Supplementary Materials

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Abstract. We give details of the targeted ciphers including the specifications and the MILP models for describing the division property propagation. All the algorithms have been realized with our C++ source codes.

1 Details of Grain-128

1.1 Specification of Grain-128

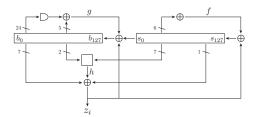


Fig. 1. Structure of Grain-128

Grain-128 [1] is a NLFSR-based stream cipher. It takes as input 128 key bits $x_{[128)}$ and 96 IV bits $v_{[96)}$. Its internal state consists of an LFSR and an NFSR, both of length 128 bits. The NFSR and LFSR, denoted as $\boldsymbol{b}, \boldsymbol{s}$, are initialized by the key and IV bits respectively as follows:

$$\boldsymbol{b}^0 = (b_0, b_1, \dots, b_{127}) = (x_0, \dots, x_{127}), \boldsymbol{s}^0 = (s_0, s_1, \dots, s_{127}) = (v_0, \dots, v_{95}, 1, \dots, 1).$$

After that, for $r = 0, \dots, 255$, the NLFSRs are updated by calling Upd as follows:

$$h^{r} \leftarrow b_{r+12}s_{r+8} + s_{r+13}s_{r+20} + b_{r+95}s_{r+42} + s_{r+60}s_{r+79} + b_{r+12}b_{r+95}s_{95}$$

$$z^{r} \leftarrow h^{r} + s_{r+93} + \sum_{j \in A} b_{r+j} \text{ where } A = \{2, 15, 36, 45, 64, 73, 89\}$$

$$(1)$$

$$g^r \leftarrow b_r + b_{r+26} + b_{r+56} + b_{r+91} + b_{r+96} + b_{r+3} b_{r+67} + b_{r+11} b_{r+13} + b_{r+17} b_{r+18} + b_{r+27} b_{r+59} + b_{r+40} b_{r+48} + b_{r+61} b_{r+65} + b_{r+68} b_{r+84}$$

$$b_{r+128} \leftarrow g^r + z^r + s_r \tag{2}$$

$$f^r \leftarrow s_r + s_{r+7} + s_{r+38} + s_{r+70} + s_{r+81} + s_{r+96}$$

$$s_{r+128} \leftarrow f^r + z^r \tag{3}$$

$$\boldsymbol{b}^r \leftarrow (b_{r+1}, \dots b_{r+128}) \tag{4}$$

$$\boldsymbol{s}^r \leftarrow (s_{r+1}, \dots s_{r+128}) \tag{5}$$

Finally, the first keystream bit z^{256} is output, computed as (1) with parameter r=256. Such a procedure can be reflected by Fig. 1.

1.2 MILP Models of Grain-128

The division property propagation corresponding to the whole procedure of updating function can be constructed by calling UpdDiv Algorithm 2. The subroutines funcZ, funcG, funcF are defined in Algorithm 3, where funcZ can also describe the DP structure of the output bit. The initialization IniDP is defined in Algorithm 1.

Algorithm 1 The initial DP structures for Grain-128/128a.

```
    procedure IniDP(MILP model M, cube index set I, non-cube IV assignment IV, initialization round number R, split set Λ.)
    Declare the DP structures k<sub>x</sub>, k<sub>v</sub> both of length 128.
    For i ∈ I, set M.con ← k<sub>v</sub>[i].val = 1 and k<sub>v</sub>[i].F = δ.
    For i ∉ I, set M.con ← k<sub>v</sub>[i].val = 0 and assign the flag value according to IV[i]: k<sub>v</sub>[i].F = 1<sub>c</sub> if IV[i] = 1 and k<sub>v</sub>[i].F = 0<sub>c</sub> if IV[i] = 0.
    Set M.con ← k<sub>x</sub>[Λ].val = 0 and k<sub>x</sub>[Λ].F = 0<sub>c</sub>. Set k<sub>x</sub>[j].F = δ for j ∉ Λ.
    return (M, k<sub>x</sub>, k<sub>v</sub>).
    end procedure
```

2 Details of Grain-128a

2.1 Specification of Grain-128a

Grain-128a [2] share the same structure with Grain-128. They both consists of a NFSR and a LFSR, both of length 128. They both have 128 key bits $x_{[128)}$ and 96 IV bits $v_{[96)}$. They both requires R=256 initialization rounds. The differences can be seen in many details as well. For Grain-128a, the initialization of the NFSR and LFSR are as follows:

$$\boldsymbol{b}^0 = (b_0, b_1, \dots, b_{127}) = (x_0, \dots, x_{127}), \boldsymbol{s}^0 = (s_0, s_1, \dots, s_{127}) = (v_0, \dots, v_{95}, 1, \dots, 1, 0).$$

Algorithm 2 MILP model for Grain-128/128a updating function.

```
1: procedure UpdDiv(the current MILP model \mathcal{M}, the DP structure \mathbf{k}^{r-1} = (\mathbf{k}_b^{r-1}, \mathbf{k}_s^{r-1}) where \mathbf{k}_b and \mathbf{k}_s are of length 128 corresponding to the DP structures of \mathbf{b}^{r-1}, \mathbf{s}^{r-1} respectively, the round number r (r = 1, 2 \dots).)

2: (\mathcal{M}, \mathbf{k}_b', \mathbf{k}_s', z) = \text{funcZ}(\mathcal{M}, \mathbf{k}_b^{r-1}, \mathbf{k}_s^{r-1})

3: (\mathcal{M}, z_g, z_f) \leftarrow \text{copyf}(\mathcal{M}, z)

4: (\mathcal{M}, \mathbf{k}_b', g) \leftarrow \text{funcG}(\mathcal{M}, \mathbf{k}_b')

5: (\mathcal{M}, \mathbf{k}_s'', f) \leftarrow \text{funcF}(\mathcal{M}, \mathbf{k}_s')

6: (\mathcal{M}, s_s^0, s_s^{*}) \leftarrow \text{copyf}(\mathcal{M}, \mathbf{k}_s'' [0], 2)

7: (\mathcal{M}, b_{r+127}) \leftarrow \text{xorf}(\mathcal{M}, g, s_0^*, z_g)

8: (\mathcal{M}, s_{r+127}) \leftarrow \text{xorf}(\mathcal{M}, f, s_0^{*}, z_f)

9: Assign \mathbf{k}_b^r \leftarrow \mathbf{k}_b'' [1, \dots, 127] \| b_{r+127} and \mathbf{k}_s^r \leftarrow \mathbf{k}_s'' [1, \dots, 127] \| s_{r+127}

10: Assign \mathbf{k}^r = (\mathbf{k}_b^r, \mathbf{k}_s^r).
```

Algorithm 3 MILP model for NLFSRs in Grain-128

```
 \begin{array}{ll} 1: \ \mathbf{procedure} \ \mathbf{funcZ}(\mathcal{M}, \boldsymbol{b}, \boldsymbol{s}) \\ 2: & (\mathcal{M}, \boldsymbol{b}_1, \boldsymbol{s}_1, a_1) \leftarrow \mathtt{CAND}( \\ 3: & (\mathcal{M}, \boldsymbol{b}_2, \boldsymbol{s}_2, a_2) \leftarrow \mathtt{CAND}( \end{array} 
                               (\mathcal{M}, \boldsymbol{b}_1, \boldsymbol{s}_1, a_1) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}, \boldsymbol{s}, \{12\}, \{8\})
                                (\mathcal{M}, \boldsymbol{b}_2, \boldsymbol{s}_2, a_2) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}_1, \boldsymbol{s}_1, \phi, \{13, 20\})
  4:
                               (\mathcal{M}, \boldsymbol{b}_3, \boldsymbol{s}_3, a_3) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}_2, \boldsymbol{s}_2, \{95\}, \{42\})
  5:
                              (\mathcal{M}, \boldsymbol{b}_4, \boldsymbol{s}_4, a_4) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}_3, \boldsymbol{s}_3, \phi, \{60, 79\})
  6:
                              (\mathcal{M}, \boldsymbol{b}_5, \boldsymbol{s}_5, a_5) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}_4, \boldsymbol{s}_4, \{12, 95\}, \{95\})
                              (\mathcal{M}, \boldsymbol{b}_6, \boldsymbol{s}_6, x) \leftarrow \mathtt{CXOR}(\mathcal{M}, \boldsymbol{b}_5, \boldsymbol{s}_5, \{2, 15, 36, 45, 64, 73, 89\}, \{93\})
                              (\mathcal{M},z) \leftarrow \texttt{xorf}(\mathcal{M},x,a_1,\ldots,a_5)
                              return (\mathcal{M}, \boldsymbol{b}_6, \boldsymbol{s}_6, z)
10: end procedure
  1: procedure funcF(\mathcal{M}, s)
                             (\mathcal{M}, \phi, \boldsymbol{s}_1, f) \leftarrow \texttt{CXOR}(\mathcal{M}, \phi, \boldsymbol{s}, \phi, \{7, 38, 70, 81, 96\})
                             return (\mathcal{M}, \boldsymbol{s}_1, f)
  4: end procedure
 1:
              procedure funcG(M, b)
                              (\mathcal{M}, \boldsymbol{b}_1, \phi, a_1) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}, \phi, \{3, 67\}, \phi)
  2:
3:
4:
                             \begin{aligned} &(\mathcal{M}, \mathbf{b}_1, \phi, a_1) \leftarrow \text{CAND}(\mathcal{M}, \mathbf{b}, \phi, \{3, 67\}, \phi) \\ &(\mathcal{M}, \mathbf{b}_2, \phi, a_2) \leftarrow \text{CAND}(\mathcal{M}, \mathbf{b}_1, \phi, \{11, 13\}, \phi) \\ &(\mathcal{M}, \mathbf{b}_3, \phi, a_3) \leftarrow \text{CAND}(\mathcal{M}, \mathbf{b}_2, \phi, \{17, 18\}, \phi) \\ &(\mathcal{M}, \mathbf{b}_4, \phi, a_4) \leftarrow \text{CAND}(\mathcal{M}, \mathbf{b}_3, \phi, \{27, 59\}, \phi) \\ &(\mathcal{M}, \mathbf{b}_5, \phi, a_5) \leftarrow \text{CAND}(\mathcal{M}, \mathbf{b}_4, \phi, \{40, 48\}, \phi) \\ &(\mathcal{M}, \mathbf{b}_6, \phi, a_6) \leftarrow \text{CAND}(\mathcal{M}, \mathbf{b}_5, \phi, \{61, 65\}, \phi) \\ &(\mathcal{M}, \mathbf{b}_7, \phi, a_7) \leftarrow \text{CAND}(\mathcal{M}, \mathbf{b}_6, \phi, \{68, 84\}, \phi) \\ &(\mathcal{M}, \mathbf{b}_1, \phi, \mathbf{x}) \leftarrow \text{CXOR}(\mathcal{M}, \mathbf{b}_{10}, \phi, \{0, 26, 56, 91, 96\}, \phi) \\ &(\mathcal{M}, \mathbf{g}) \leftarrow \text{xorf}(\mathcal{M}, \mathbf{x}, a_1, \dots, a_{10}) \end{aligned}
  6:
7:
8:
10:
                                return (\mathcal{M}, \boldsymbol{b}_{11}, g)
12: end procedure
```

