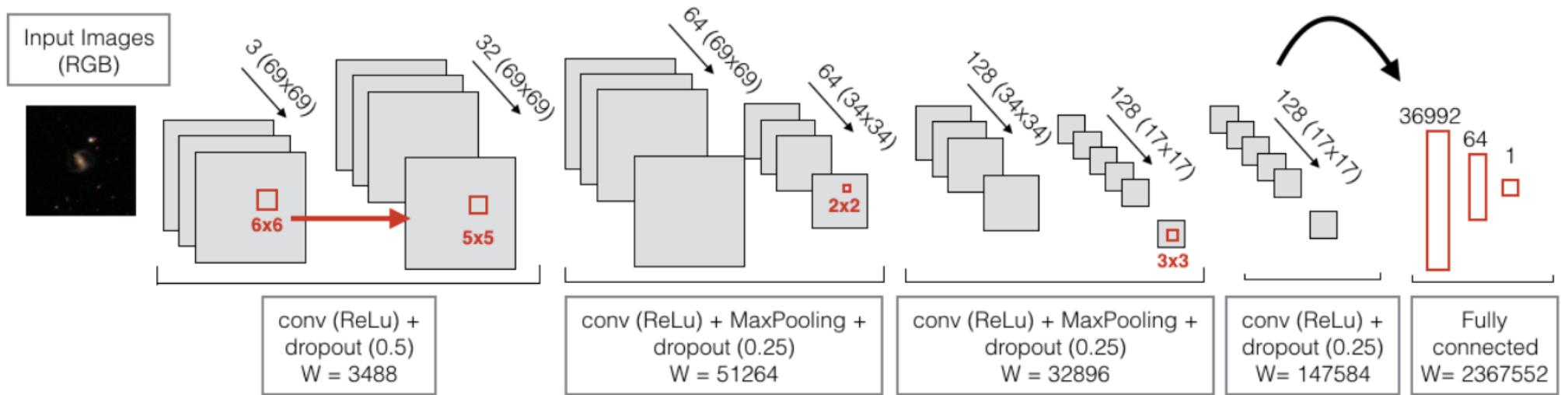


IMAGE2IMAGE

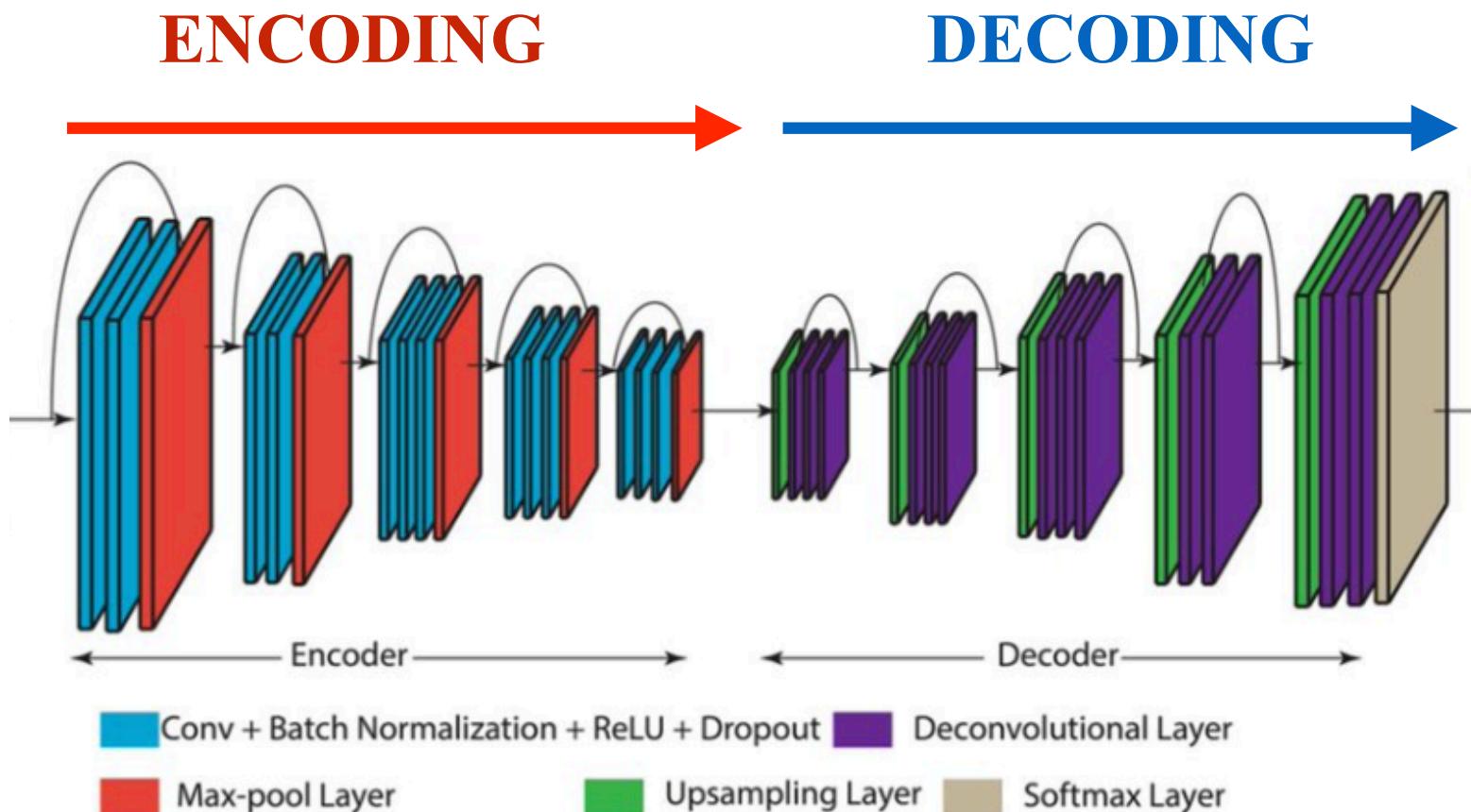
NETWORKS

UP TO NOW CNNs MAP IMAGES (SIGNALS) INTO FLOATS

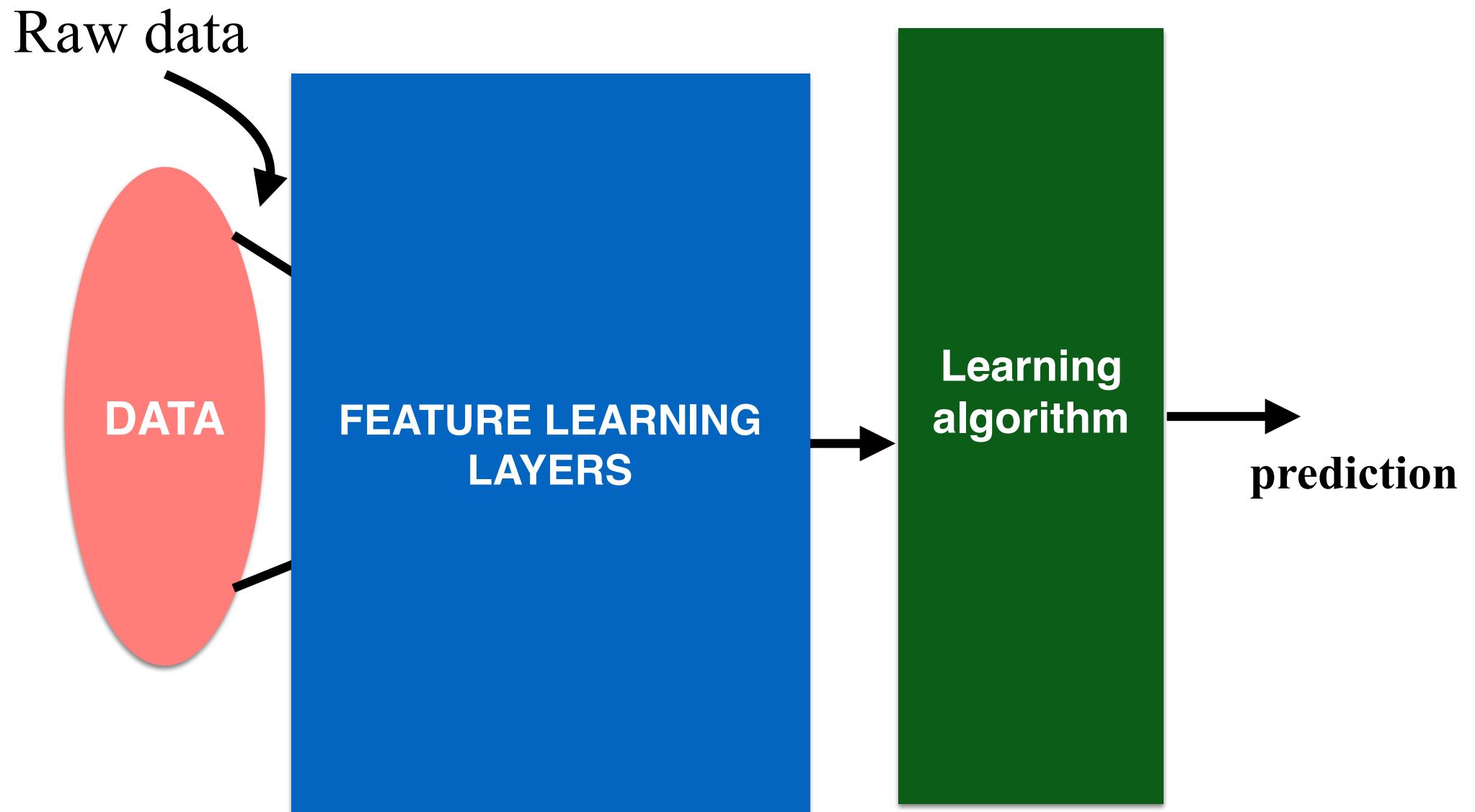


Dominguez-Sanchez+18

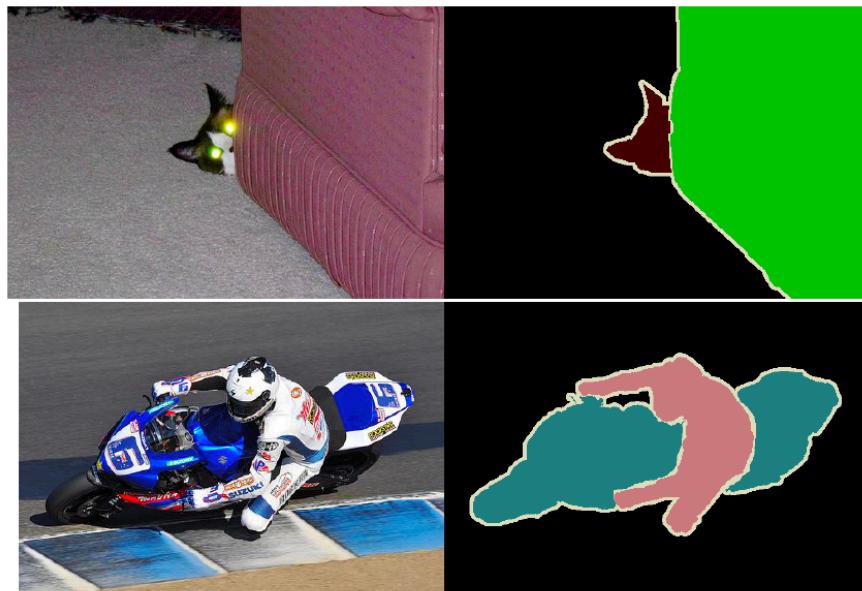
ENCODER-DECODERS GO FROM IMAGE 2 IMAGE



WE CALL THIS FULLY CONVOLUTIONAL
NEURAL NETWORKS

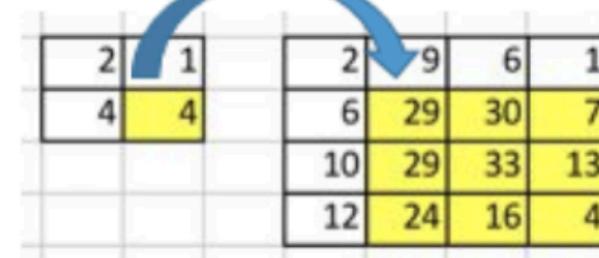
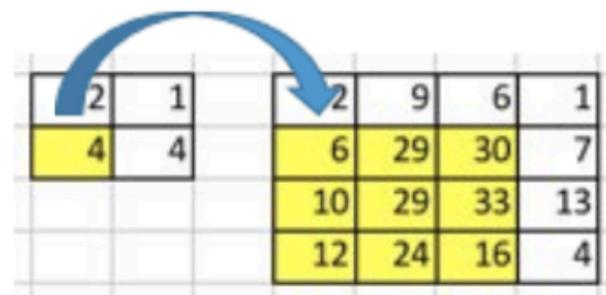
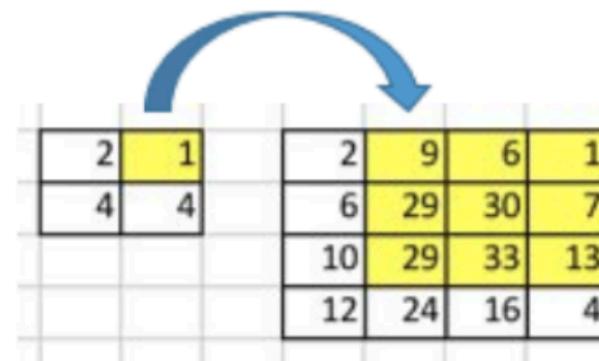
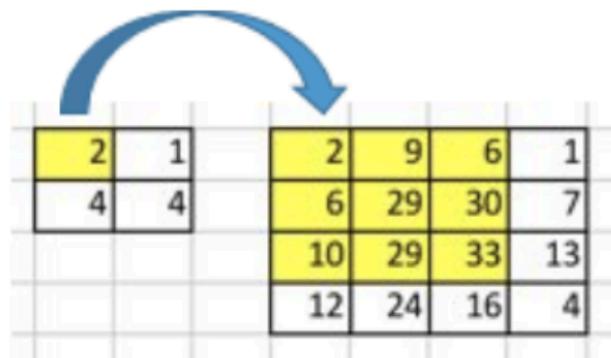


