# NPARC Specification Sheet V3

Network Path Analyzer for Regeneration and Conjugation

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## 1 Introduction and Scope

This NPARC Specification Sheet describes the final logic for:

- Regenerator Placement in long-distance optical paths, using a fixed threshold.
- Optical Phase Conjugator (OPC) Placement for dispersion mitigation.
- Residual Distance (uncompensated dispersion) calculation, consistent with practical constraints such as forbidden nodes (true source/destination, their immediate ROADMs).

NPARC reads input from a *Simon Simulator* output file, which provides a path (list of nodes) and link distances. This specification now includes a final, crucial detail: **we exclude the true source node and the true destination node from all distance-based calculations.** Only the sub-array from *source ROADM* to *destination ROADM* is analyzed for threshold checks, regenerator triggers, OPC placement, and residual distances.

## 2 Definitions and Path Exclusion

A path record from the simulator typically lists:

```
(true\_source) \rightarrow (source\_ROADM) \rightarrow \cdots \rightarrow (destination\_ROADM) \rightarrow (true\_destination).
```

Often, the distance from  $true\ source\ to\ source\ ROADM$  is a very small number (e.g., 0.01 km), and similarly from  $destination\ ROADM$  to  $true\ destination$  is also very small. We denote:

- **Node** 0: True source node (excluded from threshold calculations).
- **Node** 1: Source ROADM (start of the sub-array for analysis).
- Node (n-2): Destination ROADM (end of the sub-array).
- Node (n-1): True destination node (excluded from threshold calculations).

#### **Exclusion Rule:**

All threshold-based distance accumulations, regenerator triggers, and OPC computations occur only between  $node\ 1$  (the source ROADM) and  $node\ (n-2)$  (the destination ROADM). Links  $(0\to 1)$  and  $(n-2\to n-1)$ , typically the short 0.01 km segments, are ignored.

## 3 Regenerator Placement Logic

We assume a globally defined **regenerator threshold**, denoted as T (e.g., 1500 km). The sub-array for analysis is  $[1 \dots n-2]$  of the node list. Let D(i,j) be the distance accumulated from node i to node j within that sub-array.

## 3.1 Trigger Condition and Forbidden Nodes

- (a) **Trigger Condition:** If the cumulative distance from the last regenerator (or from sub-array start if no reg yet) exceeds T, a new regenerator is required.
- (b) Forbidden Nodes for Regenerators:
  - Node 1 (source ROADM) and node (n-2) (destination ROADM) are never allowed for regenerators.
  - Thus, in the sub-array indexing, index 0 and index (sub\_n 1), which correspond to these ROADMs, are skipped for reg placement.
  - If we need to place a regenerator but the preceding node is forbidden, the path is unreachable.
- (c) **Direct Links Exceeding Threshold:** If a single link in the sub-array surpasses T and no valid intermediate node exists, the path is unreachable.

### 3.2 No Regenerators Needed

If the entire sub-array distance  $\leq T$ , then no regenerator is placed.

# 4 OPC (Optical Phase Conjugator) Placement Logic

After placing regenerators, we apply the OPC rules.

#### 4.1 Case 1: No Regenerators in Sub-Array

- 1. If the sub-array total distance  $\leq T$  (thus no reg needed),
- 2. And if the sub-array has **3 or more nodes** in  $[1 \dots n-2]$ ,
- 3. Then place **exactly one** OPC at the node in the interior (i.e., excluding sub-array index 0 and index (sub-n-1)) closest to the midpoint distance of the entire sub-array.

If fewer than 3 sub-array nodes exist, we skip OPC entirely.

#### 4.2 Case 2: Regenerators Placed

When the sub-array does contain one or more regenerators:

1. Partition the sub-array into sections:

[source\_ROADM 
$$\rightarrow$$
 R1], [R1  $\rightarrow$  R2], ..., [Rk  $\rightarrow$  destination\_ROADM].

- 2. In each section, if there are **3 or more nodes** (counting the section's start and end),
- 3. Place **one** OPC at the interior node (excluding section endpoints) nearest that section's midpoint in distance.

### 4.3 OPC Forbidden Nodes

Similarly to regenerators, the node that is exactly the source ROADM (sub-array index  $\theta$ ) or the destination ROADM (sub-array index (sub-n-1)) is forbidden for OPC placement.

#### 5 Residual Distance Calculation

We define **Scenario 1** (no OPC) and **Scenario 2** (OPC present). Distances are always measured in the sub-array only.

#### 5.1 Scenario 1: No OPC

- If no regenerators exist, the *entire sub-array distance* is considered the residual distance.
- If one or more regenerators exist, the **residual distance** is the distance from the *last regenerator* in the sub-array to the sub-array's end (*destination ROADM*).

#### 5.2 Scenario 2: One or More OPCs

When at least one OPC is placed, we:

(i) **Compute** for each OPC:

(distance from section start to OPC) – (distance from OPC to section end).

- (ii) **Sum** all such absolute differences over all OPCs.
- (iii) **Add** the *last leftover segment distance* from the final regenerator to the end of the sub-array (i.e., from R<sub>last</sub> to destination ROADM).
- (iv) The **final residual distance** is the sum of step (i) and step (iii).

## 6 Unreachable Paths

A path is declared **UNREACHABLE** if:

- Any single link in the sub-array is > T and no intermediate node can accommodate a regenerator, or
- The logic attempts to place a regenerator at a forbidden node (source/destination ROADM) and thus fails threshold compliance.

# 7 Summary of Key Changes

This final version of the specification **excludes** the true source (nodeIDs[0]) and the true destination (nodeIDs[n-1]) from every threshold check and from the residual distance calculations. Only the sub-array [1..(n-2)] is relevant. Nodes at the extremes of this sub-array (i.e. index 1 and index (n-2) in the *original full path*) are likewise *disqualified* from receiving regenerators or OPCs.

In addition:

- If no regenerator is needed but the path has at least 3 intermediate ROADM nodes, we place a single OPC (Case 1).
- If regenerators are present, an OPC can appear in each section with 3+ nodes (Case 2).
- The residual distance in the presence of OPC(s) always incorporates the leftover from the last regenerator to the sub-array's end.

## 8 Conclusion

By following this final specification, the NPARC tool ensures:

- Correct Regenerator Placement without ever placing them at the true source, destination, or their immediate ROADMs.
- **OPC Placement** is consistent with either "no-regens" or "with-regens" scenarios, using midpoint-based selection for each sub-section.
- Accurate Residual Distance reflecting either a full sub-array or last-segment leftover, plus absolute differences for each OPC segment.

This concludes the final revision of the NPARC specification sheet with all updates included.