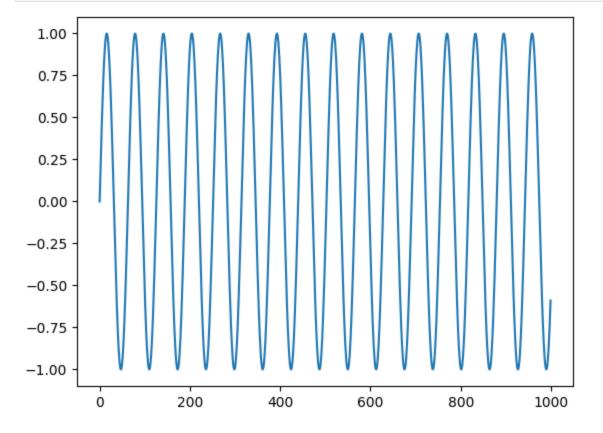
Colab only includes TensorFlow 2.x; %tensorflow\_version has no effect. 2.12.0

```
In [2]: from tensorflow.keras.layers import Input, SimpleRNN, Dense, Flatten
    from tensorflow.keras.models import Model
    from tensorflow.keras.optimizers import SGD, Adam

import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
```

```
In [3]: # make the original data
series = np.sin(0.1*np.arange(1000)) #+ np.random.randn(200)*0.1

# plot it
plt.plot(series)
plt.show()
```



```
In [4]: ### build the dataset
        # let's see if we can use T past values to predict the next value
        D = 1
        X = []
        Y = []
        for t in range(len(series) - T):
         x = series[t:t+T]
         X.append(x)
         y = series[t+T]
          Y.append(y)
        X = np.array(X).reshape(-1, T, 1) # Now the data should be N x T x D
        Y = np.array(Y)
        N = len(X)
        print("X.shape", X.shape, "Y.shape", Y.shape)
```

X.shape (990, 10, 1) Y.shape (990,)

```
In [5]: ### try autoregressive RNN model
        i = Input(shape=(T, 1))
        x = SimpleRNN(15, activation='relu')(i)
        x = Dense(1)(x)
        model = Model(i, x)
        model.compile(
          loss='mse',
          optimizer=Adam(learning_rate=0.001),
        # train the RNN
        r = model.fit(
         X[:-N//2], Y[:-N//2],
          epochs=80,
          validation_data=(X[-N//2:], Y[-N//2:]),
```

```
Epoch 1/80
16/16 [============== ] - 9s 28ms/step - loss: 0.7703 - val_loss:
0.5762
Epoch 2/80
16/16 [==============] - 0s 15ms/step - loss: 0.4788 - val_loss:
0.3944
Epoch 3/80
16/16 [==============] - 0s 14ms/step - loss: 0.3452 - val_loss:
0.3014
Epoch 4/80
16/16 [============== ] - 0s 14ms/step - loss: 0.2650 - val_loss:
0.2356
Epoch 5/80
16/16 [============== ] - 0s 17ms/step - loss: 0.2129 - val_loss:
0.1975
Epoch 6/80
16/16 [==============] - 0s 14ms/step - loss: 0.1806 - val_loss:
0.1679
Epoch 7/80
16/16 [==============] - 0s 15ms/step - loss: 0.1531 - val_loss:
0.1393
Epoch 8/80
16/16 [============== ] - 0s 15ms/step - loss: 0.1229 - val_loss:
0.1054
Epoch 9/80
16/16 [============== ] - 0s 14ms/step - loss: 0.0844 - val_loss:
