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>.-.#'9?')@%'&-9'):Tactile Sensing for OceanOneK Underwater Robot 06/2024 - 10/2024

Advisor: Mark Cutkosky, Stanford Biomimetics & Dexterous Manipulation Lab

- Designed a B+C-'D'#EE:F '#'+\$E).-\$.&' for the OceanOneK robot's hands to enhance tactile sensing.
- Collected and processed experimental data using force–torque sensors and optical interrogators.
- Implemented #)%G##/)9&\$-\$-9-()-\$-G'#B\$-" I '&'J#K4B##/'-.0)L1)-G'&\$.)-#9?0)>-M*)#9'+,#'+&\$N to predict force and contact status, with)%/@O#'9? and data preprocessing (normalization, filtering). Achieved ; !P) Q)623R0)>)Q)62=T with 80/20 train–test split and nearly identical training/validation loss (0.0521 / 0.0522).
- Assisted in developing a I ?+J-':+\$U+'-()"9'+B-).-\$.&' for underwater perception, showcased at the !"#%&' ()>&C&"9.)V-\$"-')M#G\$9?

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@%'&-9'):Student Revision Behavior Analysis)KD'&\$W-)XI #' (0)O&U)4 Y)+\$)9B#..N))))))))05/2024

- Designed and implemented statistical models (C&&.'"#U)?/U&"?-+.)."'+\$E0)9&' '-B#+&\$)#\$#B/.+.0) @&+..&\$5F-&Z-'"'+9)(+."'+CG"+&\$.) to analyze revision patterns from 40 students' projects.
- Built and evaluated [#+, -)D#/-.)9B#..+%-'. to predict project preferences, achieving up to 100% test accuracy on certain datasets, utilizing Python (NumPy, pandas, scikit-learn) for (#'#)U'-U'&9-..+\$E0) U'&C#C+B#."'+9)Z&(-B+\$E0)#\$(),+.G#B+W#"'+&\$2
- Published a research-style paper and reproducible [code on GitHub](#), demonstrating strong data analysis and machine learning skills.

V&ZUG"-')!9+-\$9-)O-#9?-')))))))))))))08/2023 - 05/2025
The Quarry Lane School, Dublin, CA

- Designed customized AP Computer Science Principles (AP CSP) and Middle School Computer Science curricula using Python, Java, HTML, and CSS, resulting in a significant increase in the AP CSP class average score from <L45R)"&)1435R (2024 California average: 3.08, global average: 2.90).

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Stanford Madera Groove Children Center, TCTM Kids IT Education Inc, Various Elementary Schools

- Taught '&C&"9U)'E'#ZZ+\$E with Scratch, Lego Mindstorms, Lego WeDo 2.0, and Python
- Utilized classroom materials to implement STEM activities and maintained communication with parents

Li, H.*, Xing, C.*, Khan, S., \&\$E0 ; 2, & Cutkosky, M. R. (2025). Whisker-Inspired Tactile Sensing: A Sim2Real Approach for Precise Underwater Contact Tracking. *IEEE Robotics and Automation Letters(RA-L)*

- @'&E'#Z+\$E])Python, C++, C, Java, JavaScript, Processing, R, HTML/CSS
- B'#Z- I &'J.) ^)O&#L.)NumPy, pandas, PyTorch, Onshape CAD, CorelDRAW, Casting, Adobe Photoshop
- M#\$EG#E-.] Mandarin (Native), English (Proficient), Cantonese (Intermediate)