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THESIS

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Abstract

Non-destructive evaluation (NDE) and fatigue damage assessment are crucial for quality control of remanufacturing processes. However, critical challenges exist in the development of NDE techniques for used components: individual NDE technology is only sensitive to specific fatigue conditions; analytics methods are lacking for quantitatively measuring accumulated mechanical damage and conducting prognostics in an early fatigue stage. In this paper, we propose a machine learning-based NDE technology by combining the strengths of linear ultrasonic (LU) and nonlinear ultrasonic (NLU) testings to detect defects at various length scales. Besides, a remaining useful life (RUL) estimation framework with hierarchical classifiers and S-N curves for identifying fatigue damage levels and inferring residual fatigue life of recycled parts is developed. In addition, regression models for estimating residual stress and full width at half maximum (FWHM) of x-ray diffraction (XRD) peak by ultrasonic testings are investigated. The effectiveness of the proposed methods are demonstrated using life cycle fatigue testing data for 5052-H32 aluminum alloy. This research aims to provide a screening system for end-of-life (EoL) products and lead to an increasing usage of secondary materials for remanufacturing and high-quality products.

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To my parents, for their love and support.

Acknowledgments

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LIST OF ABBREVIATIONS

Chapter 1

Introduction

Remanufacturing has increasingly received attention because of its energy-saving, eco-friendly, and cost-efficient characteristics. Remanufactured products have been presented in automotive, aerospace, and industrial machinery industry. For example, in the automotive industry, Ford Motor has been recycled and remanufactured components such as engine, transmission, car body, etc., as a long-term tradition. In short, remanufacturing is a process of returning a used product to at least original performance specification from the customers' perspective. To achieve this, secondary materials screening for quality control in remanufacturing process by estimating the quantities of interest, e.g., remaining useful life (RUL) and residual stress in incoming recycled end-of-life (EoL) products, becomes an essential step and is crucial in increasing the usage of recycled materials.

In recycled components, material fatigue damage is universally presented and it is one of the most influential factors that determines the RUL of a used product. Material fatigue has resulted in many catastrophic accidents in the history and has been studied for many decades; however, the fatigue damage level is hard to be monitored in real world environments due to the stochastic nature of fatigue behaviors and undetermined loading conditions [1], which is a critical issue to be addressed.

To quantitatively study fatigue damage in materials, non-destructive evaluation (NDE) methods have been developed [2]. NDE, also known as non-destructive testing (NDT), is a technique to evaluate material properties without causing damage to the testing parts. For instance, linear ultrasonic (LU) and nonlinear ultrasonic (NLU) testings send ultrasonic waves which propagate in a material and analyze the response signals to evaluate material degradation. Although there exist a variety of NDE techniques, each of these methods is only sensitive to a few specific fatigue conditions and is limited to detecting defects in certain length scales. Figure 1.1 illustrates the

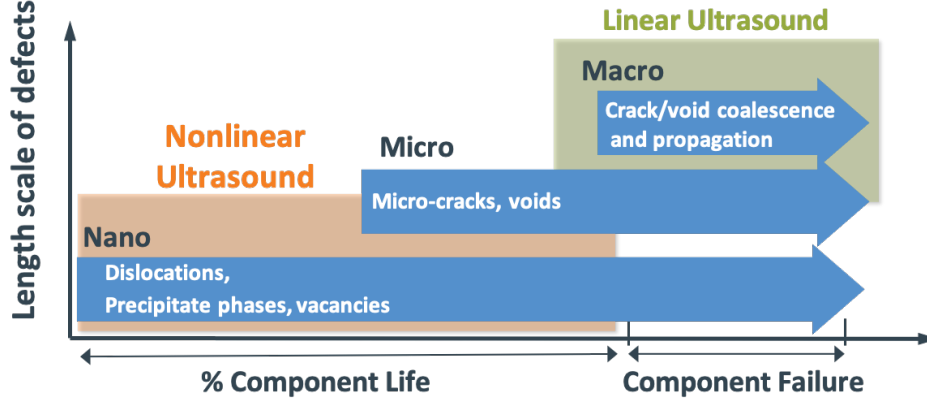


Figure 1.1: Capability of defect detection for LU and NLU testings

detectable length scales of LU and NLU testings, where LU testing is robust at detecting macro-scale defects. In contrast, NLU techniques measure non-linear material parameters to detect defects which are orders of magnitude smaller than the probing wavelength (in e.g. stainless steels, typically on the order of 1mm), providing an important data source of early stage damage characterization.

There is a lack of research on the estimation and prognosis of RUL of EoL components in the remanufacturing industry even though, with state-of-the-art machine learning (ML) models, RUL estimation has been successfully applied in many industrial components, e.g., bearing [3, 4, 5], gear [6], turbofan engine [7, 8, 9], and lithium-ion battery [7, 10, 11]. Unlike the examples in the literature, the possible difficulties for RUL estimation in remanufacturing are: *a)* Continuous and in-situ measurements are not available, i.e., unable to know the historical measurements of a recycled component. *b)* Environmental noises can affect the performance of in-situ sensors as well as the built algorithms. *c)* The data in this field is hard to collect and thus is not adequate to build robust data-driven models.

In this research, we proposed a ML-based NDE methodology for the quantification and prognostics of accumulated fatigue damage in recycled materials. First, we integrate LU and NLU testings to leverage the strength of each individual sensor, which has the potential of estimating different fatigue conditions simultaneously. Second, with multi-output hierarchical classifiers, a RUL estimation framework is developed by predicting the loading condition as well as the percentage of fatigue life that a component has undergone,

and then the RUL is estimated from a S-N curve. In the proposed approach, both ultrasonic testings serve as ex-situ measurement methods to predict the loading history of a recycled component. Therefore, without continuous monitoring data of a component from its healthy state, the RUL can be inferred by using the current measurement only. Besides, a residual stress measurement method based on the proposed NDE methodology and ML techniques is also investigated, which shows the potential of being an efficient method in terms of test speed and cost.

This research is targeted to metals that are widely used in a number of industry sectors. In this preliminary study, the target material is 5052-H32 aluminum alloy which is widely used in truck and auto industries. Life cycle fatigue testings were conducted in different settings to construct a comprehensive database for fatigue progression in the target material. The fatigued specimens were later examined by ultrasonic as well as X-ray diffraction (XRD) measurement. Here, XRD measurements serve as the calibration for residual stress and full width at half maximum (FWHM) estimation. After that, the proposed NDE methodology and prediction framework were developed and tested on the collection of fatigued samples.