 ${\bf Algorithm~4~MILP~model~for~COPY+XOR~and~COPY+AND~in~Grain-like~stream~ciphers}$

```
1: procedure CAND(\mathcal{M}, \boldsymbol{b}, \boldsymbol{s}, I, J)
2:
3:
               (\mathcal{M}, b_i', x_i) \leftarrow \mathsf{copyf}(\mathcal{M}, b_i') \text{ for all } i \in I

(\mathcal{M}, s_j', y_j) \leftarrow \mathsf{copyf}(\mathcal{M}, s_j) \text{ for all } j \in J
               for all i \in \{0, 1, \dots, 127\} - I do
                      b'_i = b_i
               end for
               for all j \in \{0, 1, ..., 127\} - J do
               end for
                (\mathcal{M},z) \leftarrow \mathtt{andf}(\mathcal{M},b'{}_{i,i\in I},s'{}_{j,j\in J})
                return (\mathcal{M}, \boldsymbol{b}', \boldsymbol{s}', z)
12: end procedure
 1: procedure CXOR(\mathcal{M}, \boldsymbol{b}, \boldsymbol{s}, I, J)
                (\mathcal{M}, b_i', x_i) \leftarrow \texttt{copyf}(\mathcal{M}, b_i) \text{ for all } i \in I \\ (\mathcal{M}, s_j', y_j) \leftarrow \texttt{copyf}(\mathcal{M}, s_j) \text{ for all } j \in J 
 3:
               for all i \in \{0, 1, ..., 127\} - I do
               end for
               for all j \in \{0, 1, ..., 127\} - J do
               end for
                (\mathcal{M},z) \leftarrow \mathtt{xorf}(\mathcal{M},b'{}_{i,i\in I},s'{}_{j,j\in J})
                return (\mathcal{M}, \boldsymbol{b}', \boldsymbol{s}', z)
12: end procedure
```

For $r=0,\ldots,R-1$, the update function in the initialization round r is as follows.

$$h^{r} \leftarrow b_{r+12}s_{r+8} + s_{r+13}s_{r+20} + b_{r+95}s_{r+42} + s_{r+60}s_{r+79} + b_{r+12}b_{r+95}s_{94}$$

$$z^{r} \leftarrow h^{r} + s_{r+93} + \sum_{j \in A} b_{r+j} \text{ where } A = \{2, 15, 36, 45, 64, 73, 89\}$$

$$g^{r} \leftarrow b_{r} + b_{r+26} + b_{r+56} + b_{r+91} + b_{r+96} + b_{r+3}b_{r+67} + b_{r+11}b_{r+13} + b_{r+17}b_{r+18}$$

$$+ b_{r+27}b_{r+59} + b_{r+40}b_{r+48} + b_{r+61}b_{r+65} + b_{r+68}b_{r+84}$$

$$+ b_{r+88}b_{r+92}b_{r+93}b_{r+95} + b_{r+22}b_{r+24}b_{r+25} + b_{r+70}b_{r+78}b_{r+82}$$

$$b_{r+128} \leftarrow g^{r} + z^{r} + s_{r}$$

$$f^{r} \leftarrow s_{r} + s_{r+7} + s_{r+38} + s_{r+70} + s_{r+81} + s_{r+96}$$

$$s_{r+128} \leftarrow f^{r} + z^{r}$$

$$(8)$$

$$b^{r} \leftarrow (b_{r+1}, \dots b_{r+128})$$

$$(9)$$

$$s^{r} \leftarrow (s_{r+1}, \dots s_{r+128})$$

$$(10)$$

After R initialization rounds, the output function (6) is called for r = R so the 1st output bit is z^R . Of course, full Grain-128a has R = 256 but our secure bounds consider R < 256.

2.2 MILP Models of Grain-128a

The updating function can also be represented as Algorithm 2 but the subroutines are substituted as Algorithm 5. These algorithms are first defined in [3].

Algorithm 5 MILP model for NLFSR and LFSR in Grain-128a

```
1: procedure funcZ(\mathcal{M}, b, s)
                               ocedure funcZ(\mathcal{M}, \boldsymbol{b}, \boldsymbol{s})

(\mathcal{M}, \boldsymbol{b}_1, \boldsymbol{s}_1, \boldsymbol{a}_1) \leftarrow \text{CAND}(\mathcal{M}, \boldsymbol{b}, \boldsymbol{s}, \{12\}, \{8\})

(\mathcal{M}, \boldsymbol{b}_2, \boldsymbol{s}_2, \boldsymbol{a}_2) \leftarrow \text{CAND}(\mathcal{M}, \boldsymbol{b}_1, \boldsymbol{s}_1, \phi, \{13, 20\})

(\mathcal{M}, \boldsymbol{b}_3, \boldsymbol{s}_3, \boldsymbol{a}_3) \leftarrow \text{CAND}(\mathcal{M}, \boldsymbol{b}_2, \boldsymbol{s}_2, \{95\}, \{42\})

(\mathcal{M}, \boldsymbol{b}_4, \boldsymbol{s}_4, \boldsymbol{a}_4) \leftarrow \text{CAND}(\mathcal{M}, \boldsymbol{b}_3, \boldsymbol{s}_3, \phi, \{60, 79\})

(\mathcal{M}, \boldsymbol{b}_5, \boldsymbol{s}_5, \boldsymbol{a}_5) \leftarrow \text{CAND}(\mathcal{M}, \boldsymbol{b}_4, \boldsymbol{s}_4, \{12, 95\}, \{94\})

(\mathcal{M}, \boldsymbol{b}_6, \boldsymbol{s}_6, \boldsymbol{x}_1) \leftarrow \text{CXOR}(\mathcal{M}, \boldsymbol{b}_5, \boldsymbol{s}_5, \{2, 15, 36, 45, 64, 73, 89\}, \{93\})
  4:
5:
                               (\mathcal{M}, z) \leftarrow \operatorname{xorf}(\mathcal{M}, x, a_1, \dots, a_5)

return (\mathcal{M}, b_6, s_6, z)
10: end procedure
               procedure funcF(M, s)
                               (\mathcal{M}, \phi, \boldsymbol{s}_1, f) \leftarrow \mathtt{CXOR}(\mathcal{M}, \phi, \boldsymbol{s}, \phi, \{0, 7, 38, 70, 81, 96\}) return (\mathcal{M}, \boldsymbol{s}_1, f)
  4: end procedure
 1: 2: 3: 4: 5: 6: 7: 8: 9:
              procedure funcG(M, b)
                                  \begin{array}{l} (\mathcal{M}, \boldsymbol{b}_1, \phi, a_1) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}, \phi, \{3, 67\}, \phi) \\ (\mathcal{M}, \boldsymbol{b}_2, \phi, a_2) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}_1, \phi, \{11, 13\}, \phi) \end{array} 
                                 (\mathcal{M}, \boldsymbol{b}_3, \phi, a_3) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}_2, \phi, \{17, 18\}, \phi)
                                 (\mathcal{M}, \boldsymbol{b}_4, \phi, a_4) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}_3, \phi, \{27, 59\}, \phi)
                                 (\mathcal{M}, \boldsymbol{b}_5, \phi, a_5) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}_4, \phi, \{40, 48\}, \phi)
                                 (\mathcal{M}, \boldsymbol{b}_6, \phi, a_6) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}_5, \phi, \{61, 65\}, \phi)
                                \begin{array}{l} (\mathcal{M}, \boldsymbol{b_6}, \phi, a_6) \leftarrow \text{Cand}(\mathcal{M}, \boldsymbol{b_5}, \phi, \{61, 65\}, \phi) \\ (\mathcal{M}, \boldsymbol{b_7}, \phi, a_7) \leftarrow \text{Cand}(\mathcal{M}, \boldsymbol{b_6}, \phi, \{68, 84\}, \phi) \\ (\mathcal{M}, \boldsymbol{b_9}, \phi, a_9) \leftarrow \text{Cand}(\mathcal{M}, \boldsymbol{b_8}, \phi, \{22, 24, 25\}, \phi) \\ (\mathcal{M}, \boldsymbol{b_{10}}, \phi, a_{10}) \leftarrow \text{Cand}(\mathcal{M}, \boldsymbol{b_9}, \phi, \{70, 78, 82\}, \phi) \\ (\mathcal{M}, \boldsymbol{b_{10}}, \phi, a_{11}) \leftarrow \text{Cand}(\mathcal{M}, \boldsymbol{b_9}, \phi, \{88, 92, 93, 95\}, \phi) \end{array} 
10:
11:
                                   (\mathcal{M}, \boldsymbol{b}_{11}, \phi, x) \leftarrow \texttt{CXOR}(\mathcal{M}, \boldsymbol{b}_{10}, \phi, \{0, 26, 56, 91, 96\}, \phi)
12:
13:
                                   (\mathcal{M}, g) \leftarrow \mathtt{xorf}(\mathcal{M}, x, a_1, \dots, a_{11})
14:
                                   return (\mathcal{M}, \boldsymbol{b}_{11}, g)
15: end procedure
```

