

Decision Trees

Decision Trees. Information Criteria.

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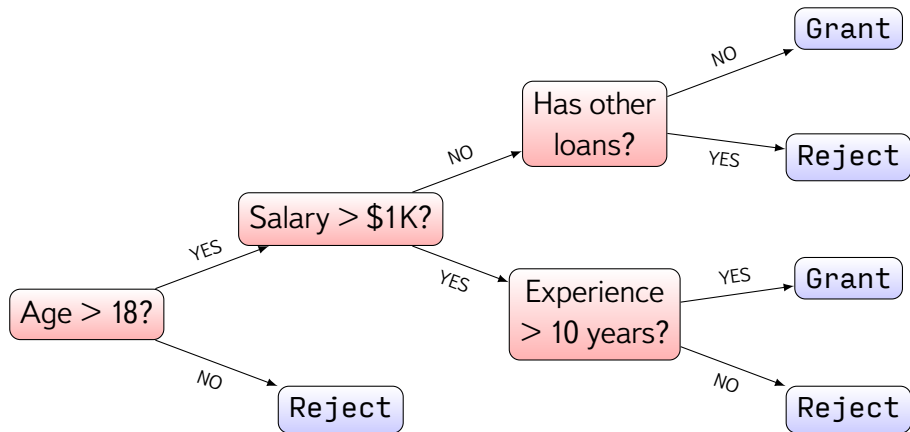
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Lecture overview

- › Decision Trees

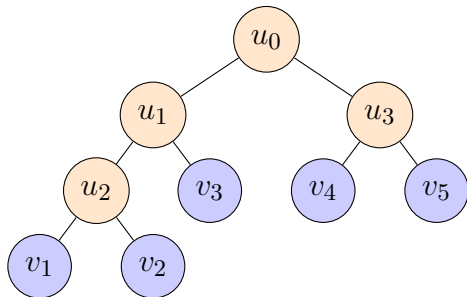
Decision trees

Decision making at a bank



Decision tree formalism

- › Decision tree is a binary tree V
- › Internal nodes $u \in V$: predicates
 $\beta_u : \mathbb{X} \rightarrow \{0, 1\}$
- › Leafs $v \in V$: predictions x
- › Algorithm $h(\mathbf{x})$ starts at $u = u_0$
 - › Compute $b = \beta_u(\mathbf{x})$
 - › If $b = 0$, $u \leftarrow \text{LeftChild}(u)$
 - › If $b = 1$, $u \leftarrow \text{RightChild}(u)$
 - › If u is a leaf, return b
- › In practice: $\beta_u(\mathbf{x}; j, t) = [\mathbf{x}_j < t]$



Greedy tree learning for binary classification

› Input: training set $X^\ell = \{(\mathbf{x}_i, y_i)\}_{i=1}^\ell$

1. Greedily split X^ℓ into R_1 and R_2 :

$$R_1(j, t) = \{\mathbf{x} \in X^\ell | \mathbf{x}_j < t\}, \quad R_2(j, t) = \{\mathbf{x} \in X^\ell | \mathbf{x}_j > t\}$$

optimizing a given loss: $Q(X^\ell, j, t) \rightarrow \min_{(j, t)}$

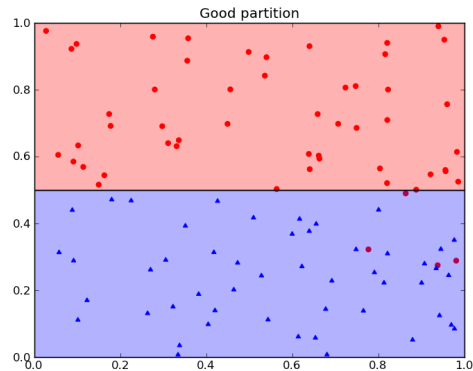
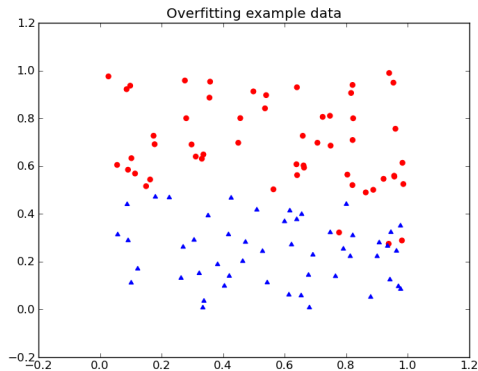
2. Create internal node u corresponding to the predicate $[\mathbf{x}_j < t]$

