

# TOPOLOGY & GEOMETRY SEMINAR WS24-25

## Lecture 9: Fillability for Confoliations

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### 0. SYMPLECTIC OVERVIEW

The notion of fillability inherently involves manifolds with a certain structure, namely a *symplectic* structure. To that end, we will define what this means.

#### 0.1 DEFINITION [G, 1.4.2]

A *symplectic form* on a manifold  $W$  of (necessarily) even dimension  $2n$  is a differential 2-form  $\omega$  that is closed ( $d\omega = 0$ ) and non-degenerate, i.e. the  $2n$ -form  $\omega^{\wedge n}$  does not vanish (i.e. it is a volume form). Therewith, a *symplectic manifold* is the pair  $(W, \omega)$ .

#### 0.2 REMARK

As with contact manifolds, there is a symplectic Darboux's theorem [CdS, theorem 8.1] which states that locally all symplectic forms are the same, symplectomorphic to the standard form

$$dx_1 \wedge dy_1 + \cdots + dx_n \wedge dy_n \quad .$$

Compare this to the corresponding result [G, 2.5.1] for contact structures,

$$dz + x_1 dy_1 + \cdots + x_{n-1} dy_{n-1} \quad .$$

An accompanying object in the bridge between symplectic and contact structures is the following special vector field.

#### 0.3 DEFINITION [G, 1.4.5]

A *Liouville vector field* on a symplectic manifold  $(W, \omega)$  is a vector field  $Y$  on  $W$  satisfying  $\mathcal{L}_Y \omega = \omega$ .

#### 0.4 REMARK

In this case,  $\omega$  is necessarily exact by Cartan's magic formula and the closedness of  $\omega$ ,

$$\omega = \mathcal{L}_Y \omega = \iota_Y d\omega + d\iota_Y \omega = d\iota_Y \omega \quad ,$$

and the 1-form  $\alpha := \iota_Y \omega$  is a contact form on any hypersurface  $M$  transverse to  $Y$ , following from the previous statement

$$\alpha \wedge (d\alpha)^{\wedge(n-1)} = (\iota_Y \omega) \wedge \omega^{\wedge(n-1)} = \frac{1}{n} \iota_Y \omega^{\wedge n}$$

is non-zero when restricted to any hypersurface transverse to  $Y$ , using the fact that  $\omega^{\wedge n}$  is a volume form. ◀

An rudimentary example of the symplectic manifold is the following.

#### 0.5 EXAMPLE [G, 1.4.8]

The disk  $D^4$  with the symplectic form

$$\omega = dx_1 \wedge dy_1 + dx_2 \wedge dy_2$$

induces a contact structure on  $S^3$  with the contact form

$$\alpha = \iota_Y \omega = \frac{1}{2}(x_1 dy_1 - y_1 dx_1 + x_2 dy_2 - y_2 dx_2) \quad ,$$

wherein the Liouville vector field is

$$Y = \frac{1}{2}r \partial_r = \frac{1}{2}(x_1 \partial_{x_1} + y_1 \partial_{y_1} + x_2 \partial_{x_2} + y_2 \partial_{y_2}) \quad .$$

# 1. FILLABILITY FOR $n = 2$

Across the literature, the notion of a *filling* is defined slightly differently: this is also the case for [G] and [E-T]. In [G, 1.7.4 & 5.1.1] for example, the notions of *weak* and *strong* symplectic fillings are defined. However, for this talk, we will be following [E-T]. To that end, we first need to define what a *confoliation* is, as the title of [E-T] suggests: this is an amalgamated class of objects of both *contact* structures and *foliations*.

## 1.1 DEFINITION [E-T, §3.2]

A (positive, resp. negative) *confoliation* is a pair  $(M, \xi)$ , where  $\xi = \ker \alpha$  for some 1-form  $\alpha$  on  $M$  such that

$$\alpha \wedge d\alpha \geq 0 \quad \text{resp.} \quad \alpha \wedge d\alpha \leq 0 \quad .$$

Therewith, we can now define what a filling is in the [E-T] context.

## 1.2 DEFINITION [E-T, §3.2]

Let  $(M, \xi)$  be a confoliation, and let  $\omega$  be a closed 2-form on  $M$ . Then,  $\omega$  is said to *dominate*  $\xi$  iff  $\omega|_{\xi} \neq 0$ .

A compact symplectic 4-manifold  $(W, \omega)$  is called a *symplectic filling* of positive confoliation  $(M, \xi)$  iff  $\omega|_M$  dominates  $\xi$  and  $\partial W = M$  as oriented manifolds. In this case,  $(M, \xi)$  is said to be *symplectically fillable*.