The goal of this research is to not only enable effective materials screening but also provide valuable information for the process optimization and control of downstream remanufacturing processes. As such, an effective NDE method that is applicable on the factory floor will lead to greater material recycling and improved quality of products that are produced using recycled materials.

The remaining of this thesis is organized as follows. Chapter 2 provides the literature review of the related topics. Chapter 3 describes the experimental setup and procedures including the design of experiments, life cycle fatigue testing, ultrasonic and XRD measurements. Chapter 4 introduces the ML model development procedure used in both Chapter ?? and Chapter 6 where the proposed RUL estimation framework and residual stress measurement method are presented, respectively, with the case study on our fatigue test dataset. Finally, in Chapter 7, the contributions of this thesis are summarized and future research directions are mentioned.

Chapter 2

Literature Review

2.1 Fatigue damage assessment

Fatigue damage is a critical issue in engineering due to the concern of safety, and accurate estimation of fatigue damage has been a decades-long study in areas such as remanufacturing, transportation equipment, and structural health monitoring. [Santecchia et al.](#) provides an extensive overview of fatigue damage models for metals from various perspectives including linear damage rule, continuum damage mechanics, multi-axial as well as variable amplitude loading, energy-based methods, and stochastic-based approaches. However, none of these can be universally accepted because of the complexity of fatigue damage behaviors in reality [\[1\]](#).

2.2 NDE of fatigue damage

In many practical scenarios, non-destructive evaluation/testing has been adopted to quantify fatigue damage by investigating the correlation between measurement data and material deterioration [\[12\]](#). Some common NDE techniques for evaluating fatigue damage are infrared thermography [\[13\]](#), holographic interferometry [\[14\]](#), microwave [\[15\]](#), ultrasonic testing, magnetic methods [\[16\]](#), acoustic emission approaches, and electrical resistance methods. While numerous NDE methods are available, each of these techniques has its own characteristics and thus is only sensitive to only one or a few specific applications. Recently, [Wisner et al.](#) presented a review of NDE in fatigue and suggested that when combined, NDE methods have been shown to improve the robustness of damage detection by complementing each other [\[2\]](#).

2.3 LU and NLU applications

Among various NDE techniques, LU and NLU has demonstrated its applicability in fatigue damage assessment [17, 18, 19, 20], defect classification [21, 22], and residual stress measurement [23, 24, 25] in materials. In terms of fatigue damage, Joshi and Green showed that ultrasonic attenuation is an indicator of fatigue damage in experiments performed on aluminum and steel [17]. Nagy introduced an experiment setup to monitor the second-order acoustic-elastic coefficient during the cyclic loading test, and demonstrated that the change in nonlinear parameter, which monotonically increases as a function of number of cycles applied, is substantially more than the corresponding change in linear parameters, wave velocity and attenuation [18]. Matlack et al. presented a comprehensive review of second harmonic generation (SGM) measurements for the NDE of fatigue, thermal aging, and radiation-induced damage [19]. An analytical model developed by Cantrell used a material nonlinearity parameter β extracted from SGM to quantify the level of dislocation substructures and cracks that evolve during cyclic fatigue of planar slip metals, which presented the potential of using SGM to assess the remaining life of the material. Nonetheless, practical implementation requires that the loading and environmental conditions of fatigue are given [20].

2.4 ML-aided NDE

In recent years, machine learning has been commonly applied to NDE techniques in the automated recognition of patterns in testing signals and the outcome of interest such as fatigue damage levels, defect types, and welding quality. For example, Baumgartl et al. implemented a CNN-based in-situ thermographic monitoring system to identify defects produced during the additive manufacturing process of H13 steel [26]. An optical interferometry-based real-time quality prediction system using ANN in laser beam welding was developed by Stadter et al. [27]. Loutas et al. proposed a framework utilizing AE signals for fatigue damage prognostics in composite materials with hidden semi Markov model and Bayesian neural network [28]. For ultrasonic testings, various features were engineered through fast Fourier transform,

wavelet transform, and statistical methods, and fed into ML models for defect classification in [21, 22]. ML-aided NDE are fast growing and more applications such as RUL estimation and residual stress measurement exist in the literature.

2.5 RUL estimation

RUL estimation has received broad interests these days in many applications such as bearing [3, 4, 5], gear [6], turbofan [7, 8, 9], and lithium-ion battery [7, 10, 11]. However, there is relatively fewer recent RUL researches directly studying material fatigue. In early years, Ray and Tangirala presented a nonlinear stochastic model for predicting fatigue life in 2024-T3 aluminum alloy based on extended Kalman filter [29]. Peng et al. proposed a Bayesian updating framework based on a physics-based fatigue crack growth model with crack length estimated from piezoelectric sensor signals by a regressor to perform the lap joint fatigue life prognosis for 2024-T3 aluminum alloy [30]. Banerjee et al. recently utilized optical and acoustic NDE techniques accompanied with Kalman filter and particle filter to predict RUL in glass fiber reinforced polymer [31]. In the literature, most of the RUL research papers associated with fatigue damage rely on physical fatigue modeling and state-space models, e.g., particle filter method. Since physical models contain assumptions and approximation, physical models are limited in complex application scenarios.

Although lots of data-driven approaches for RUL estimation existed [32, 33] especially as deep learning has become increasingly prevalent these years [34], the successful cases generally require a sufficient amount of data for training the state-of-the-art models [4, 5, 8, 9, 11]. In the field of estimating residual fatigue life, Lim et al. developed a data-driven RUL prognosis technique with an artificial neural network (ANN) and nonlinear ultrasonic measurements for 6061-T6 aluminum [35]. There is, still, much fewer data-driven researches available for residual fatigue life estimation.

Moreover, we barely found methods that makes RUL estimation by taking only the measurement at current time step as input, which is the situation we envision for our application on the screening process in the remanufacturing industry. The existing examples using approaches such as Kalman filter

[29], particle filter [31], and recurrent neural network [9] make predictions based on successive measurements. To tackle the lack of previous observations, one relevant research is Mazhar et al.'s work on EoL products, where the authors integrated Weibull analysis and an ANN model taking a single measurement to assess the RUL of components for reuse. Due to the lack of data, nonetheless, synthetic data is needed for training the ANN in this work [36].

