

# **Johns Hopkins Engineering**

## **Applied Machine Learning for Mechanical Engineers**

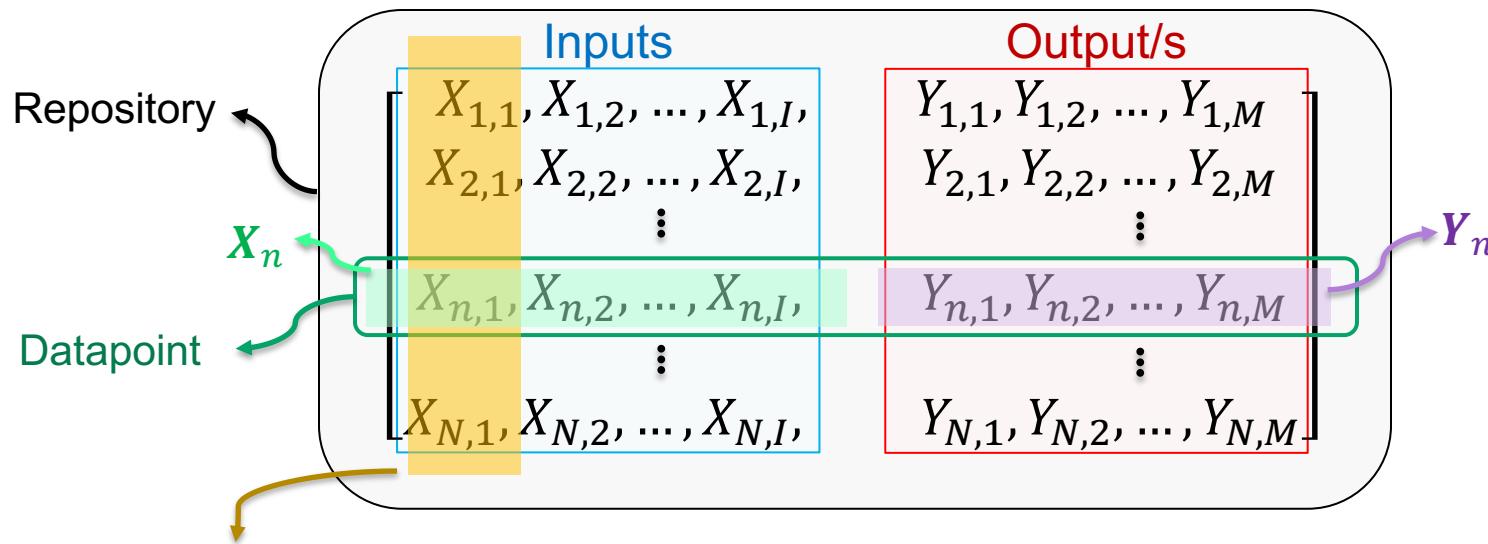
Popular Supervised Machine Learning Techniques, Part 1, C

# Convolutional Neural Networks

- By the end of this lecture you will be able to:
  - Describe data with local variations
  - Describe Convolutional Neural Networks (CNN)

# Convolutional Neural Networks

- Machine Learning data are to have unique attributes
  - What if our data have local variations (such as images, sounds, text, etc.)?



# Convolutional Neural Networks

- Machine Learning data are to be inherently unique for each attribute
  - What if our data have local variations (such as images, sounds, text, etc.)?

1.00	-1.00	-1.00	-1.00	1.00
-1.00	1.00	-1.00	1.00	-1.00
-1.00	-1.00	1.00	-1.00	-1.00
-1.00	1.00	-1.00	1.00	-1.00
1.00	-1.00	-1.00	-1.00	1.00

