

PHY 321, MARCH 27, 2023

$$\vec{R} = \frac{m_1 \vec{r}_1 + m_2 \vec{r}_2}{M} \quad M = m_1 + m_2$$

$$\vec{r} = \vec{r}_1 - \vec{r}_2$$

(i) COM frame $\vec{R} = 0$

$$\frac{d\vec{p}}{dt} = 0 \quad \vec{F}(r) = -\gamma \vec{r}/r^3$$

\vec{p} is conserved

$$\vec{p} = M \cdot \frac{d\vec{r}}{dt}$$

$$(i') \quad \vec{L} = \vec{r} \times \vec{p}$$

$$\frac{d\vec{L}}{dt} = 0 \quad \vec{L} \text{ is conserved}$$

\Rightarrow two-dim

$$\vec{r} = x \vec{i} + y \vec{j}$$

$$r \in [0, \infty) \quad r = \sqrt{x^2 + y^2}$$

$$\phi \in [0, 2\pi]$$

$$\begin{cases} x \in (-\infty, +\infty) \\ y \in \text{---} \end{cases}$$

$$\dot{r} = \frac{dr}{dt} \quad \dot{\phi} = \frac{d\phi}{dt}$$

radial velocity angular velocity

(iii)

in 2 dim (kinetic energy)

$$K = \frac{1}{2} (\dot{x}^2 + \dot{y}^2) \mu$$

$$= \frac{1}{2} \mu (\dot{r}^2 + r^2 \dot{\phi}^2)$$

$$\mu = \frac{m_1 m_2}{m}$$

(iv)

$$\dot{\phi} = \frac{d\phi}{dt} = \frac{L}{\mu r^2}$$

$$\mu \ddot{r} = \mu a_r = F(r) + \frac{L^2}{\mu r^3}$$

$$= F_{\text{eff}}(r)$$

(v)

$$E = K + V$$

$$= \frac{1}{2} \mu (\dot{r}^2 + r^2 \dot{\phi}^2) + V(r)$$

$$\frac{1}{2} \mu \dot{r}^2 + V_{\text{eff}}(r)$$

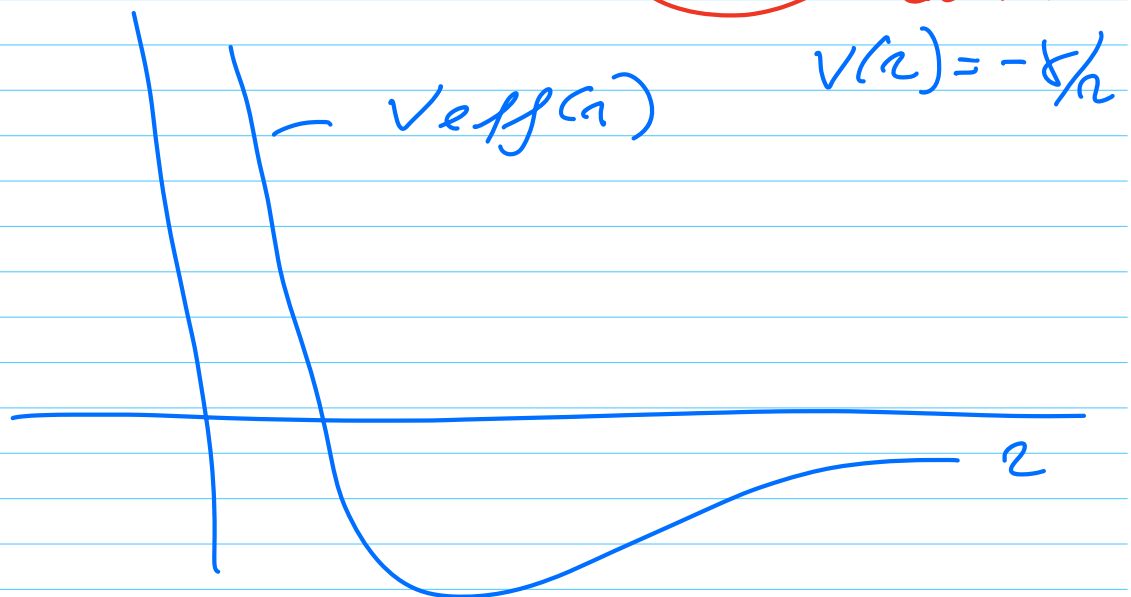
$$V_{\text{eff}}(r) = V(r) + \frac{L^2}{2\mu r^2}$$