A slightly weaker notion is that of a *symplectic semi-filling*, or correspondingly that  $(M, \xi)$  is *symplectically semi-fillable*, which is when  $M$  is only a connected component of a (disconnected) symplectically-fillable confoliated 3-manifold — that it is “symplectically cobordant” to another symplectically semi-fillable, but possibly disconnected, 3-manifold.

With that, we obtain examples of symplectically semi-fillable manifolds from the following proposition.

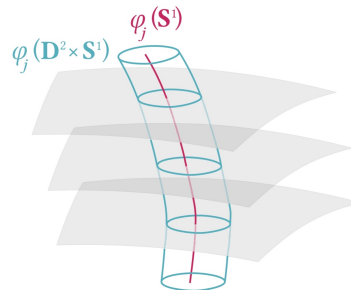
## 1.3 PROPOSITION [E-T, 3.2.2]

Taut foliations are symplectically semi-fillable.

**PROOF** From previous lectures, a (cooriented) foliation  $(M, \xi)$  is taut when there is a map  $\check{\varphi} : S^1 \rightarrow M$  such that at each point of its image is transverse to  $\xi$  while intersecting all leaves of the foliation. Following [C, §4.4], we will first show that this implies (this is actually an equivalence [C, 4.29]) that there is a vector field transverse to  $\xi$  whose flow preserves a canonical volume form on  $(M, \xi)$  relative to its leaves. To get to the proof from [E-T], we will then show that is equivalent to the existence of a 2-form dominating  $\xi$ .

Following [C], the map  $\check{\varphi}$  can be extended to a “tubular neighborhood” immersion  $\varphi : D^2 \times S^1 \rightarrow M$ , such that, for each  $p \in D^2$ ,  $\varphi(p, -)$  is transverse to  $\xi$ . In this way, because  $\varphi$  intersects each leaf transversely, we can think of homotopies of  $\varphi$  bringing any  $x \in M$  into its image, namely that there is a loop that goes through  $x$  and each leaf transversely. Moreover, it is possible (akin to the Whitney embedding theorem) to perturb  $\varphi$  to a smooth embedding keeping these properties because of the aforementioned transversality.

Now, since  $M$  is compact, we can find a finite cover of  $M$  by such open tubular neighborhoods  $\varphi(D^2 \times S^1)$  given by the homotopies of  $\varphi$ ; call the smooth embeddings that give rise to this cover  $\varphi_j : D^2 \times S^1 \rightarrow M$ , wherein the disks on each leaf corresponding to  $t \in S^1$  are, of course,  $\{\varphi_j(-, t)\}$ .



**FIGURE 1** The “tubular neighborhood”  $\varphi_j(D^2 \times S^1)$  of  $\varphi_j(S^1)$  intersecting leaves of the foliation given by  $\xi$  on  $M$ .

Next, to start constructing the “canonical” volume form of  $(M, \xi)$ : look first at  $\overline{D^2}$ , and let  $\check{\omega}$  be a 2-form which is a bump function, being positive on  $\mathring{D^2}$  and vanishing on  $\partial D^2$ . Pulling this back by the projection  $\text{pr}_1 : D^2 \times S^1 \rightarrow D^2$ , obtains a 2-form  $\omega := \text{pr}_1^* \check{\omega}$ , which is closed because it is a top

form on  $\mathbf{D}^2$  and pullback commutes with the differential. Therewith, we can obtain a closed 2-form on  $\varphi_j(\mathbf{D}^2 \times \mathbf{S}^1) \subset M$

$$\begin{aligned} M &\xleftarrow{\varphi_j} \mathbf{D}^2 \times \mathbf{S}^2 \xrightarrow{\text{pr}_1} \mathbf{D}^2 \\ (\varphi_j^{-1})^* \circ \text{pr}_1^* \tilde{\omega} : T(\varphi_j(\mathbf{D}^2 \times \mathbf{S}^1)) \times T(\varphi_j(\mathbf{D}^2 \times \mathbf{S}^1)) &\longrightarrow T(\mathbf{D}^2 \times \mathbf{S}^1) \times T(\mathbf{D}^2 \times \mathbf{S}^1) \longrightarrow T\mathbf{D}^2 \times T\mathbf{D}^2 \longrightarrow \mathbf{R} \quad , \\ &\cap \\ &TM \times TM \end{aligned}$$

which collectively across  $j$  gives in turn a (smooth) closed 2-form on  $M$

$$\omega := \sum_j (\varphi_j^{-1})^* \circ \text{pr}_1^* \tilde{\omega} \quad .$$

Note that  $\omega$  is, by construction, then smooth and strictly positive on  $\xi$ , since  $\xi$  is cooriented. It is also easy to see that  $\ker \omega$  is a 1-dimensional distribution on  $M$ , because  $\dim M = 3$  and  $\omega$  is a 2-form, and it is transverse to  $\xi$  by construction.