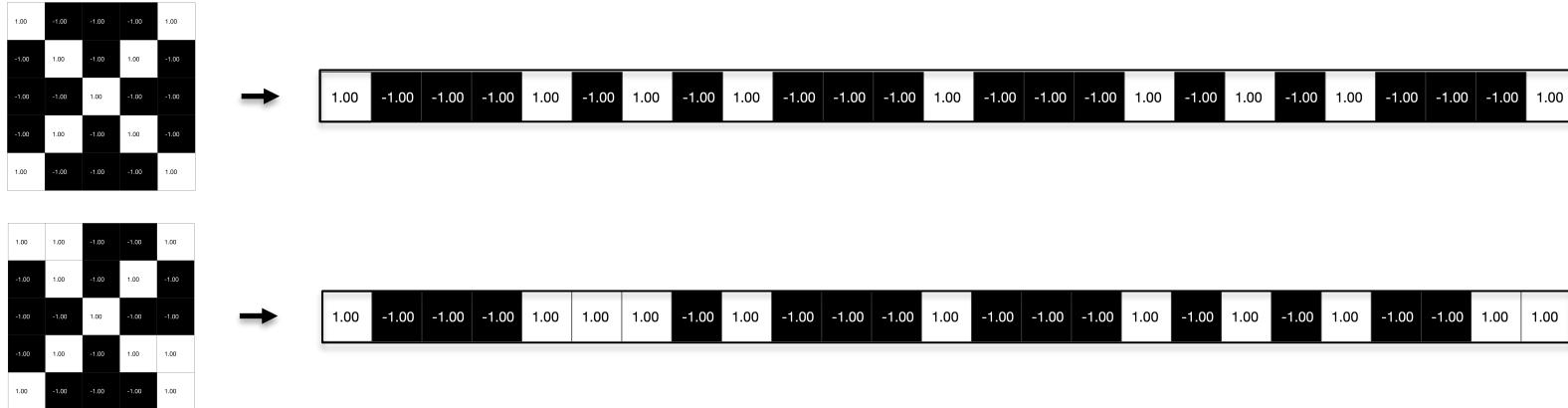
Letter X

1.00	1.00	-1.00	-1.00	1.00
-1.00	1.00	-1.00	1.00	-1.00
-1.00	-1.00	1.00	-1.00	-1.00
-1.00	1.00	-1.00	1.00	1.00
1.00	-1.00	-1.00	-1.00	1.00

Letter X

# Convolutional Neural Networks

- Machine Learning data are to have unique attributes
  - Flatten the image to turn it into one datapoint of pixel intensities



There is no unique attribute; they are all pixel intensities

# Convolutional Neural Networks

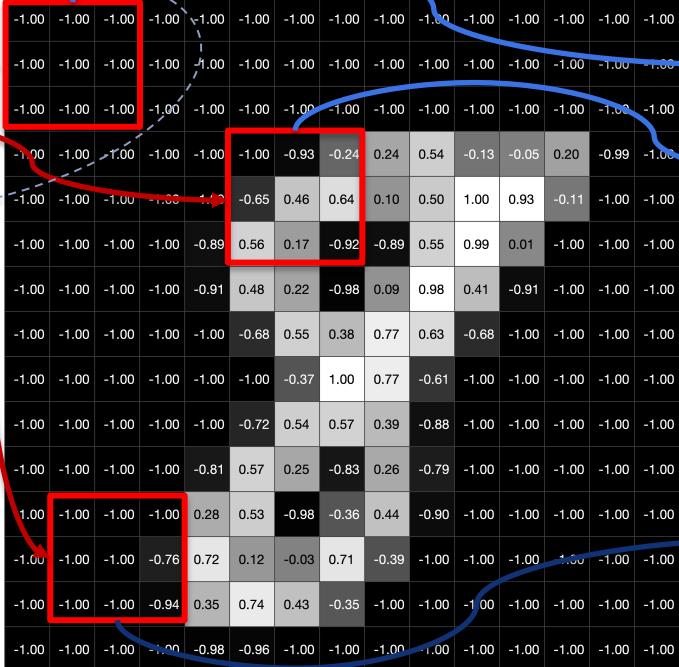
- What CNN does in general:
  - Extract features/attributes from the datapoints that address local variations of original data
  - Feed the attributes to a deep or shallow Neural Network and compute the outputs
- CNN main operations:
  - Convolution
  - Pooling
  - ReLU
  - Calibration/Normalization

