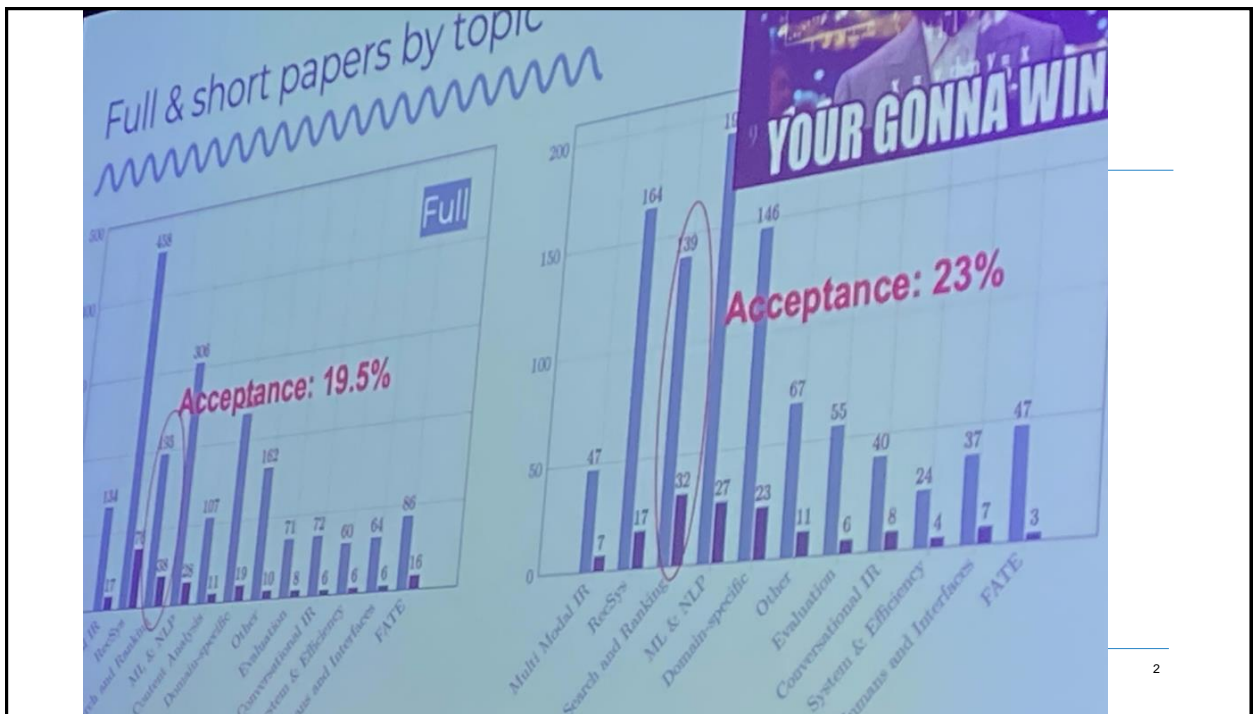


Graph 13. Graph-based Learning for Recommender Systems

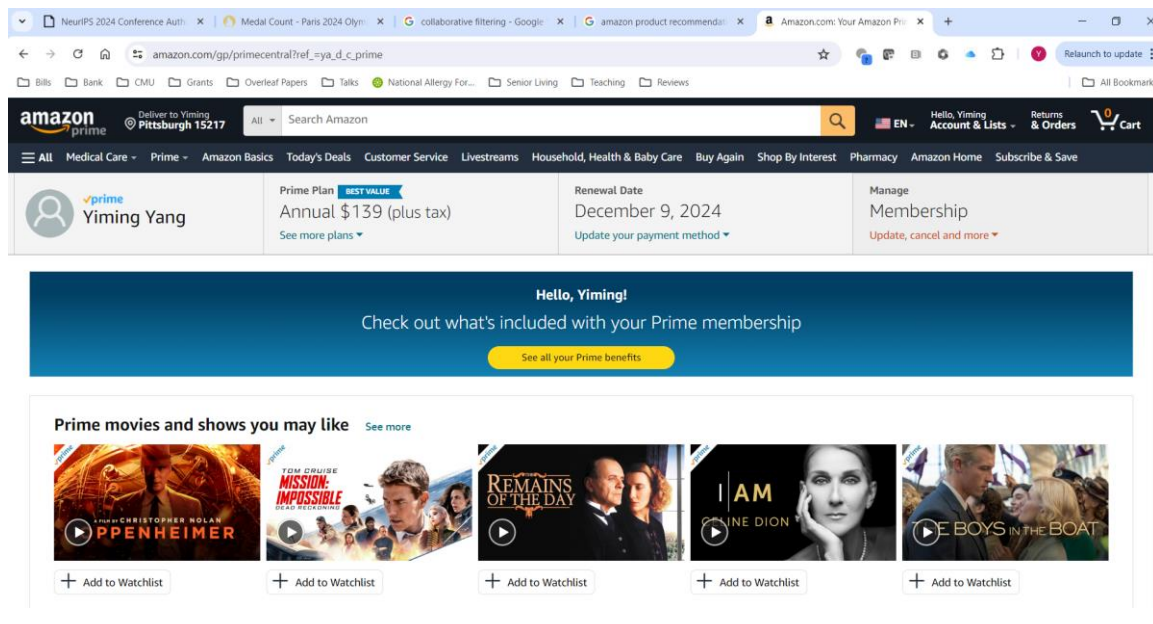
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Amazon Product Recommendation



