2.0.0-beta1

```
# Other imports
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D
```

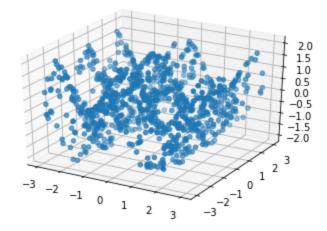
```
In [ ]:  # Make the dataset
    N = 1000
    X = np.random.random((N, 2)) * 6 - 3 # uniformly distributed between (-3, +3)
    Y = np.cos(2*X[:,0]) + np.cos(3*X[:,1])
```

This implements the function:

```
y=\cos(2x_1)+\cos(3x_2)
```

```
In [ ]: # Plot it
    fig = plt.figure()
    ax = fig.add_subplot(111, projection='3d')
    ax.scatter(X[:,0], X[:,1], Y)
    # plt.show()
```

Out[]: <mpl_toolkits.mplot3d.art3d.Path3DCollection at 0x7f2e953549e8>



```
In [ ]:  # Build the model
    model = tf.keras.models.Sequential([
        tf.keras.layers.Dense(128, input_shape=(2,), activation='relu'),
```

```
tf.keras.layers.Dense(1)
])
```

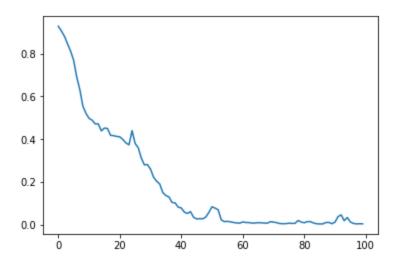
```
Epoch 2/100
1000/1000 [============= ] - 0s 58us/sample - loss: 0.9060
Epoch 3/100
1000/1000 [============== - - 0s 68us/sample - loss: 0.8808
Epoch 4/100
Epoch 5/100
1000/1000 [============= - - 0s 57us/sample - loss: 0.8115
Epoch 6/100
1000/1000 [============== ] - 0s 59us/sample - loss: 0.7682
Epoch 7/100
Epoch 8/100
Epoch 9/100
Epoch 10/100
Epoch 11/100
1000/1000 [============= - - 0s 54us/sample - loss: 0.4973
Epoch 12/100
Epoch 13/100
1000/1000 [============= - - 0s 58us/sample - loss: 0.4715
Epoch 14/100
1000/1000 [================ ] - 0s 55us/sample - loss: 0.4714
Epoch 15/100
Epoch 16/100
Epoch 17/100
1000/1000 [===============] - 0s 53us/sample - loss: 0.4498
Epoch 18/100
1000/1000 [================ ] - 0s 53us/sample - loss: 0.4180
Epoch 19/100
1000/1000 [===============] - 0s 53us/sample - loss: 0.4163
Epoch 20/100
Epoch 21/100
Epoch 22/100
Epoch 23/100
1000/1000 [============= - - 0s 58us/sample - loss: 0.3825
Epoch 24/100
1000/1000 [============= ] - 0s 52us/sample - loss: 0.3734
Epoch 25/100
1000/1000 [============== ] - 0s 54us/sample - loss: 0.4398
Epoch 26/100
1000/1000 [============== - - 0s 57us/sample - loss: 0.3796
Epoch 27/100
1000/1000 [=============== ] - 0s 53us/sample - loss: 0.3603
```

```
Epoch 28/100
Epoch 29/100
1000/1000 [============= - - 0s 58us/sample - loss: 0.2797
Epoch 30/100
1000/1000 [============= - - 0s 53us/sample - loss: 0.2815
Epoch 31/100
1000/1000 [============= ] - 0s 54us/sample - loss: 0.2600
Epoch 32/100
1000/1000 [============= ] - 0s 54us/sample - loss: 0.2221
Epoch 33/100
Epoch 34/100
1000/1000 [============= - - 0s 59us/sample - loss: 0.1905
Epoch 35/100
Epoch 36/100
Epoch 37/100
Epoch 38/100
Epoch 39/100
Epoch 40/100
1000/1000 [============= - - 0s 49us/sample - loss: 0.0823
Epoch 41/100
Epoch 42/100
1000/1000 [============= - - 0s 51us/sample - loss: 0.0593
Epoch 43/100
Epoch 44/100
1000/1000 [=============== ] - 0s 48us/sample - loss: 0.0616
Epoch 45/100
1000/1000 [================ ] - 0s 50us/sample - loss: 0.0351
Epoch 46/100
1000/1000 [============= ] - 0s 50us/sample - loss: 0.0273
Epoch 47/100
1000/1000 [================ ] - 0s 49us/sample - loss: 0.0288
Epoch 48/100
Epoch 49/100
Epoch 50/100
Epoch 51/100
1000/1000 [============= - - 0s 52us/sample - loss: 0.0842
Epoch 52/100
1000/1000 [============= - - 0s 54us/sample - loss: 0.0780
Epoch 53/100
1000/1000 [============= - - 0s 53us/sample - loss: 0.0700
Epoch 54/100
Epoch 55/100
1000/1000 [============= - - 0s 50us/sample - loss: 0.0149
Epoch 56/100
1000/1000 [============= - - 0s 49us/sample - loss: 0.0159
Epoch 57/100
Epoch 58/100
Epoch 59/100
Epoch 60/100
```

