

PHY 321, MARCH 30, 2022

$L = \text{constant}$

COM-frame  $\vec{R} = 0$

$x, y, z$  for  $\vec{r} = \vec{r}_1 - \vec{r}_2 \rightarrow$

$x, y \rightarrow x \in (-\infty, +\infty)$

$y \in (-\infty, +\infty)$

$z \in [0, \infty)$

$\phi \in [0, 2\pi]$

$x = r \cos \phi$  and  $y = r \sin \phi$

$$\frac{d\phi}{dt} = \dot{\phi} = \frac{L}{\mu r^2} \quad \mu = \frac{m_1 m_2}{M}$$

$$\mu \frac{d^2 r}{dt^2} = F(r) + \frac{L^2}{\mu r^3}$$

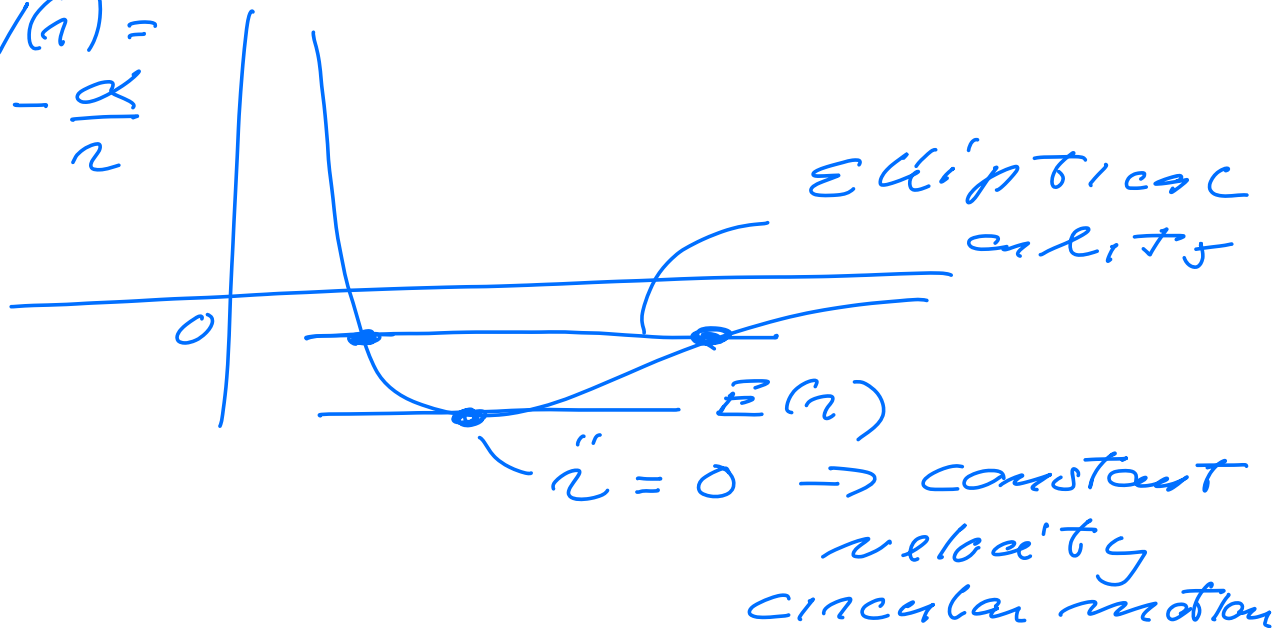
$$E(r, \phi) = V(r) + \underbrace{\frac{1}{2} \mu (\dot{r}^2 + r^2 \dot{\phi}^2)}_{\text{kinetic}}$$

$$= \frac{1}{2} \mu \dot{r}^2 + V(r) + \underbrace{\frac{1}{2} \frac{L^2}{\mu r^2}}_{\text{effective potential}}$$

$$V_{\text{eff}}(r)$$

$$= E(r)$$

$$V(r) = -\frac{\alpha}{r}$$



$$\mu \ddot{r} = F(r) + \frac{L^2}{\mu r^3}$$

$$V(r) = -\frac{\alpha}{r} \rightarrow F(r) = -\frac{\alpha}{r^2}$$

we want  $r$  as function of  $\phi$

- First trick:

$$\text{Define } u = \frac{1}{r}$$

$$\frac{dr}{d\phi} = -\frac{1}{u^2} \frac{du}{d\phi}$$

- Second trick:

rewrite  $\frac{d}{dt}$  in terms

of  $\frac{d}{d\phi}$

$$\frac{d}{dt} = \frac{d\phi}{dt} \frac{d}{d\phi} = \dot{\phi} \frac{d}{d\phi}$$

$$(\dot{\phi} = \frac{L}{\mu r^2})$$

$$= \frac{L}{\mu r^2} \frac{d}{d\phi}$$

$$u = \frac{1}{r}$$

$$\frac{d}{dt} = \frac{L}{\mu} u^2 \frac{d}{d\phi}$$

radial velocity  $\frac{dr}{dt} = \dot{r}$

$$= \frac{L u^2}{\mu} \frac{d}{d\phi} \left( \frac{1}{u} \right)$$

$$= - \frac{L}{\mu} \frac{du}{d\phi}$$

$u^2$

"