3

Recommender Systems

■ Task

- Recommending items to each user based on the system-estimated relevance

■ Question

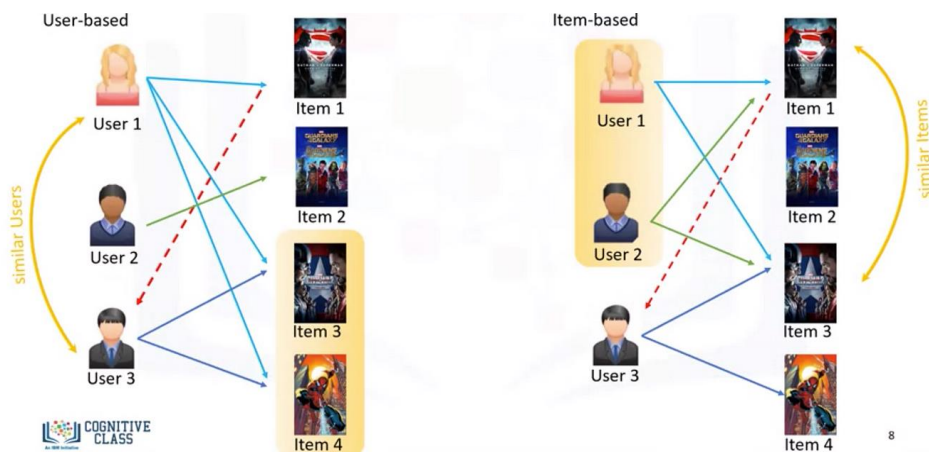
- How can the system predict the interests of each user over items?

■ Answers

- Based on the **user's query**, e.g., "recent Oscar winning movies" Content-based Retrieval
- Based on **her past records of users**, e.g., Tom Hank seems to be her favorite actor Collaborative filtering (CF)

4

Bipartite Graph with Users (Left) and Items (Right)



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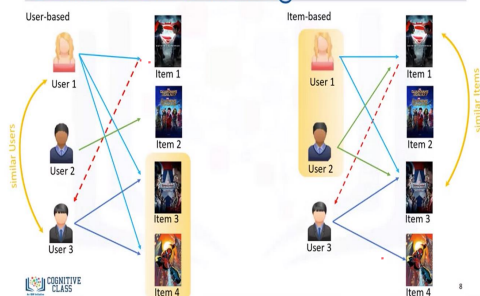
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CF with User-based or Item-based Reasoning

Collaborative filtering



- **Left (user-based):** "User1 and User3 have similar tastes" (as both like items 3 & 4) & "User1 likes Item1" → User3 also likes Item1 (red).
- **Right (item-based):** "Item3 and Item1 are similar" (as both are liked by user1) & "User3 likes Item3" → User3 also like Item1 (red).
- **Insight:** We need to measure the user-user or item-item similarity based on the bipartite graph.
- **Approach 1:** Using the adjacency matrix of the graph to compute the similarities (as **dot-product** or **cosine**).
- **Approach 2:** **Graph-based embedding** for both users and items, and then calculating their similarities (today's lecture)

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Representing CF Training Data

