $a \cdot b = \frac{E_a \Delta T}{RT_B^2}$ 

Hence the velocity profile is:

$$\frac{V(z')}{u} = \frac{\exp(\frac{E\Delta T}{RT_B^2} \frac{z}{H}) - 1}{\exp(\frac{E\Delta T}{RT_8}) - 1}$$

$$T = T_B + \frac{\Delta T}{H} z = T_B \left( 1 + \frac{\Delta T}{T_B} \frac{2}{H} \right) = T_B \left( 1 - \frac{T}{T_B} \right$$

corresponding viscosity
$$\mu = \mu_0 \exp\left(\frac{E_0}{RT}\right)$$

$$\frac{\mu}{\mu_0} = \exp\left(\frac{E_0}{RT_B} \frac{T_B}{T}\right) = \exp\left(\frac{E_0}{RT_B} \frac{1}{1-bz'}\right) = \exp\left(\frac{q}{1-bz'}\right)$$