2.6 Residual stress measurement with ultrasounds

Residual stresses are often existed in mechanical components and have been recognized as a main factor of fatigue failure [37]. Residual stress measurement, therefore, has been an active area. A review of recent progress of residual stress measurement from GUO et al. provides a comparison between a variety of methods from the aspects of resolution, applicable object, and limitations [38]. Specifically for ultrasonic testing, the theory of acoustoelastic effect (the presence of stress in solids causes changes in the speeds of ultrasonic waves) for measurement of residual stress has been studied in [23]. Tanala et al. compared ultrasonic velocity measurements with X-ray diffraction in determining residual stress across a steel pipe and a alloy plate, which stated that ultrasonic techniques are more efficient in test volume and the cost of equipment [24]. In recent studies, Liu et al. implemented a testing system to analyze the accuracy and feasibility of residual stress measurement in 6063-T4 aluminum alloy by ultrasonic longitudinal critically refracted wave based on acoustoelastic theory [25].

Chapter 3

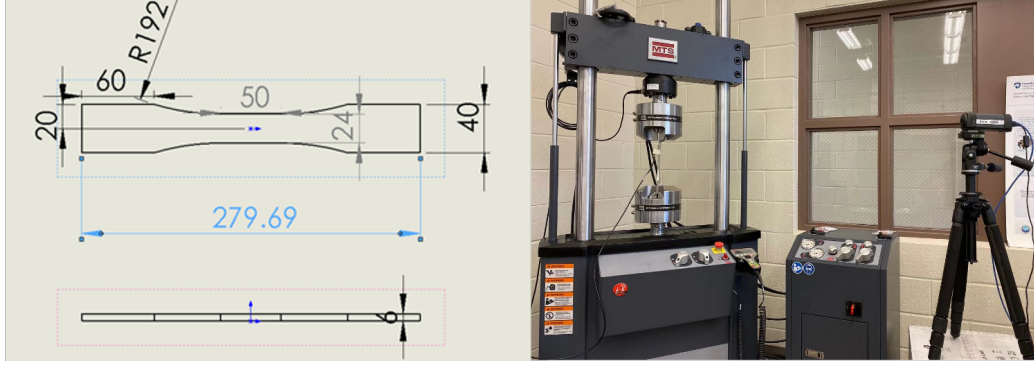
Experimental Dataset

This chapter describes the dataset and the experimental procedure used in this research for developing machine learning applications. First, the cyclic fatigue testing was conducted till the fracture of a specimen to acquire the fatigue characteristics of a material. Second, to mimic the scenarios in the remanufacturing industry, interrupted fatigue testing was utilized to produce specimens at different fatigue levels as a representation of end-of-life products. Then, linear and nonlinear ultrasound measurements are used to evaluate the fatigue damage of those specimens stopped at the predetermined number of cycles in the interrupted fatigue test. Besides, the residual stress and full width at half maximum data from X-ray diffraction are also presented.

3.1 Life cycle fatigue testing

The life cycle fatigue testing aims to collect fatigue life data to understand the fatigue behavior of our targeted material. The fatigue life of a material is defined as the total number of cycles that a material can sustain under a specified loading condition. In order to develop the S-N curve of a material, the material is tested at different loading stress amplitudes, and the fatigue test is repeated multiple times for each loading stress amplitude to account for the variance of fatigue life.

The fatigue testing in this research is led by Prof. Li's group at the Penn State University. The targeted material is 5052-H32 aluminum alloy which is widely used for car body construction in the automotive industry. Figure 3.1 shows the dimension of the specimen and the test machine. Three loading amplitudes, 11.7, 12.7, and 14.7 kN for the cyclic fatigue testing are selected to develop the S-N curve which is shown in Figure 3.2.



(a) Schematic of the 5052-H32 aluminum alloy specimen

(b) MTS 100KN Landmark fatigue testing system at Prof. Jingjing li's lab

Figure 3.1: Life cycle fatigue testing setup

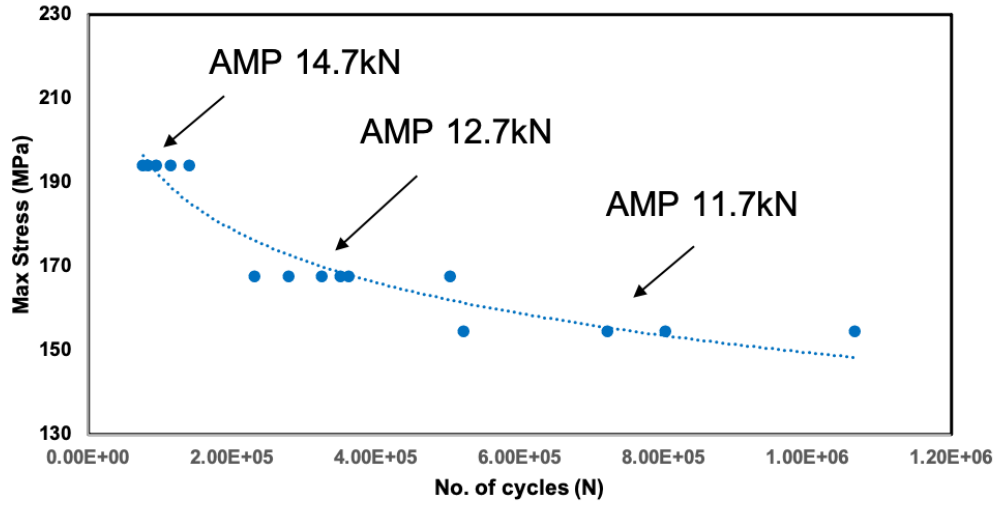


Figure 3.2: S-N curve for 5052-H32 aluminum alloy

3.2 Interrupted fatigue testing

The purpose of performing interrupted fatigue testing is to produce specimens at various fatigue levels by stopping the testing at several predetermined number of cycles. Considering the material cost and the time spent, the number of cycles applied to the specimens is set to be two levels, 33% and 67% fatigue life corresponding to the three loading amplitudes, 11.7, 12.7, and 14.7 kN. These specimens are used to represent the end-of-life products having different fatigue damage levels from the remanufacturing industry. Besides, three specimens without going through fatigue testing, i.e., 0% fatigue life, are included as specimens at the healthy state. The summary of