FIRST: IMAGE SEGMENTATION WITH ENCODERS-DECODERS



TRANSPOSED CONVOLUTION

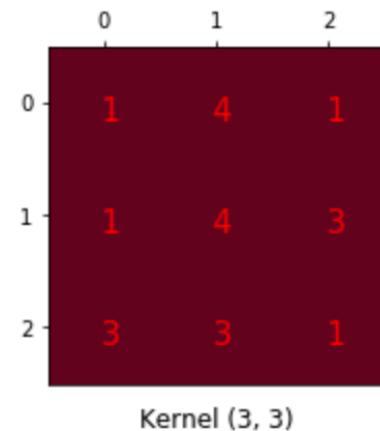
ALLOWS TO INCREASE THE SIZE



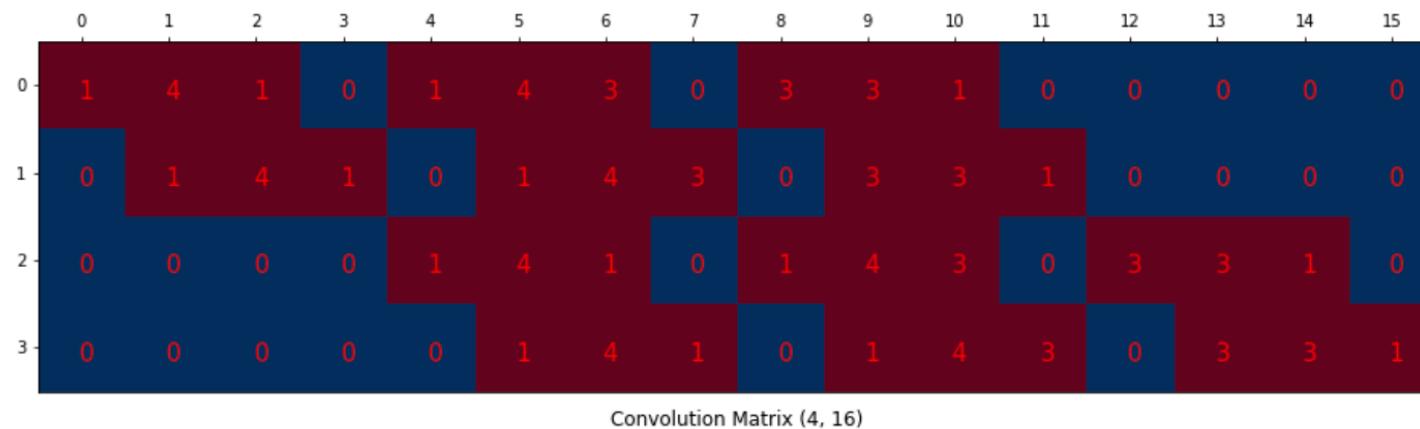
Going Backward of Convolution

EXAMPLE TAKEN FROM HERE

CONVOLUTION MATRIX

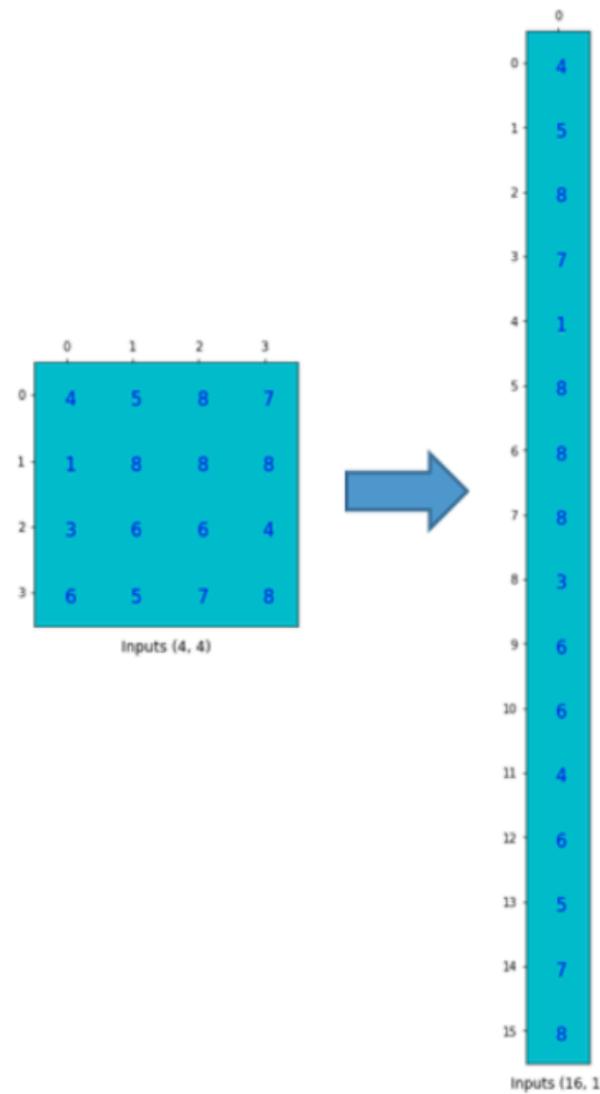


THE KERNEL CAN BE ARRANGED IN FORM OF A MATRIX:



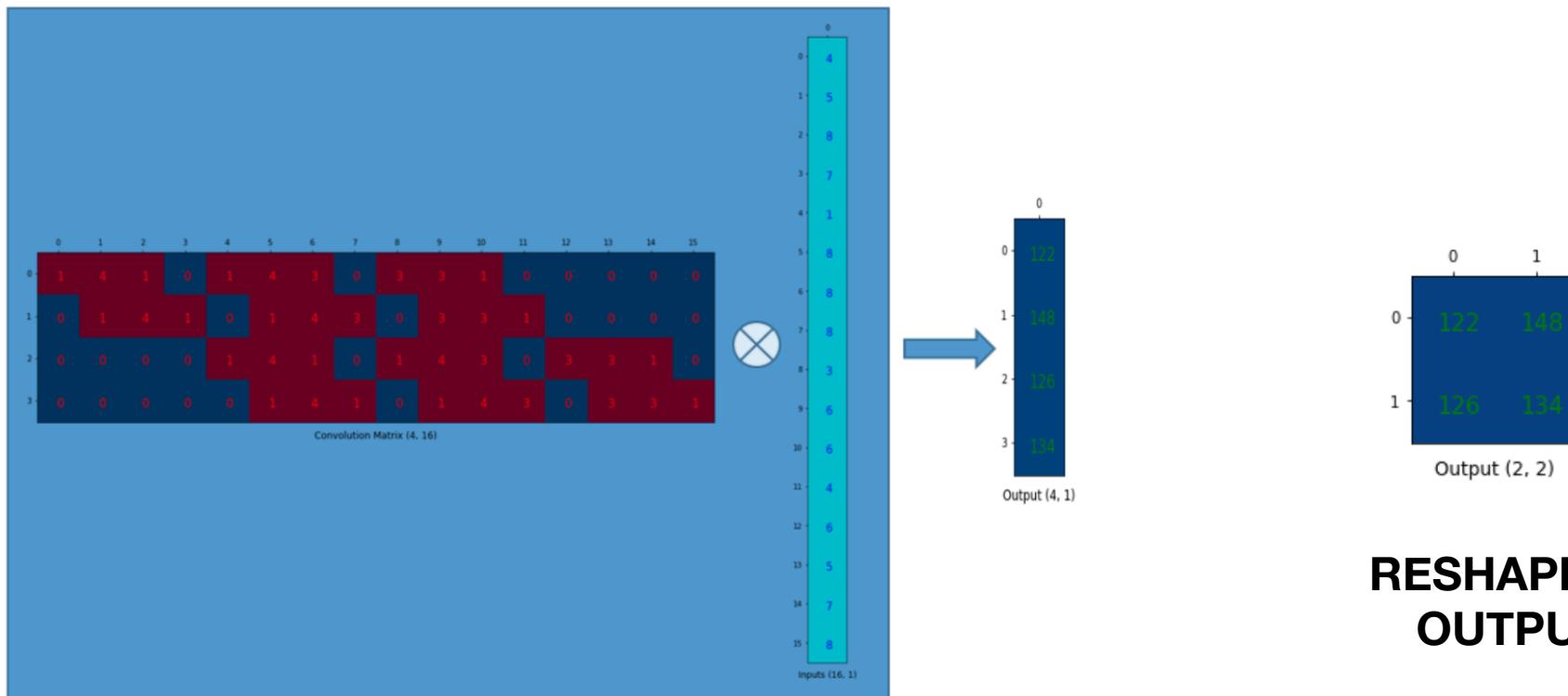
EXAMPLE TAKEN FROM HERE

THE INPUT IS FLATTENED INTO A COLUMN VECTOR

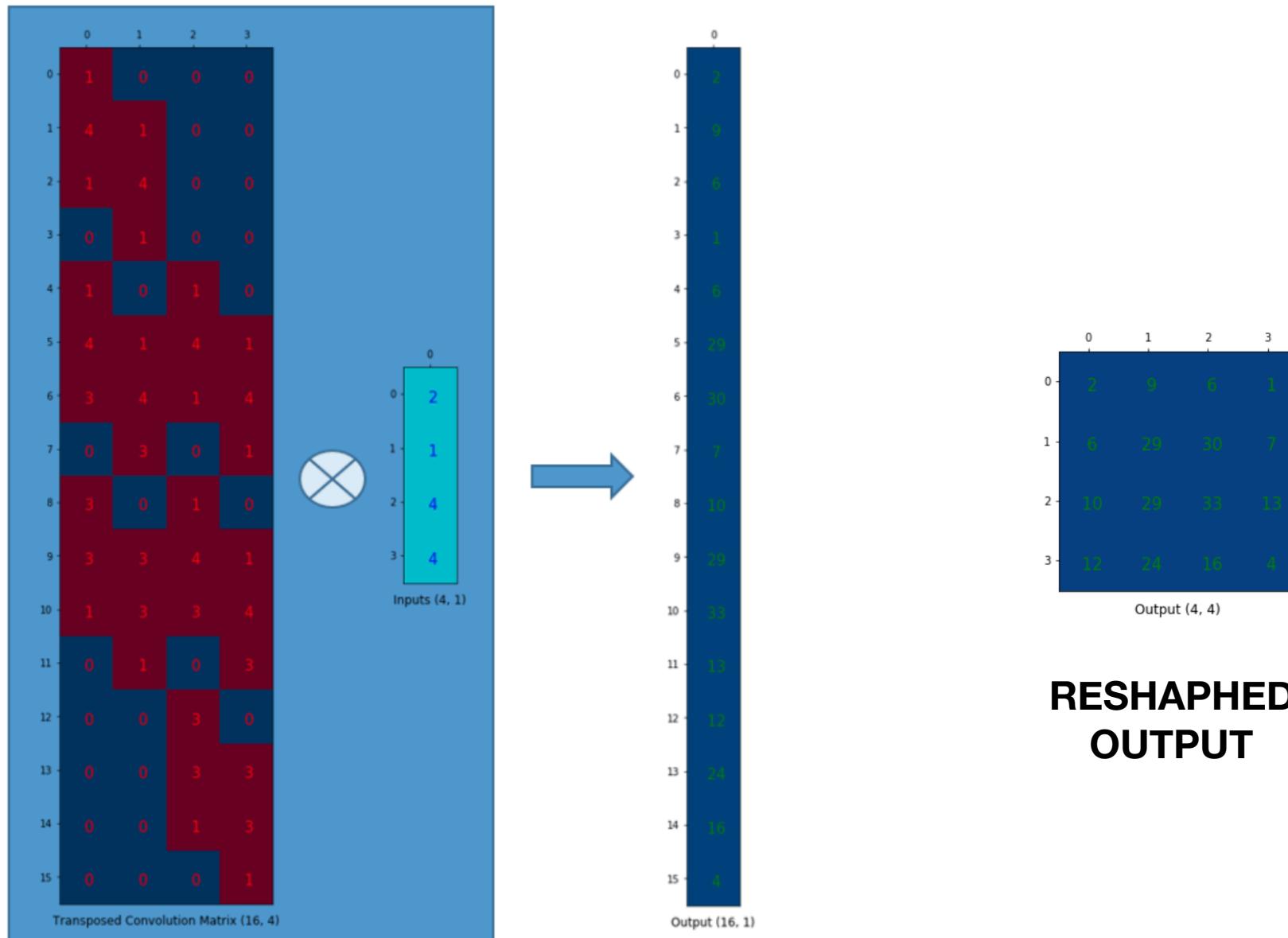


EXAMPLE TAKEN FROM HERE

THE CONVOLUTION IS TRANSFORMED INTO A PRODUCT OF MATRICES

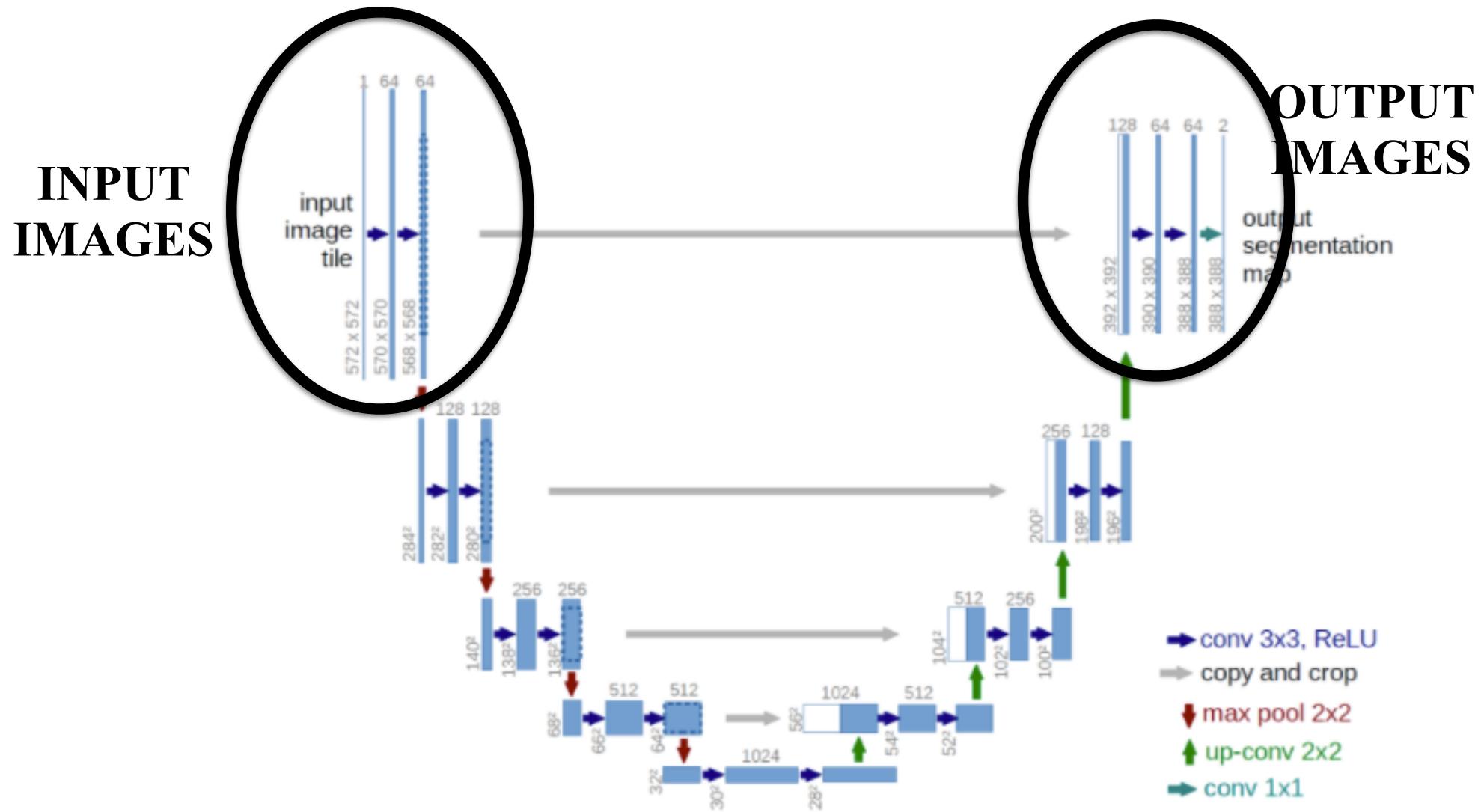


THE TRANSPOSED CONVOLUTION IS THE INVERSE OPERATION

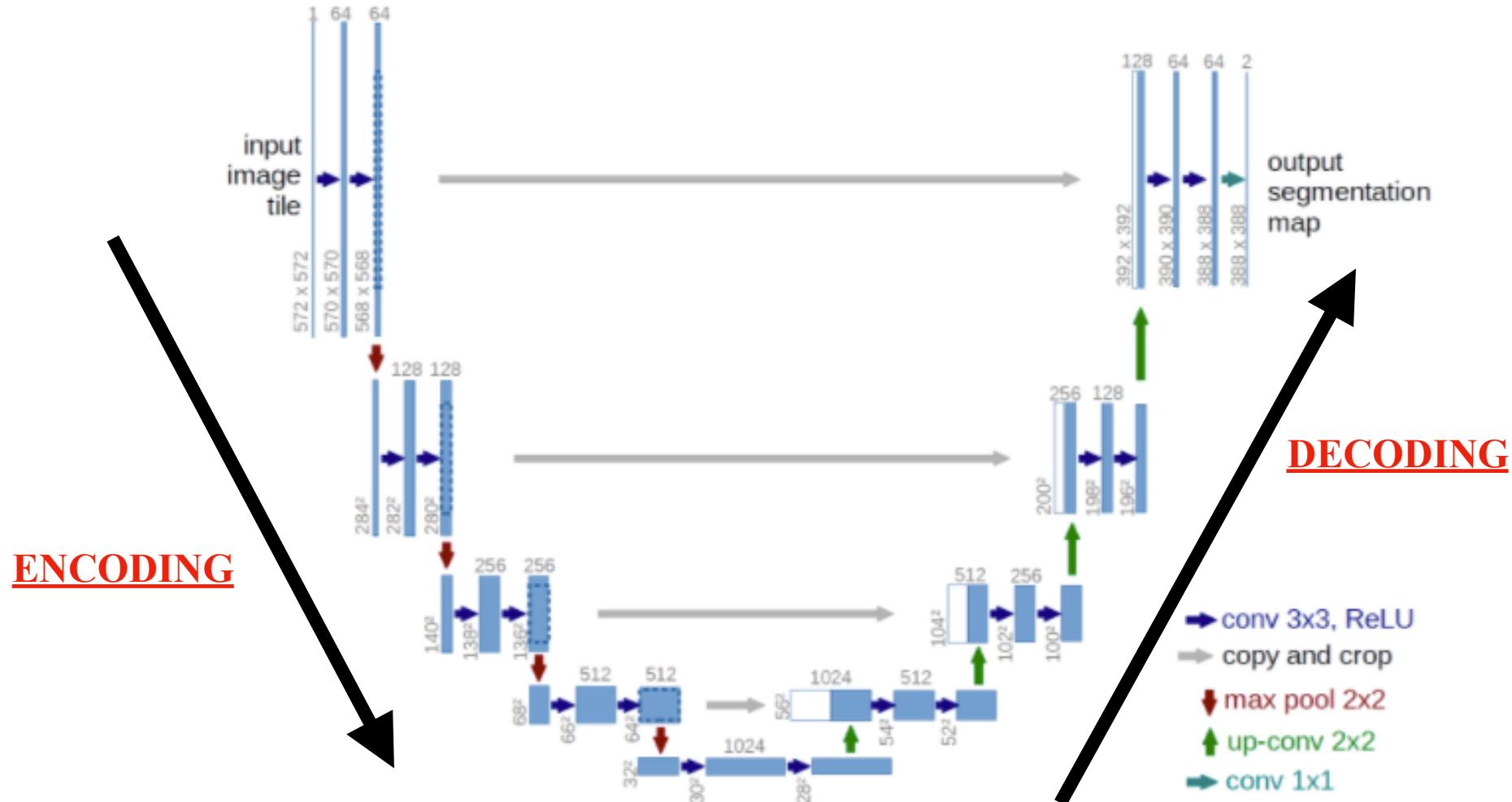


EXAMPLE TAKEN FROM HERE

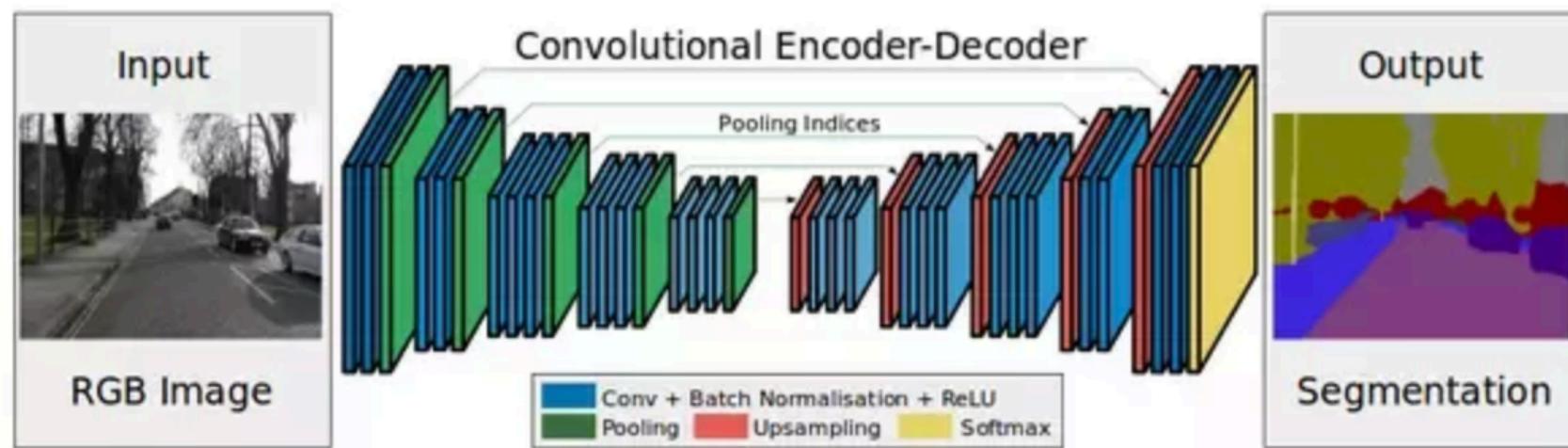
ENCODING-DECODING TO EXTRACT IMAGE FEATURES: U-NET

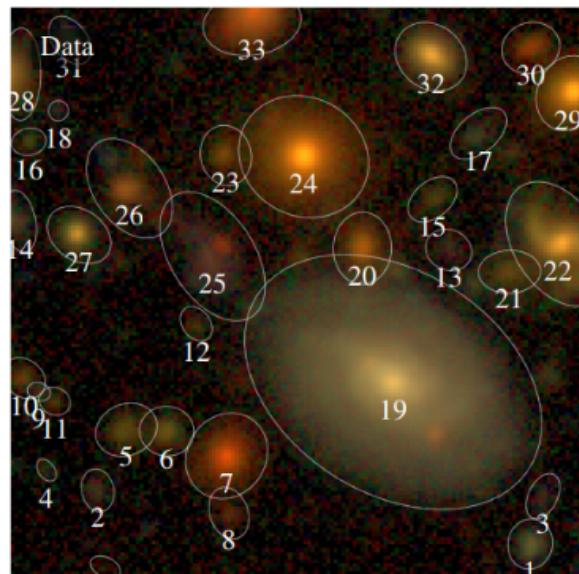
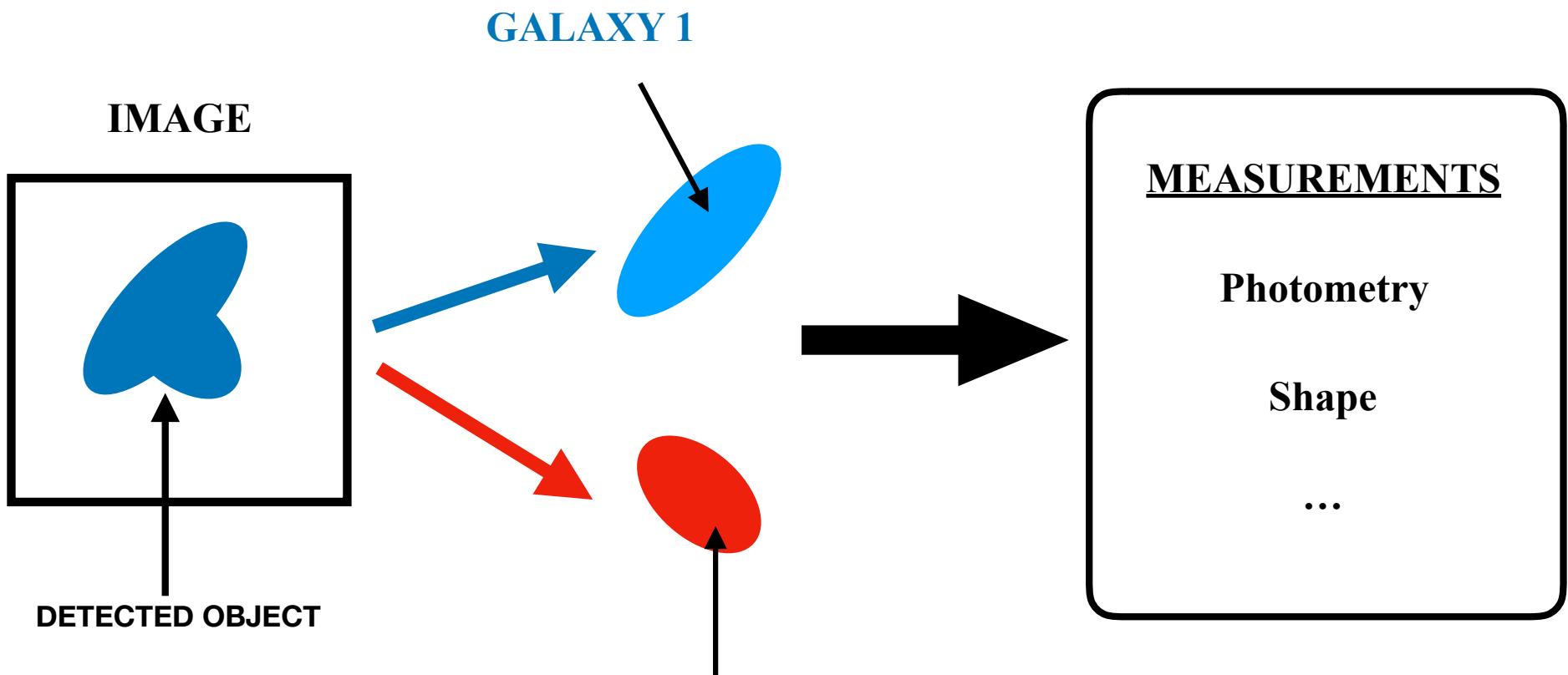


