

# Johns Hopkins Engineering

## Applied Machine Learning for Mechanical Engineers

Unsupervised Machine Learning Techniques, Part 1, A



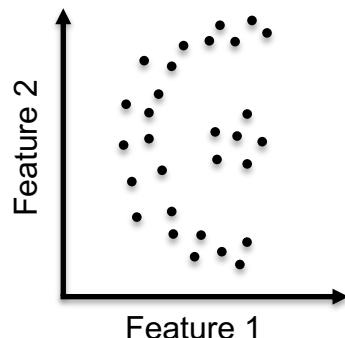
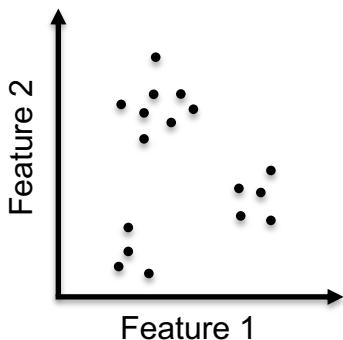
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# Clustering Algorithms

- By the end of this lecture you will be able to:
  - Describe clustering in general
  - Describe K-mean clustering algorithm
  - Describe density-based spatial clustering of applications with noise (DBSCAN)

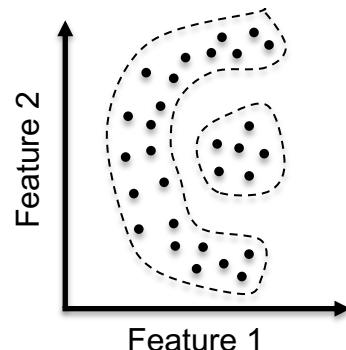
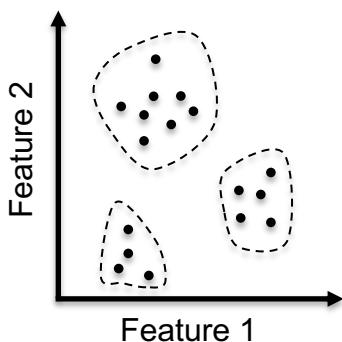
# Clustering Algorithms

- Clustering
  - Assign a category to a number of datapoints with similar patterns



# Clustering Algorithms

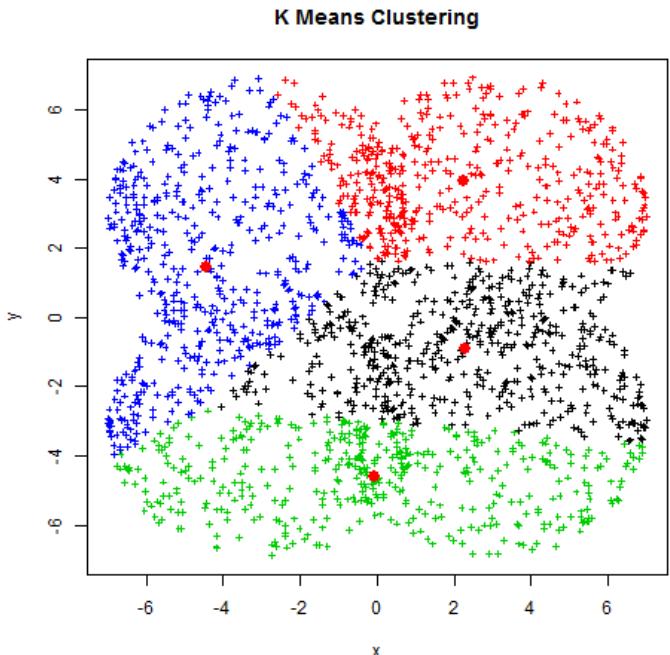
- Clustering
  - Assign a category to a number of datapoints with similar patterns