0.0598
Epoch 10/80
16/16 [============== ] - Os 14ms/step - loss: 0.0393 - val_loss:
0.0204
Epoch 11/80
0.0032
Epoch 12/80
16/16 [============== ] - 0s 15ms/step - loss: 0.0023 - val_loss:
0.0017
Epoch 13/80
0.0014
Epoch 14/80
16/16 [============== ] - 0s 15ms/step - loss: 0.0013 - val_loss:
0.0011
Epoch 15/80
8.7952e-04
Epoch 16/80
16/16 [=============] - 0s 14ms/step - loss: 8.5632e-04 - val_los
s: 7.3174e-04
Epoch 17/80
16/16 [=================== ] - 0s 14ms/step - loss: 7.2301e-04 - val los
s: 6.2362e-04
Epoch 18/80
16/16 [============== ] - 0s 14ms/step - loss: 6.3600e-04 - val_los
s: 5.4577e-04
Epoch 19/80
```

```
s: 5.0095e-04
Epoch 20/80
s: 4.4510e-04
Epoch 21/80
s: 3.8617e-04
Epoch 22/80
16/16 [============= ] - 0s 14ms/step - loss: 3.8907e-04 - val los
s: 3.3262e-04
Epoch 23/80
16/16 [============= ] - 0s 16ms/step - loss: 3.2164e-04 - val los
s: 2.9009e-04
Epoch 24/80
16/16 [============= ] - 0s 14ms/step - loss: 2.8635e-04 - val los
s: 2.6266e-04
Epoch 25/80
16/16 [============== ] - 0s 14ms/step - loss: 2.6053e-04 - val_los
s: 2.4432e-04
Epoch 26/80
16/16 [============== ] - 0s 14ms/step - loss: 2.3991e-04 - val_los
s: 2.2204e-04
Epoch 27/80
16/16 [============== ] - 0s 24ms/step - loss: 2.2486e-04 - val_los
s: 2.0467e-04
Epoch 28/80
16/16 [============= ] - 0s 22ms/step - loss: 2.1404e-04 - val_los
s: 2.2543e-04
Epoch 29/80
16/16 [============= ] - 0s 23ms/step - loss: 1.9902e-04 - val_los
s: 1.7953e-04
Epoch 30/80
16/16 [============== ] - 0s 24ms/step - loss: 1.7856e-04 - val_los
s: 1.6567e-04
Epoch 31/80
16/16 [============== ] - 0s 24ms/step - loss: 1.6436e-04 - val_los
s: 1.5489e-04
Epoch 32/80
16/16 [============= ] - 0s 23ms/step - loss: 1.5322e-04 - val_los
s: 1.5361e-04
Epoch 33/80
16/16 [============= ] - 0s 24ms/step - loss: 1.4708e-04 - val_los
s: 1.3745e-04
Epoch 34/80
16/16 [=============] - 0s 16ms/step - loss: 1.3798e-04 - val_los
s: 1.2410e-04
Epoch 35/80
16/16 [============== ] - 0s 15ms/step - loss: 1.3161e-04 - val_los
s: 1.2120e-04
Epoch 36/80
16/16 [================== ] - 0s 14ms/step - loss: 1.2318e-04 - val_los
s: 1.0887e-04
Epoch 37/80
s: 1.0264e-04
Epoch 38/80
```