3. If a stopping criterion is satisfied for u ,
declare it a leaf, setting some $c_u \in \mathbb{Y}$ as leaf prediction

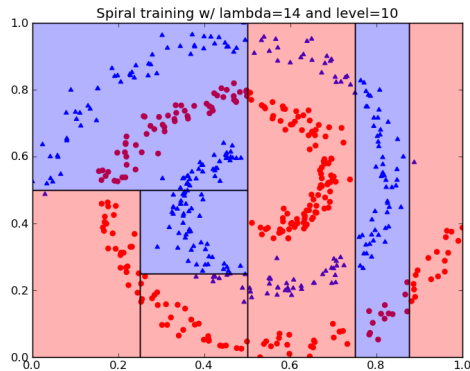
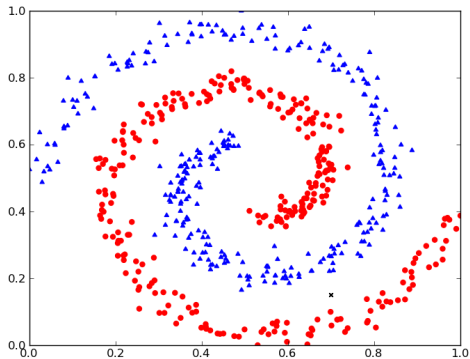
4. If not, repeat 1–2 for $R_1(j, t)$ and $R_2(j, t)$

› Output: a decision tree V

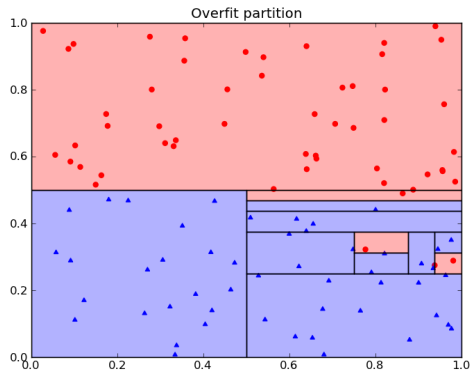
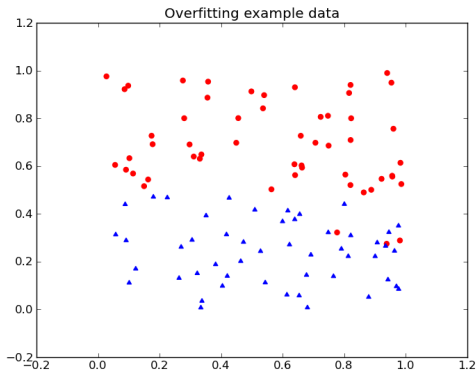
Greedy tree learning for binary classification



Greedy tree learning for binary classification



With decision trees, overfitting is extra-easy!



Design choices for learning a decision tree classifier

- › Type of predicate in internal nodes
 - › The loss function $Q(X^\ell, j, t)$
 - › The stopping criterion
 - › Hacks: missing values, pruning, etc.
-
- › CART, C4.5, ID3