3 Details of Grain-V1

3.1 Specification of Grain-V1

Grain-V1 [4] also has a NFSR and a LFSR but the sizes are 80 rather than 128. It has 80 key bits $x_{[80)}$ and 64 IV bits $v_{[64)}$. Full Grin-V1 requires R=160 initialization rounds. The initialization of the NFSR and LFSR are assinged as:

$$\boldsymbol{b}^0 = (b_0, b_1, \dots, b_{79}) = (x_0, \dots, x_{79}), \boldsymbol{s}^0 = (s_0, s_1, \dots, s_{79}) = (v_0, \dots, v_{63}, 1, \dots, 1).$$

For $r = 0, \ldots, R - 1$, the update function in the initialization round r is as follows.

$$h^{r} \leftarrow s_{r+25} + b_{r+63} + s_{r+3}s_{r+64} + s_{r+46}s_{r+64} + b_{r+63}s_{r+64} + s_{r+3}s_{r+25}s_{r+46} \\ + s_{r+3}s_{r+46}s_{r+64} + s_{r+3}s_{r+46}b_{r+63} + s_{r+25}s_{r+46}b_{r+63} + s_{r+46}s_{r+64}b_{r+63}$$

$$z^{r} \leftarrow h^{r} + \sum_{j \in A} b_{r+j} \text{ where } A = \{1, 2, 4, 10, 31, 43, 56\}$$

$$g^{r} \leftarrow b_{r} + b_{r+9} + b_{r+14} + b_{r+21} + b_{r+28} + b_{r+33} + b_{r+37} + b_{r+45} + b_{r+52} + b_{r+60} + b_{r+62} \\ + b_{r+63}b_{r+60} + b_{r+37}b_{r+33} + b_{r+15}b_{r+9} \\ + b_{r+60}b_{r+52}b_{r+45} + b_{r+33}b_{r+28}b_{r+21} + b_{r+63}b_{r+45}b_{r+28}b_{r+9} \\ + b_{r+60}b_{r+52}b_{r+37}b_{r+33} + b_{r+63}b_{r+60}b_{r+21}b_{r+15} \\ + b_{r+63}b_{r+60}b_{r+52}b_{r+45}b_{r+37} + b_{r+33}b_{r+28}b_{r+21}b_{r+15}b_{r+9} \\ + b_{r+52}b_{r+45}b_{r+37}b_{r+33}b_{r+28}b_{r+21} \\ b_{r+80} \leftarrow g^{r} + z^{r} + s_{r}$$

$$(12)$$

$$f^{r} \leftarrow s_{r} + s_{r+13} + s_{r+23} + s_{r+38} + s_{r+51} + s_{r+62} \\ s_{r+80} \leftarrow f^{r} + z^{r}$$

$$(13)$$

$$b^{r} \leftarrow (b_{r+1}, \dots b_{r+80})$$

$$s^{r} \leftarrow (s_{r+1}, \dots s_{r+80})$$

$$(15)$$

After R initialization rounds, the output function (11) is called for r=R so the 1st output bit is z^R . Of course, full Grain-V1 has R=160 but our secure bounds consider R<160.

3.2 MILP Models of Grain-V1

The initialization DP structures are assigned by calling Algorithm 6. The updating function is defined as Algorithm 7 and its subroutines defined in Algorithm 8.

Algorithm 6 The initial DP structures for Grain-V1.

```
    procedure IniDP(MILP model M, cube index set I, non-cube IV assignment IV, initialization round number R, split set Λ.)
    Declare the DP structures k<sub>x</sub>, k<sub>v</sub> both of length 80.
    For i ∈ I, set M.con ← k<sub>v</sub>[i].val = 1 and k<sub>v</sub>[i].F = δ.
    For i ∉ I, set M.con ← k<sub>v</sub>[i].val = 0 and assign the flag value according to IV[i]: k<sub>v</sub>[i].F = 1<sub>c</sub> if IV[i] = 1 and k<sub>v</sub>[i].F = 0<sub>c</sub> if IV[i] = 0.
    Set M.con ← k<sub>x</sub>[Λ].val = 0 and k<sub>x</sub>[Λ].F = 0<sub>c</sub>. Set k<sub>x</sub>[j].F = δ for j ∉ Λ.
    return (M, k<sub>x</sub>, k<sub>v</sub>).
    end procedure
```

Algorithm 7 MILP model for Grain-V1 updating function.

```
1: procedure UpdDiv(the current MILP model \mathcal{M}, the DP structure \mathbf{k}^{r-1} = (\mathbf{k}_b^{r-1}, \mathbf{k}_s^{r-1}) where \mathbf{k}_b and \mathbf{k}_s are of length 80 corresponding to the DP structures of \mathbf{b}^{r-1}, \mathbf{s}^{r-1} respectively, the round number r (r = 1, 2 \dots).)

2: (\mathcal{M}, \mathbf{k}_b', \mathbf{k}_s', z) \leftarrow \text{funcZ}(\mathcal{M}, \mathbf{k}_b^{r-1}, \mathbf{k}_s^{r-1})

3: (\mathcal{M}, z_q, z_f) \leftarrow \text{copyf}(\mathcal{M}, z)

4: (\mathcal{M}, \mathbf{k}_b', g) \leftarrow \text{funcG}(\mathcal{M}, \mathbf{k}_b')

5: (\mathcal{M}, \mathbf{k}_s', f) \leftarrow \text{funcF}(\mathcal{M}, \mathbf{k}_s)

6: (\mathcal{M}, s_0^*, s_0^{**}) \leftarrow \text{copyf}(\mathcal{M}, s_s^{**})

7: (\mathcal{M}, b_{r+79}) \leftarrow \text{xorf}(\mathcal{M}, g, s_0^{**}, z_g)

8: (\mathcal{M}, s_{r+79}) \leftarrow \text{xorf}(\mathcal{M}, f, s_0^{**}, z_f)

9: Assign \mathbf{k}_b^r \leftarrow \mathbf{k}_b''[1, \dots, 79] || b_{r+79} and \mathbf{k}_s^r \leftarrow \mathbf{k}_s''[1, \dots, 79] || s_{r+79}

10: Assign \mathbf{k}^r = (\mathbf{k}_b^r, \mathbf{k}_s^r).
```