11-2_0	_^ı	ALA_L	regression_v3			
1000/1000 [=======]	-	0s	52us/sample	-	loss:	0.0077
Epoch 61/100 1000/1000 [=======]	_	۵c	50us/samnle	_	1055.	0 0132
Epoch 62/100		03	Jous/ Sampic		1033.	0.0132
1000/1000 [======]	-	0s	50us/sample	-	loss:	0.0108
Epoch 63/100		0-	50s / s = m = 1 =		1	0 0105
1000/1000 [======] Epoch 64/100	-	05	50us/sample	-	1055:	0.0105
1000/1000 [========]	_	0s	53us/sample	_	loss:	0.0077
Epoch 65/100						
1000/1000 []	-	0s	51us/sample	-	loss:	0.0084
Epoch 66/100 1000/1000 [=======]	_	0s	50us/sample	_	loss:	0.0101
Epoch 67/100			·			
1000/1000 [=======]	-	0s	49us/sample	-	loss:	0.0093
Epoch 68/100 1000/1000 [=======]	_	95	49us/samnle	_	loss:	0.0082
Epoch 69/100			·			
1000/1000 [======]	-	0s	49us/sample	-	loss:	0.0076
Epoch 70/100 1000/1000 [========]	_	۵۶	58us/sample	_	1000	0 01/15
Epoch 71/100	_	03	Jous/ Sample	_	1033.	0.0145
1000/1000 [======]	-	0s	47us/sample	-	loss:	0.0127
Epoch 72/100 1000/1000 [=======]		0.5	Faus/sample		1000	0 0101
Epoch 73/100	_	62	3003/Sample	-	1055.	0.0101
1000/1000 [=======]	-	0s	49us/sample	-	loss:	0.0058
Epoch 74/100		0 -	FO / 1 -		1	0 0051
1000/1000 [======] Epoch 75/100	-	05	50us/sample	-	1055:	0.0051
1000/1000 [========]	-	0s	53us/sample	-	loss:	0.0053
Epoch 76/100		•	F2 / 1		,	0 0073
1000/1000 [======] Epoch 77/100	-	05	52us/sample	-	1055:	0.00/3
1000/1000 [========]	-	0s	50us/sample	-	loss:	0.0065
Epoch 78/100 1000/1000 [=======]		0-	[2/a.a.ma].		1	0.0000
Epoch 79/100	-	05	53uS/Sampie	-	1055:	0.0000
1000/1000 [=======]	-	0s	60us/sample	-	loss:	0.0202
Epoch 80/100		0-	40		1	0.0130
1000/1000 [=======] Epoch 81/100	-	05	49us/sampie	-	1055:	0.0130
1000/1000 [========]	-	0s	50us/sample	-	loss:	0.0093
Epoch 82/100		0-	40		1	0 0140
1000/1000 [======] Epoch 83/100	-	05	49us/sampie	-	1055:	0.0149
1000/1000 [========]	-	0s	50us/sample	-	loss:	0.0147
Epoch 84/100		0-	46		1	0 0005
1000/1000 [=======] Epoch 85/100	-	05	46us/sample	-	1055:	0.0085
1000/1000 [========]	-	0s	49us/sample	-	loss:	0.0048
Epoch 86/100		0-	[1/aama]a		1	0 0041
1000/1000 [======] Epoch 87/100	-	05	51us/sample	-	1055:	0.0041
1000/1000 [========]	-	0s	48us/sample	-	loss:	0.0041
Epoch 88/100		•	FO / 1		,	0.0106
1000/1000 [======] Epoch 89/100	-	ØS	50us/sample	-	loss:	0.0106
1000/1000 [=======]	-	0s	50us/sample	-	loss:	0.0112
Epoch 90/100		_	47/		1.	0 00=1
1000/1000 [======] Epoch 91/100	-	ØS	4/us/sample	-	TOSS:	0.0051
1000/1000 []	-	0s	48us/sample	-	loss:	0.0121
Epoch 92/100						
1000/1000 [=======]	-	ØS	52us/sample	-	TOSS:	0.0384