# Convolutional Neural Networks

## ■ Convolution (Conv):

$$\begin{bmatrix} 1.00 & -1.00 & -1.00 \\ -1.00 & 1.00 & -1.00 \\ -1.00 & -1.00 & 1.00 \end{bmatrix}$$

3 by 3 filter with  
stride of 1 in  
each direction



Original image (15 by 15) as  
handwritten of number 8 (MNIST)

$$\frac{(1 \times -1) + (-1 \times -1) + \dots + (1 \times -1)}{9} = 0.33$$

Outcome of convolution (13 by 13)  
(size is a function of strides and filter size)

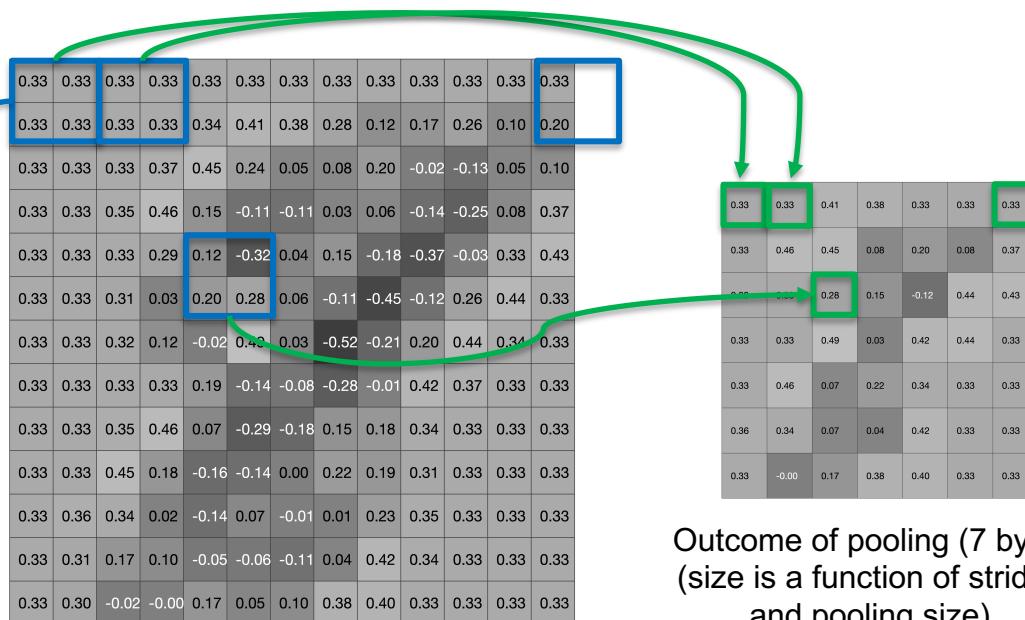
# Convolutional Neural Networks

- Pooling (Pool):
    - Max pooling
    - Average Pooling

Pool of 2 by 2 with  
stride of 2 in each  
direction

## Important things:

- Pool size in each direction
  - Stride in each direction



Outcome of convolution (13 by 13)  
(size is a function of strides and filter size)

# Convolutional Neural Networks

- ReLU:
  - Negative to zero
- Normalization/Calibration (NOCA)
  - Example: Calibrate values between -1 and 1

0.33	0.33	0.41	0.38	0.33	0.33	0.33
0.33	0.46	0.45	0.08	0.20	0.08	0.37
0.33	0.33	0.28	0.15	-0.12	0.44	0.43
0.33	0.33	0.49	0.03	0.42	0.44	0.33
0.33	0.46	0.07	0.22	0.34	0.33	0.33
0.36	0.34	0.07	0.04	0.42	0.33	0.33
0.33	0.00	0.17	0.38	0.40	0.33	0.33



0.33	0.33	0.41	0.38	0.33	0.33	0.33
0.33	0.46	0.45	0.08	0.20	0.08	0.37
0.33	0.33	0.28	0.15	0.00	0.44	0.43
0.33	0.33	0.49	0.03	0.42	0.44	0.33
0.33	0.46	0.07	0.22	0.34	0.33	0.33
0.36	0.34	0.07	0.04	0.42	0.33	0.33
0.33	0.00	0.17	0.38	0.40	0.33	0.33



