

Lecture notes for Multimedia Data Processing

Hardware for color acquisition

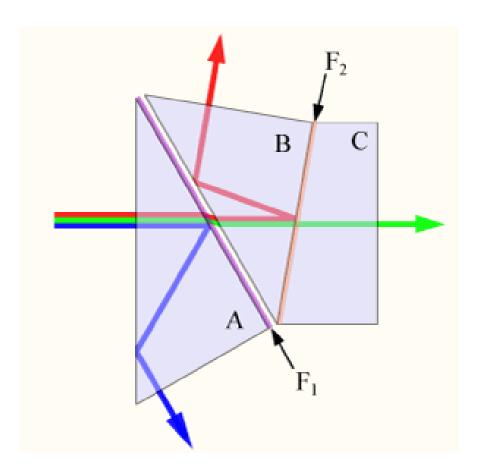
Last updated on: 19/04/2020

Dichroic prism

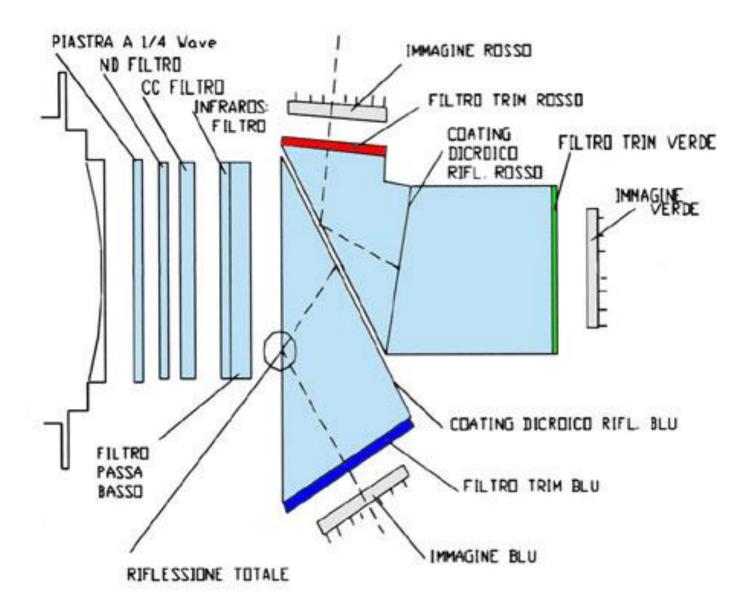
- The photosensitive cell converts the intensity of light, but is not sensitive to the wavelength, one color per pixel → Monochromatic acquisition.
- A dichroic prism is a prism that splits light into two beams of different wavelength (color).
- They are usually made combining dichroic optical coatings that selectively reflect or transmit light depending on the light's wavelength.
- A typical application is to divide the light into three components inside some cameras (the so-called 3-CCD).
- A trichroic prism combines two dichroic prisms to split an image into 3 colors, typically as red, green and blue of the RGB color model, measured by three different CCDs.

Dichroic prism

- A possible layout is shown in the diagram. A light beam enters the first prism (A), and the blue component of the beam is reflected from a lowpass filter coating (F1) that reflects blue light (high-frequency), but transmits longer wavelengths (lower frequencies).
- The blue beam undergoes total internal reflection from the front of prism A and exits it through a side face.
- The remainder of the beam enters the second prism (B) and is split by a second filter coating (F2) that reflects red light but transmits shorter wavelengths.
- The small air space between the two prisms allows total internal reflection.

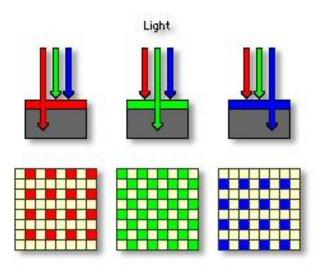


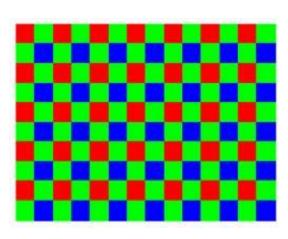
3-CCD camera schema



Bayer Pattern

- Bayer Pattern (Bryce Bayer, 1976 Kodak)
 - RGBG 2x2 cell, 2 green pixels, 1 blue, 1 red (Human eye more sensitive to green).
 - The filter decreases sensitivity to light, becomes 1/3 of the monochrome.
 - Variants: CMY-Y, CMY+G, RGB+E (Sony) more sensitive.