Let  $\alpha$  be a 1-form on  $M$  such that  $\xi = \ker \alpha$ , and pick a (smooth) vector field  $X$  such that  $\iota_X \alpha \equiv 1$ , simply a “normal” to  $\xi$  normalized to  $\alpha$ . Thusly,

$$\Omega = \omega \wedge \alpha$$

becomes a volume form, canonical in its form relative to the leaves of  $(M, \xi)$ , and

$$\begin{aligned} \mathcal{L}_X \Omega &= \mathcal{L}_X \omega \wedge \alpha + \omega \wedge \mathcal{L}_X \alpha \\ &\quad \because X \in \ker \omega \\ &= \underbrace{\iota_X \cancel{d\omega}}_{\because \text{closed}} + \underbrace{d\iota_X \omega}_{\because \text{closed}} + \omega \wedge \mathcal{L}_X \alpha \\ &\quad \because \iota_X \alpha \equiv 1 \\ &= 0 \quad , \end{aligned}$$

so the flow of  $X$  preserves the volume form  $\Omega$  on  $M$ . Therefore, tautness in the sense of the existence of the appropriate  $\tilde{\varphi} : \mathbf{S}^1 \rightarrow M$  implies that there is a vector field  $X$  on  $M$  that is transverse to  $\xi$  and preserves a volume form  $\Omega := \omega \wedge \alpha$  on  $M$ .

Moving on to [E-T], the existence of such an  $X$  is equivalent to the existence of a dominating 2-form  $\omega$ . For the sufficient direction of the equivalence: if there is such an  $X$ , then it follows from the logic above that  $\omega := \iota_X \Omega$  dominates  $\xi$  because  $\Omega$  is a non-degenerate top form, making  $\omega$  closed

$$0 = \mathcal{L}_X \Omega = d\iota_X \Omega = d\omega \quad ,$$

and  $X \pitchfork \xi$ . For the necessary direction: if  $\omega$  dominates  $\xi = \ker \alpha$ , then following the argumentation above it is possible to pick a vector field  $X$  transverse to  $\xi$  such that  $\iota_X \omega \equiv 0$  and  $\iota_X \alpha \equiv 1$ , which makes  $\mathcal{L}_X(\omega \wedge \alpha) = 0$ , so  $X$  preserves the volume form  $\omega \wedge \alpha$ .

Finally, moving on to the proof of the main statement: let  $(M, \xi)$  be a taut foliation with  $\xi = \ker \alpha$ , and let  $\omega$  be the corresponding dominating 2-form. Consider the cylinder  $M \times [0, 1]$  over  $M$  and the 2-form  $\tilde{\omega} = \text{pr}_1^* \omega + \varepsilon d(t\alpha)$  on it, where  $\text{pr}_1 : M \times [0, 1] \rightarrow M$ ,  $t \in [0, 1]$ , and  $\varepsilon > 0$  small enough. The claim is that  $\tilde{\omega}$  dominates  $\xi$  on  $M \times \{0\}$  and  $M \times \{1\}$ :

- it is non-degenerate for each  $t \in [0, 1]$  because of the non-degeneracy of  $\omega$

$$\tilde{\omega} \wedge \tilde{\omega} = \text{pr}_1^* \omega \wedge \text{pr}_1^* \omega + 2\varepsilon \text{pr}_1^* \omega \wedge d(t\alpha) + \varepsilon^2 d(t\alpha) \wedge d(t\alpha) = \varepsilon \text{pr}_1^* \omega \wedge dt \wedge \alpha \quad ,$$

since  $\omega \wedge \alpha$  is a volume form on  $M$  and  $\alpha \wedge d\alpha = 0$

- it is closed for each  $t \in [0, 1]$

$$d\tilde{\omega} = d\text{pr}_1^* \omega + \varepsilon d^2(t\alpha) = \text{pr}_1^* d\omega = 0$$

because  $\omega$  is closed and  $d^2 = 0$

- it does not vanish on  $\xi$  on the boundary of the cylinder over  $M$

$$\text{at } t = 0 \quad \tilde{\omega}|_\xi = (\text{pr}_1^* \omega)|_\xi = \omega|_\xi \neq 0$$

$$\text{at } t = 1 \quad \tilde{\omega}|_\xi = (\text{pr}_1^* \omega)|_\xi + \varepsilon (d\alpha)|_\xi \neq 0$$

for small enough  $\varepsilon > 0$  because  $\omega$  already dominates  $\xi$  and the smoothness of  $\alpha$ , since  $\ker \alpha = \xi$ .

