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BACKGROUND

Electrowetting-on-dielectric (EWOD)-based digital microfluidics (DMF) enables programmable manipulation of discrete droplets—such as dispensing, transport, merging, and splitting—using electric fields on a flat substrate as illustrated in Figure 1.1b(b), unlike traditional continuous-flow microfluidics. This eliminates the need for mechanical components like micro-pumps or valves as shown in Figure 1.1b (a). The underlying principle is governed by the Young–Lippmann equation, which relates voltage to contact angle modulation [1].

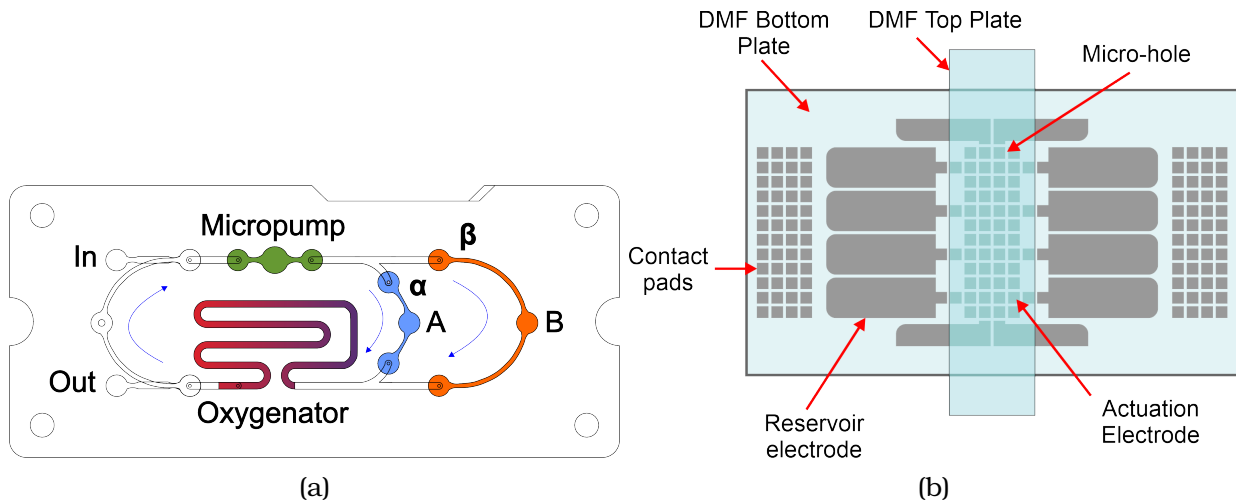


Figure 1.1: Comparison between (a) conventional microfluidics (adapted from [2]) and (b) EWOD-DMF device (adapted from [3]).

Conventional EWOD-DMF systems are typically fabricated on glass or silicon using cleanroom processes [4], which, while precise, are expensive and integration-limited. PCBs present a cost-effective, scalable alternative with mature fabrication methods, multilayer routing, and easy integration with control electronics [5–7].

METHODS

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