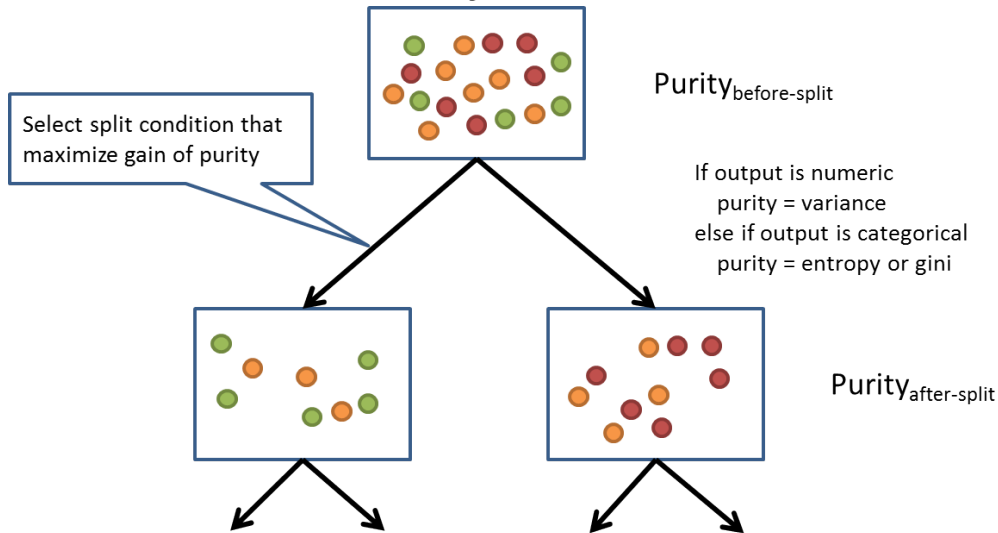
The loss function $Q(X^\ell, j, t)$

- › R_m : the subset of X^ℓ at step m
- › With the current split, let $R_l \subseteq R_m$ go left and $R_r \subseteq R_m$ go right
- › Choose **predicate** to optimize

$$Q(R_m, j, t) = H(R_m) - \frac{|R_l|}{|R_m|}H(R_l) - \frac{|R_r|}{|R_m|}H(R_r) \rightarrow \max$$

- › $H(R)$: impurity criterion
- › Generally $H(R) = \min_{c \in \mathbb{Y}} \frac{1}{|R|} \sum_{(\mathbf{x}_i, y_i) \in R} L(y_i, c)$

The idea: maximize purity



Examples of information criteria

Regression Wiki: In statistical modeling, regression analysis is a

› Regression:

- › $H(R) = \min_{c \in \mathbb{Y}} |R|^{-1} \sum_{(\mathbf{x}_i, y_i) \in R} (y_i - c)^2$
- › Sum of squared residuals minimized by $c = |R|^{-1} \sum_{(\mathbf{x}_j, y_j) \in R} y_j$
- › Impurity \equiv variance of the target

› Classification:

- › Let $p_k = |R|^{-1} \sum_{(\mathbf{x}_i, y_i) \in R} [y_i = k]$ (share of y_i 's equal to k)
- › Miss rate: $H(R) = \min_{c \in \mathbb{Y}} |R|^{-1} \sum_{(\mathbf{x}_i, y_i) \in R} [y_i \neq c]$

Minimizing miss rate $1 - p_{k_*}$,

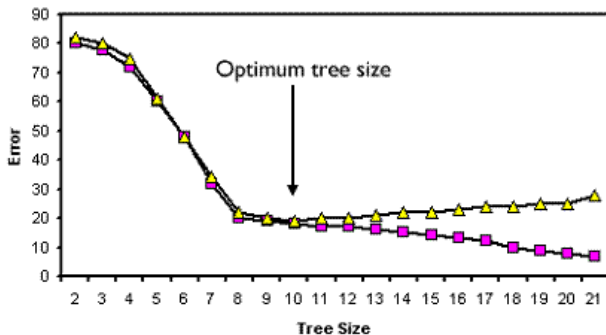
Gini index $\sum_{k=1}^K p_k (1 - p_k)$,

Cross-entropy $-\sum_{k=1}^K p_k \log p_k$

Stopping rules for decision tree learning

- › Significantly impacts learning performance
- › Multiple choices available:
 - › Maximum tree depth
 - › Minimum number of objects in leaf
 - › Maximum number of leafs in tree
 - › Stop if all objects fall into same leaf
 - › Constrain quality improvement
(stop when improvement gains drop below $s\%$)
- › Typically selected via exhaustive search and cross-validation

Decision tree pruning



- › Learn a large tree (effectively overfit the training set)
- › Detect overfitting via K -fold cross-validation
- › Optimize structure by removing least important nodes

Conclusion

- › **Decision trees:** intuitive and interpretable, yet prone to overfitting