ENCODING-DECODING TO EXTRACT IMAGE FEATURES: U-NET

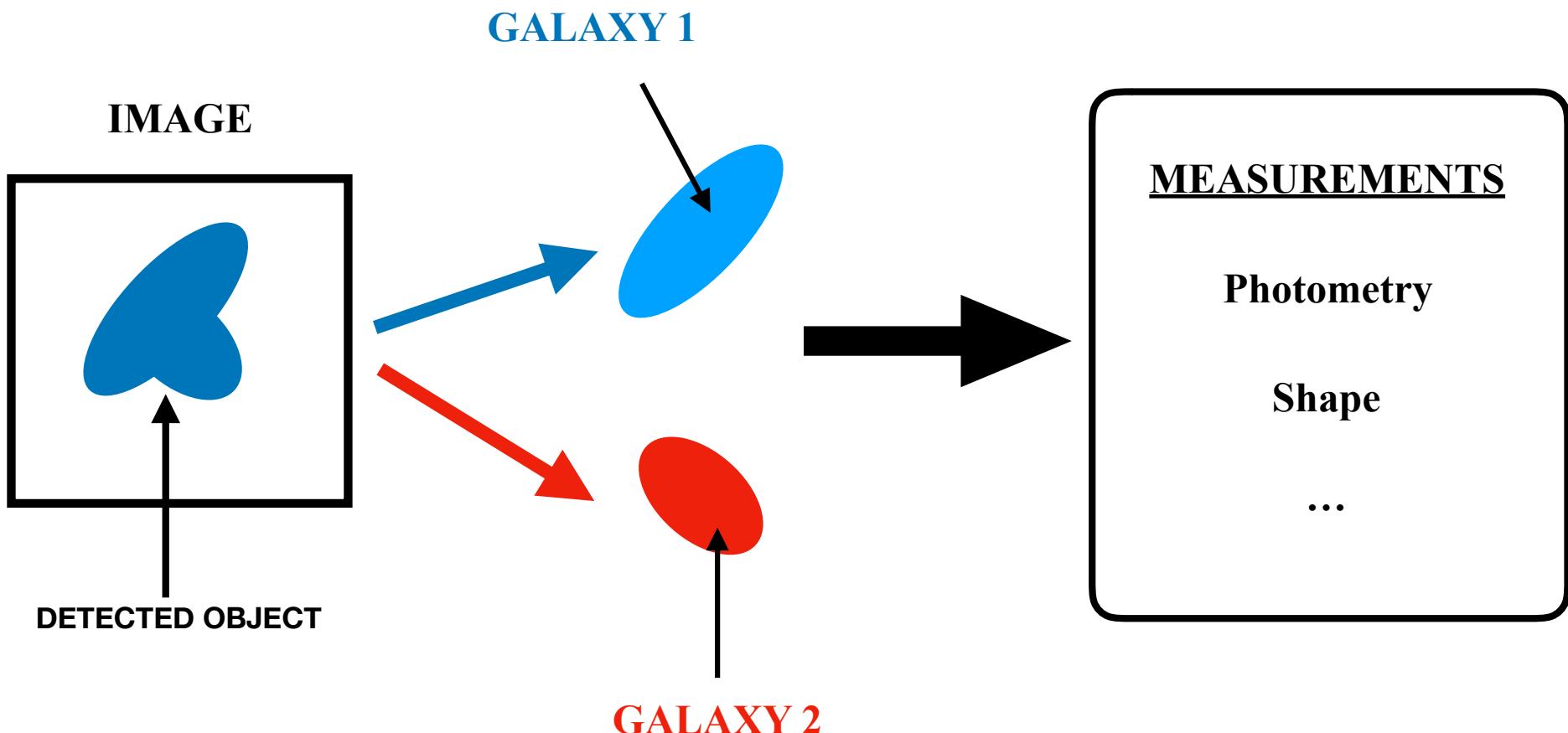


MAIN APPLICATION IS IMAGE SEGMENTATION

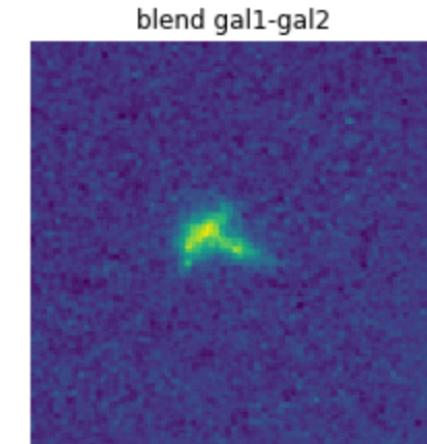
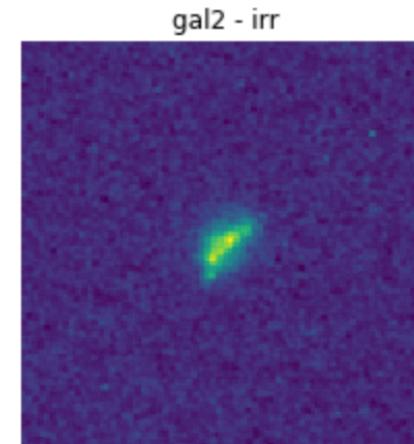
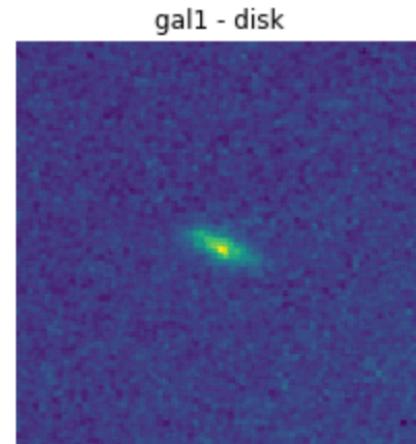




>50% of objects will be affected by blending in future deep surveys such as LSST



**ISOLATED
GALAXIES
ARTIFICIALLY
BLENDED**



U-NET (ENCODER DECODER)

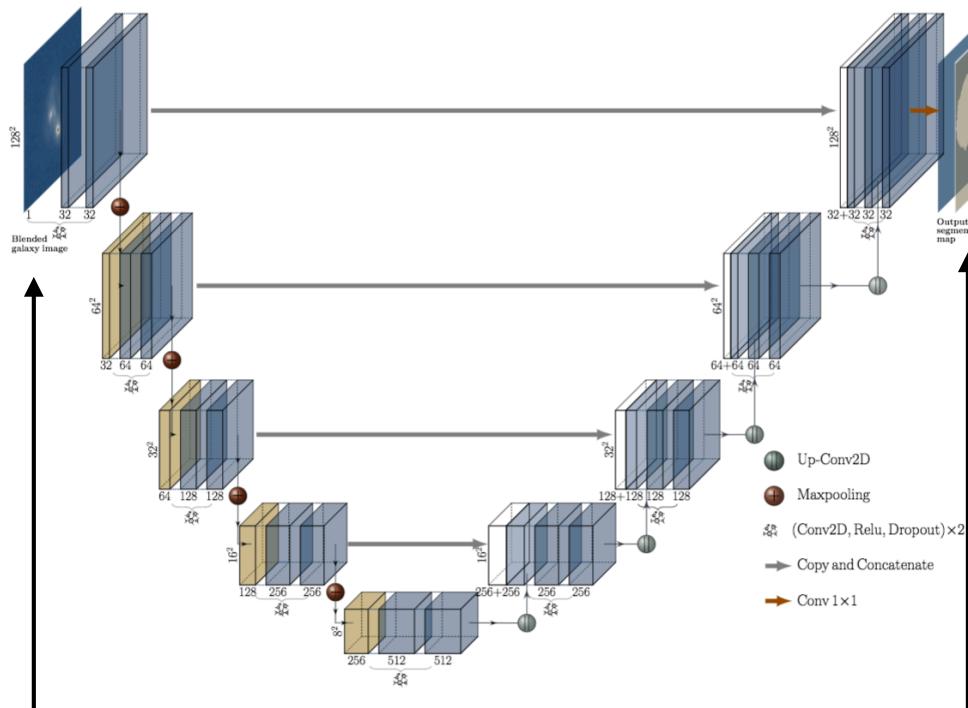
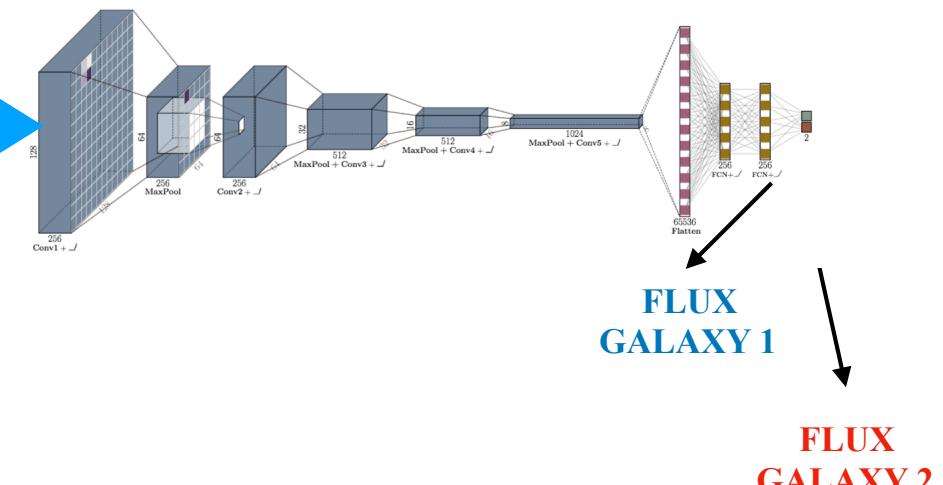
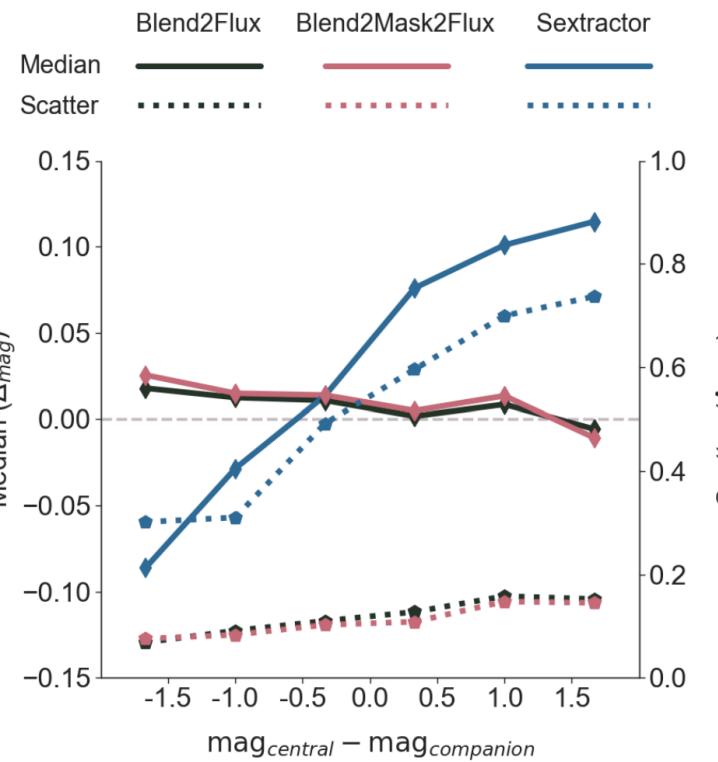
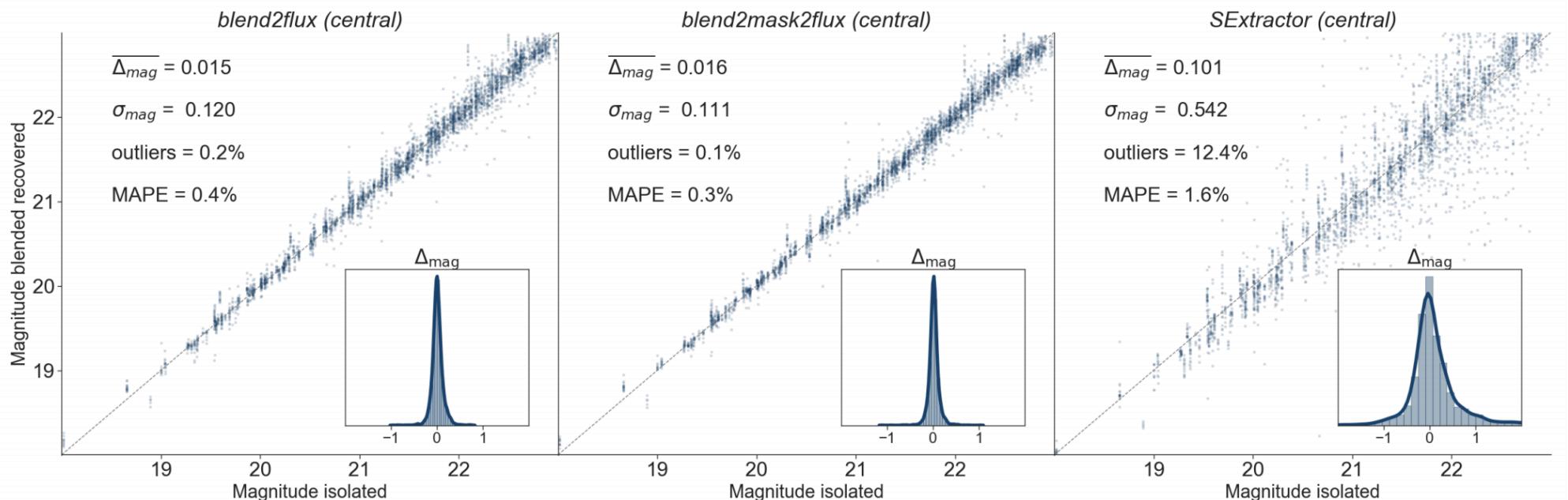