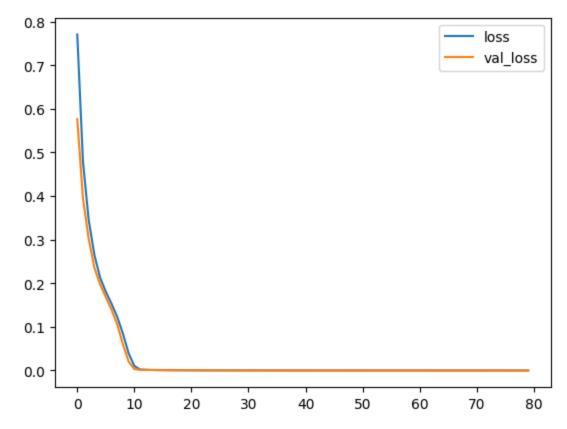
```
16/16 [============== ] - 0s 15ms/step - loss: 1.0342e-04 - val_los
s: 9.7428e-05
Epoch 39/80
16/16 [============= ] - 0s 15ms/step - loss: 1.0328e-04 - val_los
s: 8.9736e-05
Epoch 40/80
16/16 [============= ] - 0s 15ms/step - loss: 9.0687e-05 - val_los
s: 8.1909e-05
Epoch 41/80
16/16 [============== ] - 0s 16ms/step - loss: 8.4880e-05 - val_los
s: 8.4079e-05
Epoch 42/80
16/16 [============== ] - 0s 14ms/step - loss: 8.0597e-05 - val_los
s: 7.1610e-05
Epoch 43/80
16/16 [================== ] - 0s 15ms/step - loss: 7.5126e-05 - val los
s: 6.8366e-05
Epoch 44/80
16/16 [============= ] - 0s 14ms/step - loss: 6.9401e-05 - val los
s: 6.3489e-05
Epoch 45/80
16/16 [============= ] - 0s 15ms/step - loss: 6.5200e-05 - val los
s: 5.8865e-05
Epoch 46/80
16/16 [============== ] - 0s 15ms/step - loss: 6.0515e-05 - val_los
s: 5.4896e-05
Epoch 47/80
16/16 [=============] - 0s 13ms/step - loss: 5.6336e-05 - val los
s: 5.4170e-05
Epoch 48/80
16/16 [============= ] - 0s 13ms/step - loss: 5.4883e-05 - val los
s: 4.9505e-05
Epoch 49/80
16/16 [============= ] - 0s 15ms/step - loss: 5.2122e-05 - val los
s: 4.7040e-05
Epoch 50/80
16/16 [============= ] - 0s 15ms/step - loss: 4.8721e-05 - val los
s: 4.5479e-05
Epoch 51/80
16/16 [============= ] - 0s 14ms/step - loss: 4.8224e-05 - val_los
s: 4.5544e-05
Epoch 52/80
16/16 [============== ] - 0s 15ms/step - loss: 4.5515e-05 - val_los
s: 4.0861e-05
Epoch 53/80
16/16 [============= ] - 0s 14ms/step - loss: 4.1571e-05 - val_los
s: 3.9093e-05
Epoch 54/80
16/16 [============== ] - 0s 15ms/step - loss: 3.9395e-05 - val_los
s: 3.9595e-05
Epoch 55/80
16/16 [============= ] - 0s 15ms/step - loss: 3.9628e-05 - val_los
s: 3.5186e-05
Epoch 56/80
s: 3.7017e-05
```

```
Epoch 57/80
16/16 [============== ] - 0s 14ms/step - loss: 3.6061e-05 - val_los
s: 3.2282e-05
Epoch 58/80
16/16 [============= ] - 0s 16ms/step - loss: 3.4677e-05 - val_los
s: 3.6901e-05
Epoch 59/80
16/16 [============= ] - 0s 13ms/step - loss: 3.5835e-05 - val_los
s: 3.1135e-05
Epoch 60/80
16/16 [============= ] - 0s 14ms/step - loss: 3.0202e-05 - val_los
s: 2.8814e-05
Epoch 61/80
16/16 [============= ] - 0s 15ms/step - loss: 3.2129e-05 - val_los
s: 3.1352e-05
Epoch 62/80
16/16 [============= ] - 0s 14ms/step - loss: 3.0246e-05 - val_los
s: 2.7856e-05
Epoch 63/80
16/16 [============== ] - 0s 17ms/step - loss: 2.9054e-05 - val_los
s: 2.5696e-05
Epoch 64/80
16/16 [============= ] - 0s 15ms/step - loss: 2.8576e-05 - val_los
s: 2.8779e-05
Epoch 65/80
16/16 [============== ] - 0s 16ms/step - loss: 2.5991e-05 - val_los
s: 2.3803e-05
Epoch 66/80
16/16 [============= ] - 0s 14ms/step - loss: 2.5604e-05 - val_los
s: 2.8786e-05
Epoch 67/80
16/16 [================== ] - 0s 15ms/step - loss: 2.7499e-05 - val_los
s: 2.1907e-05
Epoch 68/80
16/16 [============== ] - 0s 15ms/step - loss: 2.3186e-05 - val_los
s: 2.1056e-05
Epoch 69/80
s: 2.0646e-05
Epoch 70/80
16/16 [============== ] - 0s 15ms/step - loss: 2.1064e-05 - val_los
s: 1.9784e-05
Epoch 71/80
s: 2.0592e-05
Epoch 72/80
16/16 [============= ] - 0s 14ms/step - loss: 2.2474e-05 - val_los
s: 1.9223e-05
Epoch 73/80
s: 2.3207e-05
Epoch 74/80
16/16 [============== ] - 0s 15ms/step - loss: 2.1338e-05 - val_los
s: 1.8693e-05
Epoch 75/80
```

```
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    Epoch 76/80
    s: 1.7274e-05
    Epoch 77/80
    s: 1.6030e-05
    Epoch 78/80
    s: 1.6055e-05
    Epoch 79/80
    16/16 [=============] - 0s 22ms/step - loss: 1.6160e-05 - val_los
    s: 1.6278e-05
    Epoch 80/80
    s: 1.6777e-05
In [6]: # Plot loss per iteration
    import matplotlib.pyplot as plt
    plt.plot(r.history['loss'], label='loss')
```

```
plt.plot(r.history['val_loss'], label='val_loss')
plt.legend()
```

