Lecture 24: Power-law creep

Legistics: -

Last time: Newtonian fluids

= - b = + C D = - b = + sh =

stress-strain relation is liverer

 $b^{2} \cdot \bar{h} = 0$ $\Delta^{2} \cdot \bar{h} = 0$ $\Delta^{2} \cdot \bar{h} = 0$ $\Delta^{2} \cdot \bar{h} = 0$

Navier Stobes equations (non-linear)

 $Re = \frac{v_c x_c}{v}$ $D = \frac{H}{\rho}$

le «1 ⇒ Stolus equation

MZz v = - P+pb -> linear

Tooley: Nou live et constitutive laws

Power-law everp => ductile deformation

Power law kreep

Earth Science this most supostant

neu linear rheology.

Glacies, Earth mantle

6 = stress

€ = strain rate (d)

n = sters exponent

A= pre factor

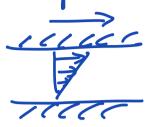
This is a scalar relation, but we need a tensor form.

=> Pheology of the earth, Ranalli

The tensor form can be established from labor a targ experiments.



Simple sheat



$$d = \dot{\xi} = \begin{bmatrix} 0 & \dot{\xi}_s & 0 \\ \dot{\xi}_s & 0 & \sigma \end{bmatrix}$$

Uniaxial compension

$$\mathcal{E} = \begin{bmatrix} \mathcal{E}_1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

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⇒ simple configurations with only I non-zero component in ⊆ and ¿

Suppose simple shear experiments lead to $\dot{\varepsilon}_s = A \, \delta_s^n$

A is function of T, P, material parameters. but hat n is combrant

Turn idro tensorial form

1) Exp. not affected by pressure

=> use deviatorie stress ¿ a strain rate ¿

2) France judifférent => use ju variants.

Consider Representation Theorem

$$\overset{\bullet}{\mathcal{E}} = \alpha_{0}(\mathbf{I}_{\delta'}) \overset{\bullet}{\mathbf{I}} + \alpha_{1}(\mathbf{I}_{\delta'}) \overset{\bullet}{\delta'} + \alpha_{2}(\mathbf{I}_{\delta'}) \overset{\bullet}{\delta'}^{2}$$
suppose $n = 2$

$$\overset{\bullet}{\mathcal{E}} = \alpha_{2}(\mathbf{I}_{\delta'}) \overset{\bullet}{\delta'}^{2} \qquad (\text{GeG}^{T}) = \text{GeG}^{T} \text{GeG}^{T} \text{GeG}^{T}$$

observe tions show (4n 45.

=> can't use & directly but power law i'ufo
has to ento a,

From lecture 3: Ireveriants

$$T_{1}(\underline{S}) = \lambda_{1} + \lambda_{2} + \lambda_{3} = \operatorname{tr}(\underline{S}) = S_{11} + S_{02} + S_{23}$$

$$T_{2}(\underline{S}) = \frac{1}{2} \left(\operatorname{tr}(\underline{S})^{2} - \operatorname{tr}(\underline{S}^{2}) \right) = \lambda_{1} \lambda_{2} + \lambda_{2} \lambda_{3} + \lambda_{1} \lambda_{3}$$
in terms of components

$$\begin{split} - & I_{2}(\underline{\varsigma}) = \begin{vmatrix} \delta_{11} & \delta_{12} \\ \delta_{21} & \delta_{22} \end{vmatrix} + \begin{vmatrix} \delta_{11} & \delta_{13} \\ \delta_{31} & \delta_{33} \end{vmatrix} + \begin{vmatrix} \delta_{22} & \delta_{23} \\ \delta_{32} & \delta_{23} \end{vmatrix} \\ & = & \delta_{11} & \delta_{22} - \delta_{12}^{2} + \delta_{11} & \delta_{33} - \delta_{13}^{2} + \delta_{22} & \delta_{33} - \delta_{23}^{2} \\ & I_{2}(\underline{\varsigma}) = - \left(\delta_{11} & \delta_{22} + \delta_{11} & \delta_{33} + \delta_{22} & \delta_{33} \right) + \delta_{12}^{2} + \delta_{23}^{2} + \delta_{13}^{2} \\ & I_{3}(\underline{\varsigma}) = & \text{def}(\underline{\varsigma}) = \lambda_{1} & \lambda_{2} & \lambda_{3} \end{split}$$

$$T_1 = 0$$
 because deviatin's tensors $T_3(\dot{\xi}) = \nabla_{x} \cdot v = 0$ (checked)

⇒ leaves Iz as only option

Inveriants of deviatoric stern:

$$I_{1}(\underline{s}') = J_{1}(\underline{s}) = 0 \qquad J_{1}(\underline{\dot{\epsilon}}) = 0 \qquad \text{deviatent}$$

$$I_{2}(\underline{\dot{s}}') = J_{2}(\underline{\dot{s}}) = \frac{1}{2} \underline{\dot{s}}' : \underline{\dot{s}}', \quad I_{2}(\underline{\dot{\epsilon}}) = J_{2}(\underline{\dot{\epsilon}}) = \frac{1}{2} \underline{\dot{s}}' : \underline{\dot{s}}'$$