Table 3.1: Summary of the interrupted fatigue testing specimens

Specimen ID	Loading Amplitude (kN)	Percentage of Fatigue Life (%)	Max Stress Applied (MPa)
1	11.7	33	176
2	11.7	33	176
3	11.7	67	176
4	11.7	67	176
5	12.7	33	195
6	12.7	33	195
7	12.7	67	195
8	12.7	67	195
9	14.7	33	221
10	14.7	33	221
11	14.7	67	221
12	14.7	67	221
13	—	0	—
14	—	0	—
15	—	0	—

the interrupted fatigue testing specimens is presented in Table 3.1

3.3 Linear and nonlinear ultrasound measurements

In this research, linear ultrasonic (LU) and nonlinear ultrasonic (NLU) testing serve as the two main NDE methods for measuring the accumulated fatigue damage in the specimens. The ultrasonic testing is led by Prof. Matlack's group, and the testing system is shown in Figure 3.3. The LU and NLU measurements are both 1-D time domain signals, but the two approaches differ based on different theories and parameters, e.g., excitation wave shape, frequency, amplitude. Examples of LU and NLU signals are presented in Figure 3.4.

LU and NLU measurements were collected at nine locations in a specimen as illustrated in Figure 3.5, and each location was measured three times to understand the measurement repeatability. As a result, for each specimen, there are $9 \times 3 = 27$ signal profiles produced.

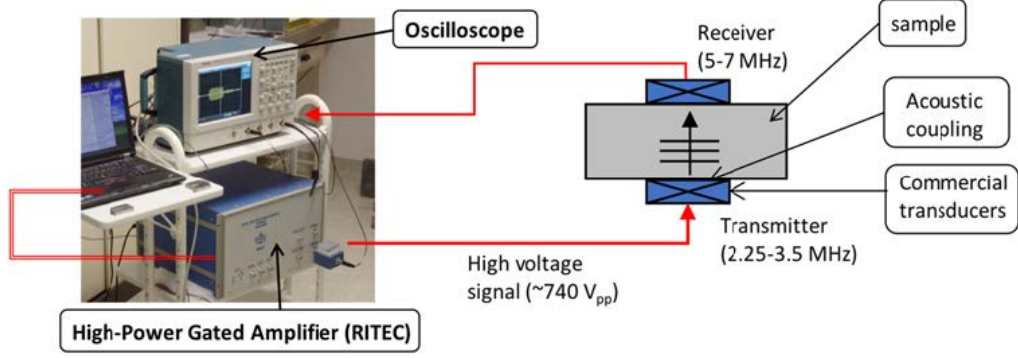


Figure 3.3: Experimental setup for LU and NLU at Prof. Matlack's Lab

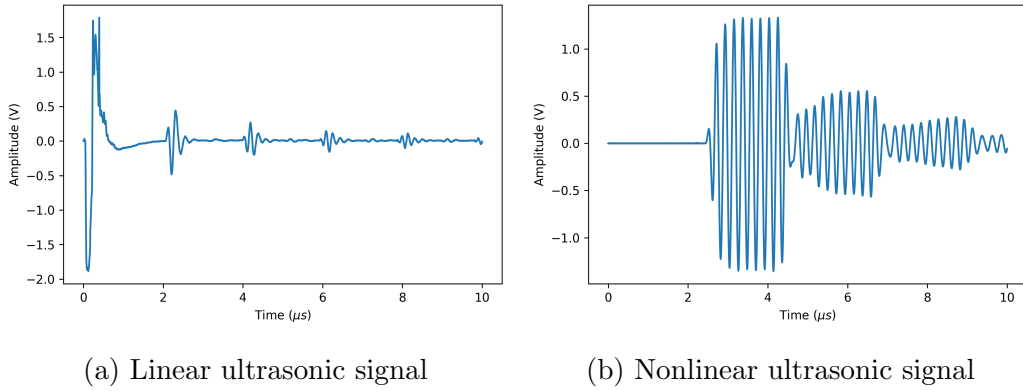


Figure 3.4: Examples of linear and nonlinear ultrasonic signals

3.4 X-ray diffraction measurement

Another quantity of interest, residual stress, is measured by X-ray diffraction (XRD) in this research. Residual stress is known to be associated with fatigue behaviors such as crack initiation and propagation. Besides, the full width at half maximum height (FWHM) of the diffraction peak in XRD is also extracted. Prof. Li's group performed the XRD measurements for a subset of specimens in the interrupted fatigue testing. The XRD data is used in the regression tasks in Chapter 6 as target variables.

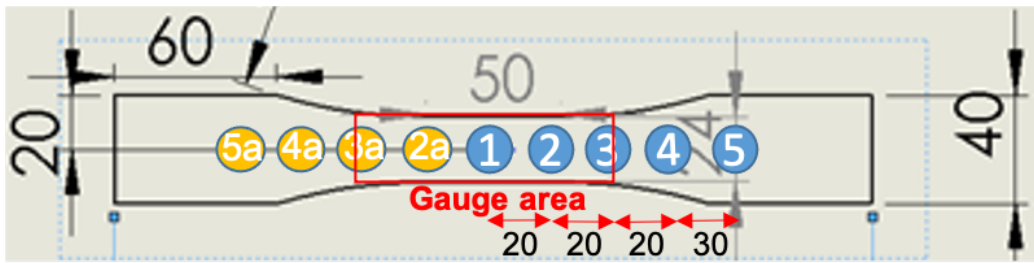


Figure 3.5: Schematic of the measurement locations for LU and NLU measurements. (The unit of length is in mm)

Chapter 4

Model Development

This chapter introduces a model development procedure used in both classification tasks in Chapter ?? and regression tasks in Chapter 6. The procedure involves: *a)* signal pre-processing, *b)* feature generation, *c)* feature selection, *d)* model training, *e)* model validation, and *f)* hyperparameter tuning, as shown in Figure .

4.1 Signal pre-processing

It is essential to reduce noises and extract regions of interest in signals by signal processing before we perform other analyses. Figure presents this process. First, DC bias was removed by subtracting the mean amplitude of a signal to prevent models from fitting on bias. Second, considering the computational cost from the high resolution data, we choose to downsample the ultrasonic signals. Third, we define the region of interest as the interval which contains the ultrasonic signal responses, and thus the other parts of a signal are discarded so that redundant information is not included.