- Consider a matrix with n users as the rows and m items as the columns
 - "+" shows an observed user-item interaction;
 - "?" shows a cell with the missing value (to predict).
- Question:** How to deal with the missing values for training?
 - Naively, we can replace "+" by 1 and "?" by 0.
 - Then, the trained model tend to predict zero for each "?", which is **not what desirable!**

[the BPR paper by Rendle et al. in UAI 2009]

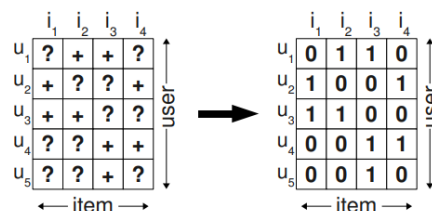


Figure 1: On the left side, the observed data S is shown. Learning directly from S is not feasible as only positive feedback is observed. Usually negative data is generated by filling the matrix with 0 values.

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Issue & Remedies

- Issue**
 - Replacing each "?" by "0" sends the wrong signal for training, i.e., it assumes each user does not want to watch any movie s/he has not watched yet.
- Remedies**
 - Imputation methods (replacing "?" by a neutral value or global average) (omitted today)
 - Bayesian Personalized Ranking (BPR) by Rendle et al. in UAI 2009
 - Neural Graph Collaborative Filtering (NGCF) by X Wang et al., SIGIR 2019

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BPR for Implicit CF (Rendle et al. in UAI 2009)

- **Construct a training set** with personalized preferences

$$D_S := \{(u, i, j) | i \in I_u^+ \wedge j \in I \setminus I_u^+\}$$

- Here I is the full set of items; $I_u^+ \subseteq I$ is the subset of items which user u has observed links;
- $I \setminus I_u^+$ is the complement set of items which user u are not linked to (i.e., the ones with “?”).

- **Bayesian Objective for Training**

$$\max_{\Theta} \sum_{(u,i,j) \in D_S} \{ \ln P(f_{\Theta}(u, i) > f_{\Theta}(u, j)) + \ln P(\Theta) \}$$

- Here Θ is the set of model parameters; $f_{\Theta}(\cdot, \cdot)$ is the system-learnt similarity function.
- The 1st term in the objective is used to reinforce pairwise preference over items for each user; the 2nd term is to impose a Bayesian-prior of the model parameters.

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How to model user preference over item pairs?

- **BPR-MF** as an example (and BPR-KNN as another example in the paper)

- Define $\Theta \in \mathbb{R}^{(n+m) \times d}$ as the embedding matrix (each row is the embedding of a user or item).
- Denote the embeddings of u, i and j by $e_u, e_i, e_j \in \mathbb{R}^d$, respectively.
- Define $f_{\Theta}(u, i) = \langle e_u, e_i \rangle$ as the choice of similarity function (other choices could be cosine, MLP or any kernel function).
- Estimate probabilities as

$$P(f_{\Theta}(u, i) > f_{\Theta}(u, j)) := \sigma(x_{uij}) := \frac{1}{1 + e^{-x_{uij}}}, \quad x_{uij} \triangleq \langle e_u, e_i \rangle - \langle e_u, e_j \rangle$$

$$\ln P(\Theta) = \lambda \|\Theta\|^2 \quad \text{under the assumption } \Theta \sim N(0, \lambda I)$$

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BPR-MF vs. SVD (as a baseline)

■ BPR

- Using the ?-marked cells (right) to formulate personalized preferences

■ SVD

- Treating all the ?'s as the same value of 0
- Overfitting the matrix after unreasonable imputation

[from the BPR paper by Rendle et al. in UAI 2009]

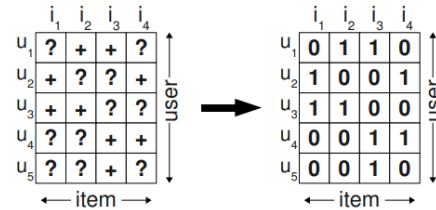


Figure 1: On the left side, the observed data S is shown. Learning directly from S is not feasible as only positive feedback is observed. Usually negative data is generated by filling the matrix with 0 values.