IMAGE OF
BLENDED
OBJECTS

OUTPUT
SEGMENTATIO
N MAP (BINARY
2 CHANNELS)

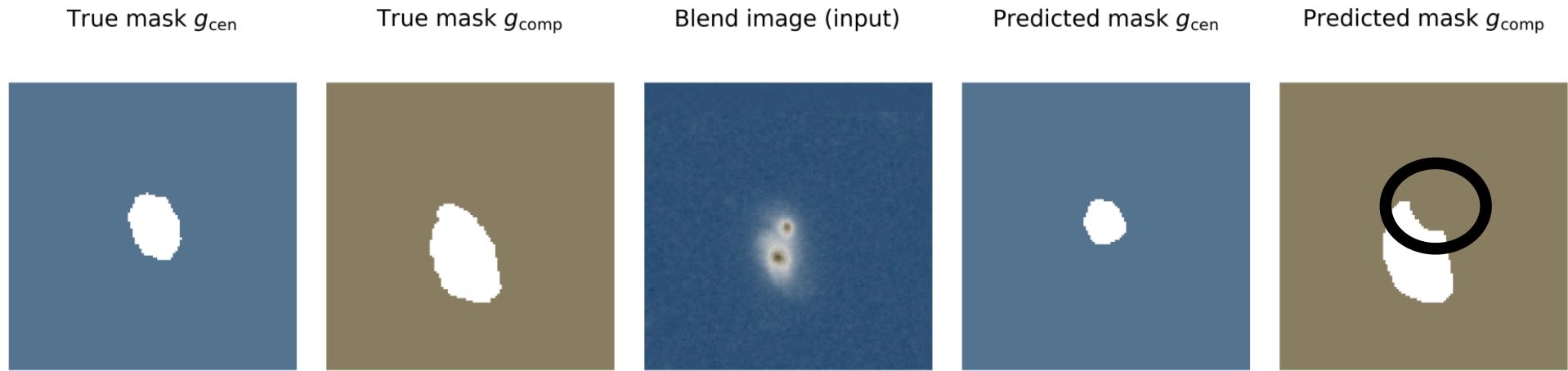
VANILLA CNN





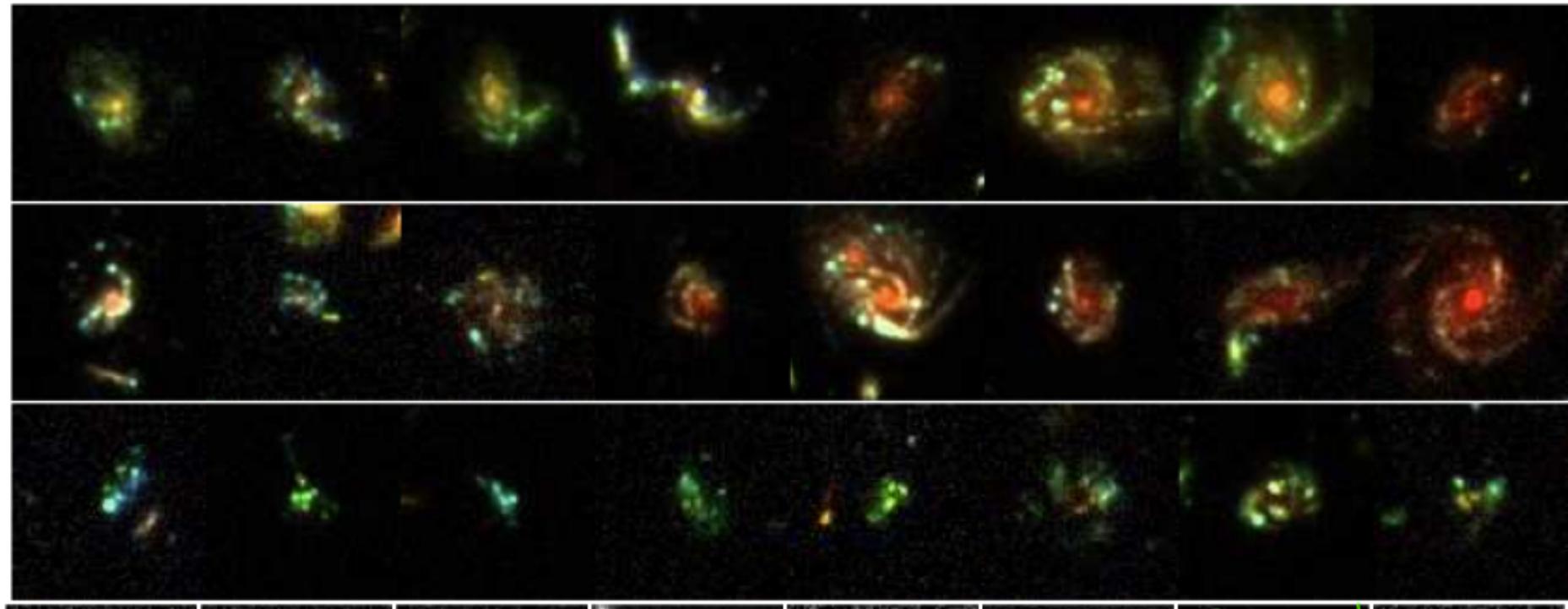
LESSONS LEARNED:

- It is easy to do better than SExtractor
- Masks do not provide additional information



THE U-NET LEARNS TO IGNORE THE BLENDED REGION...

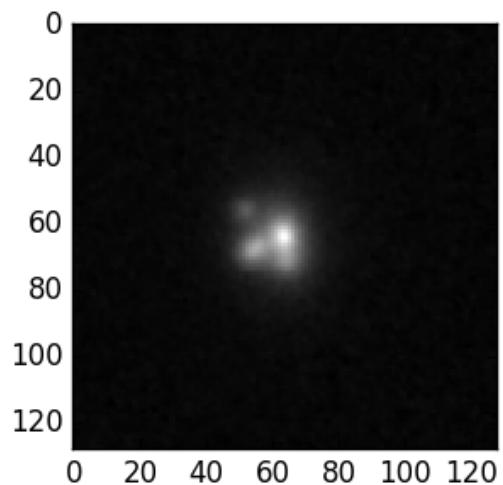
CLUMP DETECTION



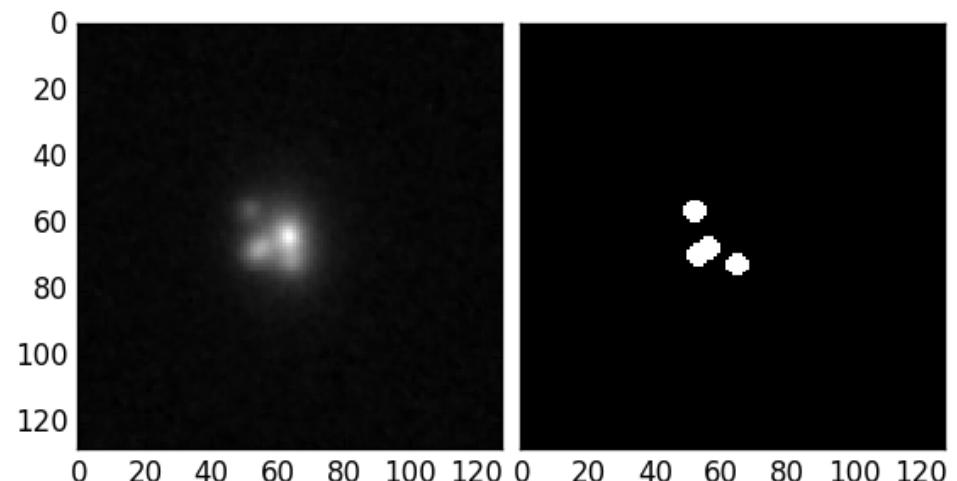
Guo+15,18

HIGH REDSHIFT GALAXIES PRESENT CLUMPS - THEIR
ROLE IN BULGE FORMATION IS DEBATED

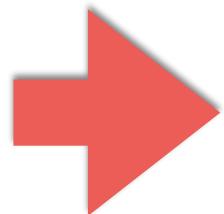
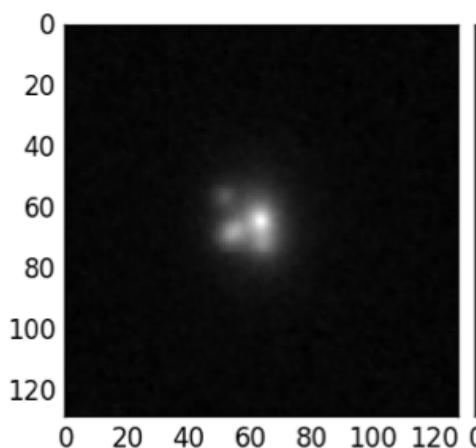
**VERY SIMPLE SERSIC
ANALYTIC
SIMULATIONS
+ UNRESOLVED
CLUMPS**



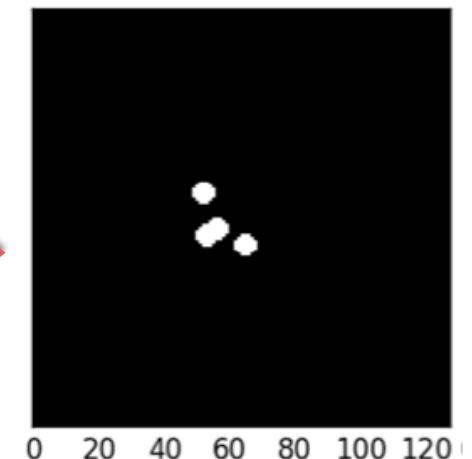
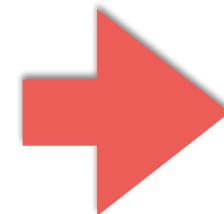
**VERY SIMPLE SERSIC
ANALYTIC
SIMULATIONS
+ UNRESOLVED
CLUMPS**