4.2 Feature generation

Since ultrasonic sensor signals are unstructured, which is difficult to process, feature extraction methods are needed to create a representative set of values, i.e., features that aggregate the information from an entire signal. In this stage, physics-based and data-driven features are generated. The hybrid feature pool enables us to incorporate both physics knowledge and data-driven information into models.

4.2.1 Physics-based features

Given that physics modeling is built on theories or comprehensive experiment studies, physics-based features are robust, explainable, and suitable for applications having limited amounts of data such as the fatigue testing data in this research. Therefore, features from traditional LU and NLU testings become potential candidates for the model.

- Wave velocity

In LU testing, ultrasonic wave velocity is a stiffness based measure which is associated with macroscopic damage such as crack/void coalescence and propagation. The wave speed is the distance divided by the time-of-flight (TOF) that a ultrasonic wave transverses in the material, as shown by Equation (4.1)

$$v = \frac{2D}{\Delta t} \quad (4.1)$$

where wave velocity is denoted by v , and D is the thickness of the specimen. Δt is the time difference between the actuation pulse and the response signal. Notice that, in our LU testing setup, one transducer severs as both the transmitter and receiver. Thus, the excitation signal travels $2D$ and the phase is changed 180° when received.

- Nonlinear acoustic parameter β

While wave velocity from LU testing is able to detect fatigue damage at macro-scale, it is limited because it cannot detect defects much smaller than the probing wavelength, e.g., 1mm. In contrast, NLU techniques are based on a different physical principle: nonlinear elasticity from nano- and micro-scale defects induce harmonic generation. The nonlinear acoustic parameter is related to the amplitude of generated harmonics. This nonlinear parameter changes due to defects such as dislocations, local plastic strain, precipitates, and micro-cracks, all of which are orders of magnitude smaller than the probing wavelength. Here, we apply fast Fourier transform (FFT) to a NLU measurement and simply calculate the nonlinear parameter by using the ratio between the amplitudes of the fundamental and the harmonic waves given by Equation (4.2)

$$\beta = \frac{A_2}{A_1} \quad (4.2)$$

where A_1 , A_2 is the amplitude of the fundamental wave and the second-order harmonic wave, respectively.

4.2.2 Data-driven features

The physics-based features alone, however, are not enough to capture all of the information from the LU and NLU signals. As a result, a large number of features engineered from the time domain, frequency domain, and time-frequency domain of ultrasonic measurements are added to the feature pool.

- Time domain features

Time domain features are peak amplitudes, ratios between peak amplitudes, and components from Principal Component Analysis (PCA) and Independent Component Analysis (ICA). Statistics in time domain such as median, quantiles, variance, skewness, and kurtosis are also included. Besides, from the envelope analysis of a NLU signal, wave duration, wave energy, and the ratios between these quantities are calculated.

- Frequency domain features

Frequency domain analysis offers some of the information that is not presented in the time domain. This information is especially valuable for periodic signals such as ultrasonic measurements. Thus, after applying fast Fourier transform (FFT), peak amplitudes, ratios between peak amplitudes, peak frequencies, frequency centroid and variance in FFT spectrum are extracted as the frequency domain features.

- Time-frequency domain features

Ultrasonic signals are usually not stationary, i.e., frequency changes in time, because the interaction between ultrasonic waves and discontinuities within the material. Therefore, time-frequency analysis is needed to describe the phenomena. Discrete wavelet transform (DWT) is adopted to decompose ultrasonic measurements into several frequency

bands. Then, statistics such as mean, median, kurtosis, and skewness are recorded for each frequency band.

We concatenate features from LU and NLU testing together, and thus the feature pool contains XXX features in total. A list of candidate features for LU and NLU measurements is displayed in Table

4.3 Feature selection

Feature selection aims to remove features that are redundant. Irrelevant features are common to see when we construct features without fully understanding a physical process. For example, the relationship between fatigue mechanism and ultrasonic responses. By including only the best subset of features for a prediction task, feature selection helps develop robust models against overfitting and improve model generalizability. There exists various feature selection techniques which can be mainly classified into three categories: filter methods, wrapper methods, and embedded methods. Each of these methods has its advantages, disadvantages, and suitable application scenarios.

In the model development pipeline, we adopted a wrapper method called Recursive Feature Elimination with Cross-validation (RFECV) to obtain the optimal feature subset that achieves the best predictive performance in multiple training/test data splits for a single model. Figure X shows the RFECV algorithm. First, recursive feature elimination (RFE) starts from a set with all available features and eliminate k features step by step based on the feature ranking with regressors/classifiers until the predetermined number of features n is reached. Nevertheless, the best number of features to select n^* is not determined. To find out n^* while alleviating the problem of overfitting, cross-validation (CV), a statistical model validation technique, is used along with RFE. CV partitions a dataset into training set and validation set in each fold. A model is evaluated multiple times with different partitions, and n^* is determined by the overall validation results. Then, RFE selects the optimal n^* features from the feature pool. We choose 5-fold classification in this feature selection procedure to avoid adding too much computation cost due to the fact that RFE is already computationally expensive.

4.4 Model training and validation

Model training and validation involve another CV loop. However, the CV here is not for finding the best feature subset but for providing a generalized estimate of a model's performance. Specifically, leave-one-group-out CV (LOGOCV) is applied, where each group contains three repeated measurements at one measurement location in one specimen. Here, we make an assumption that each group, i.e., each measurement location in a specimen, is an independent sample because of the differences in microstructure. In LOGOCV, each group is tested once and received validation scores by a predictor trained on the other groups, which efficiently utilizes the dataset and assesses the generalization capacity of a model.

4.5 Hyperparameter tuning

Searching an optimal set of hyperparameters is another crucial stage that significantly influences model performance in ML model development. We use grid search accompanied with the validation scores from the LOGOCV to tune hyperparameter in a simple and faster manner. Grid search exhaustively considers all candidates from predefined hyperparameter combinations. The number of hyperparameters and the range of each hyperparameter vary in different learning algorithms. The detailed settings will be discussed in Chapter ?? and 6.

