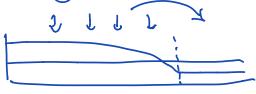
Lecture 24! Filling Craters

Logistics: - Course evaluation

- HU 9 poskel

- HWIB - steady un confined for

Last time: - Steady Ocean-GW coupling



-V.kh Th = gp + grup

=> intorshing BC: has Shotx

Today: Filling - eraters

transient

Filling Craters crater forms instantaneous half

Constraint that water volume is constant.

$$V = V_G + V_L = \phi \int_{h}^{e} h \, dx + w h_L \neq column for h_L = \frac{V}{w} - \frac{\phi}{w} \int_{h}^{e} h \, dx$$

Steady shahe head: h = h_ = h

$$V = \phi h_{\infty} l + \omega h_{\infty} = (\phi l + \omega) h_{\infty}$$

$$h_{\infty} = \frac{V}{\phi l + \omega} = \frac{\phi l h_{\infty}}{\phi l + \omega}$$

$$V = h_{\infty} l \phi$$

We have the following transient problem:

PDE:
$$\phi \frac{\partial h}{\partial t} - \nabla \cdot [Kh \nabla h] = 0$$
 $\times \in [0, 0]$

BC's:
$$q \cdot \hat{w}|_{o} = 0$$
 $h(l) = \frac{V}{\omega} - \frac{\Phi}{\omega} \int h dx$

IC:
$$h(x,t=0) = h_0$$

=> Coupled Dir BC is similar to the last problem

Non-dimensionalize

$$x' = \frac{x}{\ell}$$
 $h' = \frac{h}{h_0}$ $t' = \frac{t}{\ell_c}$

substitute into PDE:

$$\frac{\partial h_{\bullet}}{\partial t} = \frac{\partial h'_{\bullet}}{\partial t'} - \frac{Kh_{\bullet}^{2}}{\ell^{2}} \nabla \cdot h' \nabla h' = 0 \qquad \times \in [0, 1]$$

$$\frac{\partial h'_{\bullet}}{\partial t'} - \frac{Kh_{\bullet}t_{c}}{\ell^{2}} \nabla \cdot h' \nabla h' = 0 \qquad \Rightarrow t_{c} = \frac{p\ell^{2}}{Kh_{\bullet}}$$

substitute subs BC:

$$h'(1) = \frac{dl_{\infty}}{\omega} - \frac{d}{\omega} |_{\omega} l \int_{\omega} h' dx'$$

$$h'(1) = \frac{dl}{\omega} (1 - \int_{\omega} h' dx')$$

Dimensionless problem

PDE:
$$\frac{\partial h'}{\partial E'} - \nabla \cdot h' \nabla h' = 0$$
 $\times 6 [0, 1]$
BC's: $\frac{\partial h'}{\partial E'} = 0$ $\frac{1}{2} (1 - \frac{1}{2} h' dx')$

=> first solu steady problem from last time $-\nabla \cdot h' \nabla h' = Pr$ $q. \hat{u}|_{c} = 0 \qquad h'(1) = 1 + Ca(1-\int h' dx')$

Newton - Raphson with new BC $r(\underbrace{h}) = 1 + \frac{1}{ca} (1 - h \cdot \text{Grid.V}) - \underbrace{Bh}$ h_{Nx} $\frac{d}{dr} r_{Nx} (\widehat{h} + e \widehat{h}) \Big|_{E=0} = 1 + \underbrace{da}_{E=0} - \underbrace{da}_{E=0} (\underbrace{h} + e \widehat{h}) \cdot e \text{Grid.V} - \underbrace{B}_{f} \cdot \underbrace{h}_{f} + e \widehat{h})$ $= -\frac{1}{ca} \text{Grid.V} \cdot \widehat{h} - \underbrace{B}_{f} \cdot \widehat{h}$ $= -\left(\underbrace{d}_{f} \text{Grid.V} - \widehat{h}_{f}\right) \cdot \widehat{h}$ $= -\left(\underbrace{d}_{f} \text{Grid.V} - \widehat{h}_{f}\right) \cdot \widehat{h}$ $= -\left(\underbrace{d}_{f} \text{Grid.V} - \widehat{h}_{f}\right) \cdot \widehat{h}$