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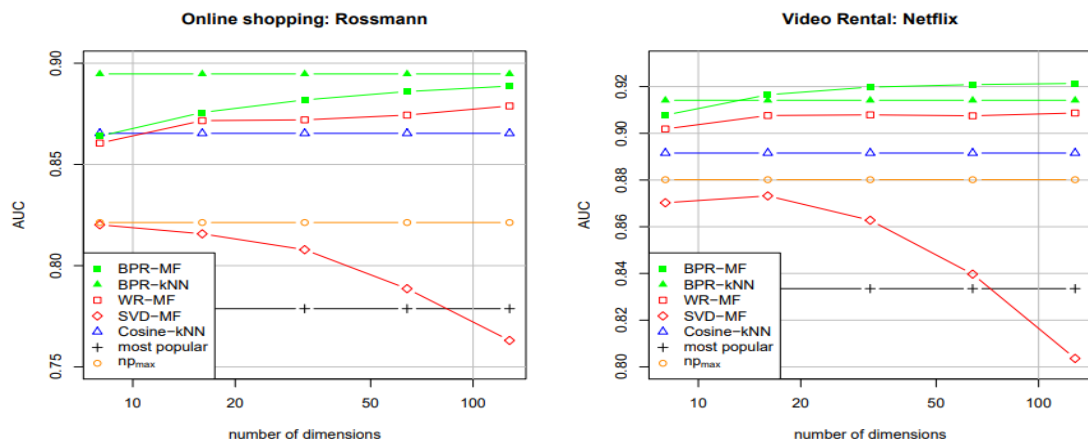


Figure 6: Area under the ROC curve (AUC) prediction quality for the Rossmann dataset and a Netflix subsample. Our BPR optimizations for matrix factorization BPR-MF and k-nearest neighbor BPR-kNN are compared against weighted regularized matrix factorization (WR-MF) [5, 10], singular value decomposition (SVD-MF), k-nearest neighbor (Cosine-kNN) [2] and the most-popular model. For the factorization methods BPR-MF, WR-MF and SVD-MF, the model dimensions are increased from 8 to 128 dimensions. Finally, np_{max} is the theoretical upper bound for any non-personalized ranking method.

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Issue & Remedies

- Issue.
 - Replacing each “?” by “0” sends the wrong signal for training, i.e., it assumes each user does not want to watch any movie s/he has not watched yet.
- Remedies
 - Imputation methods (replacing “?” by a neutral value or global average) (omitted)
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Major Difference between BPR and NGCF

- BPP (and many **early CF** methods) leverages **first-order connectivity** only.
- NGCF (and many **later CF** methods) leverages **higher-order connectivity** by performing multi-layer embedding of nodes with a graph neural network.

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Higher-order Connectivity over a Bipartite

[X Wang et al., SIGIR 2019]

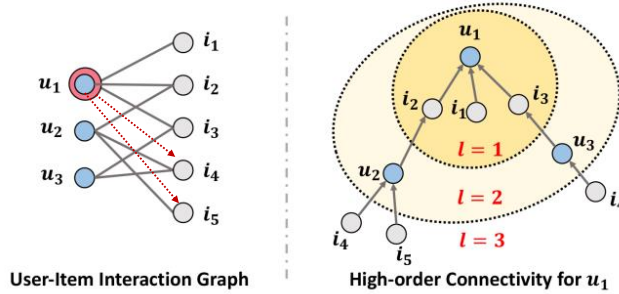


Figure 1: An illustration of the user-item interaction graph and the high-order connectivity. The node u_1 is the target user to provide recommendations for.

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NGCF Node/Item Embedding in Vector Formulation

[X. Wang et al., SIGIR 2019]

- **Multi-layer Node Embedding** (item embedding is similar)

$$h_u^{(l+1)} := \sigma \left(v_{u \leftarrow u}^{(l)} + \sum_{i \in \mathcal{N}_u} v_{u \leftarrow i}^{(l)} \right)$$

$$v_{u \leftarrow u}^{(l)} := W_1^{(l)} h_u^{(l)}, \quad \text{Self-looping}$$

$$v_{u \leftarrow i}^{(l)} := \frac{1}{\sqrt{|\mathcal{N}_u|} \sqrt{|\mathcal{N}_i|}} \left(W_1^{(l)} h_i^{(l)} + W_2^{(l)} (h_i^{(l)} \odot h_u^{(l)}) \right) \quad \text{Neighborhood Aggregation}$$

- Node embedding and item embedding are mutually depending on each other.
- Through multi-layer embedding we capture the **user-item connectivity in the higher-order graph**.

