

HW 13

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Q1

First note that for $i \neq j$

$$q(i, j) = \lim_{t \rightarrow 0} \frac{p_t(i, j)u(i, j)}{t}$$

Then by definition of p' and the Chapman-Kolmogorov equation,

$$\begin{aligned} p'_t(i, j) &= \lim_{h \rightarrow 0} \frac{p_{t+h}(i, j) - p_t(i, j)}{h} \\ &= \lim_{h \rightarrow 0} \frac{\sum_k (p_t(i, k)p_h(k, j)) - p_t(i, j)}{h} \\ &= \lim_{h \rightarrow 0} \frac{\sum_{k \neq j} (p_t(i, k)p_h(k, j)) + p_t(i, j)(p_h(j, j) - 1)}{h} \\ &= \lim_{h \rightarrow 0} \frac{\sum_{k \neq j} (p_t(i, k)p_h(k, j))}{h} + \lim_{h \rightarrow 0} \frac{p_t(i, j)(p_h(j, j) - 1)}{h} \\ &= \sum_{k \neq j} p_t(i, k)q(k, j) - \lim_{h \rightarrow 0} \frac{p_t(i, j)(\sum_{k \neq j} p_h(j, k))}{h} \quad \text{By definition of } q \\ &= \sum_{k \neq j} p_t(i, k)q(k, j) + p_t(i, j)(-\sum_{k \neq j} q(j, k)) \\ &= \sum_{k \neq j} p_t(i, k)q(k, j) + p_t(i, j)(-\lambda_j) \\ &= p_t(i, \cdot)Q(\cdot, j) \end{aligned}$$

Q2

Note

$$\begin{aligned}
 \frac{\delta}{\delta t} p_t &= \frac{\delta}{\delta t} e^{Qt} \\
 &= Q \sum_{n=1}^{\infty} \frac{n Q^{n-1} t^{n-1}}{n!} \\
 &= Q \sum_{n=1}^{\infty} \frac{Q^{n-1} t^{n-1}}{(n-1)!} \\
 &= Q p_t \quad \text{by the given solution of KBE}
 \end{aligned}$$

Q3

$$\begin{aligned}
 (\tilde{\pi} \tilde{p})_i &= \frac{1}{\sum_{k \in S} \pi_k \lambda_k} \sum_{k \neq i} \pi_k \lambda_k \tilde{p}(k, i) \\
 &= \frac{1}{\sum_{k \in S} \pi_k \lambda_k} \sum_{k \neq i} \pi_k \lambda_k \frac{q(k, i)}{\lambda_k} \\
 &= \frac{1}{\sum_{k \in S} \pi_k \lambda_k} \sum_{k \neq i} \pi_k q(k, i)
 \end{aligned}$$

We know that $\pi Q = 0$ so This is equal to

$$\begin{aligned}
 &\frac{-\pi_i Q_{i,i}}{\sum_{k \in S} \pi_k \lambda_k} \\
 &= \frac{\pi_i \lambda_i}{\sum_{k \in S} \pi_k \lambda_k}
 \end{aligned}$$

so $\tilde{\pi}$ is a stationary measure, and clearly by the normalizing term it is also a distribution.

Q4

i

Note

$$\lim_{t \rightarrow \infty} P_t(B, C) = \pi_C$$

Then we solve for

$$\pi \begin{bmatrix} Q_{A,A} & Q_{A,B} & 1 \\ Q_{B,A} & Q_{B,B} & 1 \\ Q_{C,A} & Q_{C,B} & 1 \end{bmatrix} = [0, 0, 1]$$

and we get $\pi = [1/2, 1/4, 1/4]$ so $\pi_C = 1/4$.

ii

The limiting fraction for the time in each city is simply the stationary distribution. So the limiting fraction for Atlanta is $1/2$, the limiting fraction for Boston is $1/4$ and the limiting fraction for Chicago is $1/4$.

iii

Let $N(t)$ be the number of cities visited t years, X_i be the amount of time spent in the i^{th} city and $Z_{B_i} = 1$ if city i is Boston.

The average number of visits to Boston per year is equal to

$$\begin{aligned} & \lim_{t \rightarrow \infty} \frac{\sum_{i=1}^{N(t)} Z_{B,i}}{t} \\ &= \lim_{t \rightarrow \infty} \frac{N(t)}{t} \frac{\sum_{i=1}^{N(t)} Z_{B,i}}{N(t)} \\ & \lim_{t \rightarrow \infty} \frac{N(t)}{t} \lim_{t \rightarrow \infty} \frac{\sum_{i=1}^{N(t)} Z_{B,i}}{N(t)} \end{aligned}$$

We know from previously by solving the stationary distribution that,

$$\lim_{t \rightarrow \infty} \frac{\sum_{i=1}^{N(t)} Z_{B,i} X_i}{t} = \pi_B = 1/4$$

Then note

$$E[Z_{B,i} X_i] = E[Z_{B,i}] E[X_i | Z_{B,i} = 1] = E[Z_{B,i}] * 1/4$$

Then

$$\begin{aligned} & \lim_{t \rightarrow \infty} \frac{\sum_{i=1}^{N(t)} Z_{B,i} X_i}{t} \\ &= \lim_{t \rightarrow \infty} \frac{N(t)}{t} \frac{\sum_{i=1}^{N(t)} Z_{B,i} X_i}{N(t)} \\ & \lim_{t \rightarrow \infty} \frac{N(t)}{t} \lim_{t \rightarrow \infty} \frac{\sum_{i=1}^{N(t)} Z_{B,i} X_i}{N(t)} \end{aligned}$$

Which by the Strong Law of Large Numbers is equal to

$$\begin{aligned} & \lim_{t \rightarrow \infty} \frac{N(t)}{t} E[Z_{B,i} X_i] \\ &= \lim_{t \rightarrow \infty} \frac{N(t)}{t} E[Z_{B,i}] 0.25 \end{aligned}$$

We know this value is equal to $\pi_B = 0.25$ which implies

$$\lim_{t \rightarrow \infty} \frac{N(t)}{t} E[Z_{B,i}] = 1$$

which is the expected number of visits per year in Boston.

iv

The expected number of times she flies from Boston to Atlanta is

$$E\left[\sum_{i=1}^{N(1)} Z_{B,i}\right] * P(B, A) = 3/4$$

Q5

$$Q = \begin{array}{c|c|c|c|c} & 0 & 1 & 2 & 3 \\ \hline 0 & -1 & 0 & 1 & 0 \\ \hline 1 & 2 & -3 & 0 & 1 \\ \hline 2 & 0 & 2 & -2 & 0 \\ \hline 3 & 0 & 0 & 2 & -2 \end{array}$$

Solving for $\pi Q = 0$ we get

$$\pi = [0.4, 0.2, 0.3, 0.1]$$

Q6

a

There are 5 states in this model,

0 is when no machines are broken.

1 is when machine 1 is broken.

2 is when machine 2 is broken.

12 is when both machines are broken but 1 broke first.

21 is when both machines are broken but 2 broke first.

0 can transition to 1 or 2

1 can transition to 0, or 12

12 can transition to 2

21 can transition to 1

b

This gives a Q matrix of

	0	1	2	12	21
0	-4	1	3	0	0
1	2	-5	0	3	0
2	4	0	-5	0	1
12	0	0	2	-2	0
21	0	4	0	0	-4

Solving for $\pi Q = 0$ we get

$$\pi = [0.34108527, 0.12403101, 0.27906977, 0.18604651, 0.06976744]$$