Algorithm 8 MILP model for NLFSRs in Grain-V1

```
1: procedure funcZ(\mathcal{M}, b, s)
                               (\mathcal{M}, \boldsymbol{b}_1, \boldsymbol{s}_1, a_1) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}, \boldsymbol{s}, \phi, \{3, 64\})
  3:
                                (\mathcal{M}, \boldsymbol{b}_2, \boldsymbol{s}_2, a_2) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}_1, \boldsymbol{s}_1, \phi, \{46, 64\})
  4:
                               (\mathcal{M}, \boldsymbol{b}_3, \boldsymbol{s}_3, a_3) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}_2, \boldsymbol{s}_2, \{63\}, \{64\})
  5:
                              (\mathcal{M}, \boldsymbol{b}_4, \boldsymbol{s}_4, a_4) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}_3, \boldsymbol{s}_3, \dot{\phi}, \{3, 25, 46\})
                              (\mathcal{M}, \boldsymbol{b}_5, \boldsymbol{s}_5, a_5) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}_4, \boldsymbol{s}_4, \phi, \{3, 46, 64\})
                             9:
10:
                                (\mathcal{M}, \boldsymbol{b}_9, \boldsymbol{s}_9, x) \leftarrow \texttt{CXOR}(\mathcal{M}, \boldsymbol{b}_8, \boldsymbol{s}_8, \{1, 2, 4, 10, 31, 43, 56, 63\}, \{25\})
                                (\mathcal{M},z) \leftarrow \texttt{xorf}(\mathcal{M},x,a_1,\ldots,a_8)
                                return (\mathcal{M}, \boldsymbol{b}_9, \boldsymbol{s}_9, z)
12:
13: end procedure
              procedure funcF(\mathcal{M}, s)
                              (\mathcal{M}, \phi, \mathbf{s}_1, f) \leftarrow \mathtt{CXOR}(\mathcal{M}, \phi, \mathbf{s}, \phi, \{13, 23, 38, 51, 62\})
                             return (\mathcal{M}, \boldsymbol{s}_1, f)
  3:
  4: end procedure
              procedure funcG(\mathcal{M}, b)
                             Greature Tunicity, \boldsymbol{b}) \leftarrow Cand (\mathcal{M}, \boldsymbol{b}_1, \phi, a_1) \leftarrow Cand (\mathcal{M}, \boldsymbol{b}_1, \phi, \{63, 60\}, \phi) (\mathcal{M}, \boldsymbol{b}_2, \phi, a_2) \leftarrow Cand (\mathcal{M}, \boldsymbol{b}_1, \phi, \{33, 37\}, \phi) (\mathcal{M}, \boldsymbol{b}_3, \phi, a_3) \leftarrow Cand (\mathcal{M}, \boldsymbol{b}_2, \phi, \{15, 9\}, \phi) (\mathcal{M}, \boldsymbol{b}_4, \phi, a_4) \leftarrow Cand (\mathcal{M}, \boldsymbol{b}_3, \phi, \{60, 52, 45\}, \phi)
                             \begin{aligned} &(\mathcal{M}, \mathbf{b_4}, \phi, a_4) \leftarrow \mathtt{CAND}(\mathcal{M}, \mathbf{b_3}, \phi, \{60, 52, 45\}, \phi) \\ &(\mathcal{M}, \mathbf{b_5}, \phi, a_5) \leftarrow \mathtt{CAND}(\mathcal{M}, \mathbf{b_4}, \phi, \{33, 28, 21\}, \phi) \\ &(\mathcal{M}, \mathbf{b_6}, \phi, a_6) \leftarrow \mathtt{CAND}(\mathcal{M}, \mathbf{b_5}, \phi, \{63, 45, 28, 9\}, \phi) \\ &(\mathcal{M}, \mathbf{b_7}, \phi, a_7) \leftarrow \mathtt{CAND}(\mathcal{M}, \mathbf{b_6}, \phi, \{60, 52, 37, 33\}, \phi) \\ &(\mathcal{M}, \mathbf{b_8}, \phi, a_8) \leftarrow \mathtt{CAND}(\mathcal{M}, \mathbf{b_7}, \phi, \{63, 60, 21, 15\}, \phi) \\ &(\mathcal{M}, \mathbf{b_9}, \phi, a_9) \leftarrow \mathtt{CAND}(\mathcal{M}, \mathbf{b_8}, \phi, \{63, 60, 52, 45, 37\}, \phi) \\ &(\mathcal{M}, \mathbf{b_{10}}, \phi, a_{10}) \leftarrow \mathtt{CAND}(\mathcal{M}, \mathbf{b_{10}}, \phi, \{33, 28, 21, 15, 9\}, \phi) \\ &(\mathcal{M}, \mathbf{b_{11}}, \phi, a_{11}) \leftarrow \mathtt{CAND}(\mathcal{M}, \mathbf{b_{10}}, \phi, \{52, 45, 37, 33, 28, 21\}, \phi) \\ &(\mathcal{M}, \mathbf{b_{12}}, \phi, x) \leftarrow \mathtt{CXOR}(\mathcal{M}, \mathbf{b_{11}}, \phi, \{0, 9, 14, 21, 28, 33, 37, 45, 52, 60, 62\}, \phi) \\ &(\mathcal{M}, \mathbf{a}) \leftarrow \mathtt{vorf}(\mathcal{M}, \mathbf{x}, \mathbf{a_1}, \mathbf{a_{11}}) \end{aligned}
  6:
7:
8:
  9:
10:
11:
12:
13:
                                (\mathcal{M}, g) \leftarrow \text{xorf}(\mathcal{M}, x, a_1, \dots, a_{11})
return (\mathcal{M}, \mathbf{b}_{12}, g)
14:
15:
16: end procedure
```

4 Details of Plantlet

4.1 Specification of Plantlet

Plantlet [5] has 80 key bits $x_{[80)}$ and 90 IV bits $v_{[90)}$. It is composed of a 40-bit NFSR and a LFSR of length 60^1 The NFSR and LFSR are initialized by the key and IV bits respectively as follows:

$$\boldsymbol{b}^0 = (b_0, b_1, \dots, b_{39}) = (v_0, \dots, v_{39}), \boldsymbol{s}^0 = (s_0, s_1, \dots, s_{59}) = (v_{40}, \dots, v_{89}, 1, \dots, 1).$$

For initialization round number $r=0,\ldots,R-1,$ the following updating function is called:

$$h^{r} \leftarrow b_{r+4l} s_{r+6} + s_{r+8l} s_{r+10} + s_{t+17} s_{r+32} + s_{r+19} s_{r+23} + b_{r+4} s_{r+32} b_{r+38}$$

$$z^{r} \leftarrow h^{r} + s_{r+30} + \sum_{j \in A} b_{r+j} \text{ where } A = \{1, 6, 15, 17, 23, 28, 34\}$$

$$(16)$$

$$g^{r} \leftarrow b_{r} + b_{r+13} + b_{r+19} + b_{r+35} + b_{r+39} + b_{r+2}b_{r+25} + b_{r+3}b_{r+5} + b_{r+7}b_{r+8}$$

$$+ b_{r+14}b_{r+21} + b_{r+16}b_{r+18} + b_{r+22}b_{r+24} + b_{r+26}b_{r+32} + b_{r+33}b_{r+36}b_{r+37}b_{r+38}$$

$$+ b_{r+10}b_{r+11}b_{r+12} + b_{r+27}b_{r+30}b_{r+31}$$

$$b_{r+40} \leftarrow g^r + z^r + s_r + K[r] + c_4^r$$
 (17)

$$f^r \leftarrow s_r + s_{r+14} + s_{r+20} + s_{r+34} + s_{r+43} + s_{r+54}$$

$$s_{r+60} \leftarrow f^r + z^r \tag{18}$$

$$\boldsymbol{b}^{r} \leftarrow (b_{r+1}, \dots b_{r+40}) \tag{19}$$

$$\boldsymbol{s}^r \leftarrow (s_{r+1}, \dots s_{r+60}) \tag{20}$$

Note that in (17), we denote K as a vector of length R and its ith entry is defined as $K[i] \leftarrow x_{i \mod 80}$. The number c_4^r is the 4th bit of a counter and it can be determined purely by r as

$$c_4^r = \lfloor \frac{r \mod 80}{2^4} \rfloor \tag{21}$$

4.2 MILP Models for Plantlet

It is noticeable that the updating function of Plantlet requires K. Therefore, in IniDP, we should determine the DP structures of both IV bits and K. Such a process is described as Algorithm 9. The updating function can be defined as Algorithm 10 and its subroutines are in Algorithm 11.

5 Details of Kreyvium

5.1 Specification of Kreyvium

Kreyvium is designed for the use of fully Homomorphic encryption [6]. It claims 128-bit security and accepts 128-bit IV. Kreyvium consists of 5 registers. Two

Only during the initialiation phase. Afterwards, the length of LFSR becomes 61 [5].

