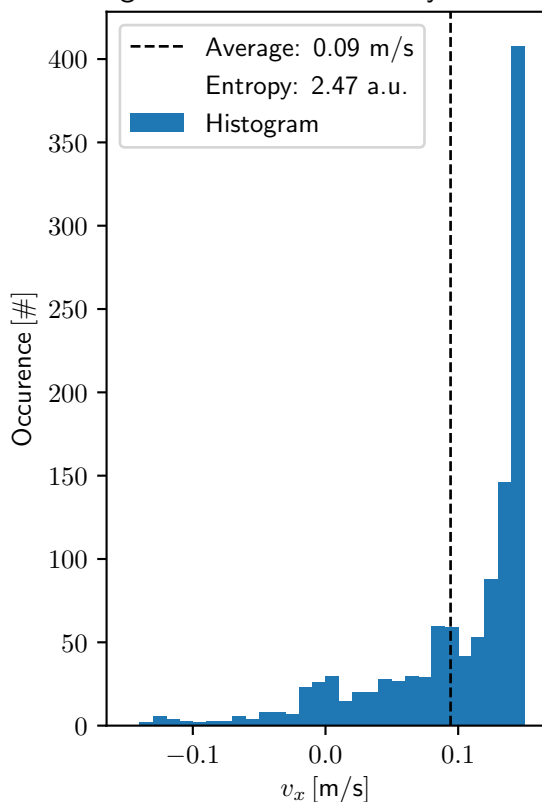


Distribution of Linear Velocity
along x-Axis - Autonomously Controlled



Distribution of Angular Velocity
about z-Axis - Autonomously Controlled