**CLUMP
POSITION IS
KNOWN**

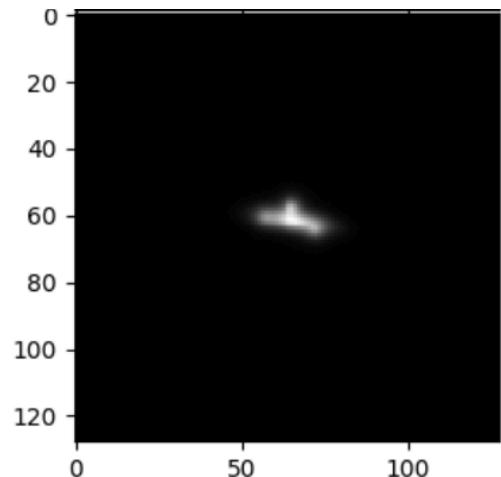


U-NET

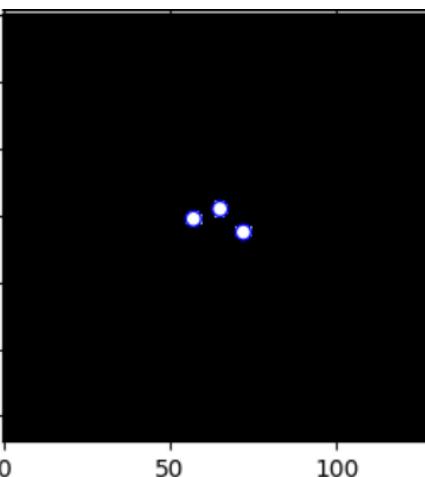


LEE, MHC, PRIMACK, GUO+

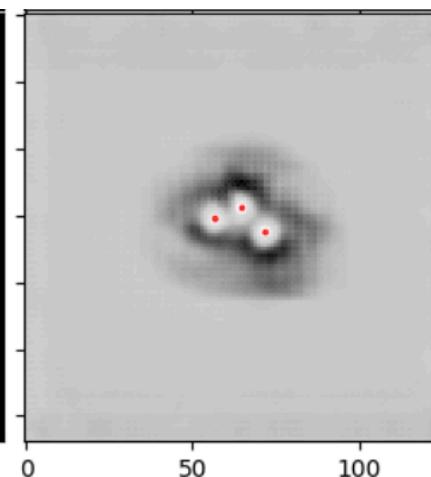
SIMULATED
GALAXY



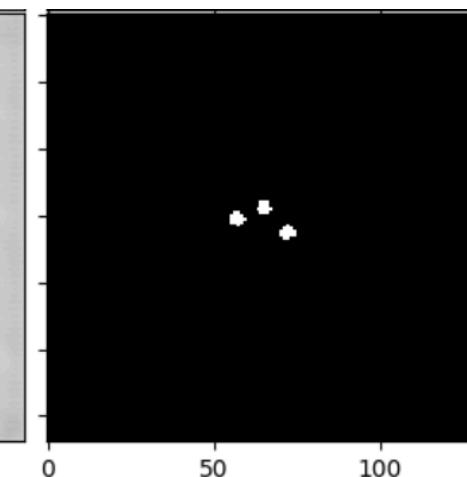
CLUMP
MASK



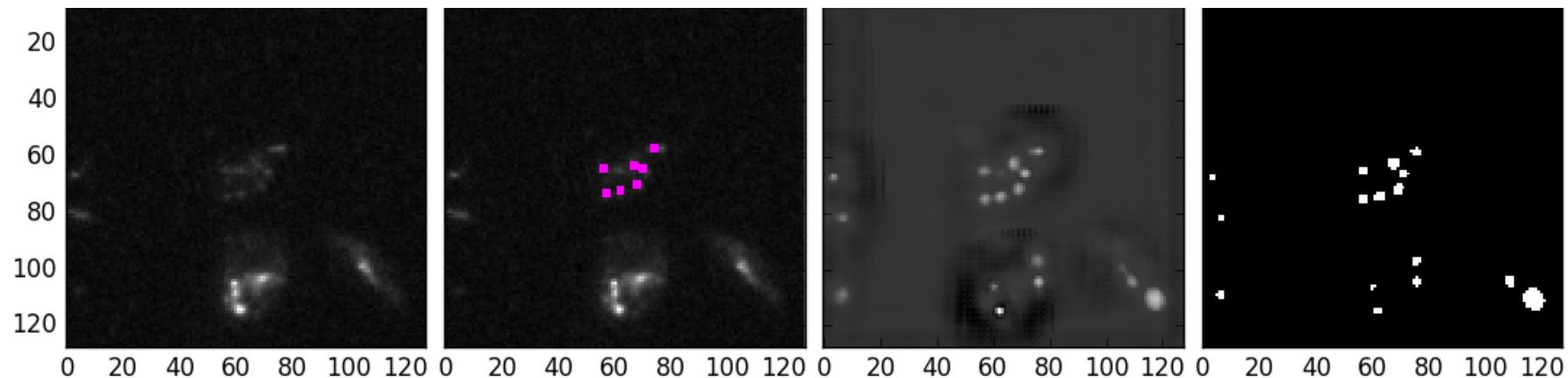
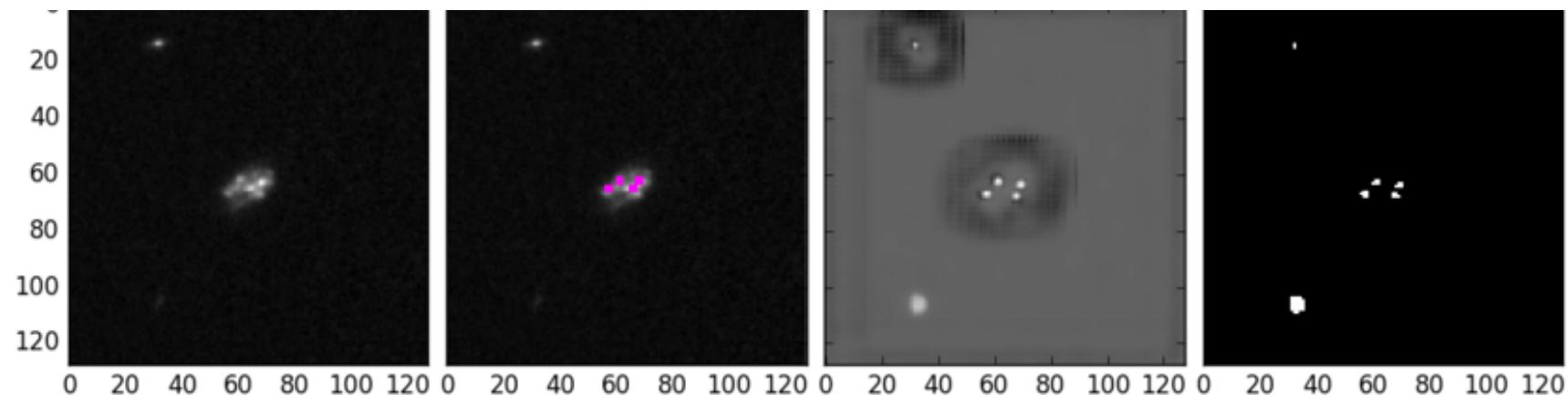
NETWORK
PROBA
MAP



NETWORK
OUTPUT
THRESHOLDED
(SEXTRACTOR)



SEEMS TO WORK REASONABLY WELL ON REAL OBSERVATIONS



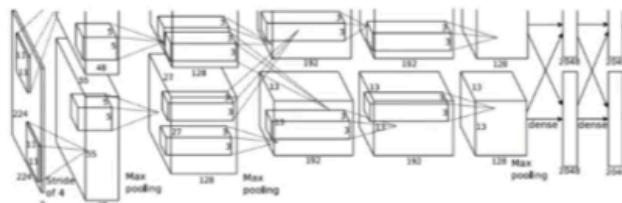
OBSERVED
GALAXY

CLUMPS
DETECTED BY
GUO+

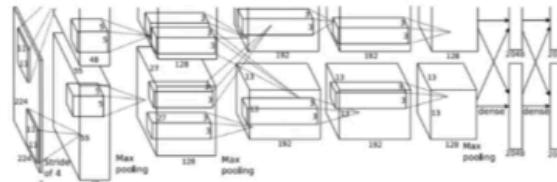
U-NET OUTPUTS

A WORD ON R-CNNs..

JUST FOR YOUR RECORDS...



CAT: (x, y, w, h)



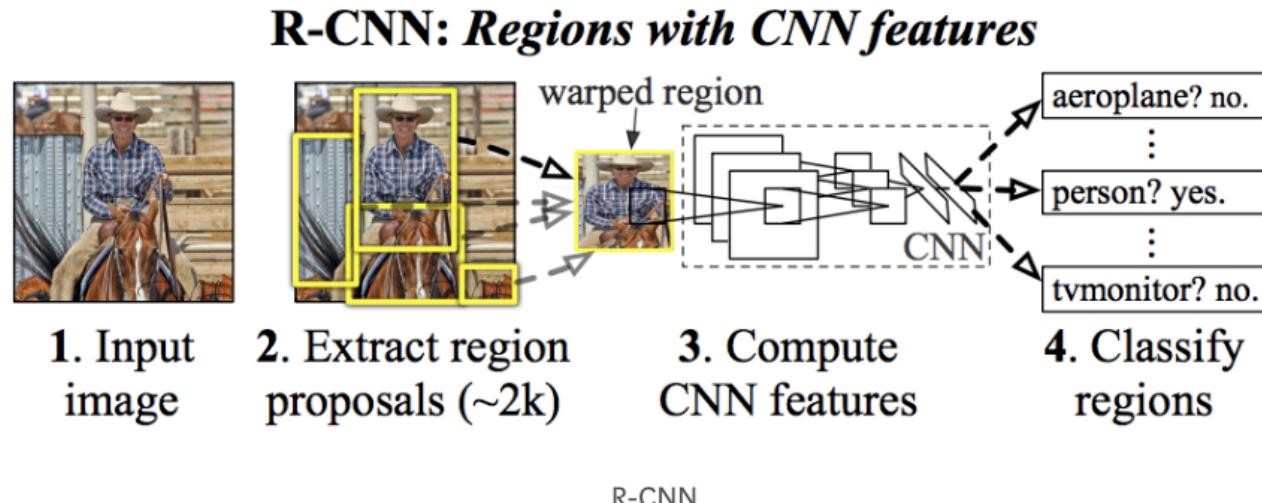
DUCK: (x, y, w, h)
DUCK: (x, y, w, h)

....

Girshick+14

A WORD ON R-CNNs..

JUST FOR YOUR RECORDS...

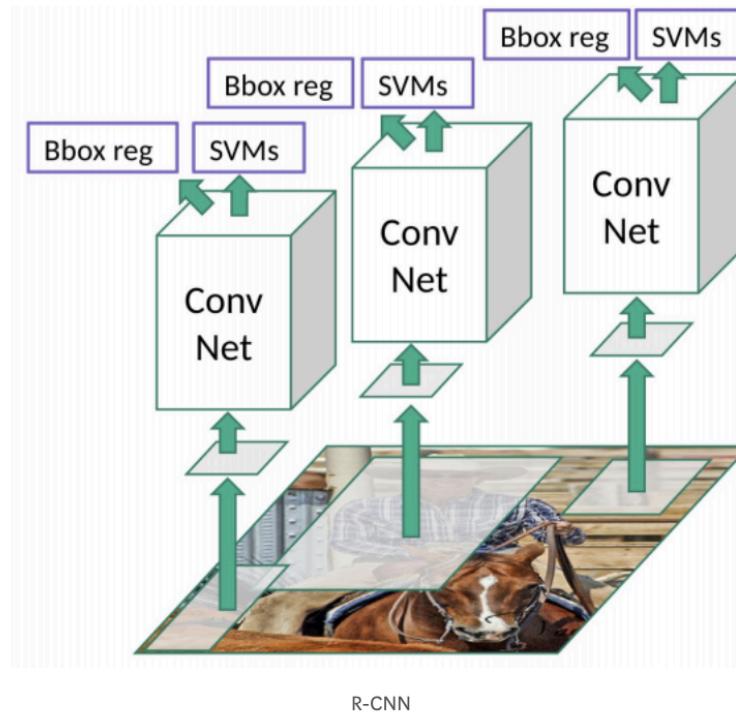


A WORKD ON R-CNNs..

JUST FOR YOUR RECORDS...

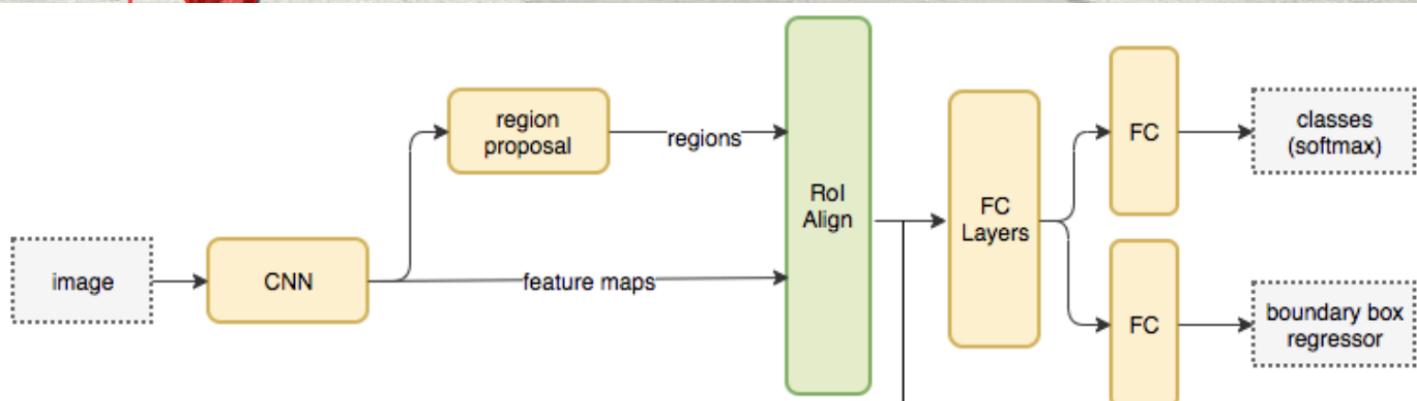
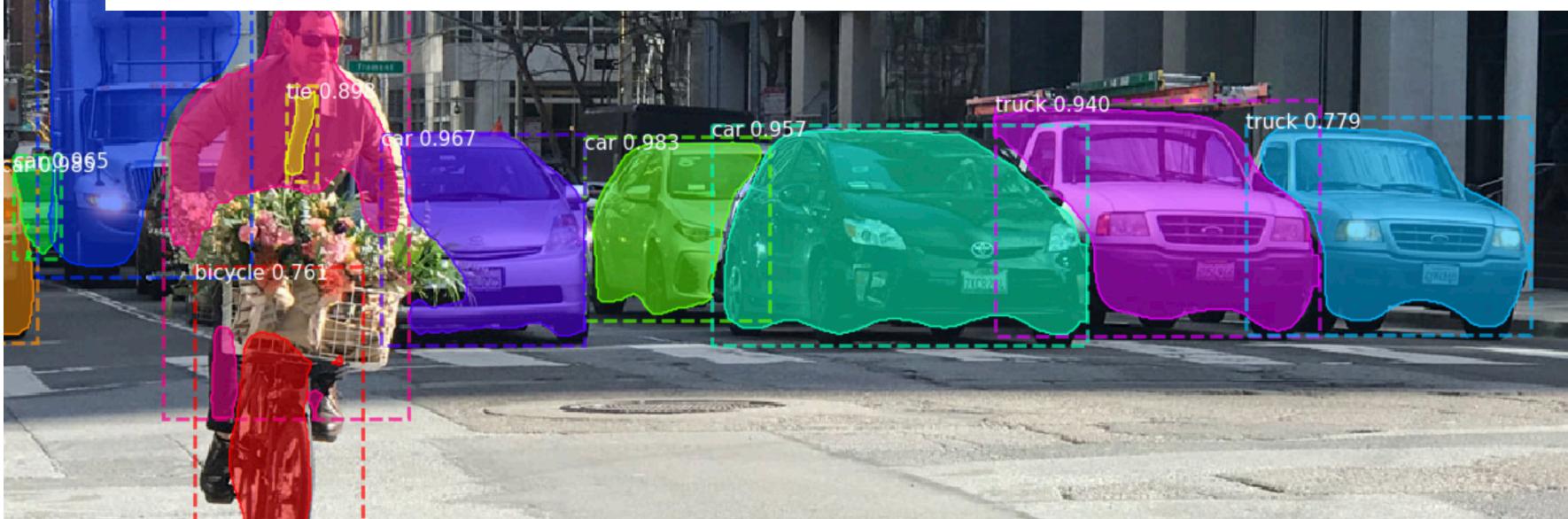


