

PHY 321 February 7, 2022

Center of mass is the average position of a set of masses weighted by the total mass

$$M = \sum_{i=1}^N m_i$$

$$\vec{R} = \frac{\sum_{i=1}^N m_i \vec{r}_i}{\sum_{i=1}^N m_i} = \frac{1}{M} \sum_{i=1}^N m_i \vec{r}_i$$

rate of change

$$\frac{d\vec{R}}{dt} = \frac{1}{M} \sum_{i=1}^N m_i \underbrace{\frac{d\vec{r}_i}{dt}}_{\vec{v}_i}$$

$$= \frac{1}{M} \underbrace{\sum_{i=1}^N \vec{p}_i}_{\vec{P}}$$

$$= \underline{\vec{P}}$$

\overline{M}

if $\frac{d\vec{p}}{dt} = 0$, the
 rate of change \vec{R}
 $(\frac{d\vec{R}}{dt})$ is constant.

Example: Torque (hw4, ex9)

$$t_0 = 0 \quad \vec{r}_0 = x_0 \vec{i} + y_0 \vec{j}$$

Add a force in the x-direction

$$\vec{F} = F_x \vec{i} = \frac{d\vec{p}}{dt}$$

$$\vec{v}_0 = 0 \text{ m/s}$$

$$\vec{a} = \vec{F}/m = F_x \vec{i}$$

$$\vec{v}(t) = \vec{v}_0 + \int_{t_0}^t \vec{a} dt'$$

$$\vec{v}(t) = \left(\int_{t_0}^t \frac{F_x}{m} dt' \right) \vec{i}$$

$$= \frac{F_x}{m} t \cdot \vec{i}$$

$$\vec{p} = m \cdot \vec{v}(t)$$

$$= \vec{F}_x \cdot t \cdot \vec{v}$$

$$\vec{v}(t) = \vec{v}_0 + \int_{t_0}^t \vec{a}(t) dt$$

$$\vec{v}_0 = x_0 \vec{i} + y_0 \vec{j}$$

$$\vec{v}(t) = \left(x_0 + \frac{1}{2} \frac{F_x}{m} t^2 \right) \vec{i} + y_0 \vec{j}$$

angular momentum

$$\vec{L} = \vec{r} \times \vec{p}$$

$$\vec{L} = -y_0 F_x \cdot t \cdot \vec{k}$$

$$\frac{d\vec{L}}{dt} = \vec{\tau} = -y_0 F_x \vec{k}$$

* —————

Conservative forces-

$$(i) \quad \vec{F} = \vec{F}(\vec{r})$$

$$(ii) \quad W = \int_C \vec{F}(\vec{r}) d\vec{r}$$

... independent of C .

is independent of path

$$(iii) \quad \vec{\nabla} \times \vec{F} = 0$$

We will show that

$$\vec{F}(\vec{r}) = - \vec{\nabla} \underbrace{V(\vec{r})}_{\text{number}}$$

work-energy theorem

work done by displacing
an object from \vec{r} to
 $\vec{r} + d\vec{r}$

$$W(\vec{r} \rightarrow \vec{r} + d\vec{r}) = \vec{F}(\vec{r}) d\vec{r}$$

$$= - [V(\vec{r} + d\vec{r}) - V(\vec{r})]$$

Back to last week

$$\left[\begin{aligned} \frac{1}{2} m v_1^2 - \frac{1}{2} m v_0^2 &= W_0 \\ &= V(x_0) - V(x_1) \end{aligned} \right]$$

$$F(x) = -kx$$

$$\frac{1}{2} k x_0^2 - \frac{1}{2} k x_1^2$$

$$\frac{1}{2} m v_1^2 + \frac{1}{2} k x_1^2 = \frac{1}{2} m v_0^2 + \frac{1}{2} k x_0^2$$

$$\begin{aligned}
 W(\vec{r} \rightarrow \vec{r} + d\vec{r}) &= \vec{F}(\vec{r}) d\vec{r} \\
 &= - \left[V(\vec{r} + d\vec{r}) - V(\vec{r}) \right] \\
 &= F_x dx + F_y dy + F_z dz
 \end{aligned}$$

$$\begin{aligned}
 V(\vec{r} + d\vec{r}) - V(\vec{r}) &= \\
 V(x+dx, y+dy, z+dz) - V(x, y, z)
 \end{aligned}$$

$$f(x, y, z)$$

$$\begin{aligned}
 df &= \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy \\
 &\quad + \frac{\partial f}{\partial z} dz
 \end{aligned}$$

$$\begin{aligned}
 V(\vec{r} \rightarrow \vec{r} + d\vec{r}) &= - dV \\
 &= - \left[\underbrace{\frac{\partial V}{\partial x}}_{\parallel} dx + \underbrace{\frac{\partial V}{\partial y}}_{\parallel} dy + \underbrace{\frac{\partial V}{\partial z}}_{\parallel} dz \right] \\
 &= F_x dx + F_y dy + F_z \cdot dz
 \end{aligned}$$

$$F_x = - \frac{\partial V(x, y, z)}{\partial x}$$

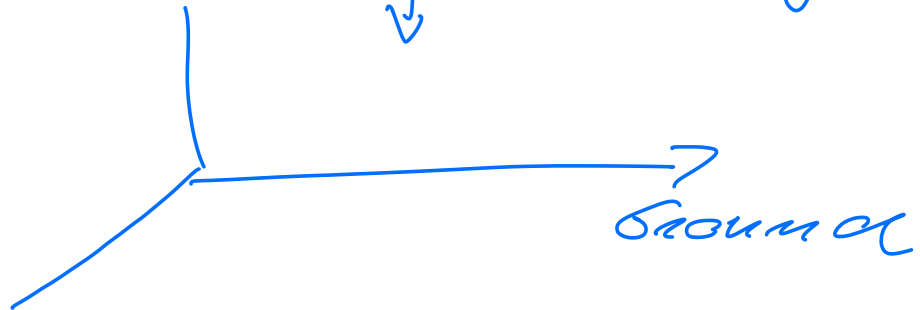
$$\left. \begin{aligned} F_y &= - \frac{\partial V}{\partial y} \\ F_z &= - \frac{\partial V}{\partial z} \end{aligned} \right\} \Rightarrow \vec{F} = -\vec{\nabla} V$$

Example (hw4, exercises)

Falling object

phase
1

$$\vec{G} = -mg\vec{j}$$



phase
2