Algorithm 9 The initial DP structures for Kreyvium.

```
1: procedure IniDP(MILP model \mathcal{M}, cube index set I, non-cube IV assignment IV, initialization round number R (R \geq 80), split set \Lambda.)

2: Declare the DP structures \mathbf{k}_x, \mathbf{k}_v both of lengths 80 and 90 respectively.

3: For i \in I, set \mathcal{M}.con \leftarrow \mathbf{k}_v[i].val = 1 and \mathbf{k}_v[i].F = \delta.

4: For i \notin I, set \mathcal{M}.con \leftarrow \mathbf{k}_v[i].val = 0 and assign the flag value according to IV[i]: \mathbf{k}_v[i].F = 1_c if IV[i] = 1 and \mathbf{k}_v[i].F = 0_c if IV[i] = 0.

5: Set \mathcal{M}.con \leftarrow \mathbf{k}_x[A].val = 0 and \mathbf{k}_x[A].F = 0_c. Set \mathbf{k}_x[j].F = \delta for j \notin A.

6: Initialize \mathbf{k}_K \leftarrow \mathbf{k}_x.

7: for r = 80, \ldots, R - 1 do

8: (\mathcal{M}, t_1, t_2) \leftarrow \text{copyf}(\mathcal{M}, \mathbf{k}_K[r \mod 80], 2).

9: Update \mathbf{k}_K[r \mod 80] \leftarrow t_1 and \mathbf{k}_K \leftarrow \mathbf{k}_K \parallel t_2.

10: end for return (\mathcal{M}, \mathbf{k}_v, \mathbf{k}_K).

12: end procedure
```

Algorithm 10 MILP model for Plantlet updating function.

```
1: procedure UpdDiv(the current MILP model \mathcal{M}, the DP structure \mathbf{k}^{r-1} = (\mathbf{k}_b^{r-1}, \mathbf{k}_s^{r-1}) where \mathbf{k}_b and \mathbf{k}_s are of lengths 40 and 60 corresponding to the DP structures of \mathbf{b}^{r-1}, \mathbf{s}^{r-1} respectively, the round number r (r=1,2\ldots), the DP structure \mathbf{k}_K corresponding to the division property of \mathbf{K}.)

2: (\mathcal{M}, \mathbf{k}_b', \mathbf{k}_s', z) \leftarrow \text{funcZ}(\mathcal{M}, \mathbf{k}_b^{r-1}, \mathbf{k}_s^{r-1})

3: (\mathcal{M}, \mathbf{z}_g, \mathbf{z}_f) \leftarrow \text{copyf}(\mathcal{M}, \mathbf{z})

4: (\mathcal{M}, \mathbf{k}_b', g) \leftarrow \text{funcG}(\mathcal{M}, \mathbf{k}_b')

5: (\mathcal{M}, \mathbf{k}_s', f) \leftarrow \text{funcF}(\mathcal{M}, \mathbf{k}_s')

6: (\mathcal{M}, \mathbf{s}_0', \mathbf{s}_0^{**}) \leftarrow \text{copyf}(\mathcal{M}, \mathbf{k}_s'')

6: (\mathcal{M}, \mathbf{s}_0', \mathbf{s}_0^{**}) \leftarrow \text{copyf}(\mathcal{M}, \mathbf{k}_s'')

7: Compute c_4^{r-1} according to (21) and declare a DP structure o with constraint \mathcal{M}.con \leftarrow o.val = 0.

8: If c_4^{r-1} = 0, set the flag value o.F = 0_c; otherwise, o.F = 1_c.

9: (\mathcal{M}, b_{r+39}) \leftarrow \text{xorf}(\mathcal{M}, g, \mathbf{s}_0^*, z_g, \mathbf{k}_K[r-1], c_4^{r-1})

10: (\mathcal{M}, \mathbf{s}_{r+59}) \leftarrow \text{xorf}(\mathcal{M}, f, \mathbf{s}_0^{**}, z_f)

11: Assign \mathbf{k}_0^r \leftarrow \mathbf{k}_b''[1, \ldots, 39] || b_{r+39} and \mathbf{k}_s^r \leftarrow \mathbf{k}_s''[1, \ldots, 59] || \mathbf{s}_{r+59}

12: Assign \mathbf{k}_0^r \leftarrow (\mathbf{k}_b', \mathbf{k}_s').
```

of them are LFSRs denoted as \pmb{K} and \pmb{V} respectively. The remaining is three concatenated NFSRs making up a 288-bit state \pmb{s} denoted as

$$(s_0,\ldots,s_{92})\|(s_{93},\ldots,s_{176})\|(s_{177},\ldots,s_{287})$$

The registers are initialized with the 128 key bits, $x_{[127)}$, and 128 IV bits, $v_{[127)}$ as follows:

$$\mathbf{s}^{0}[0,\ldots,92] = (s_{0}^{0},\ldots,s_{93}^{0}) \leftarrow (x_{0},\ldots,x_{92}),$$

$$\mathbf{s}^{0}[93,\ldots,176] = (s_{93}^{0},\ldots,s_{176}^{0}) \leftarrow (v_{0},\ldots,v_{83}),$$

$$\mathbf{s}^{0}[177,\ldots,287] = (s_{177}^{0},\ldots,s_{287}^{0}) \leftarrow (v_{84},\ldots,v_{127},1,1,\ldots,1,0),$$

$$\mathbf{V}^{0} = (V_{127}^{0},V_{126}^{0},\ldots,V_{0}^{0}) \leftarrow (v_{0},\ldots,v_{127}),$$

$$\mathbf{K}^{0} = (K_{127}^{0},K_{126}^{0},\ldots,K_{0}^{0}) \leftarrow (x_{0},\ldots,x_{127}),$$

For initialization round R, the updating function is called as $(s^r, V^r, K^r) \leftarrow \text{Upd}(s^{r-1}, V^{r-1}, K^{r-1})$ for r = 1, ... R. The procedure of Upd can be depicted

```
Algorithm 11 MILP model for NLFSRs in Plantlet
  1: 2: 3: 4: 5: 6: 7: 8:
                   {\tt procedure} \; {\tt funcZ}(\mathcal{M}, \boldsymbol{b}, \boldsymbol{s})
                                            (\mathcal{M}, \boldsymbol{b}_1, \boldsymbol{s}_1, a_1) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}, \boldsymbol{s}, \{4\}, \{6\})
                                        \begin{array}{l} (\mathcal{M}, \boldsymbol{b}_1, \boldsymbol{s}_1, a_1) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}, \boldsymbol{s}, \{4\}, \{6\}) \\ (\mathcal{M}, \boldsymbol{b}_2, \boldsymbol{s}_2, a_2) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}_1, \boldsymbol{s}_1, \phi, \{8, 10\}) \\ (\mathcal{M}, \boldsymbol{b}_3, \boldsymbol{s}_3, a_3) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}_2, \boldsymbol{s}_2, \phi, \{17, 32\}) \\ (\mathcal{M}, \boldsymbol{b}_4, \boldsymbol{s}_4, a_4) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}_3, \boldsymbol{s}_3, \phi, \{19, 23\}) \\ (\mathcal{M}, \boldsymbol{b}_5, \boldsymbol{s}_5, a_5) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}_4, \boldsymbol{s}_4, \{4, 38\}, \{32\}) \\ (\mathcal{M}, \boldsymbol{b}_6, \boldsymbol{s}_6, x) \leftarrow \mathtt{CXOR}(\mathcal{M}, \boldsymbol{b}_5, \boldsymbol{s}_5, \{1, 6, 15, 17, 23, 28, 34\}, \{30\}) \\ (\mathcal{M}, z) \leftarrow \mathtt{xorf}(\mathcal{M}, x, a_1, \dots, a_5) \\ \mathtt{return}(\mathcal{M}, \boldsymbol{b}_6, \boldsymbol{s}_6, z) \\ \mathtt{nd} \ \mathtt{procedure} \end{array} 
   9:
10: end procedure
  1: procedure funcF(\mathcal{M}, s)
                                           (\mathcal{M}, \phi, \boldsymbol{s}_1, f) \leftarrow \texttt{CXOR}(\mathcal{M}, \phi, \boldsymbol{s}, \phi, \{14, 20, 34, 43, 54\})
\mathbf{return} \ (\mathcal{M}, \boldsymbol{s}_1, f)
  2:
3:
   4: end procedure
  1: procedure funcG(\mathcal{M}, \boldsymbol{b})
2: (\mathcal{M}, \boldsymbol{b}_1, \phi, a_1) \leftarrow \text{CAN}
                                         coedure funcG(\mathcal{M}, \mathbf{b})

(\mathcal{M}, \mathbf{b}_1, \phi, a_1) \leftarrow \text{CAND}(\mathcal{M}, \mathbf{b}, \phi, \{2, 25\}, \phi)

(\mathcal{M}, \mathbf{b}_2, \phi, a_2) \leftarrow \text{CAND}(\mathcal{M}, \mathbf{b}_1, \phi, \{3, 5\}, \phi)

(\mathcal{M}, \mathbf{b}_3, \phi, a_3) \leftarrow \text{CAND}(\mathcal{M}, \mathbf{b}_2, \phi, \{7, 8\}, \phi)

(\mathcal{M}, \mathbf{b}_4, \phi, a_4) \leftarrow \text{CAND}(\mathcal{M}, \mathbf{b}_3, \phi, \{14, 21\}, \phi)

(\mathcal{M}, \mathbf{b}_5, \phi, a_5) \leftarrow \text{CAND}(\mathcal{M}, \mathbf{b}_4, \phi, \{16, 18\}, \phi)

(\mathcal{M}, \mathbf{b}_6, \phi, a_6) \leftarrow \text{CAND}(\mathcal{M}, \mathbf{b}_5, \phi, \{22, 24\}, \phi)

(\mathcal{M}, \mathbf{b}_7, \phi, a_7) \leftarrow \text{CAND}(\mathcal{M}, \mathbf{b}_6, \phi, \{26, 32\}, \phi)

(\mathcal{M}, \mathbf{b}_8, \phi, a_8) \leftarrow \text{CAND}(\mathcal{M}, \mathbf{b}_7, \phi, \{33, 36, 37, 38\}, \phi)

(\mathcal{M}, \mathbf{b}_9, \phi, a_9) \leftarrow \text{CAND}(\mathcal{M}, \mathbf{b}_8, \phi, \{10, 11, 12\}, \phi)
  3: 4: 5: 6: 7: 8: 9:
10:
                                               (\mathcal{M}, \boldsymbol{b}_9, \phi, a_9) \leftarrow \mathtt{CAND}(\mathcal{M}, \boldsymbol{b}_8, \phi, \{10, 11, 12\}, \phi)
                                                 \begin{array}{l} (\mathcal{M}, \mathbf{b}_{10}, \phi, a_{10}) \leftarrow \mathtt{CAND}(\mathcal{M}, \mathbf{b}_{9}, \phi, \{27, 30, 31\}, \phi) \\ (\mathcal{M}, \mathbf{b}_{11}, \phi, x) \leftarrow \mathtt{CXOR}(\mathcal{M}, \mathbf{b}_{10}, \phi, \{0, 13, 19, 35, 39\}, \phi) \\ (\mathcal{M}, g) \leftarrow \mathtt{xorf}(\mathcal{M}, x, a_{1}, \dots, a_{10}) \end{array} 
11:
12:
13:
14:
                                               return (\mathcal{M}, \boldsymbol{b}_{11}, g)
15: end procedure
```