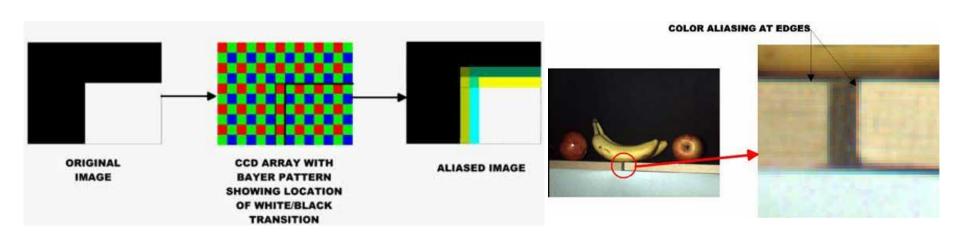




Bayer Pattern

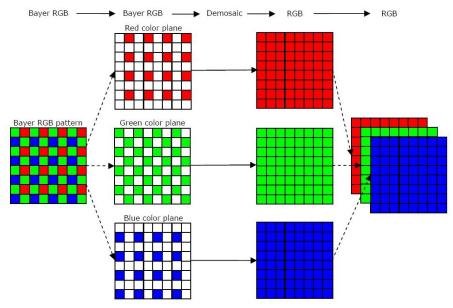
The Bayer pattern has some advantages over 3-CCD technology:

- Only one sensor needed;
- No prisms are needed;
- Lower cost and size;
- Lower weight: portable devices;
- On the other hand, the information of the Bayer pattern is sampled.
 In each pixel it is necessary to reconstruct the missing components
 → DEMOSAICING.



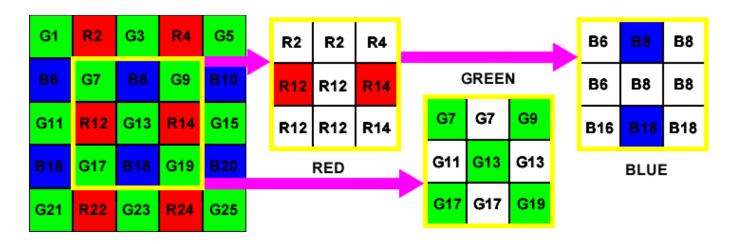
Demosaicing

- Transform the Bayer pattern into a full color RGB image.
- Interpolation by convolution: Nearest neighbor, bilinear, cubic [Sak98], [Ram02], etc.
- In this course we will analyze three:
 - Nearest Neighbor Replication (NNR)
 - Bilinear Interpolation (BI)
 - Linear Interpolation with Laplacian Second-order Correction Terms (LIL2)



Nearest Neighbor Replication

- Missing components are interpolated with neighboring pixel values.
- The closest pixel can be in any of the four fundamental directions, above, below, left or right.



STRENGTHS:

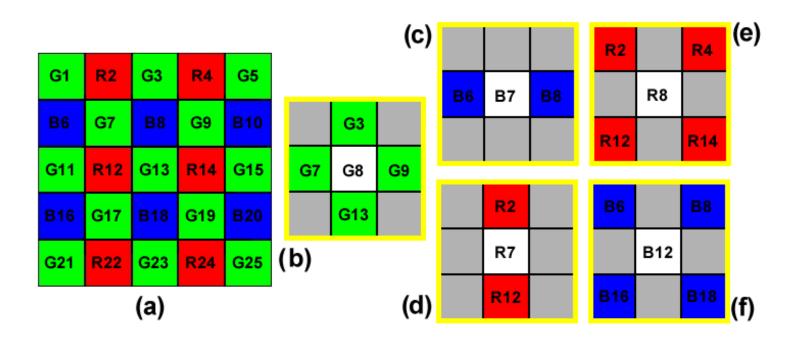
Computationally faster interpolation.

WEAKNESSES:

- Creation of many false colors that can create problems for image processing.
- Zipper effect: high gradient transitions are very jagged.
- The interpolated image tends to be noisy.

Bilinear Interpolation

- The missing components are interpolated with a bilinear interpolation of neighboring pixels.
- The components can be interpolated simultaneously.



Bilinear Interpolation

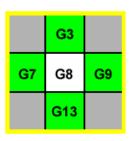
$$G8 = \frac{\left(G3 + G7 + G9 + G13\right)}{4} \; ;$$

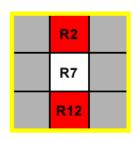
$$B7 = \frac{(B6 + B8)}{2};$$

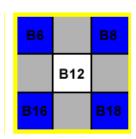
$$R7 = \frac{(R2 + R12)}{2};$$

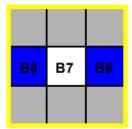
$$R8 = \frac{(R2 + R4 + R12 + R14)}{4};$$

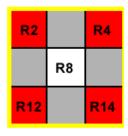
$$B12 \ = \ \frac{(B6+B8+B16+B18)}{4} \ ;$$











Bilinear Interpolation

STRENGTHS:

 This algorithm is very efficient and often forms the basis for other better ones.

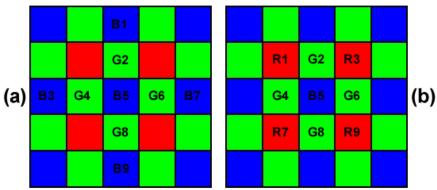
WEAKNESSES:

- The "pure" color of adjacent pixels can change abruptly.
- Blur effect: the whole image is subject to low pass filtering.
- Zipper effect reduced but not eliminated.

