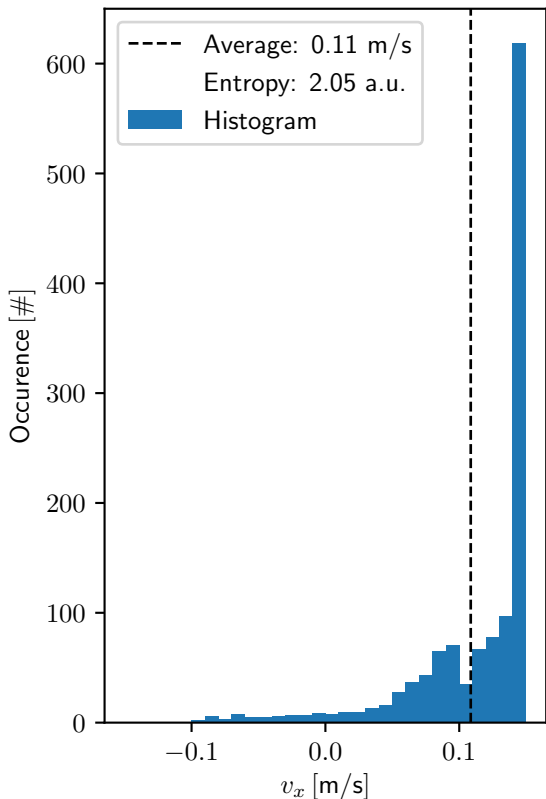


Distribution of Linear Velocity  
along x-Axis - Autonomously Controlled



Distribution of Angular Velocity  
about z-Axis - Autonomously Controlled

