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Dedication.

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Abstract

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Contents

1	Introduction	1
1.1	Section	1
2	Literature review	2
3	Humanoid motion generation in a world of stairs	3
4	Feasibility aware plan adaptation in humanoid gait generation	4
5	Nonlinear model predictive control for steerable wheeled mobile robots	5
6	Conclusions	6
A	Feasibility aware plan adaptation in humanoid gait generation	7
B	Real-time nonlinear model predictive control	8

Chapter 1

Introduction

Todo. [1]

1.1 Section

Todo.

Chapter 2

Literature review

Todo.

Chapter 3

Humanoid motion generation in a world of stairs

Todo.

Chapter 4

Feasibility aware plan adaptation in humanoid gait generation

Todo.

Chapter 5

Nonlinear model predictive control for steerable wheeled mobile robots

Todo.

Chapter 6

Conclusions

Todo.

Appendix A

Feasibility aware plan adaptation in humanoid gait generation

Todo.

Appendix B

Real-time nonlinear model predictive control

Todo.

Bibliography

- [1] Michele Cipriano, Paolo Ferrari, Nicola Scianca, Leonardo Lanari, and Giuseppe Oriolo. Humanoid Motion Generation in a World of Stairs. *Robotics and Autonomous Systems (accepted for publication)*, 2023.