To see this:

$$\begin{split} \overline{L}_{2}(\underline{s}') &= \delta_{12}^{2} + \delta_{18}^{2} + \delta_{28}^{2} \\ \underline{s}' : \underline{s}' &= \delta_{11}^{2} \delta_{12}^{2} + \delta_{13}^{2} + \delta_{13}^{2} + \delta_{23}^{2} + \delta_{21}^{2} + \delta_{31}^{2} + \delta_{32}^{2} \\ &= 2\left(\varepsilon_{12}^{2} + \varepsilon_{13}^{2} + \varepsilon_{23}^{2}\right) = 2 J_{2}(\underline{s}) \end{split}$$

We can define an effective stern & strain rate $\dot{\varepsilon}_{E} = \int_{\frac{1}{2}}^{1} \underline{\varepsilon}' \cdot \underline{\varepsilon}' \, dz = \dot{\varepsilon}_{E} = \dot{\varepsilon}_{E}^{2} = \int_{\frac{1}{2}}^{1} \underline{\varepsilon} \cdot \underline{\varepsilon}' \, dz$

power law in terms of effective quantities $\dot{s}_{E} = A \dot{\sigma}_{E}^{n}$

is in terms est invariants and bence objection To make this tensorial the Representation

The leaves us only one aption $\stackrel{\circ}{\underline{\mathcal{E}}} = \alpha_1(\mathbf{I}_{\mathbf{z}'}) \stackrel{\circ}{\underline{\mathcal{E}}} + \alpha_2(\mathbf{I}_{\mathbf{z}'}) \stackrel{\circ}{\underline{\mathcal{E}}}^2$

 \Rightarrow $\dot{e}_{\varepsilon} = \alpha_{\iota}(T_{\delta'}) \ \delta'_{\overline{\varepsilon}}$

combine and solve for a,

 $A s_{\varepsilon}^{n} = \alpha_{1}(T_{\delta'}) s_{\varepsilon}^{\prime}$ $\alpha_{1}(T_{\delta'}) = A s_{\varepsilon}^{n-1}$

Tensor form for power-law creep $\stackrel{\circ}{\underline{\epsilon}} = A \stackrel{\circ}{\underline{\sigma}}_{\underline{\epsilon}}^{(n-1)} \stackrel{\circ}{\underline{\underline{\sigma}}}_{\underline{\epsilon}}$

=> clearly frame invarient.

Example: Simple shect

$$\mathcal{E} = \begin{pmatrix} 0 & \mathbf{a} & \mathbf{c} \\ \mathbf{c} & \mathbf{c} & \mathbf{c} \end{pmatrix} \Rightarrow \mathbf{e}' \qquad \qquad \mathbf{e}' = \mathbf{e}'$$

$$\mathcal{E}' = \int \frac{1}{2} \mathbf{G}' \cdot \mathbf{G}' = \mathcal{E}_{S}$$
Subshiftuhe
$$\dot{\mathbf{E}} = A \mathcal{E}'_{S}^{n-1} \mathbf{G}' \Rightarrow \dot{\mathcal{E}}_{S} = A \mathcal{E}'_{S}^{(n-1)} \mathbf{E}_{S}$$

$$= A \mathcal{E}_{S}^{n-1} \mathbf{G}_{S}$$

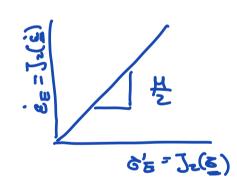
$$= A \mathcal{E}_{S}^{n-1} \mathbf{G}_{S}$$

Effective viscosity of powo low creep

Newtoniau:
$$\underline{\delta} = -p\underline{I} + 2\mu\underline{\hat{\epsilon}}$$

$$\underline{\delta}' = 2\mu\underline{\hat{\epsilon}}$$

$$\Rightarrow \mu = \frac{161}{2|\hat{\epsilon}|} = \frac{3\hat{\epsilon}}{2\hat{\epsilon}}$$



Nou-Newtouiau: $\underline{\sigma}' = \frac{1}{A} \overset{e}{\varepsilon}' \overset{e}{\varepsilon}$ $\overset{2}{\times} \overset{1-u}{\varepsilon} \overset{e}{\varepsilon}$ $\overset{2}{\times} \overset{1-u}{\varepsilon} \overset{e}{\varepsilon}$ $\overset{2}{\times} \overset{1-u}{\varepsilon} \overset{e}{\varepsilon}$ $\overset{2}{\times} \overset{1-u}{\varepsilon} \overset{e}{\varepsilon} \overset{1}{\times} \overset{1}{\varepsilon} \overset{1}{$

is function of stess level.