$$F_{\text{eff}}(r) = -\frac{dV_{\text{eff}}}{dr} =$$

$$= -\frac{dV}{dr} + \frac{L^2}{\mu r^3}$$

$$= F(r) + \frac{L^2}{\mu r^3}$$

centrifugal barrier



2-Dim Harmonic oscillator

$$V(r) = \frac{1}{2} k r^2 =$$

$$V(x, y) = \frac{1}{2} k (x^2 + y^2)$$

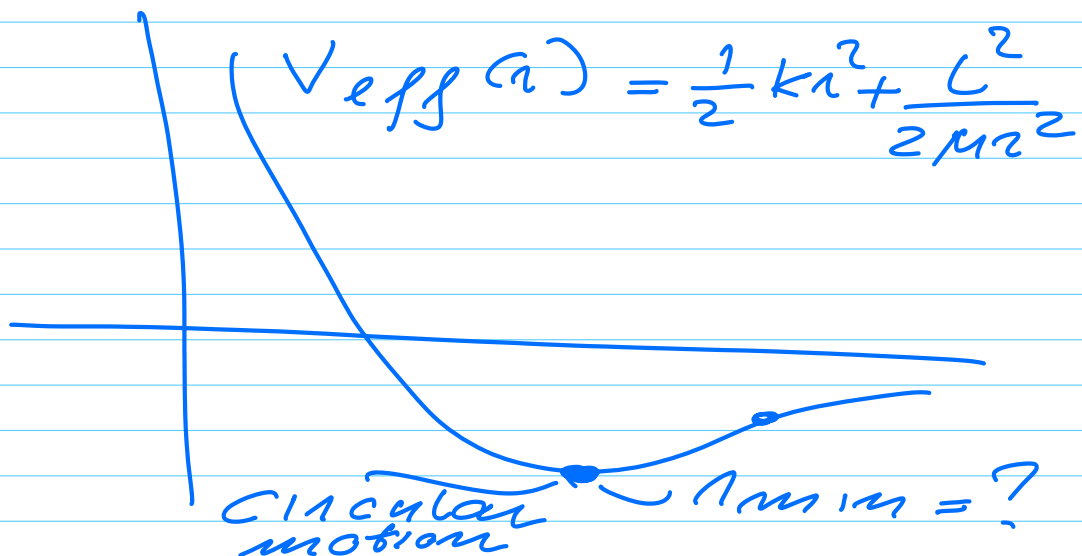
$$x, y \rightarrow r, \phi$$

$$E = \frac{1}{2} \mu (\dot{x}^2 + \dot{y}^2) + \frac{1}{2} k (x^2 + y^2)$$

$$= \frac{1}{2} \mu (\dot{r}^2 + r^2 \dot{\phi}^2) + \frac{1}{2} k r^2$$

$$V_{\text{eff}}(r) = \frac{1}{2} \mu r^2 \dot{\phi}^2 + \frac{1}{2} k r^2$$
$$= \frac{1}{2} \frac{L^2}{\mu r^2} + \frac{1}{2} k r^2$$