0.35	0.35	0.66	0.54	0.35	0.35	0.35
0.35	0.84	0.82	-0.68	-0.18	-0.69	0.49
0.35	0.34	0.14	-0.39	-1.00	0.76	0.75
0.35	0.35	1.00	-0.86	0.71	0.80	0.35
0.35	0.85	-0.73	-0.12	0.38	0.35	0.35
0.46	0.36	-0.72	-0.84	0.68	0.35	0.35
0.35	-1.00	-0.31	0.55	0.62	0.35	0.35

Outcome of pooling (7 by 7)  
(size is a function of strides  
and pooling size)

Outcome of ReLU (7 by 7)

Outcome of calibration (7 by 7)

# Convolutional Neural Networks

- Stack operations (also referred to as layers) and feed it to Neural Networks

- One round

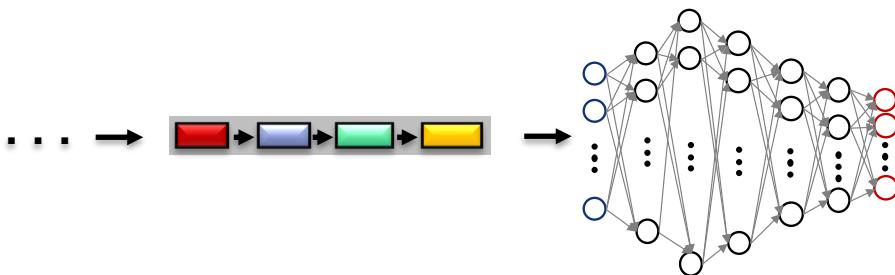


Size of filters and pooling, strides, and size of original images limit the number of times we can stack each round