$d(1/r)$

$$\frac{u^2}{dt^2} = \ddot{r} = \frac{d}{dt}(\dot{r})$$

$$= \frac{1}{m} \frac{d}{dt} \left[ \frac{1}{2} m \dot{r}^2 \right]$$

$$= - \frac{\mathcal{L}^2 u^2}{\mu^2} \frac{\alpha^2 u}{\alpha \phi^2}$$

$$= \frac{F(r=\frac{1}{a})}{\mu} + \frac{L^2}{\mu^2 a^3}$$

Divide with  $L^2$  and  $a^2$

$$\frac{d^2 u}{d\phi^2} = - \frac{F(u) \mu}{L^2 u^2} - u$$

$$V(r) = -\frac{\alpha}{r} \Rightarrow F(r) = -\frac{\alpha}{r^2}$$

$$= -\alpha r^2$$

$$d^2 u \perp M \alpha \quad 11$$

$$\frac{d^2 \phi^2}{d\phi^2} = -\frac{\mu \alpha}{L^2} - u$$

$$\frac{\mu \alpha}{L^2} = 0$$

$$\frac{d^2 u}{d\phi^2} = -u \quad \left/ \begin{array}{l} \frac{d^2 x}{dt^2} \\ = -\omega_0^2 x \end{array} \right.$$

$$u = C \cos \phi + D \sin \phi$$

$$= A \cos(\phi - \delta)$$

$$r(\phi) = \frac{1}{u(\phi)} = \frac{1}{A \cos(\phi - \delta)}$$

$$w(\phi) = u(\phi) - \frac{\mu \alpha}{L^2}$$

$$\frac{d^2 w}{d\phi^2} = -w$$

$$w = B \cos(\phi - \delta)$$

$$u(\phi) = B \cos(\phi - \delta) + \frac{\mu \alpha}{L^2}$$

$\angle \angle$

Scale  $\delta = 0$

$$u(\phi) = \frac{\mu \alpha}{L^2} + B \cos(\phi)$$

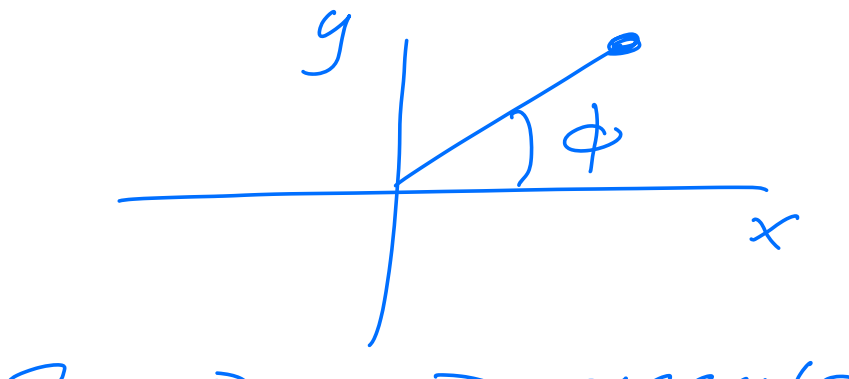
$$= \frac{\mu \alpha}{L^2} (1 + \epsilon \cos \phi)$$

$$\epsilon = \frac{B L^2}{\alpha \mu}$$

$$\alpha = G m_1 m_2$$

$$C = \frac{L^2}{\mu \alpha}$$

$$r(\phi) = \frac{C}{1 + \epsilon \cos \phi}$$



$\epsilon = 0 \Rightarrow$  circular motion,

Min and Max values of  $r(\phi)$ ?

$$r(\phi) = \frac{C}{1 + \epsilon \cos \phi}$$

$$\frac{dr}{d\phi} = 0 = \frac{C \epsilon \sin \phi}{(1 + \epsilon \cos \phi)^2}$$

$\epsilon \neq 1$  ( $\epsilon = 1$ , parabolic motion)

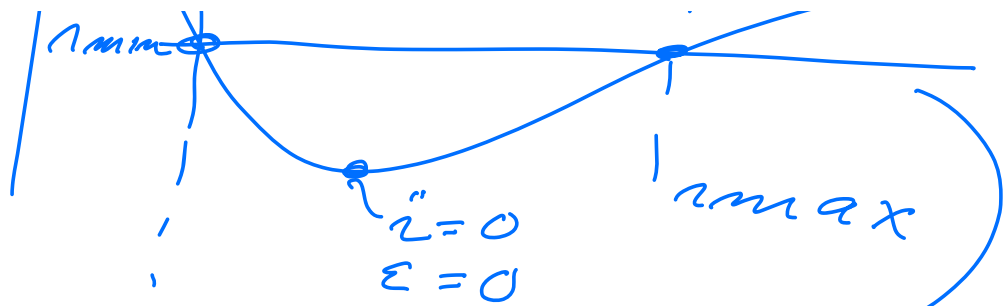
$$\phi = 0 \quad \vee \quad \phi = \pi$$

$$\phi = 0 \Rightarrow r(\phi) = \frac{C}{1 + \epsilon} = r_{\min}$$

$$\phi = \pi \Rightarrow r(\phi) = \frac{C}{1 - \epsilon} = r_{\max}$$

$$\epsilon \neq 1, \epsilon > 0$$





↓  
elliptical orbit

$$r(\phi) = \frac{C}{1 + \epsilon \cos \phi}$$