Chapter 5

Remaining Useful Life Prediction

Chapter 6

Residual Stress and FWHM Prediction

Because of the efficiency of ultrasonic testings in terms of inspection area and cost, we explore the potential of using ultrasonic testings to measure quantities of interest, residual stress (RS) and full width at half maximum (FWHM), which are originally obtained from XRD analysis. In this chapter, we present regression models for estimating the RS and the FWHM of XRD peaks on fatigue damaged samples based on the ultrasonic measurements.

6.1 Problem formulation

Following the same manner in Section ??, we first translate the prediction tasks into ML regression problems based on the available dataset.

6.1.1 Dataset

The dataset for predicting RS and FWHM is composed of the XRD results and ultrasonic measurements. To obtain the RS and FWHM, the XRD analysis were performed on a subset of samples in the RUL dataset in Table ??, containing 8 specimens and 3 measurement locations for each specimen. Table 6.1 and 6.2 are the summary of the RS and FWHM dataset, respectively. It is worth mentioning that specimen 7's relatively low FWHM values could indicate that there are microcrack initiations, and the discussion about specimen 7 is presented in Section 6.4.

6.1.2 Target variables

RS and FWHM are the target variables in this chapter. RS is known to influence the fatigue behaviors including crack initiation and propagation.

Table 6.1: Summary of the RS prediction dataset

Specimen ID	Residual Stress (MPa)		
	Location 1	Location 2	Location 3
2	-61.7	-75.6	-80.2
4	-59.9	-69.6	-76.6
6	-60.3	-75.3	-79.6
7	-50.8	-59.6	-66.2
8	-57.3	-65.5	-79.7
10	-43.3	-47.0	-50.8
12	-38.8	-43.2	-50.0
14	-79	-76.7	-85.7

The negative sign indicates the compressive residual stresses.

Table 6.2: Summary of the FWHM prediction dataset

Specimen ID	FWHM ($^{\circ}$)		
	Location 1	Location 2	Location 3
2	0.354	0.353	0.355
4	0.350	0.354	0.353
6	0.358	0.359	0.363
7	0.307	0.320	0.321
8	0.357	0.355	0.358
10	0.356	0.358	0.360
12	0.354	0.353	0.355
14	0.338	0.340	0.346

FWHM is also an indicator for evaluating crack propagation. As a result, accurately predicting RS and FWHM based on ultrasonic measurements is beneficial to assist the fatigue level estimation. Here, the problem is formulated as two regression tasks separately: *a*) an univariate regression with RS as the target variable, and *b*) an univariate regression with FWHM as the target variable.

6.2 Residual stress prediction

A regression model, RFECV-SVM_{RS}, for predicting RS based on ultrasonic signals is developed by following the procedure in Chapter 4. Besides, we also compare the RFECV-SVM_{RS} model with other approaches such as Lasso regression, linear regression with top 5 features from Lasso regression, and random forest, as shown in Table 6.3. Root mean squared error (RMSE),

Table 6.3: Summary of regression models for residual stress estimation and model performance

Method	No. Selected Features	LOGOCV Test	
		RMSE (MPa)	MAPE (%)
Lasso regression	37	5.90	8.71
Linear regression	5	4.92	7.54
Random forest	283	7.74	12.85
RFECV-SVM	29	3.24	4.73

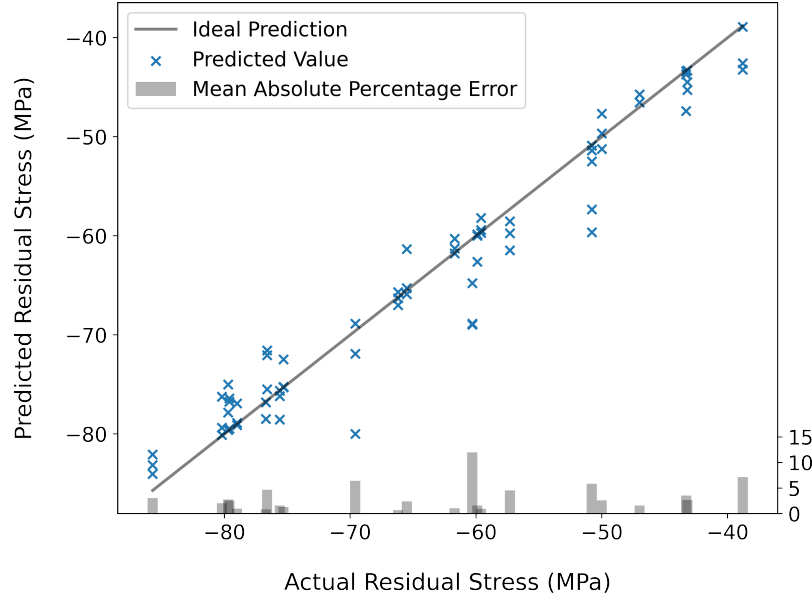


Figure 6.1: Scatter plot of actual vs predicted residual stress by RFECV-SVM

and mean absolute percentage error (MAPE) are used to assess the model performance with the LOGOCV results. In this task, the RFECV-SVM model performs the best with the MAPE equal 4.73%. Figure 6.1 illustrates the RFECV-SVM_{RS} model prediction by showing the actual and predicted RS, where a perfect model should follow the black line. It is observed that in most groups, at least one prediction among the three repeated measurements (three predictions for the same actual residual stress) is close to the ideal prediction, and the MAPEs for each group is mostly below 10%.

Table 6.4: Summary of regression models for FWHM estimation and model performance

Method	No. Selected Features	LOGOCV Test	
		RMSE (MPa)	MAPE (%)
Lasso regression	20	0.0081	2.40
Linear regression	5	0.0056	1.62
Random forest	283	0.0099	2.81
RFECV-SVM	7	0.0063	1.89

