Table 1: Number of observations made in each of the 11 runs (10 stochastic and 1 deterministic) for each of the three starting positions

| | **Position 1** | **Position 2** | **Position 3** |
|---|---|---|---|
| **Stochastic 1** | 9 | 13 | 15 |
| **Stochastic 2** | 17 | 11 | 17 |
| **Stochastic 3** | 14 | 15 | 15 |
| **Stochastic 4** | 9 | 22 | 8 |
| **Stochastic 5** | 16 | 8 | 10 |
| **Stochastic 6** | 10 | 11 | 12 |
| **Stochastic 7** | 18 | 13 | 15 |
| **Stochastic 8** | 9 | 19 | 15 |
| **Stochastic 9** | 17 | 10 | 8 |
| **Stochastic 10** | 14 | 11 | 17 |
| **Deterministic** | 9 | 10 | 8 |

The number of observations made by the robot for each run and starting position were found by looking at the robot's display which displayed this information.

Table 2: Mean number of observations performed by the stochastic algorithm for each of the three starting positions

| | **Position 1** | **Position 2** | **Position 3** |
|---|---|---|---|
| **Mean** | 13.3 | 13.3 | 13.2 |

Table 3: Colour values for the block detection using the ColoredSensor (to be completed)

| **Block Colour** | **Trial** | **Red Value** | **Green Value** | **Blue Value** |
|---|---|---|---|---|
| **Blue** | **1** | | | |
| | **2** | | | |
| | **3** | | | |
| **Red** | **1** | | | |
| | **2** | | | |
| | **3** | | | |
| **White** | **1** | | | |
| | **2** | | | |
| | **3** | | | |
| **Yellow** | **1** | | | |
| | **2** | | | |
| | **3** | | | |