- Stack

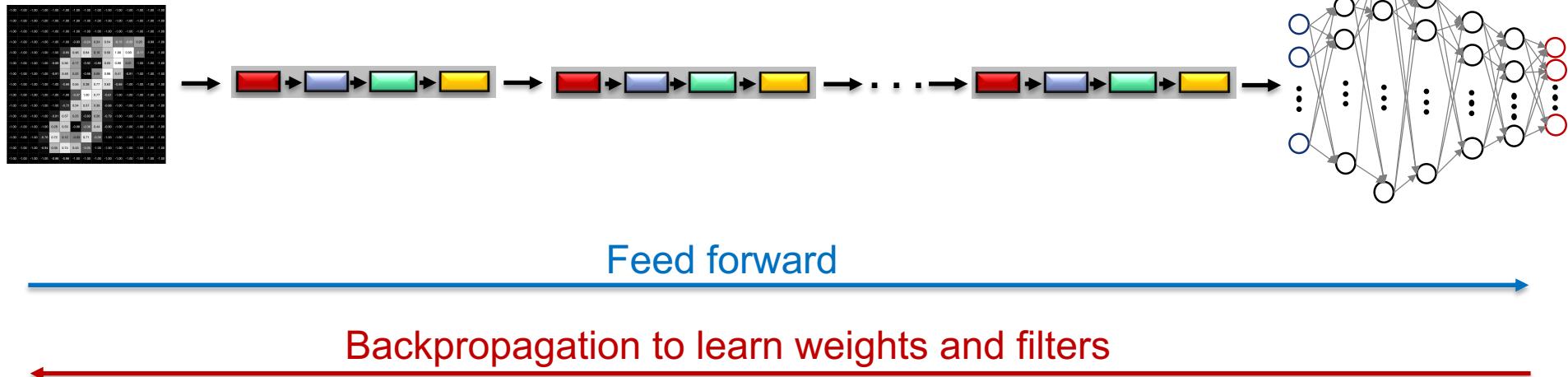


- Flatten and feed it to a deep or shallow Neural Network



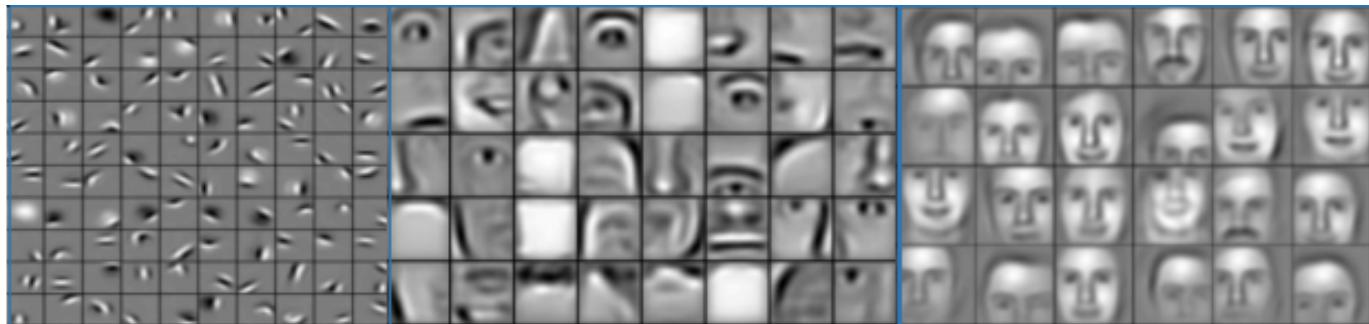
# Convolutional Neural Networks

- CNN Learning (initiate with random filters, weight, biases, and other parameters)



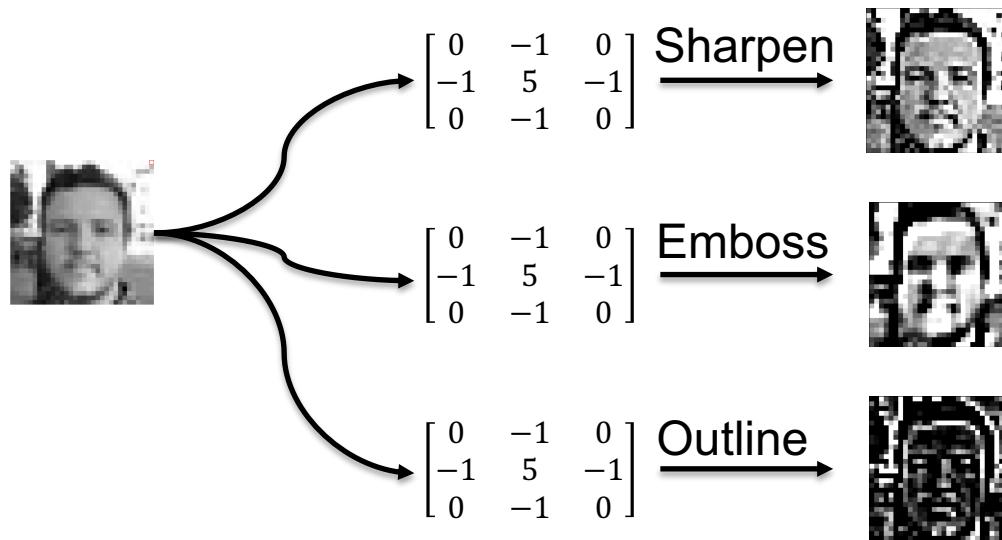
# Convolutional Neural Networks

- By learning, some filters (kernels) might become pixel intensities of sensible features in an image (e.g. eyes, lips, nose, etc. in faces)



