In my inference engine I have divided the task of predicting if a person is wearing a mask and safety helmet into two separate tasks:

**Task 1:** First, an object detector network is used to predict bounding boxes containing heads in the image

**Task 2:** Next, two parallel image classifier networks are used to classify the detected head bounding boxes into 4 classes for the presence of mask(yes, no, invisible, wrong) and 2 classes for the presence of safety helmets(yes, no).

So, the engine consists of two stages:

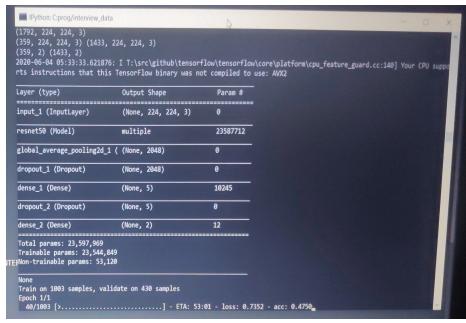
**Stage-1**: Object detector network(Faster RCNN.) that takes an RGB image as input and produces bounding box locations for heads in the image. The object classifier branch of faster Rcnn classifies each ROI into three classes: head, nonhead and background. The object bounding box regressor branch produces 4 coordinates xtl, ytl, xbr, ybr specifying the bounding box location.

## Stage-2: 2 parallel Image classifier networks for mask and helmet.

Classifier 1(mask classifier): Takes the bounding boxes labeled as head from the faster Rcnn detector and crops the bounding boxes from the image and takes them as input. The output has 4 classes( depending on values present in annotation) viz (invisible, no, wrong, yes) denoting the presence of masks in the image. The architecture summary is shown below. Note that the final dense layer has 4 classes.

ayer (type)	Output	Shape	Param #	
nput_7 (InputLayer)	(None,	224, 224, 3)	0	
esnet50 (Model)	multip:	le	23587712	
lobal_average_pooling2d_1 (	(None,	2048)	0	
ropout_1 (Dropout)	(None,	2048)	0	
ense_5 (Dense)	(None,	5)	10245	
ropout_2 (Dropout)	(None,	5)	0	
ense_6 (Dense)	(None,	4)	24	
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Classifier 2(safety helmet classifier): Takes the bounding boxes labeled as head from the faster Rcnn and crops the bounding boxes from the image and takes them as input. The output has 2 classes( depending on values present in annotation) viz (yes, no) denoting the presence of safety helmets in the image. The architecture summary is shown below. Note that the final dense layer has 2 classes.



Helmet classifier