Out[6]: <matplotlib.legend.Legend at 0x7f49315d81c0>



```
In [7]: # "Wrong" forecast using true targets

validation_target = Y[-N//2:]
validation_predictions = []

# index of first validation input
```

```
i = -N//2
while len(validation_predictions) < len(validation_target):
    p = model.predict(X[i].reshape(1, -1, 1))[0,0] # 1x1 array -> scalar
    i += 1

# update the predictions list
    validation_predictions.append(p)
```

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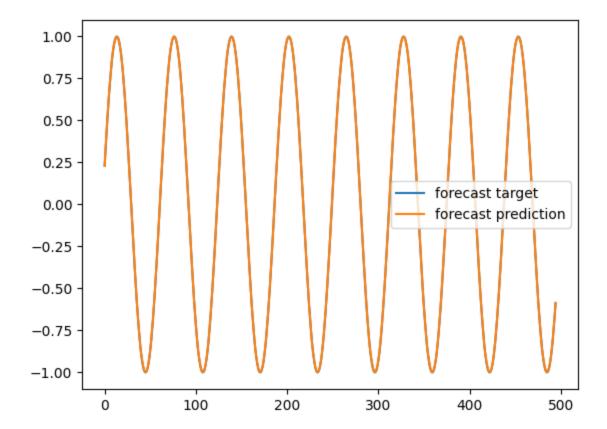
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  In [8]: plt.plot(validation_target, label='forecast target')
  plt.plot(validation predictions, label='forecast prediction')
  plt.legend()
```

Out[8]: <matplotlib.legend.Legend at 0x7f48a1e1e6e0>



```
In [9]: # Forecast future values (use only self-predictions for making future predictions)

validation_target = Y[-N//2:]
validation_predictions = []

# first validation input
last_x = X[-N//2] # 1-D array of length T

while len(validation_predictions) < len(validation_target):
    p = model.predict(last_x.reshape(1, -1, 1))[0,0] # 1x1 array -> scalar

# update the predictions list
validation_predictions.append(p)

# make the new input
last_x = np.roll(last_x, -1)
last_x[-1] = p
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1/1	[======]	-	0s	34ms/step
1/1	[=======]	-	0s	30ms/step
1/1	[=======]	-	0s	33ms/step
	[=======]			
	[=======]			
	[=======]			
	[=======]			

1/1	. [======]	-	0s	30ms/step
1/1	. [======]	-	0s	33ms/step
1/1	. [======]	-	0s	31ms/step
1/1	. [=======]	-	0s	31ms/step
1/1	. [=======]	-	0s	30ms/step
1/1	. [======]	-	0s	30ms/step
1/1	. [=======]	-	0s	32ms/step
1/1	. [=======]	-	0s	27ms/step
1/1	. [=======]	-	0s	30ms/step
1/1	. [=======]	-	0s	27ms/step
1/1	. [=======]	-	0s	28ms/step
1/1	. [=======]	-	0s	31ms/step
1/1				30ms/step
1/1	. [=======]	-	0s	31ms/step
1/1	. [=======]	-	0s	38ms/step
1/1	. [=======]	-	0s	31ms/step
1/1	. [=======]	-	0s	33ms/step
1/1	. [=======]	-	0s	32ms/step
1/1	. [=======]	-	0s	38ms/step
1/1	. [=======]	-	0s	31ms/step
1/1	. [=======]	-	0s	34ms/step
1/1	. [=======]	-	0s	33ms/step
1/1	. [=======]	-	0s	21ms/step
1/1	. [=======]	-	0s	21ms/step
1/1				•
1/1	. [=======]	-	0s	27ms/step
1/1				•
1/1				22ms/step
1/1				
1/1				
1/1				21ms/step
1/1	. []	-	0s	19ms/step
1/1	. []	-	0s	21ms/step
1/1	. []	-	0s	22ms/step
-	. [======]			
	. [======]			•
	. [======]			
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1/1				
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1/1	-			
	. [=======]			
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1/1				
	. [========]			
	. [=======]			
1/1	2			
	. [=======]			
	. [========]			
	. [========]			
1/1	. [=======]	-	ØS	20ms/step

```
1/1 [=======] - 0s 24ms/step
   1/1 [=======] - 0s 19ms/step
   1/1 [======] - 0s 19ms/step
   1/1 [=======] - 0s 18ms/step
   1/1 [======] - 0s 21ms/step
   1/1 [======] - 0s 23ms/step
   1/1 [======] - 0s 24ms/step
   1/1 [======] - 0s 24ms/step
   1/1 [=======] - 0s 25ms/step
   1/1 [======] - 0s 28ms/step
   1/1 [=======] - 0s 22ms/step
   1/1 [=======] - 0s 21ms/step
   1/1 [======] - 0s 22ms/step
   1/1 [=======] - 0s 19ms/step
   1/1 [=======] - 0s 20ms/step
   1/1 [=======] - 0s 18ms/step
   1/1 [======] - 0s 20ms/step
   1/1 [======] - 0s 20ms/step
   1/1 [=======] - 0s 21ms/step
   1/1 [=======] - 0s 20ms/step
   1/1 [======] - 0s 20ms/step
   1/1 [=======] - 0s 27ms/step
   1/1 [======] - 0s 20ms/step
   1/1 [=======] - 0s 23ms/step
   1/1 [=======] - 0s 20ms/step
   In [10]: plt.plot(validation_target, label='forecast target')
   plt.plot(validation predictions, label='forecast prediction')
   plt.legend()
```

Out[10]: <matplotlib.legend.Legend at 0x7f48a01fa470>