1. Input image



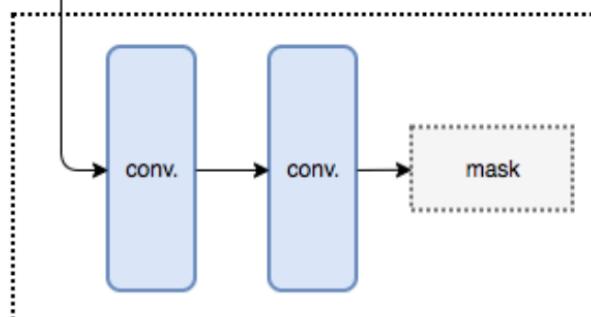
eroplane? no.
⋮
erson? yes.
⋮
vmonitor? no.
. Classify regions

SIMULTANEOUS DETECTION + SEGMENTATION + CLASSIFICATION



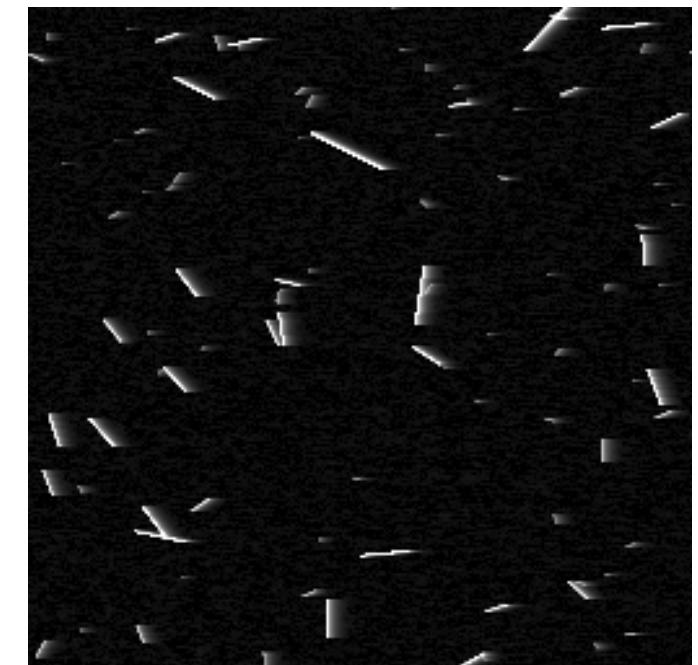
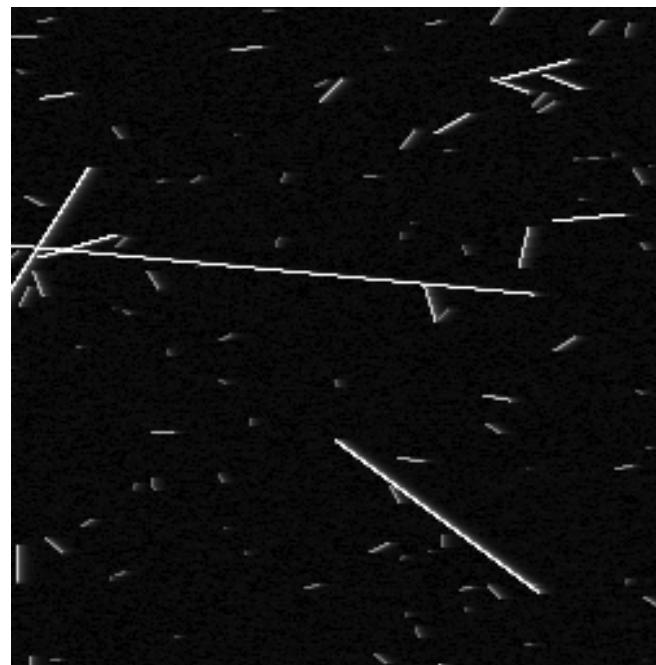
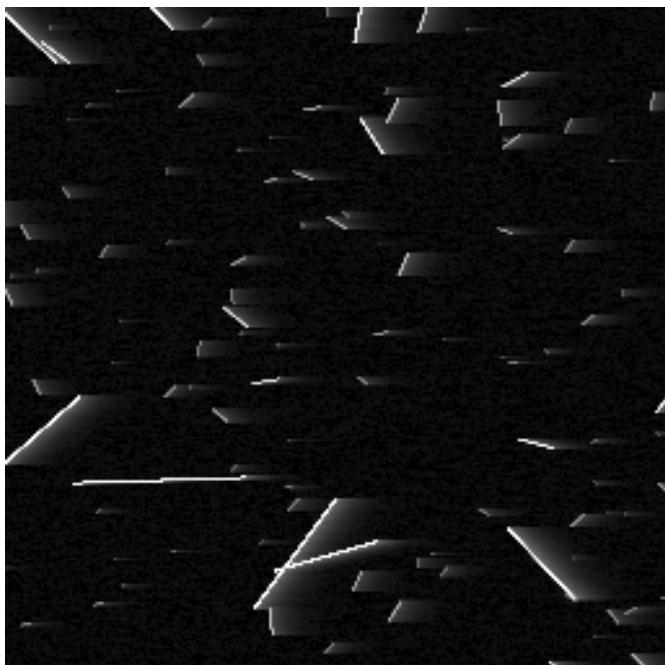
MASK R-CNN

He+17



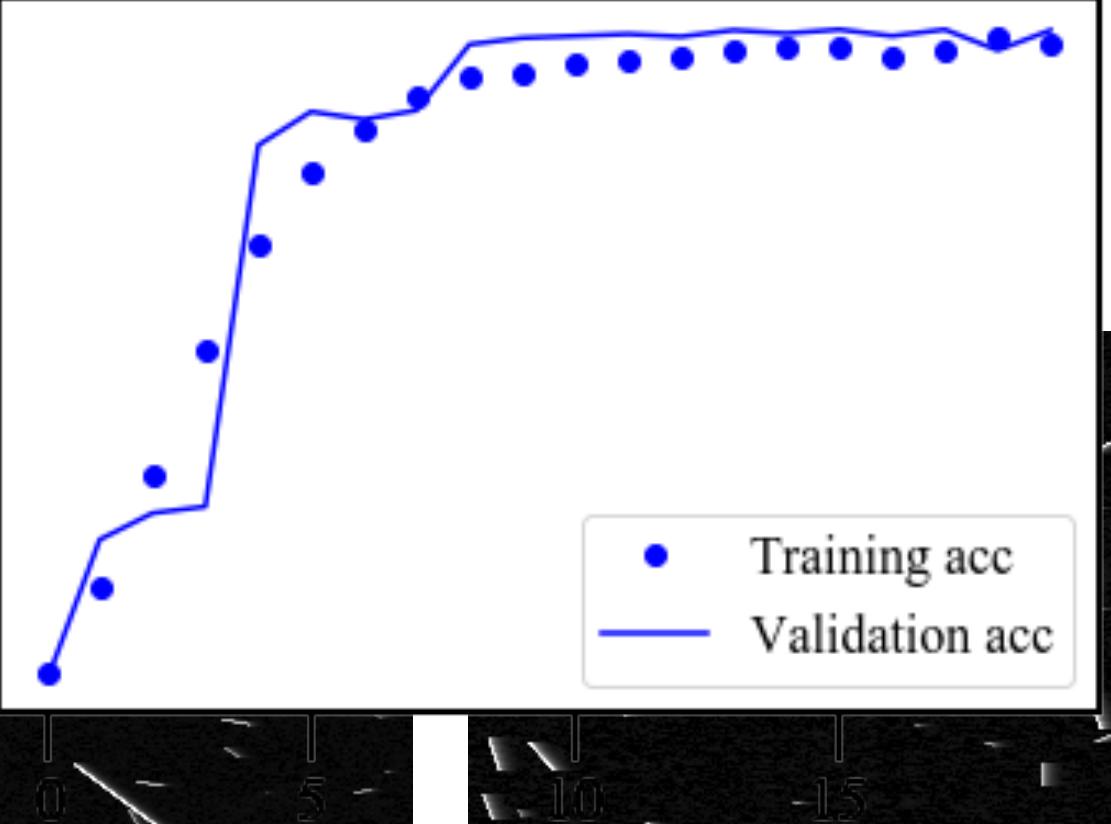
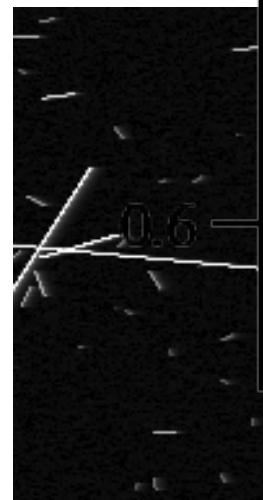
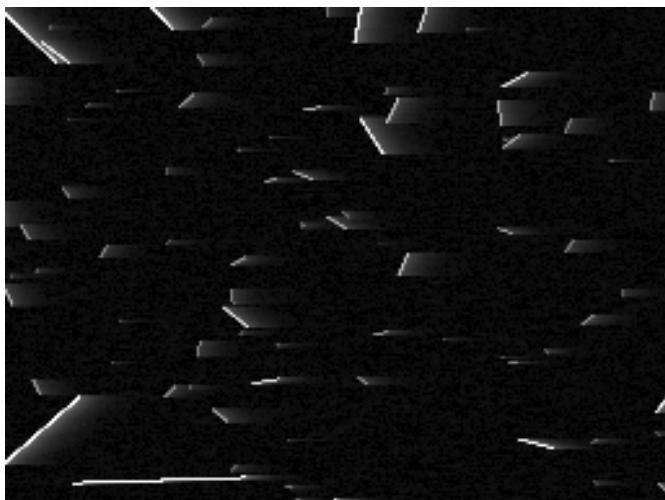
Mask

DATA QUALITY SELECTION FOR EUCLID

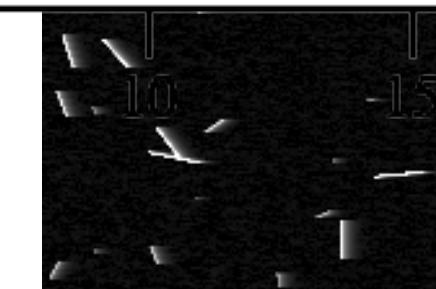
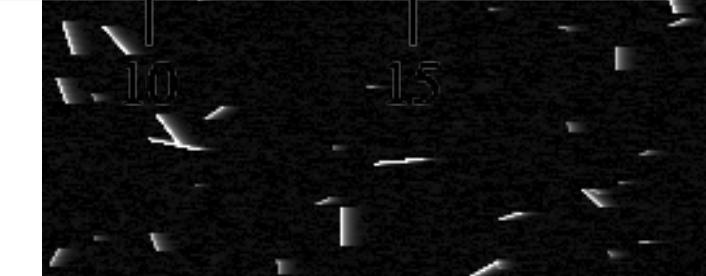