$$\mu \ddot{r} = \mu a_r = -k r + \frac{L^2}{\mu r^3}$$



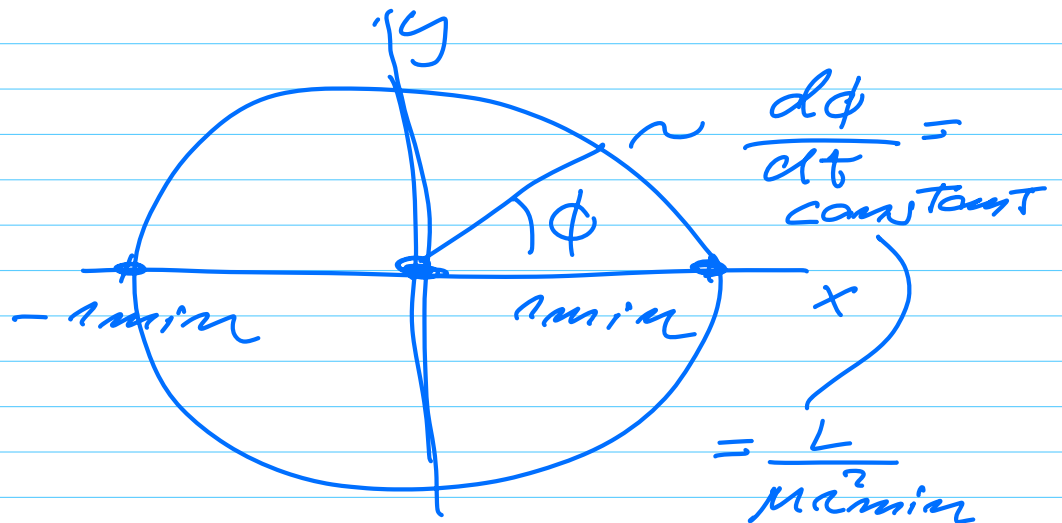
$$\left. \frac{dV_{\text{eff}}(r)}{dr} \right|_{r=r_{\text{min}}} = 0$$

$$r_{\text{min}} = \left[\frac{L^2}{k\mu} \right]^{1/4}$$

$$- \left. \frac{dV_{\text{eff}}}{dr} \right|_{r=r_{\text{min}}} = 0 = F_{\text{eff}}(r)$$

$$= \mu a_r = \mu \ddot{r} = 0$$

$$\frac{d\phi}{dt} = \frac{L}{\mu r^2}$$



Cartesian coordinates

$$\mu \frac{d^2 x}{dt^2} = -Kx$$

$$\mu \frac{d^2 y}{dt^2} = -Ky$$

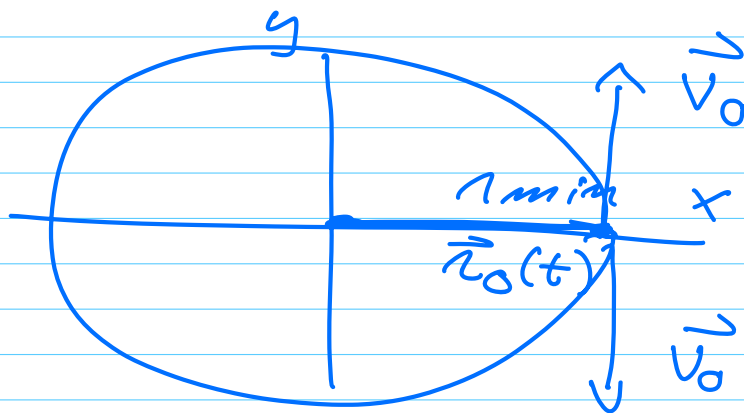
$$x(t) = A \cos(\omega_0 t) + B \sin(\omega_0 t)$$

$$\omega_0 = \sqrt{K/\mu}$$

$$y(t) = C \cos(\omega_0 t) + D \sin(\omega_0 t)$$

at r_{min} we have $\ddot{r} = a_r = 0$

initial conditions



$$\vec{r}_0(t_0) = \vec{r}_0 = x_0 \vec{i} + y_0 \vec{j}$$

$$y_0 = 0 \quad x_0 = r_{min}$$

Centripetal acceleration

$$a_c = a_r = \frac{v_0^2}{r_{min}}$$

$$= \frac{k a_{\min}}{\mu} \Rightarrow$$

$$(\omega_0^2 = k/\mu)$$

$$v_0^2 = \omega_0^2 a_{\min}^2$$

$$v_0 = \omega_0 a_{\min}$$

$$\vec{v}_0 = \vec{v}(t_0) = v_{0x} \vec{i} + v_{0y} \vec{j}$$

$$\vec{v}_0 = 0 \cdot \vec{i} + \underbrace{\omega_0 a_{\min}}_{v_{0y}} \vec{j}$$

$$x_0 = A \cdot \cos(0) + B \sin(0)$$

$$= a_{\min} = A$$

$$v_{0x} = 0 = -A\omega_0 \sin(\omega_0 t_0) + B\omega_0 \cos(\omega_0 t_0)$$

$$\Rightarrow B = 0$$

$$x(t) = a_{\min} \cos(\omega_0 t)$$

$$y(t) = a_{\min} \sin(\omega_0 t)$$