Linear Interpolation w. Laplacian 2° Correction

- The missing components are interpolated in an adaptive way, following the chromatic gradients.
- Maximum performance in the case of images with vertical or horizontal edges.
- Interpolation of green pixels has priority.
- Assumption: the color planes are perfectly correlated in small areas of the image. That is, the following equation is true for the constants k and j:
 - -G = B + k
 - -G = R + j

Adaptive = operates in a different way adapting to the typical variability of the addressed image.



end for

Laplacian 2° Correction

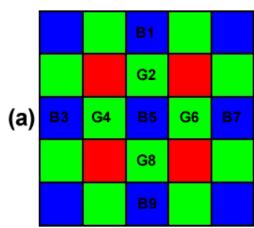
GREEN: horizontal and vertical gradients are defined,

$$\Delta H = |G4 - G6| + |B5 - B3 + B5 - B7|;$$

 $\Delta V = |G2 - G8| + |B5 - B1 + B5 - B9|;$

Interpolation follows the algorithm

for all i such that i is a RED or BLUE pixel do if $(\Delta H < \Delta V)$ then $G5 = \frac{(G4+G6)}{2} + \frac{(B5-B3+B5-B7)}{4}$ else if $(\Delta H > \Delta V)$ then $G5 = \frac{(G2+G8)}{2} + \frac{(B5-B1+B5-B9)}{4}$ else $G5 = \frac{(G2+G4+G6+G8)}{4} + \frac{(B5-B1+B5-B3+B5-B7+B5-B9)}{8}$ end if

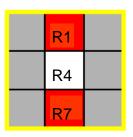


Laplacian 2° Correction

R1 G2 R3
G4 B5 G6 (b)
R7 G8 R9

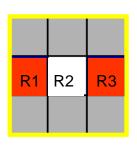
- RED: there are 3 possible cases
 - The two nearest pixels of the same color of the missing component are in the same column:

$$R4 = \frac{(R1 + R7)}{2} + \frac{(G4 - G1 + G4 - G7)}{4}$$
;



The two nearest pixels of the same color of the missing component are in the same row:

$$R2 = \frac{(R1+R3)}{2} + \frac{(G2-G1+G2-G3)}{4} ;$$



Laplacian 2° Correction

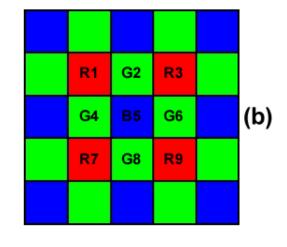
RED: We define compound gradients,

$$\Delta N = |R1 - R9| + |G5 - G1 + G5 - G9|;$$

 $\Delta P = |R3 - R7| + |G5 - G3 + G5 - G7|;$

Interpolation follows the algorithm

for all
$$i$$
 such that i is BLUE pixel in case 3 do if $(\Delta N < \Delta P)$ then
$$R5 = \frac{(R1+R9)}{2} + \frac{(G5-G1+G5-G9)}{4}$$
 else if $(\Delta N > \Delta P)$ then
$$R5 = \frac{(R3+R7)}{2} + \frac{(G5-G3+G5-G7)}{4}$$
 else
$$R5 = \frac{(R1+R3+R7+R9)}{4} + \frac{(G5-G1+G5-G3+G5-G7+G5-G9)}{8}$$
 end if end for



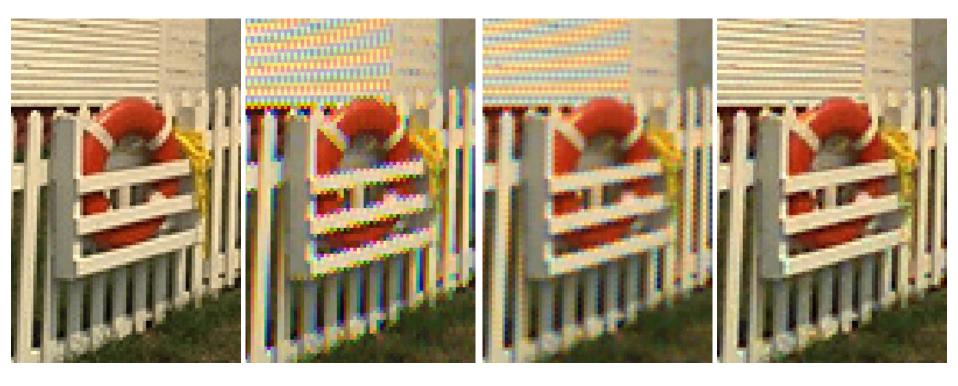
The interpolation of the blue color is the same as that of the red.

Comparison Interpolation



Original Nearest Bilinear Laplacian

Comparison Interpolation



Original Nearest Bilinear Laplacian