Autonomy	Behaviour	Knowledge	Application Description
Full Autonomy	Selfish	Minimal	Autonomous cars deciding which route to take based on individual goals and *only* observing neighbours.
		Maximal	Autonomous cars sharing information about destination, speed, etc. but each car pursues its own goals.
	Altruistic	Minimal	Software components processing data stream owned by a single provider, (restricted knowledge access due to bandwidth/scalability).
		Maximal	Traffic lights aiming to optimise the traffic flow taking other traffic lights into account (e.g., signalisation, control of green light duration, routing, coordination).
No Autonomy	Selfish	Minimal	Bike sharing system with agents acting on behalf of humans, utilising the bike sharing stations.
		Maximal	Self-adapting software components (considering other components data) that contribute to a global behaviour (e.g. self-healing) through prioritising their own goals.
	Altruistic	Minimal	Car sharing system where software controls cars to serve other users, maximising the interest of car owners.
		Maximal	Robots jointly monitoring and splitting an area for distributed tasks such as surveillance, cleaning, etc.