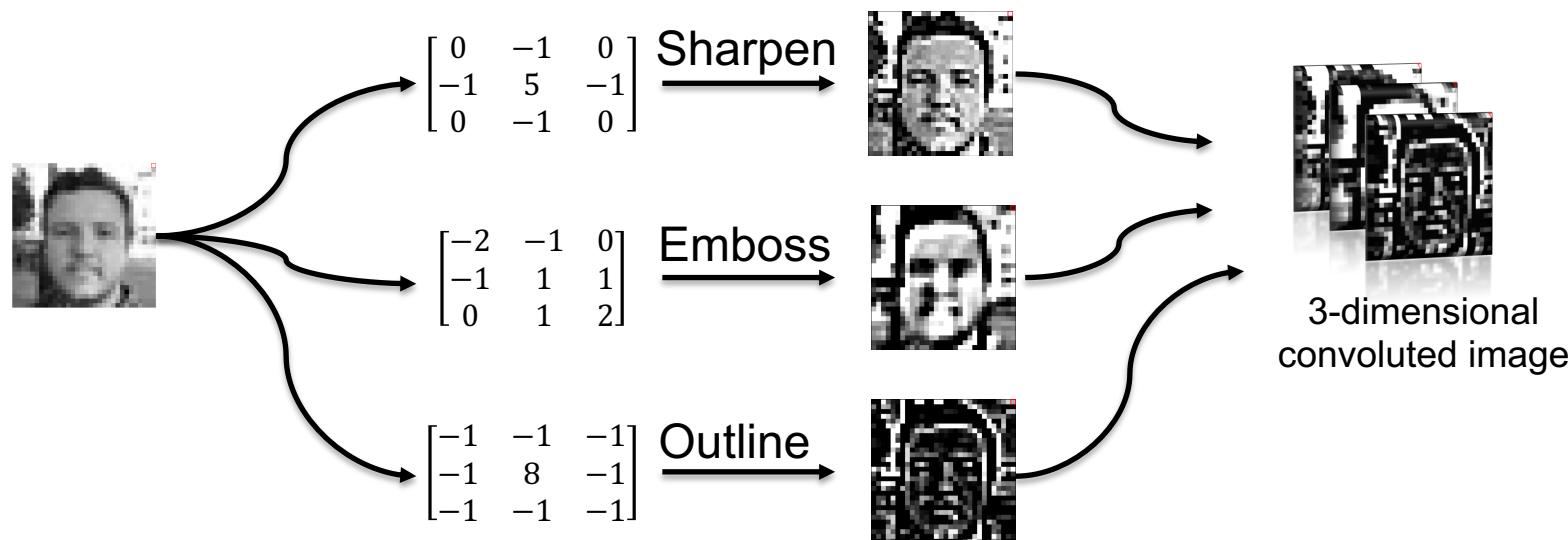
# Convolutional Neural Networks

- What filters, also referred to as Kernels, actually do?
  - Detect edges, characteristics, objects, features.