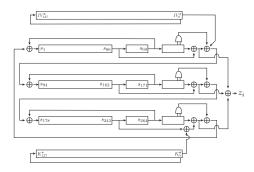


Fig. 2. Structure of Kreyvium

as Fig. 2 defined as follows:

$$\begin{split} t_1^{r-1} &\leftarrow s_{65}^{r-1} \oplus s_{92}^{r-1} \\ t_2^{r-1} &\leftarrow s_{161}^{r-1} \oplus s_{176}^{r-1} \\ t_3^{r-1} &\leftarrow s_{242}^{r-1} \oplus s_{287}^{r-1} \oplus K_0^{r-1} \\ z^{r-1} &\leftarrow t_1^{r-1} \oplus t_2^{r-1} \oplus t_3^{r-1} \\ t_1^{r-1} &\leftarrow t_1^{r-1} \oplus s_{90}^{r-1} \cdot s_{91}^{r-1} \oplus s_{170}^{r-1} \oplus IV_0^{r-1} \\ t_2^{r-1} &\leftarrow t_1^{r-1} \oplus s_{174}^{r-1} \cdot s_{175}^{r-1} \oplus s_{263}^{r-1} \\ t_3^{r-1} &\leftarrow t_3^{r-1} \oplus s_{285}^{r-1} \cdot s_{286}^{r-1} \oplus s_{68}^{r-1} \\ s^r[0, \dots, 92] &= (s_0^r, \dots, s_{92}^r) \leftarrow (t_3^{r-1}, s_{93}^{r-1}, \dots, s_{175}^{r-1}) \\ s^r[93, \dots, 176] &= (s_{93}^r, \dots, s_{176}^r) \leftarrow (t_1^{r-1}, s_{93}^{r-1}, \dots, s_{286}^{r-1}) \\ s^r[177, \dots, 287] &= (s_{177}^r, \dots, s_{287}^r) \leftarrow (t_2^{r-1}, s_{177}^{r-1}, \dots, s_{286}^{r-1}) \\ K^r &= (K_{127}^r, K_{126}^r, \dots, K_0^r) \leftarrow (K_0^{r-1}, K_{127}^{r-1}, K_{126}^{r-1}, \dots, K_1^{r-1}) \\ V^r &= (V_{127}^r, V_{126}^r, \dots, V_0^r) \leftarrow (V_0^{r-1}, V_{127}^{r-1}, V_{126}^{r-1}, \dots, V_1^{r-1}) \end{split}$$

After R initialization rounds, the output keystream is output as z^R, z^{R+1}, \ldots According to [6], full Kreyvium requires R = 1152 initialization rounds.

5.2 MILP Model of Kreyvium

The initialization division property assignments for key and IV bits can be assigned by calling Algorithm 12. The division property propagation corresponding to Kreyvium updating function can be described by the MILP model generated with Algorithm 13. Both algorithms have already been given in [3].

Algorithm 12 The initial DP structures for Kreyvium.

```
1: procedure IniDP(MILP model \mathcal{M}, cube index set I, non-cube IV assignment IV, initialization round number R, split set \Lambda.)

2: Declare the DP structures \mathbf{k}_x, \mathbf{k}_v both of length 128.

3: For i \in I, set \mathcal{M}.con \leftarrow \mathbf{k}_v[i].val = 1 and \mathbf{k}_v[i].F = \delta.

4: For i \notin I, set \mathcal{M}.con \leftarrow \mathbf{k}_v[i].val = 0 and assign the flag value according to IV[i]: \mathbf{k}_v[i].F = 1_c if IV[i] = 1 and \mathbf{k}_v[i].F = 0_c if IV[i] = 0.

5: Set \mathcal{M}.con \leftarrow \mathbf{k}_x[A].val = 0 and \mathbf{k}_x[A].F = 0_c. Set \mathbf{k}_x[j].F = \delta for j \notin \Lambda.

6: For j = 0, \ldots, 92, (\mathcal{M}, \mathbf{k}_K^0[127 - j], \mathbf{k}_s^0[j]) \leftarrow \operatorname{copyf}(\mathcal{M}, \mathbf{k}_x[j], 2).

7: For j = 93, \ldots, 127, \mathbf{k}_K^0[127 - j], \mathbf{k}_s^0[93 + j]) \leftarrow \operatorname{copyf}(\mathcal{M}, \mathbf{k}_v[j], 2).

8: For j = 0, \ldots, 127, (\mathcal{M}, \mathbf{k}_V^0[127 - j], \mathbf{k}_s^0[93 + j]) \leftarrow \operatorname{copyf}(\mathcal{M}, \mathbf{k}_v[j], 2).

9: For j = 221, \ldots, 287, \mathcal{M}.con \leftarrow \mathbf{k}_s^0[j].val = 0.

10: For j = 221, \ldots, 286, \mathbf{k}_s^0[j].F = 1_c and \mathbf{k}_s^0[287].F = 0_c.

11: return (\mathcal{M}, \mathbf{k}^0) where \mathbf{k}^0 = (\mathbf{k}_s^0, \mathbf{k}_V^0, \mathbf{k}_K^0).
```