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NGCF Node/Item Embedding in Matrix Formulation

[X. Wang et al., SIGIR 2019]

At the input layer

- We have $H^{(0)}$ as an $(n + m) \times d$ matrix whose rows are the initial embeddings of users and items..

At a higher layer

$$H^{(l+1)} := \sigma \left(\tilde{A} H^{(l)} W_1^{(l)} + \left(A_{sys} (H^{(l)} \odot H^{(l)}) \right) W_2^{(l)} \right)$$

At the final layer

$$e_u^* = e_u^{(0)} \parallel e_u^{(1)} \parallel \dots e_u^{(L)}, \quad e_i^* = e_i^{(0)} \parallel e_i^{(1)} \parallel \dots e_i^{(L)}$$

$$\hat{y}_{u,i} = \langle e_u^*, e_i^* \rangle, \quad Loss = \sum_{(u,i,j) \in D_s} \{ \ln \sigma(\hat{y}_{u,i} - \hat{y}_{u,j}) + \lambda \|\Theta\|^2 \}$$

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Comparison of GCN vs. NGCF

Conventional GCN [Thomas N. Kipf and Max Welling, ICLR 2017]

$$H^{(l+1)} := \sigma \left(\tilde{D}^{-\frac{1}{2}} \tilde{A} \tilde{D}^{-\frac{1}{2}} H^{(l)} W^{(l)} \right), \quad H^{(l)} \in \mathbb{R}^{(n+m) \times d^{(l)}}$$

where $H^{(l+1)} \in \mathbb{R}^{n \times d}$ is a matrix of **graph-based node embeddings**.

Neural Graph Collaborative Filtering (NGCF) [X. Wang et al., SIGIR 2019]

$$H^{(l+1)} := \sigma \left(\tilde{A} H^{(l)} W_1^{(l)} + \left(A_{sys} (H^{(l)} \odot H^{(l)}) \right) W_2^{(l)} \right)$$

where $H^{(l+1)} \in \mathbb{R}^{(n+m) \times d}$ is a matrix of higher-order graph **node/edge embeddings**.

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Adjacency Matrix for a Bipartite Graph

- Initial Adjacency Matrix

$$A \triangleq \begin{bmatrix} 0 & R \\ R^T & 0 \end{bmatrix} \in \{0,1\}^{(m+n) \times (m+n)} \text{ with } A[u, i] = 1 \text{ iff } \text{edge}(u, i) \in E$$

- Symmetrical Normalization

$$A_{sym} \triangleq D^{-\frac{1}{2}} A D^{-\frac{1}{2}} \text{ with } A_{sym}[i, j] = \frac{A_{ij}}{\sqrt{N_i} \sqrt{N_j}} \quad (N_i \text{ and } N_j \text{ are the node degrees})$$

$$D \triangleq \text{diag}\{D_{ii}\}_{i=1}^{m+n}, \quad D_{ii} = \sum_{j=1}^n A_{ij} \quad (\text{sum of the elements in each row})$$

- Adding Self-loop

$$\tilde{A} \triangleq I + A^{sys} = I + D^{-\frac{1}{2}} A D^{-\frac{1}{2}}$$

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Closer Look at $H^{(l+1)} := \sigma \left(\tilde{A} H^{(l)} W_1^{(l)} + \left(A_{sys} (H^{(l)} \odot H^{(l)}) \right) W_2^{(l)} \right)$

$$\tilde{A} H^{(l)} = (I + A_{sym}) H^{(l)} = H^{(l)} + A_{sym} H^{(l)}$$

0	R_{sym}	$H_u^{(l)}$	$=$	$H_u^{(l+1)} = R_{sym} H_i^{(l)}$	\leftarrow Neighborhood Aggregation
R_{sym}^T	0	$H_i^{(l)}$		$H_i^{(l+1)} = R_{sym}^T H_u^{(l)}$	

$$R_{sys}[i, j] = \frac{1}{\sqrt{|\mathcal{N}_i| |\mathcal{N}_j|}}$$

$A_{sys} H^{(l)}$ is doing the cross-bipartite update.