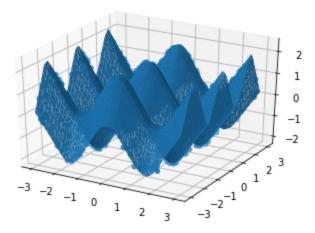
```
Epoch 93/100
      Epoch 94/100
     1000/1000 [============== ] - 0s 49us/sample - loss: 0.0190
      Epoch 95/100
     1000/1000 [============== ] - 0s 49us/sample - loss: 0.0340
      Epoch 96/100
     1000/1000 [============= - - 0s 52us/sample - loss: 0.0133
      Epoch 97/100
     1000/1000 [============= - - 0s 49us/sample - loss: 0.0062
     Epoch 98/100
     1000/1000 [===========] - Os 67us/sample - loss: 0.0043
      Epoch 99/100
     1000/1000 [============= - - 0s 67us/sample - loss: 0.0050
     Epoch 100/100
     In [ ]:
      # Plot the loss
      plt.plot(r.history['loss'], label='loss')
```

Out[]: [<matplotlib.lines.Line2D at 0x7f2e95406a58>]



```
In []:
    # Plot the prediction surface
    fig = plt.figure()
    ax = fig.add_subplot(111, projection='3d')
    ax.scatter(X[:,0], X[:,1], Y)

# surface plot
    line = np.linspace(-3, 3, 50)
    xx, yy = np.meshgrid(line, line)
    Xgrid = np.vstack((xx.flatten(), yy.flatten())).T
    Yhat = model.predict(Xgrid).flatten()
    ax.plot_trisurf(Xgrid[:,0], Xgrid[:,1], Yhat, linewidth=0.2, antialiased=True)
    plt.show()
```



```
In []: # Can it extrapolate?
    # Plot the prediction surface
    fig = plt.figure()
    ax = fig.add_subplot(111, projection='3d')
    ax.scatter(X[:,0], X[:,1], Y)

# surface plot
    line = np.linspace(-5, 5, 50)
    xx, yy = np.meshgrid(line, line)
    Xgrid = np.vstack((xx.flatten(), yy.flatten())).T
    Yhat = model.predict(Xgrid).flatten()
    ax.plot_trisurf(Xgrid[:,0], Xgrid[:,1], Yhat, linewidth=0.2, antialiased=True)
    plt.show()
```

