## Ax-matrices

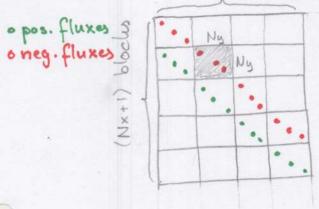
Ax computes Ny by (Nx+1) fluxes from Ny by Nx concentration



Nx columns of Ny concentration Nx+1 columns of Ny flaxos

Nx-blocks

Each block is Ny by Ny



Iy = speye (Ny);

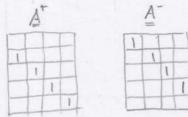
Positive fluxes are on -1 block diagonal

Axp1 = spoliags (ones (Nx,1),-1, Nx+1, Nx);

ID 1 matrix:

Axn1 = spaliags (ones(Nx,1),0, Nx+1, Nx);

1D matrios:

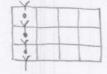


2D matrices:

Axp = kron (Axp1, Iy);

Axn = Krou(Axn1) Ty);

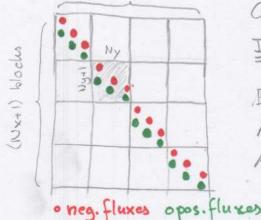
Ay compules Nx columns of Nytl fluxes from Nx columns of Ny concentrations



=> Ay is Nx by Nx block matrix

with blocks of size Ny+1 by Ny

Nx - blocks



Overall block structure Ix = speye (Nx);

Each block is 1D Hatix:

Axp1 = spoliags (onus (Ny,1),-1, Ny+1, Ny);

Axn1 = spaliags (onus (Ny, 1), 0, Ny+1, Ny);

Assemble 2D y-matrices: Ayp = kron(Ix, Ayp1);

Ayn = Krou(Ix, Ayn1);

Assemble overall 2D matrices:

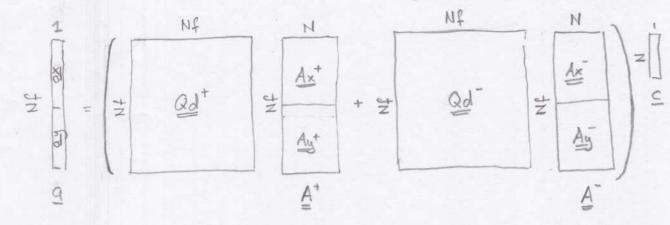
$$\Delta P = \begin{bmatrix} \Delta x P \\ \Delta y P \end{bmatrix}$$
  $\Delta n = \begin{bmatrix} \Delta x n \\ \Delta y n \end{bmatrix}$ 

## Kronecker product assembly of advection matrices

Problem: In D and G the matrix blocks are identical, but in A each block has same structure but values differ because 9's vary across the domain.

Solution: Separate the structure, ie. the 1's and 0's from the magnitudes.

The overall scheme for computing advective fluxes a:



Where we have following sparse matrices:

Qd = Nf by Nf matrix with positive fluxes on diagonal } magnitudes

Qd = Nf by Nf matrix with negative fluxes on diagonal } magnitudes

At = Nf by N matrix with ones in location of pos. fluxes } structure

At = Nf by N matrix with ones in location of neg. fluxes } structure

If flow is evolving only and and and must be updated?

Qdp = spoliags (max(9,0), 0, Nf, Nf);

Qdn = spoliags (min(9,0), 0, Nf, Nf);

So that: A(q) = Qdp(q) \* Ap + Qdn(q) \* An