Thanks to H. McCracken

DATA QUALITY SE

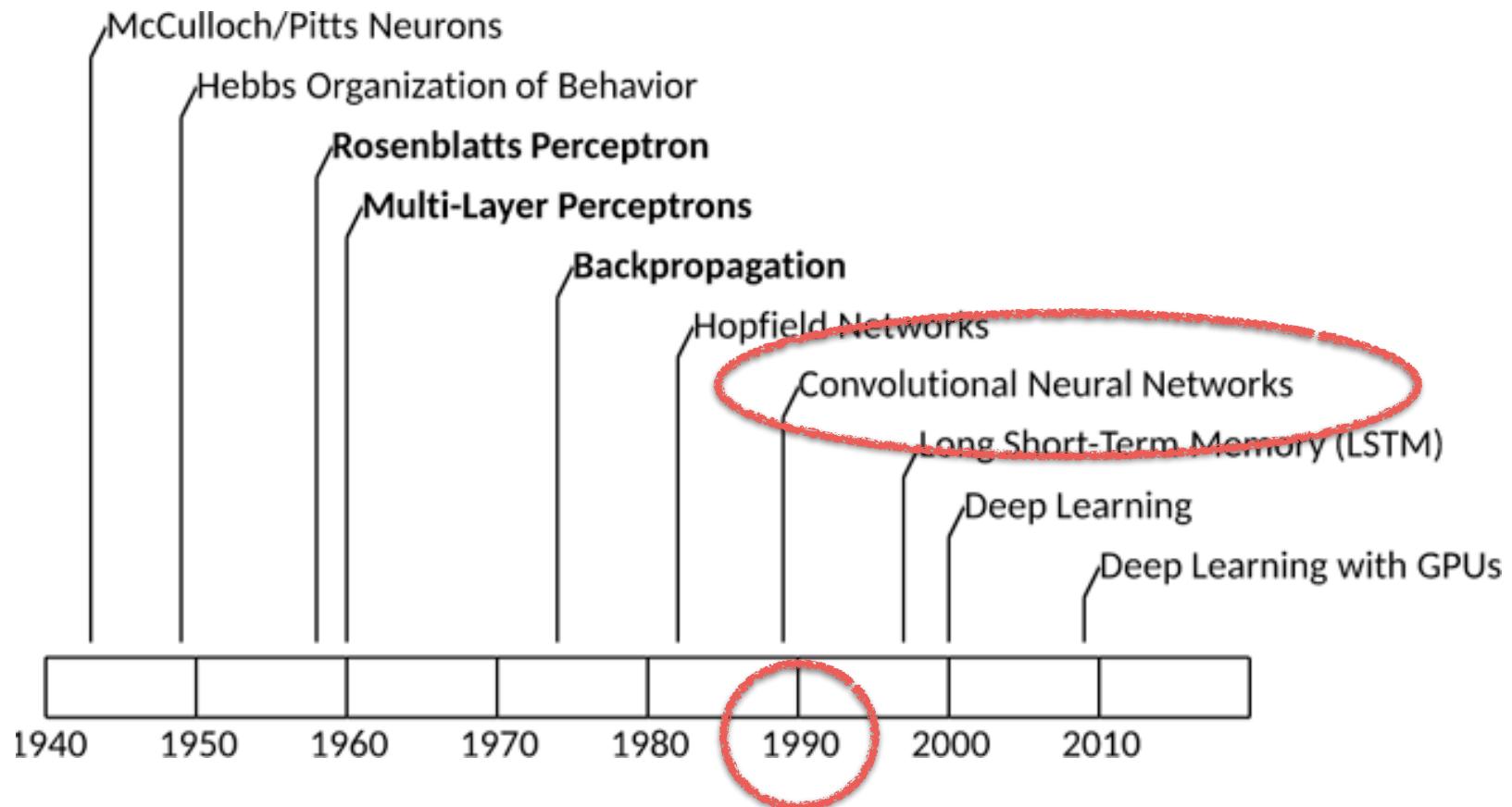


```
model = models.Sequential()
model.add(layers.Conv2D(32, (3, 3), activation='relu',
                      input_shape=(150, 150, 1)))
model.add(layers.MaxPooling2D((2, 2)))
model.add(layers.Conv2D(64, (3, 3), activation='relu'))
model.add(layers.MaxPooling2D((2, 2)))
model.add(layers.Conv2D(64, (3, 3), activation='relu'))
model.add(layers.MaxPooling2D((2, 2)))
model.add(layers.Flatten())
model.add(layers.Dense(128, activation='relu'))
model.add(layers.Dense(1, activation='sigmoid'))
```



Thanks to H. McCracken

WELL, BUT THIS IS AN “OLD” IDEA - WHY NOW?



WELL, BUT THIS IS AN “OLD” IDEA - WHY NOW?

1 - MORE DATA TO TRAIN! DEEP NETWORKS HAVE A
LARGE NUMBER OF PARAMETERS - THX TO SOCIAL
MEDIA ...

WELL, BUT THIS IS AN
“OLD” IDEA - WHY NOW?

2 - GPUs - TRAINING OF THESE DEEP NETWORKS
HAS REMAINED PROHIBITIVELY TIME CONSUMING
WITH CPUs - THX TO VIDEO GAMES...

GPUs



NVIDIA TITANX GPU

GPUs vs. CPUs

CPUs

FEWER CORES (~10x)

EACH CORE IS FASTER

USEFUL FOR
SEQUENTIAL TASKS

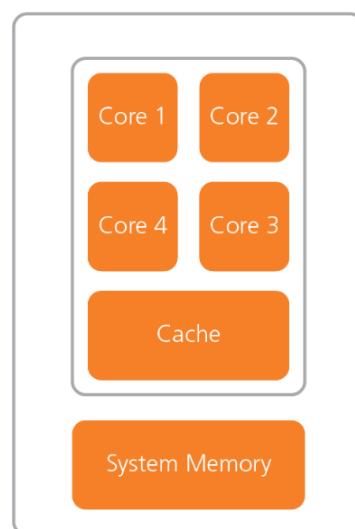
GPUs

MORE CORES (100x)

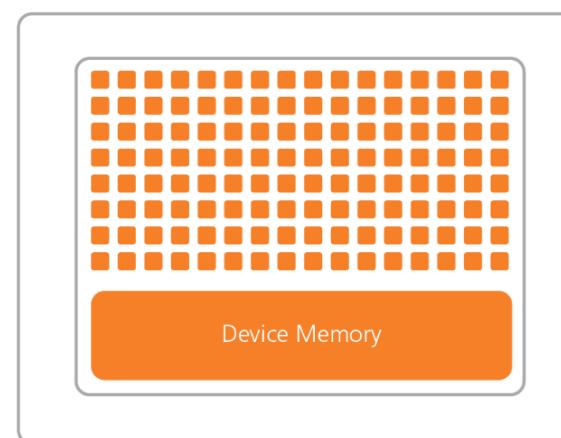
EACH CORE IS SLOWER

USEFUL FOR PARALLEL
TASKS

CPU (Multiple Cores)



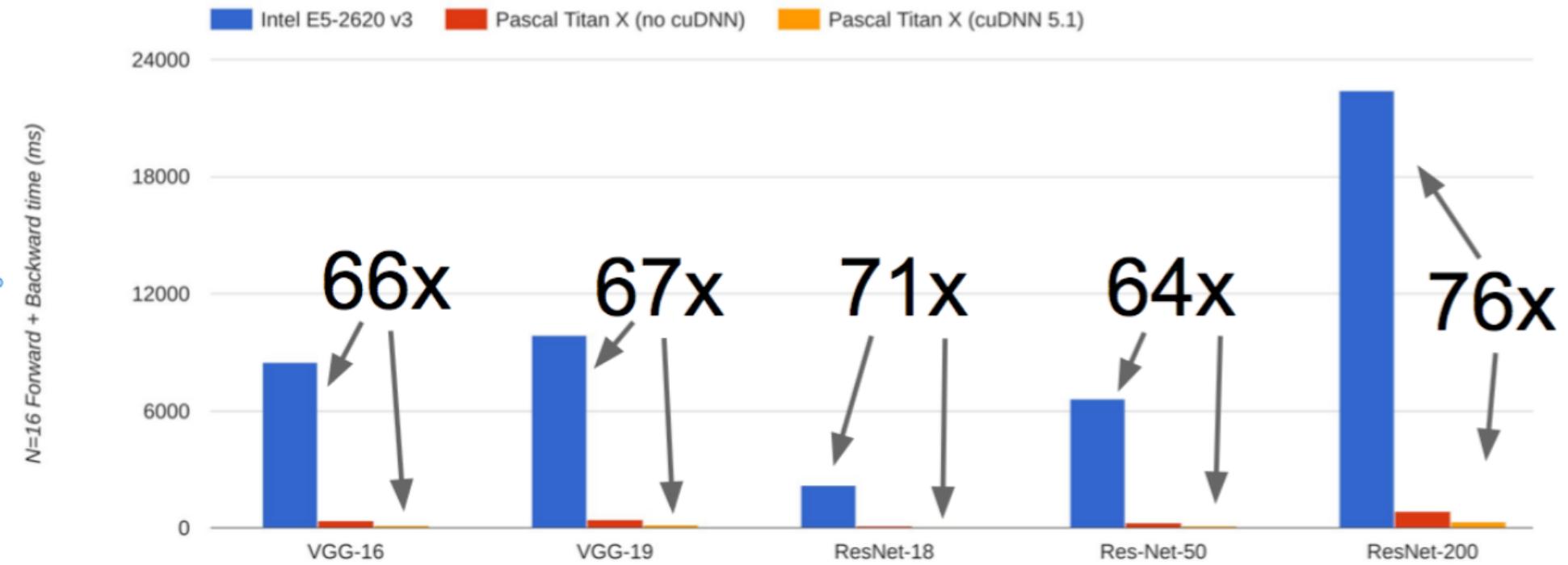
GPU (Hundreds of Cores)



Slide Credit:

GPUs vs. CPUs

More benchmarks available [here](#).



GPUs for deep learning

NVIDIA GPUs ARE PROGRAMMED THROUGH CUDA
[Compute Unified Device Architecture]

ANOTHER ALTERNATIVE IS OPENCL, SUPPORTED BY
SEVERAL MANUFACTURES, LESS INVESTMENT [Way less
used]

CuDNN IS A LIBRARY FOR SPECIFIC DEEP LEARNING
COMPUTATIONS ON NVIDIA GPUs

THE PRICE TO PAY?

1. LARGE NUMBER OF PARAMETERS IMPLIES LARGE DATASETS TO TRAIN
2. LOOSE EVEN MORE DEGREE OF CONTROL OF WHAT THE ALGORITHM IS DOING SINCE THE FEATURE EXTRACTION PROCESS BECOMES UNSUPERVISED

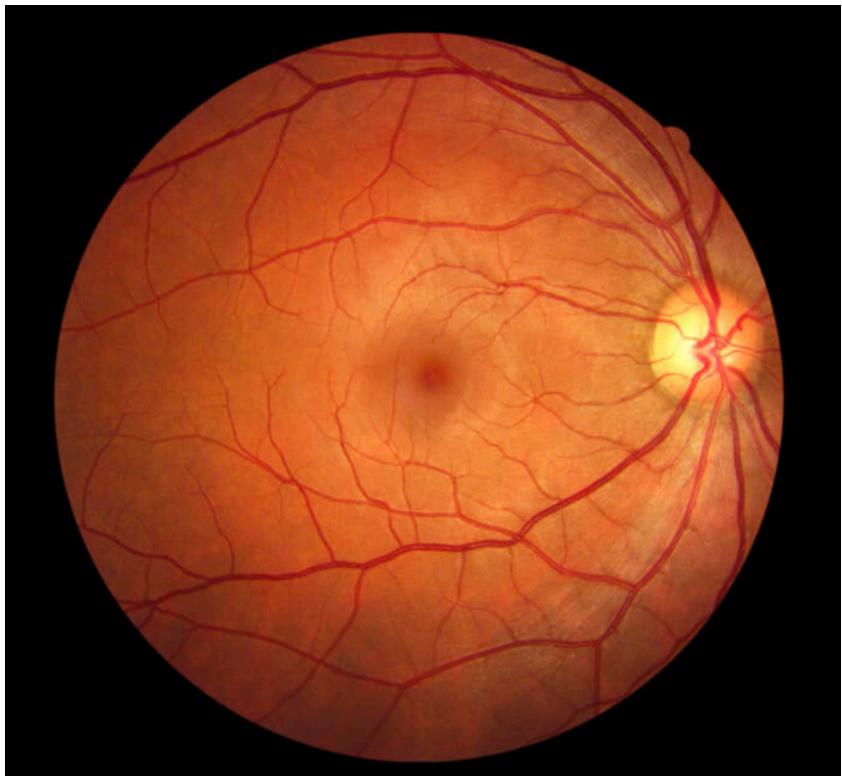
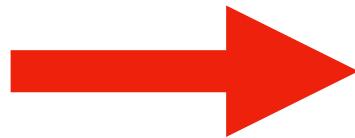
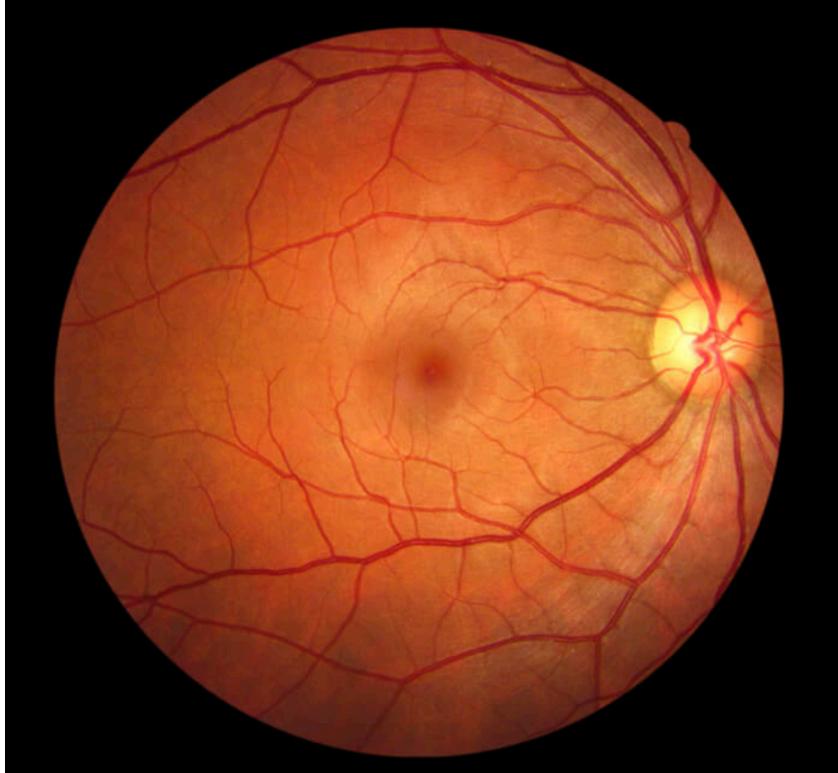


IMAGE OF THE BACK OF THE EYE





**DEEP LEARNING CAN
IDENTIFY
THE PATIENT'S
GENDER WITH 95%
ACCURACY**

IMAGE OF THE BACK OF THE EYE

