

FlappyPi

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# The Summer C Project and FlappyPi

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Group 16

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# Overview

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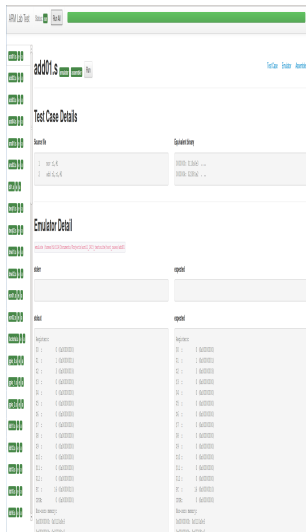
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# Our Approach

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- We based the design on the structure of the CPU
- This allowed us to split the design into functional sections
- We emulated specific functionalities of the CPU with corresponding method names
- The code was written so as not to be repetitive

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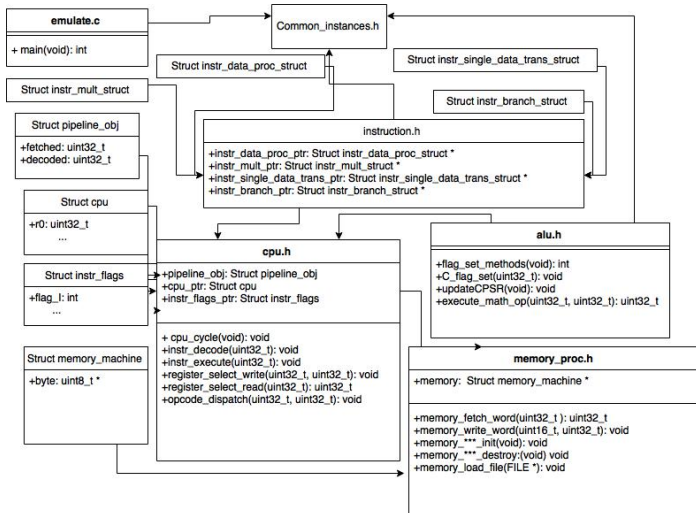
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# Outcome

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The screenshot displays the ARM Emulator-Assembler Testing Tool interface. The top bar shows the application name and a progress bar. The left sidebar contains a vertical list of icons for different components. The main area is titled 'Test Case Details' and shows the source file 'eor02.s' with two lines of assembly code: '1 mov r1, #0x0' and '2 mov r2, r1, #0x0F'. The equivalent binary is shown as '00000000: E10A0000 ....' and '00000004: 52021000 . 1,'. The 'Emulator Detail' section shows the 'stdout' and 'stderr' output, which is empty. The 'Registers' section shows a list of registers (R0 to R15) and their values, all set to 0. The 'Non-data memory' section shows a list of memory addresses and their values, all set to 0.

ARM Emulator-Assembler Testing Tool - Mozilla Firefox

ARM Emulator-Asse... x

@ localhost:16000

Most Visited • Getting Started N/ arm11\_16/icc at mas... ARM111 - 2014/11 ARM Emulator-Asse...

ARM Lab Test Status **Test** Run All

**eor02.s** **emulator** **assembler** **Run**

Test Case Emulator Assembler

**Test Case Details**

Source file

```
1 mov r1, #0x0
2 mov r2, r1, #0x0F
```

Equivalent binary

```
00000000: E10A0000 ....
00000004: 52021000 . 1,
```

**Emulator Detail**

emulator /home/cvalls/rev1/3401\_testsuite/test\_cases/eor02.s

**stdout**

**stderr**

**Registers:**

R0	0	0x00000000
R1	0	0x00000000
R2	0	0x00000000
R3	0	0x00000000
R4	0	0x00000000
R5	0	0x00000000
R6	0	0x00000000
R7	0	0x00000000
R8	0	0x00000000
R9	0	0x00000000
R10	0	0x00000000
R11	0	0x00000000
R12	0	0x00000000
R13	0	0x00000000
R14	0	0x00000000
R15	0	0x00000000

**Non-data memory:**

**expected**

**expected**

R0	0	0x00000000
R1	0	0x00000000
R2	0	0x00000000
R3	0	0x00000000
R4	0	0x00000000
R5	0	0x00000000
R6	0	0x00000000
R7	0	0x00000000
R8	0	0x00000000
R9	0	0x00000000
R10	0	0x00000000
R11	0	0x00000000
R12	0	0x00000000
R13	0	0x00000000
R14	0	0x00000000
R15	0	0x00000000

**Non-data memory:**

# Problems and Challenges

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## Design

We were initially unsure of the most efficient (or readable) way to design our implementation.

## I want to break free

We had difficulty freeing pointers in the correct place, leading to segmentation faults

## Debugging

It took us the same amount of time to debug our code as to write it. We debugged our code by using Eclipse, which was useful in showing us which variable values we had at any given time. Implement a pipeline at the start not at the end, which caused us offset issues

# Improvements

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- Make our code more compact and not be as explicit
- Write our code to be reusable
- Plan THEN code
- A good night's sleep - for general health

# Our Approach

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We used a simple 3 modules approach - *assemble.c*, *dictionary.c* and *encode.c*.