Hence, the taut foliation  $(M, \xi)$  is symplectically semi-fillable, with its symplectic semi-filling being the cylinder over itself with the symplectic form  $\tilde{\omega}$  and with  $M \subset \partial(M \times [0, 1])$  agreeing with the orientation of  $M \times \{1\}$ . ■

We can also say something about fillability for contact structures. First, recall [G, §4.5] (cf. [E-T, §3.1]) from the previous lecture that an *overtwisted* contact structure  $(M, \xi)$  is one for which it is possible to embed a disk into  $M$  such that its interior is transverse to  $\xi$  while its boundary is tangent to it; going along with this, was the complementary notion of being *tight*, which is not overtwisted. With that, we can state the following result.

**1.6 THEOREM** [E-T, 3.2.4]

Symplectically semi-fillable contact structures are necessarily tight.

To finish off, a remark looping Liouville vector fields into the discussion of fillability, an example from before, and an example in a canonical symplectic manifold.

**1.7 REMARK**

As discussed in [remark ¶0.4](#), a Liouville vector field  $Y$  of  $(W, \omega)$  affords contact structures to its hypersurfaces that are transverse to  $Y$ . This sounds similar to the existence of a transverse vector field  $X$ , as above, which preserves a volume form. However, the existence of a Liouville vector field is a stronger condition: of course, if such a  $Y$  exists, then  $(M, \xi)$  such that  $M \subset \partial W$  and  $\xi := \ker \iota_Y \omega|_{TM}$  satisfies  $\omega|_\xi \neq 0$  since  $\xi \subset Y^\perp \omega$  by definition and  $\omega$  is non-degenerate.

In this way, [G, 1.7.4 & 5.1.1] defines a *weak* and a *strong* fillability. ◀

**1.8 EXAMPLE**

Actually [example ¶0.5](#) is an example of a (strong *à la* [G, 1.7.4]) symplectic filling:  $(D^4, \omega)$  is a symplectic filling of  $(S^3, \ker \iota_Y \omega)$ . ▶

**1.9 EXAMPLE**

Using [example ¶0.5](#) again, we will construct other examples of symplectic fillings from the canonical example [CdS, §§2.2-3] [G, 1.2.3 & §1.4] of symplectic manifold from the cotangent bundle  $T^*Q$  of any (smooth) manifold  $Q$ .

$$\begin{array}{ccccc} T^*Q & \xleftarrow{\text{pr}_1} & TT^*Q & & T^*T^*Q \\ \downarrow \text{pr}_1 & & \downarrow T\text{pr}_1 & & \downarrow T^*\text{pr}_1 \\ Q & \xleftarrow{\text{pr}_1} & TQ & & T^*Q \end{array}$$

Consider following *tautological* 1-form in  $T^*_{(q,p)} T^*Q$ , where  $q$ -coördinates are on  $Q$  and  $p$ -coördinates are for the fibre  $T^*_q Q$

$$\alpha_{(q,p)} := (T_{(q,p)} \text{pr}_1)^* p \quad .$$

Expanding this further in coördinates

$$\alpha_{(q,p)} = \sum_j p_j dq_j \quad ,$$

wherein with a conflation of notation  $dq_j \circ T_{(q,p)} \text{pr}_1 \rightsquigarrow dq_j$ , lifting  $dq_j \in T^*_q Q$  naturally into  $T^*_{(q,p)} T^*Q$ .

Setting  $\omega := -d\alpha = \sum_j dq_j \wedge dp_j$  obtains the so-called *canonical* symplectic structure on  $T^*Q$ : it is closed  $d\omega = -d^2\alpha = 0$  and non-degenerate  $\omega^n = \bigwedge_j dq_j \wedge dp_j \neq 0$ .

Bringing this back to our context ( $n = 2$ ), for a surface  $\Sigma$ ,  $(T^*\Sigma, \omega)$  is a symplectic manifold:

$$\omega := dq_1 \wedge dp_1 + dq_2 \wedge dp_2$$

is a symplectic form, as discussed, and

$$Y = p_1 \partial_{p_1} + p_2 \partial_{p_2}$$

is a Liouville vector field in the fibres above  $\Sigma$

$$\iota_Y \omega = -p_1 dq_1 - p_2 dq_2 = -\alpha \quad \implies \quad \mathcal{L}_Y \omega = d\iota_Y \omega = -d\alpha = \omega \quad .$$

Thus, if we consider a disk bundle  $DT^*\Sigma$  (the fibres above  $\Sigma$  are unit disks), then the corresponding sphere bundle  $ST^*\Sigma$  (the boundaries spheres of those disks) is symplectically fillable by  $DT^*\Sigma$ . Moreover, any hypersurface (in the fibres above  $\Sigma$ ) transverse to  $Y$  (a radial vector field) is a contact manifold that is symplectically filled by its interior. ▶

## REFERENCES

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