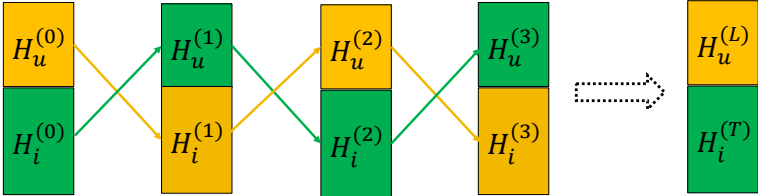
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Multi-layer Neighborhood Aggregation



$H^{(L)} = f(A_{sym}H^{(L-1)}) = \dots = f(\dots f(A_{sym}H^{(0)}) \dots)$

$H_u^{(l+1)} = R_{sym}H_i^{(l)} \quad H_i^{(l+1)} = R_{sym}^T H_u^{(l)}$

$y^{(l+1)} = Ax^{(l)} \quad x^{(l+1)} = A^T y^{(l)} \quad \Rightarrow \quad \text{HITS}$

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Empirical Results [X Wang et al., SIGIR 2019]

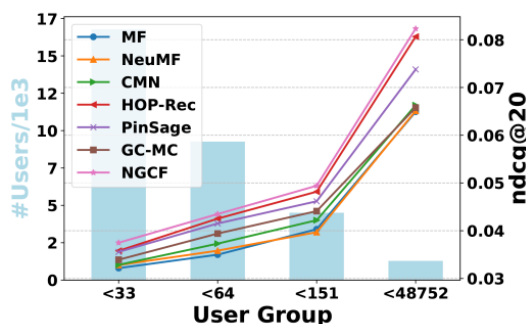
Table 2: Overall Performance Comparison.

	Gowalla		Yelp2018*		Amazon-Book	
	recall	ndcg	recall	ndcg	recall	ndcg
BPR-MF MF	0.1291	0.1109	0.0433	0.0354	0.0250	0.0196
NeuMF	0.1399	0.1212	0.0451	0.0363	0.0258	0.0200
CMN	<u>0.1405</u>	<u>0.1221</u>	0.0457	0.0369	0.0267	0.0218
HOP-Rec	0.1399	0.1214	<u>0.0517</u>	<u>0.0428</u>	<u>0.0309</u>	<u>0.0232</u>
GC-MC	0.1395	0.1204	0.0462	0.0379	0.0288	0.0224
PinSage	0.1380	0.1196	0.0471	0.0393	0.0282	0.0219
3 layers NGCF-3	0.1569*	0.1327*	0.0579*	0.0477*	0.0337*	0.0261*
%Improv.	11.68%	8.64%	11.97%	11.29%	9.61%	12.50%
p-value	2.01e-7	3.03e-3	5.34e-3	4.62e-4	3.48e-5	1.26e-4

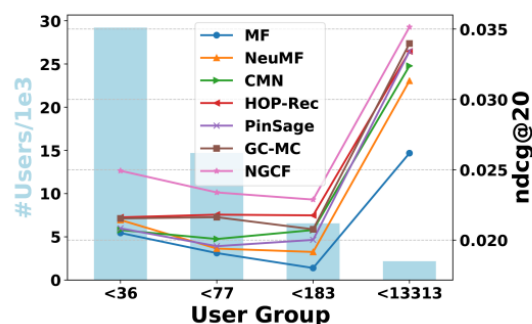
Compared to the best baseline (underlined)

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Empirical Results [X Wang et al., SIGIR 2019]



(b) ndcg on Yelp2018*



(c) ndcg on Amazon-book

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Concluding Remarks

- Recommender systems are a **prominent research topic** and hold significant practical importance across **various industries**.
- Neural representation learning for users/items** plays a key role in recent methods.
- GNNs allow us to leverage **higher-order connectivity in bipartite graphs**.
- Limitation1:** BPR and NGCF cannot handle multi-grade feedback (e.g., 1-5 star book/hotel/restaurant ratings)
- Limitation 2:** BPR and NGCF do not leverage the rich **rich information beyond the bipartite graph** has been widely studied (e.g., user profiles, friendships, user groups, movie actors/actresses/producers/genre, etc.)
- Cold-start** issue remains to be a big challenge in the field.

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- Xiang Wang, Xiangnan He, Meng Wang, Fuli Feng, Tat-Seng Chua. **Neural Graph Collaborative Filtering**, SIGIR-2019, <https://arxiv.org/pdf/1905.08108>
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