## Lecture 10: Cylindrical & spherical shell coords Logistics: - HW2 V - HW3 due Thursday ? - HW4 -> variable coefficients Last time: - Neumann BC's & fluxes - Example: Lineor steady confined aguist with precip a poler redurge - Neumann BC: In = 96 AN source/sink solve\_lbup(L, fs+fn, ... => = fs+fn=f - Fluxes: - q = - Kd xG xh interior qb=\rb)V/A / boundery => conserves mans exactly Today: - New coordinate systems

## Cylindrical coordinates

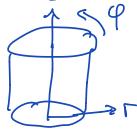
Problem with poles recharge Clifford 1993  $Q_i = 0.01 - 2.3 \text{ km}^3/\text{yr} \qquad \frac{L^3}{T}$   $Q_b = \frac{Q_b^2}{A} = 9i \frac{L^3}{2T} = \frac{L}{T} \qquad A = b W$ 



96 ~ T

=> only way to make @ information meaning[1]

1s to go. to cylindrical coordinates.

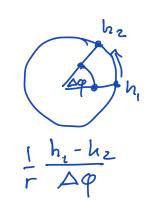


One of the reasons for  $\nabla$   $\nabla$  ·  $\nabla$  × notation

is that it hides the dimension and the coordinate system?

-Vo[K Vh] = fs

is true i'u avey dim. & coord. syst.



To maintain ID model we cersume

soluis const in 9 - diretion.

$$\nabla h = \frac{dh}{dx}$$

$$\nabla \cdot q = \frac{1}{x} \frac{d}{dx} (x q)$$

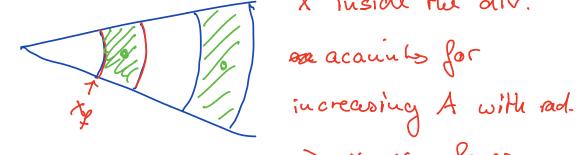
=> discrete gradient stays the same & modify discrete divergence D

Geometric interpretation of x=v terms

- (1) d (xb k dh) = fs

multiply by x

$$-\frac{d}{dx}\left(\frac{xb}{xb} \times \frac{dy}{dx}\right) = x fs$$



x inside the div.

=> x = xf faces

x autside divergence accounts for the increase ine cell volume as radius increase X = Xc cell centers.

>> Lhe Script

Exemple problem: Steady confined aguifo polet recharge in cylind. coord.

PDE:  $-\frac{1}{r} \frac{d}{dr} \left[ rbk \frac{dy}{dr} \right] = 0$   $r \in \left[ rp, R \right]$ BC:  $q_i = \frac{Q_i}{A} = -k \frac{dy}{dr} \Big|_{rp}$   $-\frac{dy}{dr} \Big|_{rp} = \frac{q_i}{K}$  dichoromy

Wen-dim.: 
$$\Gamma' = \frac{\Gamma}{\ell}$$
  $h' = \frac{h-ho}{h_c}$ 

subst:

PDE: 
$$-\frac{d}{dr'} \left[ \frac{dl'}{dr'} \right] = 0$$
  $r' \in [p, l] p = \frac{T_p}{dr'}$ 

BC:  $q' = -\frac{dl'}{dr'} |_p = 1$   $h'(l) = 0$ 

Aualytic solu: 
$$h' = -p \log(r')$$
  $h_c = \frac{qil}{k}$ 

$$q' = -\frac{dh'}{dr'} = \frac{p}{r'}$$

Dim: 
$$h = h_0 - \frac{qik}{k} \frac{r_p}{k} \left( \frac{r_p}{e} \right)$$

## Sperical shell coordinates

Steady confined aguifir with precipitation on a sphrical shell.

PDE: 
$$-\frac{1}{R \sin \theta} \frac{d}{d\theta} \left[ \sin \theta \right] = q_P \quad \text{on } \theta \in [0, \theta_b]$$

BC:  $q = -k \frac{dh}{d\theta} \left[ = 0 \quad h(\theta_b) = h_0 \right]$ 

## Dineusion les equations

What about 
$$\theta$$
?  $\theta = \frac{s}{r}$ 

$$\theta \in [0, \pi]$$



substitute

PPE: 
$$-\frac{1}{\sin\theta} \frac{d}{d\theta} \left[ \sin\theta \frac{db}{d\theta} \right] = \frac{9bR^2}{kbhc} = 1$$
  $h_e = \frac{9bR}{kb}$ 

$$BC: q' = -\frac{dh'}{dG} = 0 \quad h'(\theta_b) = 0$$

$$\sin\theta \frac{du'}{d\theta} = \cos\theta + c_1$$

Neumann B: C,=-1

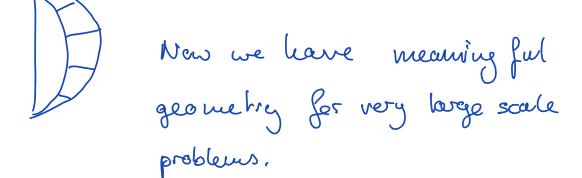
$$\left(\begin{array}{c} \frac{dh'}{d\theta} = \frac{\cos\theta}{\sin\theta} - \frac{1}{\sin\theta} = \cot\theta - \csc\theta \\ \frac{\sin\theta}{\sin\theta} = \frac{\cos\theta}{\sin\theta} = \frac{1}{\sin\theta} = \cot\theta - \cot\theta - \cot\theta \\ \frac{\sin\theta}{\sin\theta} = \frac{\cos\theta}{\sin\theta} = \frac{1}{\sin\theta} = \frac{1$$

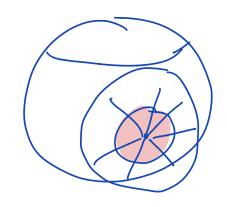
lutegrate: 
$$h' = \int \cot \theta - \cos \theta \, d\theta$$

$$= \log (\cos \theta + 1) + C_2$$
BC at  $\theta_p \Rightarrow c_2 = -\log (\cos \theta_b + 1)$ 

Analytic solution: 
$$h' = log \left( \frac{cos\theta + l}{cos\theta_b + l} \right)$$

$$q' = -\frac{dh'}{d\theta} = csc\theta - cot\theta$$





Sperical cap aroused helles besin to look at filling of belles.

Next steps:

Steady Lineer confined agnifit
spheroculap

transfeut (easig) challenging)