Characteristics of our assembler include:

- 2 pass assembler method
- Polymorphic AVL Tree ADT dictionary
- Using the Dictionary to map functions to Opcodes
- Each Function decodes the instruction string themselves



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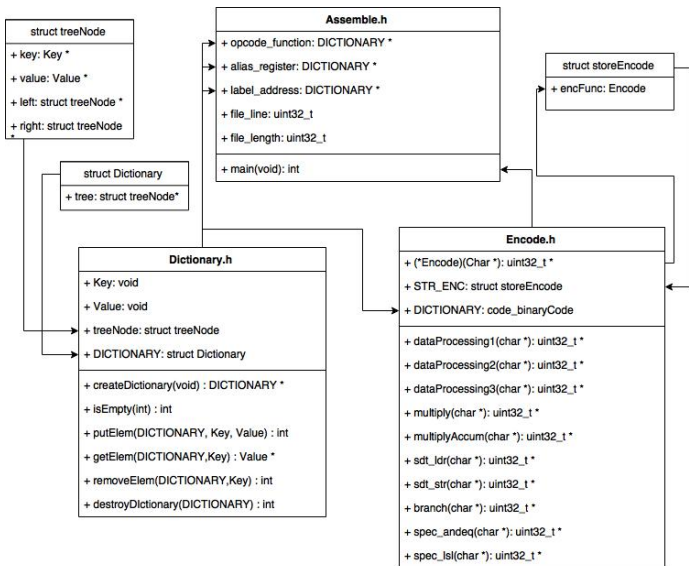
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# Outcome - Disassembler

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factorial + (~/.Documents/Projects/arm11\_1415\_testsuite/test\_cases) - VIM

```
File Edit View Search Terminal Help
1 00000000: 0100 a0e3 0510 a0e3 9100 02e0 0200 a0e1 .....
2 00000010: 0110 41e2 0000 51e3 faff ff1a 013c a0e3 ..A...Q.....<..
3 00000020: 0020 83e5 0a
```

Examples ▾ Help ▾ Blog Contact Us!

Disassembly Hex Sections File Info

.data:00000000	e3a00001	mov r0, #1
.data:00000004	e3a01005	mov r1, #5
.data:00000008		
.data:00000008		loc_00000008:
.data:00000008	e0020091	mul r2, r1, r0
.data:0000000c	e1a00002	mov r0, r2
.data:00000010	e2411001	sub r1, r1, #1
.data:00000014	e3510000	cmp r1, #0
.data:00000018	1affffff	bne loc_00000008
.data:0000001c	e3a03c01	mov r3, #256 ; 0x100
.data:00000020	e5832000	str r2, [r3]

factorials x

```
mov r0, #1
mov r1, #5
loop:
mul r2, r1, r0
mov r0, r2
sub r1, r1, #1
cmp r1, #0
bne loop
mov r3, #0x100
str r2, [r3]
```

Plain Text ▾ Tab Width: 8 ▾ Ln 1, Col 1 INS

# Problems and Challenges

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## String Tokenising

Using **strtok()** and **sscanf()** proved to be very limiting

## Dictionary ADT

Development of the AVL tree was time consuming and took a long time before it was bug free

## Memory Allocation

Many mistakes and errors ended up being A problem with the use of **malloc()** and **free()**.

## Code Reuse

We definitely could have made a better attempt to reuse code from emulator

# Improvements

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- Creating our own string tokeniser which is more flexible than the implementation of **strtok()**.
- Spending a bit more time optimising and improving the quality of the code.
- Reducing redundant code
- Rethinking the use of pointers

# Flashing GPIO

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Figure : Our Flashing Gpio Led

# FlappyPi

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Figure : The Bird Is The Word.

# Extending the Assembler

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To make it possible for us to use our own Assembler to process the assemble source code, we have had to do the following:

## Stack (block data transfer)

Enabling the use of **stm** and **ldm** in the assembler, so that the stack can be utilised.

## Opcodes Suffixes

Supporting the addition of condition codes appended to existing opcodes.

## Aliasing

Supporting the aliasing of registers and commands for clearer use code.

## Commenting

Supporting commenting for clearer programs.

## Multi-File Programs

Enabling the use of larger programs.

# Problems and Challenges - Assembler extension

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## Aliasing

Memory corruption due to lack of compatibility with our dictionary

## push/pop

Difficult to debug as the error was very hard to find



# Problems and Challenges - FlappyPi

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## Lack of resources

There is a small number of helpful articles online covering assembly, As a result it was difficult to implement. However, the Cambridge bakingPi tutorial was very helpful for the screen output

**Tedious** Flappy bird sprite was 1200+ lines of assembly which was very repetitive

# Improvements

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- Stop the bird from flashing
- Randomly generate terrain
- Include a button and the ability to move the bird
- Collision detection to allow the game to be played

# Problems and Solutions

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## Organisation

- Lack of a Complete Plan from the start
- Redundant code
- Regularly missed personal deadlines
- Distribution of tasks

## Communication

- Instant messenger issues
- Lack of Clarity
- Sleeping Patters

## Effectiveness

- C knowledge
- Testing and Debugging
- Git

# Use of GIT

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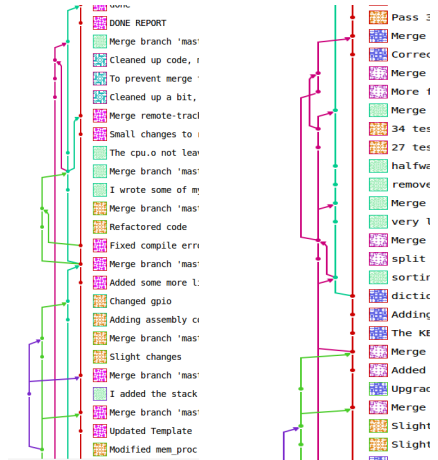
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We did not use Git  
effectively nor efficiently

- Branching
- Merging
- Excessive use of Master Branch
- Non-compiling/  
broken code  
regularly pushed



# Conclusion

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Evaluation

- Enjoyable and informative
- Learned new languages of Assembly and C
- Deeper understanding of the CPU
- Low level Graphical Interfaces
- Learnt key aspects of working in a team.