Algorithm 13 MILP model description to the division property propagation for Kreyvium updating function.

```
1: procedure UpdDiv(the current MILP model \mathcal{M}, the DP structure k^{r-1} =
       (\mathbf{k}_s^{r-1}, \mathbf{k}_V^{r-1}, \mathbf{k}_K^{r-1}) where \mathbf{k}_s, \mathbf{k}_K and \mathbf{k}_V are of lengths 288, 128, 128 corresponding to the DP structures of \mathbf{s}^{r-1}, \mathbf{K}^{r-1} and \mathbf{V}^{r-1} respectively, the round number r
        (r = 1, 2, \ldots)
              (\mathcal{M}, \boldsymbol{x}) \leftarrow \mathtt{Core}(\mathcal{M}, \boldsymbol{k}_s^{r-1}, 90, 91, 65, 170, 92)
 2:
              (\mathcal{M}, \boldsymbol{k}_V^r, v^*) \leftarrow \text{LFSR}(\mathcal{M}, \boldsymbol{k}_V^{r-1})
 3:
              (\mathcal{M}, t_1) \leftarrow \mathtt{xorf}(\mathcal{M}, v^*, x_{92})
 4:
 5:
              x_{92} \leftarrow t_1
                                                                                                                   \triangleright Update the 93rd entry of \boldsymbol{x}
 6:
              (\mathcal{M}, y) \leftarrow \text{Core}(\mathcal{M}, x, 174, 175, 161, 263, 176)
 7:
              (\mathcal{M}, \boldsymbol{z}) \leftarrow \mathtt{Core}(\mathcal{M}, \boldsymbol{y}, 285, 286, 242, 68, 287)
              (\mathcal{M}, \boldsymbol{k}_K^r, k^*) \leftarrow \text{LFSR}(\mathcal{M}, \boldsymbol{k}_K^{r-1})
 8:
              (\mathcal{M}, t_3) \leftarrow \texttt{xorf}(\mathcal{M}, k^*, z_{287})
 9:
10:
               z_{288} \leftarrow t_3
                                                                                                                 \triangleright Update the 288th entry of \boldsymbol{z}
11:
               \boldsymbol{k}_s^r = \boldsymbol{z} \ggg 1
12:
               return \mathcal{M} and \mathbf{k}^r = (\mathbf{k}_s^r, \mathbf{k}_V^r, \mathbf{k}_K^r).
13: end procedure
 1: procedure LFSR(\mathcal{M}, x)
 2:
              (\mathcal{M}, a, o) \leftarrow \mathsf{copyf}(\mathcal{M}, x_0, 2)
 3:
              for all i \in \{0, 1, \dots, 126\} do
 4:
                     y_i = x_{i+1}
              end for
 5:
 6:
              y_{127} = a
 7:
              return (\mathcal{M}, \boldsymbol{y}, o)
 8: end procedure
 1: procedure Core(\mathcal{M}, \boldsymbol{x}, i_1, i_2, i_3, i_4, i_5)
              (\mathcal{M}, y_{i_1}, y'_{i_1}) \leftarrow \mathtt{copyf}(\mathcal{M}, x_{i_1}, 2).
 2:
              (\mathcal{M}, y_{i_2}, y'_{i_2}) \leftarrow \mathsf{copyf}(\mathcal{M}, x_{i_2}, 2).
 3:
              (\mathcal{M}, z_1) \leftarrow \mathtt{andf}(\mathcal{M}, y'_{i_1}, y'_{i_2}).
 4:
              (\mathcal{M}, y_{i_3}, y'_{i_3}) \leftarrow \text{copyf}(\mathcal{M}, x_{i_3}, 2).
 5:
              (\mathcal{M}, y_{i_4}, y'_{i_4}) \leftarrow \mathsf{copyf}(\mathcal{M}, x_{i_4}, 2).
 6:
 7:
              (\mathcal{M}, y_{i_5}) \leftarrow \operatorname{xorf}(\mathcal{M}, z_1, y'_{i_3}, y'_{i_4}, x_{i_5}).
              for all i \in [288) \setminus \{i_1, i_2, i_3, i_4, i_5\} do
 8:
 9:
                     y_i = x_i
               end for
10:
               return (\mathcal{M}, y)
11:
12: end procedure
```

6 Details of Acorn

6.1 Specification of Acorn

ACORN is an authenticated encryption algorithm and is one of the finalists in CAESAR competition [7]. The structure is based on NLFSR, and the internal state is represented by a 293-bit state $\mathbf{s} = (s_0, \dots, s_{292})$. There are two component functions, $ks = KSG128(\mathbf{s})$ and $f = FBK128(\mathbf{s})$, in the update function, and each is defined as

$$ks = s_{12} \oplus s_{154} \oplus maj(s_{235}, s_{61}, s_{193}) \oplus ch(s_{230}, s_{111}, s_{66}),$$

 $f = s_0 \oplus (s_{107} \oplus 1) \oplus maj(s_{244}, s_{23}, s_{160}) \oplus (ca \wedge s_{196}) \oplus (cb \wedge ks),$

where ks is used as the key stream, and maj and ch are defined as

$$maj(x,y,z) = (x \land y) \oplus (x \land z) \oplus (y \land z),$$

$$ch(x,y,z) = (x \land y) \oplus ((x \oplus 1) \land z).$$

Initialized as $s^0 = 0$, the following updating function is called for round number r = 1, ..., R:

$$s_{289}^{r-1} \leftarrow s_{289}^{r-1} \oplus s_{235}^{r-1} \oplus s_{230}^{r-1}$$
 (22)

$$s_{230}^{r-1} \leftarrow s_{230}^{r-1} \oplus s_{196}^{r-1} \oplus s_{193}^{r-1}$$
 (23)

$$s_{193}^{r-1} \leftarrow s_{193}^{r-1} \oplus s_{160}^{r-1} \oplus s_{154}^{r-1}$$
 (24)

$$s_{154}^{r-1} \leftarrow s_{154}^{r-1} \oplus s_{111}^{r-1} \oplus s_{107}^{r-1} \tag{25}$$

$$s_{107}^{r-1} \leftarrow s_{107}^{r-1} \oplus s_{66}^{r-1} \oplus s_{61}^{r-1} \tag{26}$$

$$s_{61}^{r-1} \leftarrow s_{61}^{r-1} \oplus s_{23}^{r-1} \oplus s_0^{r-1}$$
 (27)

$$ks^{r-1} = KSG128(s^{r-1}) (28)$$

$$f^{r-1} = FBK128(s^{r-1}, ca, cb)$$
(29)

$$\mathbf{s}^{r} = (s_{0}^{r}, s_{1}^{r}, \dots, s_{292}^{r}) \leftarrow (s_{1}^{r-1}, s_{2}^{r-1}, \dots, S_{292}^{r-1}, f^{r-1} \oplus \mathbf{m}[r-1])$$
(30)

The full Acorn requires R = 1792. The vector m is of length R:

- The first 256 entries are assigned as $m[j] = x_j$ and $m[128 + j] = v_j$ for $j \in [128)$.
- For $r \ge 256$: if $128|r, m[r] = x_{r \mod 128} + 1$; otherwise, $m[r] = x_{r \mod 128}$.

After the R initialization rounds, the 1st output keystream bit is simply ks^r generated by the process from (22) to (28). Of course, the associated data is always loaded before the output of the key stream. But in our attack, the initialization round number R is smaller than 1792 so we do not consider the associate data. This is the same setting with [8,3]. Fig. 3 shows the structure of ACORN and more detailed specification of ACORN can be found in [9].

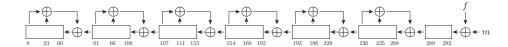


Fig. 3. Structure of ACORN

6.2 MILP Model of Acorn

According to the description in Section 6.1, the MILP model describing the division property propagation of ACORN updating function can be constructed as Algorithm 15. The subroutines are described in detail: as Algorithm 16, 17 and 18. xorFB is called for the LFSR updating (22) (Algorithm 17); ksg128 and fbk128 corresponds to KSG128 and FBK128 respectively (Algorithm 18); maj and ch are also handled (Algorithm 16). Since $s^0 = 0$, k_s^0 can be defined without the DP structures of key and IV bits. But, in addition to the division property of the internal state k_s^{r-1} , Algorithm 15 also requires k_m , the division property of m. Such k_m is determined at the very beginning of model construction as IniDP in Algorithm 14 This is identical to the MILP descriptions in [3].

Algorithm 14 The initial DP structures for Acorn.

```
1: procedure IniDP(MILP model \mathcal{M}, cube index set I, non-cube IV assignment IV, initialization
      round number R, split set \Lambda.)
            Declare the DP structures k_x, k_v both of length 128.
 3:
            For i \in I, set \mathcal{M}.con \leftarrow \mathbf{k}_v[i].val = 1 and \mathbf{k}_v[i].F = \delta.
 4:
            For i \notin I, set \mathcal{M}.con \leftarrow k_v[i].val = 0 and assign the flag value according to IV[i]: k_v[i].F =
      1c if IV[i] = 1 and k_v[i].F = 0_c if IV[i] = 0.

Set \mathcal{M}.con \leftarrow k_x[A].val = 0 and k_x[A].F = 0_c. Set k_x[j].F = \delta for j \notin A.

For j \in [128), set k_m[j] \leftarrow k_x[j] and k_m[128 + j] \leftarrow k_v[j].
 6:
7:
8:
            for r = 256, ..., R - 1 do
                  (\mathcal{M}, t_1, t_2) \leftarrow \mathsf{copyf}(\mathcal{M}, \mathbf{k}_m[r \mod 128], 2).
                 if r \mod 128 = 0 then

Declare DP structure o as \mathcal{M}.con \leftarrow o.val = 0 and o.F = 1_c.
10:
11:
12:
13:
14:
                        Compute (\mathcal{M}, t_3) \leftarrow \text{xorf}(\mathcal{M}, o, t_2).
                        Update \mathbf{k}_m[r \mod 128] \leftarrow t_1 and \mathbf{k}_m \leftarrow \mathbf{k}_m || t_3
                        Update \mathbf{k}_m[r \mod 128] \leftarrow t_1 \text{ and } \mathbf{k}_m \leftarrow \mathbf{k}_m || t_2.
15:
                  end if
16:
             end for
17:
            return (\mathcal{M}, \boldsymbol{k}_m).
18: end procedure
```