6.3 FWHM prediction

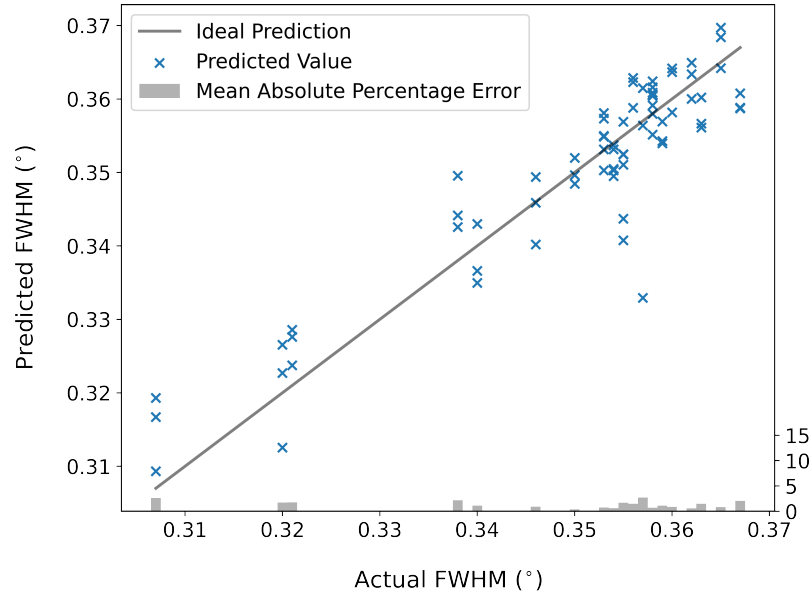
Similarly, the FWHM prediction model, RFECV-SVM_{FWHM}, is built based on the procedure in Chapter 4 and is evaluated with the same metrics in Section 6.2. Table 6.4 is the comparison of the RFECV-SVM_{FWHM} with other regression methods. It is worth mentioning that the linear regression model with top 5 features selected from Lasso regression achieves a 1.89% MAPE, performing slightly better than the RFECV-SVM_{FWHM}, and Figure 6.2a and 6.2b illustrates the predictions of these two models. For the RFECV-SVM_{FWHM}, one can observe that the predictions of the small FWHM values from specimen 7 significantly deviate from the ideal predictions; nevertheless, the linear regression model is able to make close predictions. As mentioned earlier, we surmise that specimen 7 has developed cracks and the difference in the model performance led us to have a further investigation about specimen 7 in Section 6.4. Before having further analysis, by excluding specimen 7, we can conclude that both models achieve a good performance in predicting FWHM with errors less than 2%.

6.4 Discussion

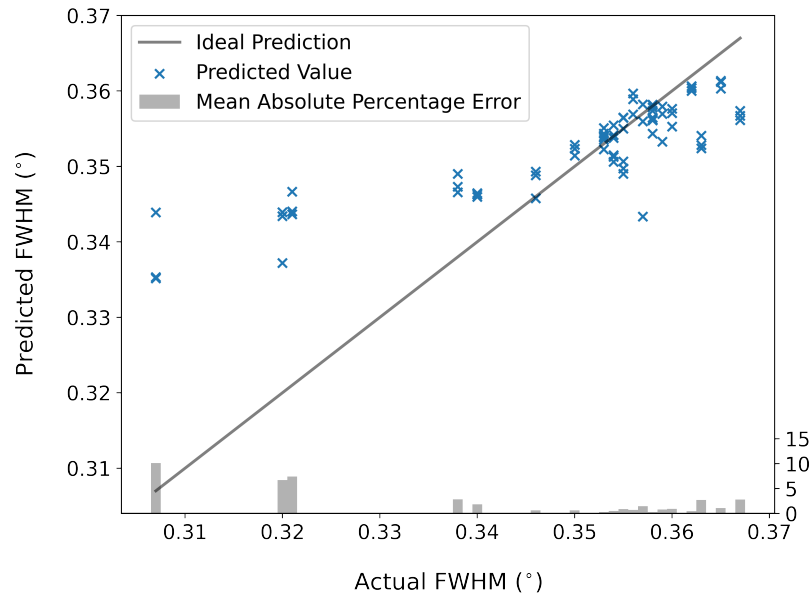
In this section, since we conjecture that specimen 7 has developed cracks based on the relatively small FWHM values, the potential of using our ultrasonic technology to detect cracks is discussed.

6.4.1 Crack detection through LU and NLU measurements

To investigate whether our ultrasonic technology can detect cracks or not, we first assume specimen 7 is cracked and the differences in ultrasonic signals between specimen 7 and specimen 8 are resulted from the existence of cracks since specimen 7 and 8 were under the same experimental setting. Secondly, independent t-test is performed to test if the mean of a feature is significantly different between two groups, specimen 7 (15 measurements from location 3a to 3) and specimen 8 (15 measurements from location 3a to 3). Finally, Figure 6.3 displays several specimen 7's and specimen 8's probability density plots of those selected features. The distributions are not identical between specimen 7 and 8, indicating that these features are possible to distinguish cracked samples from normal samples; however, given that we only have 2 specimens in the test and there exist other factors causing the difference, the further research on crack detection through our ultrasonic technology is required.

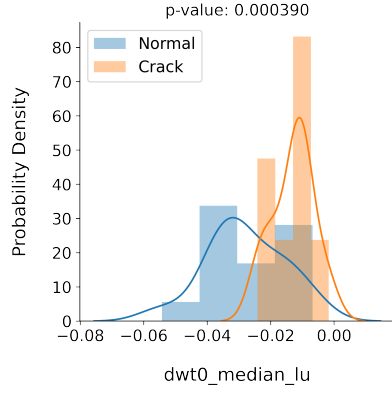


(a) Linear regression

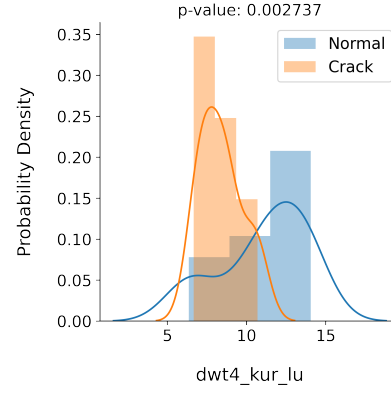


(b) RFECV-SVM

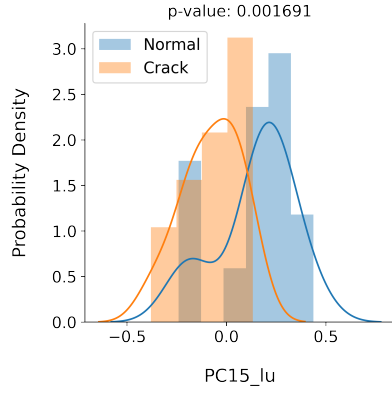
Figure 6.2: Scatter plot of actual vs predicted FWHM