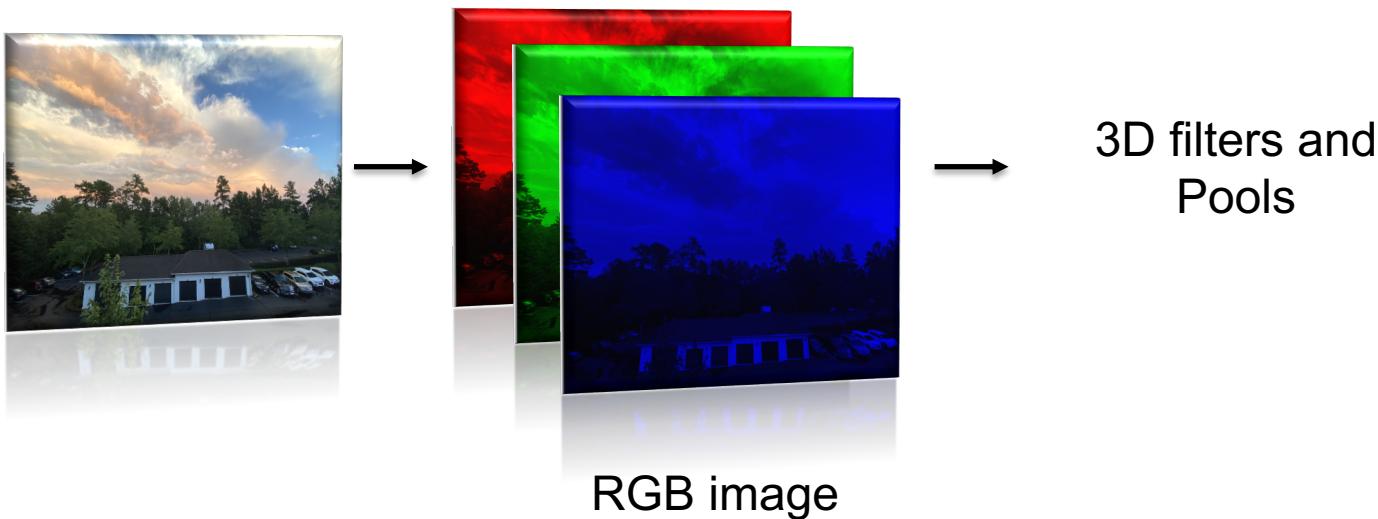
# Convolutional Neural Networks

- You can have multiple filters, say K filters, in each round, then the convoluted image will be K-dimensional (i.e. K channels) where each dimension is the outcome of a different filter



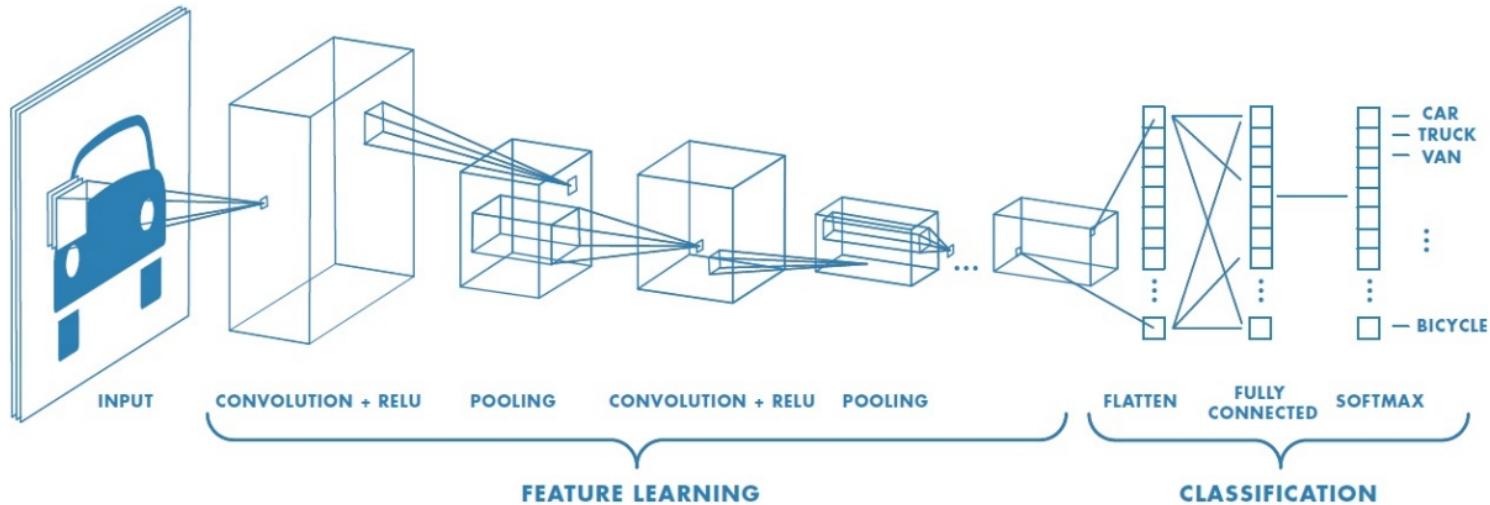
# Convolutional Neural Networks

- Multi-channel data (e.g. color images)



# Convolutional Neural Networks

- Multi-channel data (e.g. color images) and GPU computing



# Overview of Machine Learning in General

- In this lecture, you learned about:
  - Data with local variations
  - Convolutional Neural Networks (CNN)
- In the next lecture, we will briefly introduce K-Nearest Neighbor (KNN), Recurrent Neural Networks (RNN), and Long Short-Term Memory as other supervised machine learning techniques.



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