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Algorithm 15 MILP model for ACORN updating function

```
1: procedure UpdDiv(The current MILP model \mathcal{M}, the DP structures for s^{r-1} and m denoted as
          {m k}_s^{r-1} and {m k}_m respectively, round number r (r=1,\ldots,R) )
                   (\mathcal{M}, \boldsymbol{T}) \leftarrow \texttt{xorFB}(\mathcal{M}, \boldsymbol{k}_s^{r-1}, 289, 235, 230) \\ (\mathcal{M}, \boldsymbol{U}) \leftarrow \texttt{xorFB}(\mathcal{M}, \boldsymbol{T}, 230, 196, 193)
 3: 4: 5: 6: 7: 8: 9:
                   (\mathcal{M}, \boldsymbol{V}) \leftarrow \texttt{xorfb}(\mathcal{M}, \boldsymbol{U}, 193, 160, 154) \\ (\mathcal{M}, \boldsymbol{W}) \leftarrow \texttt{xorfb}(\mathcal{M}, \boldsymbol{V}, 154, 111, 107) \\ (\mathcal{M}, \boldsymbol{X}) \leftarrow \texttt{xorfb}(\mathcal{M}, \boldsymbol{W}, 107, 66, 61)
                    (\mathcal{M}, \mathbf{Y}) \leftarrow \text{xorFB}(\mathcal{M}, \mathbf{X}, 61, 23, 0)
                   (\mathcal{M}, \mathbf{Z}, ks) \leftarrow \text{ksg128}(\mathcal{M}, \mathbf{Y})

(\mathcal{M}, \mathbf{A}, f) \leftarrow \text{fbk128}(\mathcal{M}, \mathbf{Z}, ks)
10:
                    for i=0 to 291 do
                             \boldsymbol{k}_s^r[i] = A_{i+1}
11:
12:
                     end for
13:
                    (\mathcal{M}, \boldsymbol{k}_s^r[292]) \leftarrow \operatorname{xorf}(\mathcal{M}, ks, f, \boldsymbol{m}[r-1]).
14:
                    return (\mathcal{M}, \boldsymbol{k}_{s}^{r}).
15: end procedure
```

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Algorithm 16 MILP model for maj and ch in Acorn

```
\textbf{procedure} \; \texttt{maj}(\mathcal{M}, \boldsymbol{X}, i, j, k)
 2:
3:
4:
5:
6:
                    if X_i.F \oplus X_j.F = 0_c then (\mathcal{M}, Y_i, a) \leftarrow \mathsf{copyf}(\mathcal{M}, X_i)
                               (\mathcal{M}, Y_j, b) \leftarrow \mathtt{copyf}(\mathcal{M}, X_j)
                   (\mathcal{M}, 3), \emptyset \leftarrow \text{supp}(\mathcal{M}, 3), \emptyset

(\mathcal{M}, 0) \leftarrow \text{sudf}(\mathcal{M}, a, b)

Y_s = X_s \text{ for all } s \in \{0, \dots, 292\} - \{i, j\}

else if X_i.F \oplus X_k.F = 0_c then
 7:
8:
                              (\mathcal{M}, Y_i, a) \leftarrow \text{copyf}(\mathcal{M}, X_i)

(\mathcal{M}, Y_k, c) \leftarrow \text{copyf}(\mathcal{M}, X_k)
9:
10:
                       \begin{array}{l} (\mathcal{M},o) \leftarrow \operatorname{andf}(\mathcal{M},a,c) \\ Y_s = X_s \text{ for all } s \in \{0,\ldots,292\} - \{i,k\} \\ \text{else if } X_j.F \oplus X_k.F = 0_c \text{ then} \end{array} 
11:
12:
                                (\mathcal{M}, Y_j, b) \leftarrow \mathtt{copyf}(\mathcal{M}, X_j)
13:
14:
                                 (\mathcal{M}, Y_k, c) \leftarrow \mathsf{copyf}(\mathcal{M}, X_k)
                                \begin{array}{l} (\mathcal{M}, a_k, c) \leftarrow \mathsf{andf}(\mathcal{M}, b, c) \\ (\mathcal{M}, o) \leftarrow \mathsf{andf}(\mathcal{M}, b, c) \\ Y_s = X_s \text{ for all } s \in \{0, \dots, 292\} - \{j, k\} \end{array} 
15:
16:
17:
18:
                                 (\mathcal{M}, Y_j, a_1, a_2) \leftarrow \mathsf{copyf}(\mathcal{M}, X_i)
                                (\mathcal{M}, Y_j, b_1, b_2) \leftarrow \operatorname{copyf}(\mathcal{M}, X_j)

(\mathcal{M}, Y_k, c_1, c_2) \leftarrow \operatorname{copyf}(\mathcal{M}, X_k)
19:
20:
21:
22:
                                (\mathcal{M}, a) \leftarrow \mathtt{andf}(\mathcal{M}, a_1, b_1)
                                 (\mathcal{M},b) \leftarrow \mathtt{andf}(\mathcal{M},a_2,c_1)
23:
24:
                                 (\mathcal{M},c) \leftarrow \mathtt{andf}(\mathcal{M},b_2,c_2)
                                (\mathcal{M}, o) \leftarrow \texttt{xorf}(\mathcal{M}, a, b, c)
25:
                                 Y_s = X_s for all s \in \{0, \dots, 292\} - \{i, j, k\}
26:
27:
                      return (\mathcal{M}, Y, o)
28: end procedure
 1: procedure ch(\mathcal{M}, \mathbf{X}, i, j, k)
                   if X_i.F = 0_c or X_j.F \oplus X_k.F = 0_c then
 3:
                              (\mathcal{M}, Y_k, o) \leftarrow \mathsf{copyf}(\mathcal{M}, X_k)
                              Y_s = X_s \text{ for all } s \in \{0, \dots, 292\} - \{k\}
                    else if X_i.F = 1_c then
                             (\mathcal{M}, Y_j, o) \leftarrow \mathsf{copyf}(\mathcal{M}, X_j)

Y_s = X_s \text{ for all } s \in \{0, \dots, 292\} - \{j\}
                              \begin{array}{l} (\mathcal{M},Y_j,a_1,a_2) \leftarrow \operatorname{copyf}(\mathcal{M},X_i) \\ (\mathcal{M},Y_j,b_1) \leftarrow \operatorname{copyf}(\mathcal{M},X_j) \\ (\mathcal{M},Y_k,c,c_1) \leftarrow \operatorname{copyf}(\mathcal{M},X_k) \\ (\mathcal{M},a) \leftarrow \operatorname{andf}(\mathcal{M},a_1,b_1) \end{array} 
10:
11:
                                (\mathcal{M}, a) \leftarrow \operatorname{andf}(\mathcal{M}, a_1, b_1)

(\mathcal{M}, b) \leftarrow \operatorname{andf}(\mathcal{M}, a_2, c_1)

(\mathcal{M}, o) \leftarrow \operatorname{xorf}(\mathcal{M}, a, b, c)
13:
14:
15:
                                 Y_s = X_s \text{ for all } s \in \{0, \dots, 292\} - \{i, j, k\}
16:
                      end if
                      return (M, Y, o)
17:
18: end procedure
```

Algorithm 17 MILP model for LFSR in ACORN

```
1: procedure \operatorname{xorFB}(\mathcal{M}, X, i, j, k)

2: (\mathcal{M}, Y_j, a) \leftarrow \operatorname{copyf}(\mathcal{M}, X_j)

3: (\mathcal{M}, Y_k, b) \leftarrow \operatorname{copyf}(\mathcal{M}, X_k)

4: (\mathcal{M}, Y_i) \leftarrow \operatorname{xorf}(\mathcal{M}, a, b, X_i)

5: Y_s = X_s for all s \in \{1, \dots, 293\} - \{i, j, k\}

6: return (\mathcal{M}, Y)

7: end procedure
```

Algorithm 18 MILP model for ksg128 and fbk128 in ACORN

```
1: procedure ksg128(\mathcal{M}, X)

2: (\mathcal{M}, A_{12}, x_1) \leftarrow copyf(\mathcal{M}, X_{154})

4: A_t = X_t for all t \in \{0, \dots, 292\} - \{12, 154\}

5: (\mathcal{M}, B, x_3) \leftarrow maj(\mathcal{M}, A, 235, 61, 193)

6: (\mathcal{M}, Y, x_4) \leftarrow ch(\mathcal{M}, B, 230, 111, 66)

7: (\mathcal{M}, z) \leftarrow vorf(\mathcal{M}, x_1, x_2, x_3, x_4)

8: return (\mathcal{M}, Y, z)

9: end procedure

1: procedure fbk128(\mathcal{M}, X, ks)

2: (\mathcal{M}, A_{0}, x_1) \leftarrow copyf(\mathcal{M}, X_{0})

3: (\mathcal{M}, A_{107}, x_2) \leftarrow copyf(\mathcal{M}, X_{107})

4: (\mathcal{M}, A_{196}, x_3) \leftarrow copyf(\mathcal{M}, X_{196})

5: A_t = X_t for all t \in \{0, \dots, 292\} - \{0, 107, 196\}

6: (\mathcal{M}, Y, x_4) \leftarrow maj(\mathcal{M}, A, 244, 23, 160).

7: Declare a variable o s.t. o.val = NULL, o.F = 1_c. \triangleright The complementary of A_{107}.

8: (\mathcal{M}, z) \leftarrow vorf(\mathcal{M}, x_1, x_2, x_3, x_4, ks, o)

9: return (\mathcal{M}, Y, z)

10: end procedure
```