# Clustering Algorithms

## ■ K-Mean

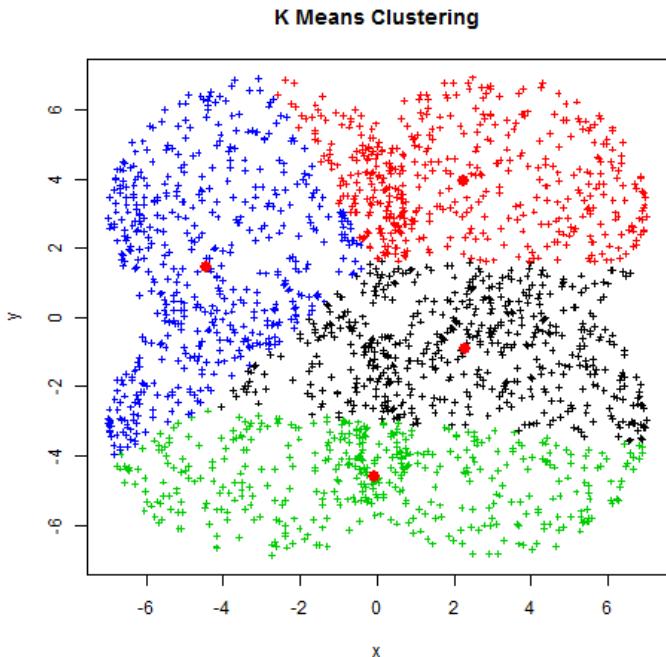
- Cluster the data into  $K$  clusters (iterative)
  - Step 1: assign  $K$  random coordinates (i.e., datapoints), referred to as centroids, representing the centroid of the clusters within the feature space.
  - Step 2: for every centroid, compute the distance between every datapoint and that centroid.
  - Step 3: assign a datapoint to the cluster of the centroid with minimum distance from.
  - Step 4: compute the new centroids of each cluster and repeat steps 2 to 4.
  - Stopping criteria: insignificant changes to the location of centroids or reaching to the total number of iterations.



# Clustering Algorithms

## ■ K-Mean

- Simple implementation
- Convergence is guaranteed
- K is not being automatically identified
- Does not exclude outliers
- Relies on distances rather than density

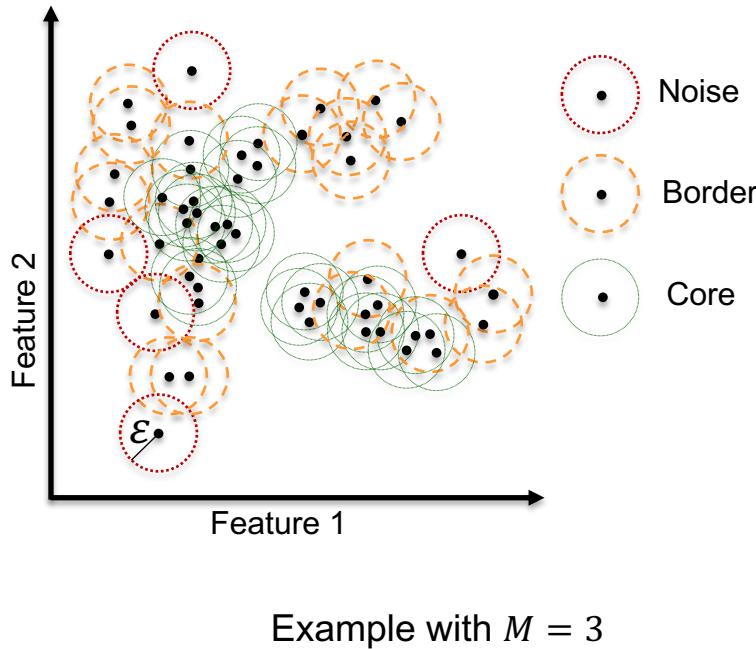


# Clustering Algorithms

- Density-Based Spatial Clustering of Applications with Noise (DBSCAN)

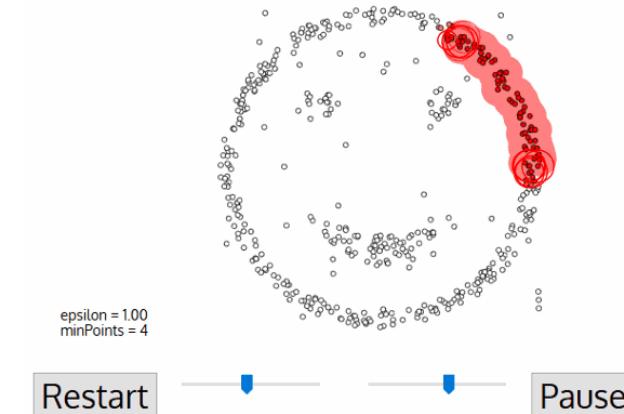
- Jargon

- Radius or epsilon ( $\varepsilon$ ): the radius of a hypersphere with centroid to be a datapoint.
    - Minimum Points threshold ( $M$ ): minimum number of datapoints within a hypersphere (excluding the centroid) to call that datapoint a “core point.”
    - Border point: the datapoint which at least one but less than  $M$  other datapoints fall within its hypersphere.
    - Noise datapoint: a datapoint with no other datapoints within its hypersphere.



# Clustering Algorithms

- Density-Based Spatial Clustering of Applications with Noise (DBSCAN)
  - Core and border points with overlaps are clustered together
  - Great for high density clustering
  - Discover outliers (noises are not clustered)
  - Computationally intensive



# Clustering Algorithms

- In this lecture, you learned about:
  - Clustering in general
  - K-mean clustering algorithm
  - Density-based spatial clustering of applications with noise (DBSCAN)
- In the next lecture, we will talk about Deep Belief Networks and Auto-Encoders



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