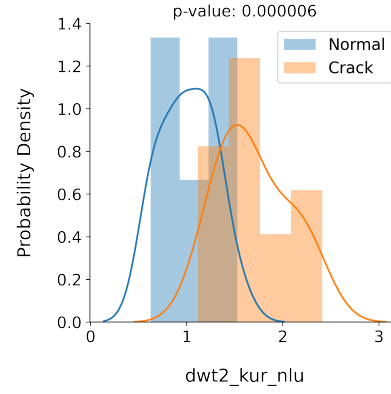
(a) Median of level 0 DWT coefficient of LU signal



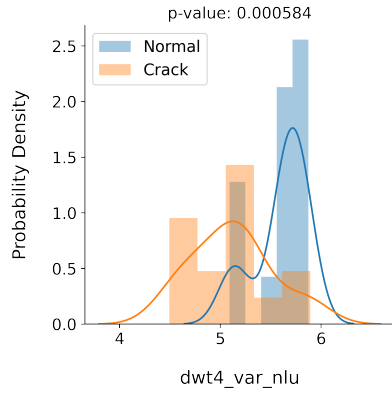
(b) Kurtosis of level 4 DWT coefficient of LU signal



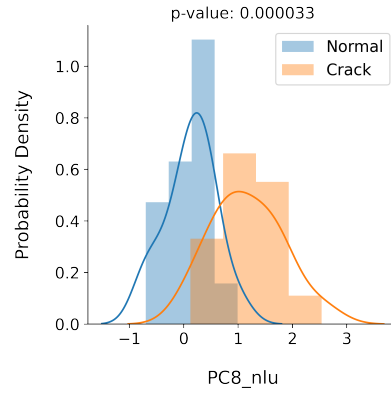
(c) Principal component 15 of LU signal



(d) Kurtosis of level 2 DWT coefficient of NLU signal



(e) Variance of level 4 DWT coefficient of NLU signal



(f) Principal component 8 of NLU signal

Figure 6.3: Scatter plot of actual vs predicted FWHM

Chapter 7

Conclusion and Future Work

7.1 Conclusion

A ML-based NDE methodology for assessing the accumulated fatigue damage level in terms of RUL, FWHM of XRD peak, and residual stress in recycled materials is developed, which aims to detect defects at various fatigue stages by combining the LU and NLU measurements and providing an ex-situ approach for the prognosis of useful life. An automatic pipeline is used to generate a pool of engineered features from raw ultrasonic signals, select useful features, validate models, and optimize classifiers and regressors appeared in this thesis.

A data-driven RUL prediction framework with the hierarchical classifiers and the statistical S-N curve is presented to bridge the research gap of RUL estimation in EoL products. The design of hierarchical classification scheme utilizes the characteristics of the fatigue dataset to predict the 7 combinations of the loading amplitude and the percent of fatigue life. Then, the use of statistical S-N curve incorporates the stochastic nature of fatigue life into the estimation of RUL. The framework relies on simple learning algorithms and does not require a large amount of data for training and validation, which shows the potential to be quickly adopted to other materials. More importantly, the algorithm does not need successive observations to conduct accurate prognostics of RUL; instead, one measurement at the time a sample is received is enough to provide RUL estimation, addressing the issue that the historical measurements may not be available for recycled components.

In addition, two regression tasks for predicting residual stress and FWHM measured by XRD using ultrasonic testings both achieve high prediction accuracy. The little inconsistency between ultrasonic predictions and XRD measurements implies the potential to apply LU and NLU testings on mea-

asuring residual stress and other fatigue damage indicators in a more cost-efficient and faster way.

We envision the proposed NDE methodology and the prediction framework can will equip manufacturers with responsive screening of incoming recycled materials, and lead to a significant increase in using recycled materials for remanufacturing and high-quality products that meet customer expectations.

7.2 Future works

In practice, nevertheless, there exist several limitations for the current work and suggested future research efforts are discussed in the following directions.

7.2.1 Collect more data for model development and validation

More data is needed to make our models generalizable in real world applications even though we have utilized a cross-validation method, LOGOCV, to achieve good prediction accuracy while retaining the generalizability of the model performance with the limited amount of data. In the current LOGOCV, the group left out in the testing set is the 3 repeated measurements at one location; however, training data from neighboring locations at the same specimen still exist high similarity with the testing group, which causes the potential data leakage in the training phase. As a result, more data could enable better estimate of model performance by treating each specimen as a individual group in LOGOCV.

True fatigue life, i.e., the number of cycles which a sample fails at, for a interrupted fatigue testing specimen is required to justify the proposed RUL estimation framework. Currently, the samples used to generate the predicted RUL were not tested until fracture, which prevents us from quantifying the error of our RUL prediction. Besides, more fatigue life data allows us to fit the distributions more precisely and/or select a distribution family, e.g., Weibull, exponential, log-normal, etc., that better describes the fatigue life behavior. As a result, improvements in the accuracy and robustness of the RUL estimation can be achieved.

Additionally, a finer measurement interval can extend the classification task so that our classifiers can classify a sample into more fatigue levels, e.g.,

15%, 33%, 50%, 67%, and 85%, or enable us to directly treat the estimation RUL as a regression task. With this, more advanced models can be researched and better applicability as well as flexibility for practitioners are expected.

7.2.2 Multi-sensor fusion for fatigue damage assessment

The integration of multiple sensors has the capability of detecting different types of defects and improving the robustness of fatigue damage evaluation. However, this work only studies the combination of LU and NLU testings. There are other NDE techniques such as infrared thermography, acoustic emission, etc., available to be added to the proposed NDE methodology. By integrating more sensors into the system, prediction performance will be further improved.

Moreover, sensor fusion can be categorized into several levels, e.g., data level, feature level, and decision level. We present a feature level fusion of LU and NLU signals in this thesis. Other fusion methods, especially decision level, are worth investigating because sensor selection can be conducted by for example, discarding sensors that degrade the model performance at different fatigue damage levels. Therefore, a cost-effective quantitative evaluation of fatigue progression system can be designed.

7.2.3 Spatial and temporal modeling for fatigue damage evaluation

With the measurements being made at multiple spatial locations and at multiple time increments, spatiotemporal modeling/interpolation can be performed and thus provide a full map containing the fatigue damage information for a specimen in space and time. For example, spatial statistics can be used to relate the correlation between measurement locations. Also, the temporal relation can also be modeled if enough data measured at different life time of a component. Having the spatiotemporal map for fatigue evolution can give practitioners a better understanding in the decision-making process.

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