

#### PhD Thesis

Sapienza University of Rome Dottorato di Ricerca in Automatica, Bioingegneria e Ricerca Operativa -XXXVI Ciclo

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Academic Year 2023/2024

Thesis defended on TBD May 2024 in front of a Board of Examiners composed by:

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Version: January 15, 2024

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#### Acknowledgments

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#### Abstract

Abstract.

### Contents

1	Introduction	1
	1.1 Section	1
<b>2</b>	Conclusions	•

# Chapter 1

### Introduction

Todo. [1]

#### 1.1 Section

Todo.

### Chapter 2

### Conclusions

Todo.

# Bibliography

[1] Michele Cipriano, Paolo Ferrari, Nicola Scianca, Leonardo Lanari, and Giuseppe Oriolo. Humanoid Motion Generation in a World of Stairs. *Robotics and Autonomous Systems (accepted for publication)*, 2023.