

$$V(r) = \frac{1}{2} k r^2$$

$$= \frac{1}{2} k (x^2 + y^2)$$

↳ 2D

Week 12 notes 2
lectures

$$V^2 = \dot{x}^2 + \dot{y}^2 = \dot{r}^2 + r^2 \dot{\theta}^2$$

$$E = KE + PE$$

$$= \frac{1}{2} m v^2 + \frac{1}{2} k r^2$$

$$= \frac{1}{2} m \dot{r}^2 + \left(\frac{1}{2} m r^2 \dot{\theta}^2 + \frac{1}{2} k r^2 \right)$$

centrifugal term

effective potential

$$V_{\text{eff}} = \frac{1}{2} k r^2 + \frac{1}{2} m r^2 \dot{\theta}^2$$

$$= \frac{1}{2} k r^2 + \frac{L^2}{2 m r^2}$$

$r_{\text{min}} \rightarrow$ value of r that minimizes V_{eff}

$$\frac{dV_{\text{eff}}}{dr} = 0 \Rightarrow$$

$$k r_{\text{min}} - \frac{L^2}{m r_{\text{min}}^3} = 0$$

$$k r_{\text{min}} = \frac{L^2}{m r_{\text{min}}^3}$$

$$k r_{\text{min}}^4 = \frac{L^2}{m} \Rightarrow r_{\text{min}} = \left(\frac{L^2}{m k} \right)^{1/4}$$

Note: $\vec{r} = r_{\min}$, $\dot{r} = 0 \Rightarrow$

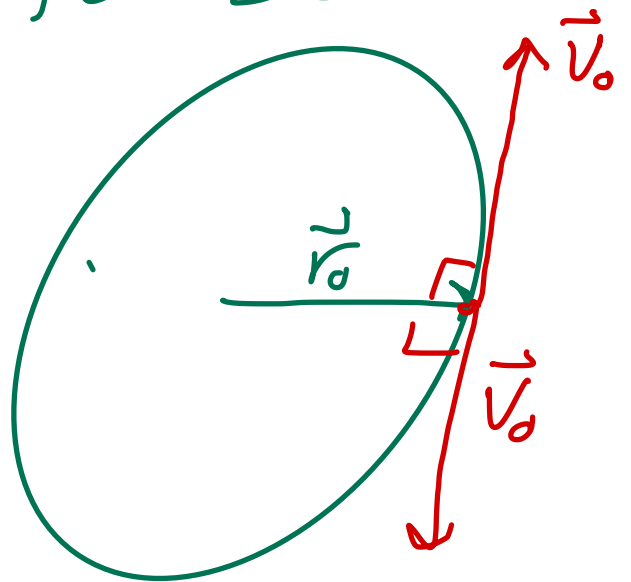
Circular orbit, change L
to change the radius

$$w_0 = \sqrt{\frac{k}{m}}$$

if $r = r_{\min}$ then we have
a circular orbit

1) initial position & the initial
velocity have to be

perpendicular



2) r_0 must be equal to r_{\min}

$$\vec{r}_0 = (r_{\min}, 0)$$

3) $V(r) = \frac{1}{2} K r^2$

$$F(\vec{r}) = -\nabla V = -K\vec{r}$$

$$\vec{a}(\vec{r}) = -\frac{K}{m} \vec{r}$$

$$a(r) = \frac{K}{m} r$$

Centripetal acceleration

$$a_c = \frac{V_0^2}{r_{\min}} = \frac{K}{m} r_{\min}$$

$$V_c^2 = \frac{K}{m} r_{\min}^2$$

$$V_0 = \sqrt{\frac{K}{m}} r_{\min}$$

$$V_c = \omega_c r_{\min} \rightarrow \text{magnitude}$$

$$\vec{r}_0 = (r_{\min}, 0)$$

$$\vec{v}_0 = (0, \omega_0 r_{\min})$$

$$\ddot{\vec{r}} = -\frac{k}{m} \vec{r}$$

$$= -\omega_0^2 \vec{r}$$

Analytical Solutions for
Position

Because $\ddot{x} = -\frac{k}{m} x$

$$\ddot{y} = -\frac{k}{m} y$$

x & y equations of motion
are separate

$$X = A \cos(\omega_0 t) + B \sin(\omega_0 t)$$

$$y = C \cos(\omega_0 t) + D \sin(\omega_0 t)$$

initial conditions

$$\vec{r}_0 = (r_{\min}, 0) \quad \begin{matrix} A = r_{\min} \\ C = 0 \end{matrix}$$

$$\vec{v}_0 = (0, \omega_0 r_{\min}) \quad \begin{matrix} B = 0 \\ D = r_{\min} \end{matrix}$$

$$X(0) = A = r_{\min} \Rightarrow A = r_{\min}$$

$$y(0) = C = 0 \Rightarrow C = 0$$

$$X = r_{\min} \cos(\omega_0 t) + B \sin(\omega_0 t)$$

$$\dot{X} = -r_{\min} \omega_0 \sin(\omega_0 t) + \omega_0 B \cos(\omega_0 t)$$

$$\dot{X}(0) = \omega_0 B = 0 \Rightarrow B = 0$$

$$y = D \sin(\omega_0 t) \quad \dot{y}(0) = \omega_0 D = \omega_0 r_{\min}$$

$$\dot{y} = \omega_0 D \cos(\omega_0 t) \Rightarrow D = r_{\min}$$

$$X = r_{\min} \cos(\omega_c t)$$

$$y = r_{\min} \sin(\omega_c t)$$

$$\vec{a} = -\omega_c^2 \vec{r}$$

$$\vec{r}_0 = (r_{\min}, 0)$$

$$\vec{v}_0 = (0, \omega_c r_{\min})$$