Constraint Logic Programming and Vehicle Routing Problem

Mikael Arakelian

ezhome

May 24, 2017

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Constraint Programming

So what is Constraint Programming?

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So you don't specify the sequence of steps of finding a solution, but rather define the properties you want the solution to satisfy.

Constraint Satisfaction Problem Definition

Given a set of variables $\{X_1, X_2, \ldots, X_n\}$ where with each variable we associate its domain $D(X_i)$ and a set of constraints $\{C_1, C_2, \ldots, C_m\}$ we need to assign each variable to a value, such that all constraints are satisfied

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Constraint Optimization Problem Definition

Basically almost the same as the CSP, with an objective function defined, which needs to be minimized (maximized).

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So... How does it work?

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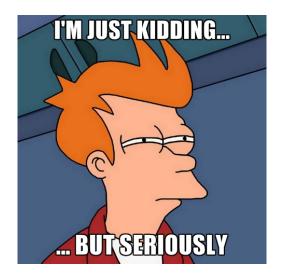
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Main Approaches

There are 2 main approaches for solving the CSP and COP

- Complete Search (Backtracking and Constraint Propagation)
- 2 Local Search

Complete Search

- Use constraints to reduce the set of values each variable can take without losing (Constraint Propagation or Pruning)
- ② Choose a value for a variable when no further deduction can be made. If the choice did not result in a solution then backtrack (Backtracking)

Complete Search

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Pros: If a solution exists, we will necessarily find it

Cons: It has an exponential behaviour

Local Search

- Make an initial assignment of variables (possibly violating some of constraints)
- Iteratively change the assigned values of the variables by making a small pertubation of assigned values (looking at the neighbourhood of current solution), maximizing the number of constraints satisfied (or depending on the objective function to be optimizer)

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Pros: Much faster, suits better for using CP for optimization (in optimization we may forbid visiting solutions that violate constraints) Cons: We might not find a solution, even if it exists. In optimization problems optimality is not guaranteed

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It is a mathematical game where the digits of some numbers in an equation are represented by letters. Each letter represents a unique digit. The goal is to find the digits such that a given mathematical equation is verified. We are going to solve the following cryptarithmetic:

$$GREEN + GARDEN = EZHOME$$

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GREEN + GARDEN = EZHOME

To model the problem in terms of CSP we need to answer the following questions

- What are the variables in the problem? What are their domains?
- What are the constraints of the problem?



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GREEN + GARDEN = EZHOME

Let's model our problem the following way:

- We have a variable for each letter in the equation. All of them should be digits, so the domain of each variable is the set $\{0, 1, \dots, 9\}$. Let's denote the variables as X_{letter}
- **2** The constraints are: $X_G \neq 0, X_E \neq 0, X_{l_i} \neq X_{l_j}$, and the actual equation

$$\sum_{I_i \in \textit{GREEN}} 10^i * X_{I_i} + \sum_{I_i \in \textit{GARDEN}} 10^i * X_{I_i} = \sum_{I_i \in \textit{EZHOME}} 10^i * X_{I_i}$$

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The first question we may ask is: is it possible to split them into m rooms? (CSP version)

We can also pose the problem in a different way: what is the minimal number of necessary rooms? (COP version)

The Room Sharing Problem (CSP)

Let's model the problem:

- For each person we have a variable $Room_i$ and $D(Room_i) = \{0, 1, \dots, m-1\}$
- Constraints: $\sum_{i=1}^{n} (Room_i = j) \le 2$, $Room_i \ne Room_j$ for all (i, j) that don't want to be in the same room.

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The Room Sharing Problem (COP)

In the optimization version we don't know the of rooms beforehand, so the previous model won't work



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As a result, here is our new model:

- **1** N_i represents the neighbour of *i*th person. $D(N_i) = \{1, 2, ..., n\}$
- 2 N_i 's must be all different, preferences and $N_{N_i} = i$,
- **3** Objective function: $\sum_{i=1}^{n} (N_i = i) \rightarrow \min$

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Vehicle Routing Problem Definition

The Vehicle Routing Problem is a combinatorial optimization problem which asks the following question: "What is the optimal set of routes for a fleet of vehicles delivering goods or services to various locations?"

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The Vehicle Routing Problem is a combinatorial optimization problem which asks the following question: "What is the optimal set of routes for a fleet of vehicles delivering goods or services to various locations?" There are various generalizations of this problem, such as Capacitated VRP (the total demand of the locations on a vehicle's route cannot exceed its capacity), VRP with Time Windows and a whole zoo of them

How we think about a VRP

Suppose we have n customers and m vehicles. We usually think about the VRP in terms of a graph on n+2m nodes. In terms of this graph we can reformulate the problem as follows: given a graph G=(V,E) and 2m nodes $\{start_1, start_2, \ldots, start_m\}$ and $\{end_1, end_2, \ldots, end_m\}$ from V break down G into m simple paths where the ith path starts at $start_i$ and ends at end_i .

CP formulation of Classical VRP

So how can we reformulate graph representation of VRP in terms of CP?

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- Let's introduce the variables $Next_i$, $Vehicle_i$, $Active_i$, where $Next_i$ corresponds the number of the next of ith node, $Vehicle_i$ corresponds to which vehicle node i corresponds to and $Active_i$ shows whether the ith node belongs to any route or not
- ② $D(Next_i) = V$, $D(Active_i) = \{0, 1\}$, $D(Vehicle_i) = \{-1, 0, 1, ..., m 1\}$
- Necessary constraints in VRP are: AllDifferent(Nexti), Vehiclei = VehicleNexti and a special constraint called NoCycle

VRP with Time Windows

Many vehicle routing problems involve scheduling deliveries or service calls to customers. A natural constraint for these problems is that a customer can only receive a delivery or service in a specified window of time. For example, a company might need to schedule a time window when a customer will be at home.

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How can we model this?

Modelling Time Windows in VRP

For simplicity, let's assume that all of the vehicles happen at the same day. For each node let us create an additional variable called $Time_i$ (arrival time in seconds) with its domain equal to

 $D(Time_i) = \{0, 1, ..., 24 * 60 * 60 - 1\}$ and constraints if $Active_i = 1$ then $Time_{Next_i} = Time_i + duration_i + driving_time_i$.

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 $D(Time_i) = \{0, 1, \dots, 24*60*60-1\}$ and constraints if $Active_i = 1$ then $Time_{Next_i} = Time_i + duration_i + driving_time_i$. This variables enable us to model all types of constraints on time. For example:

- 10 $12 * 3600 \le Time_i \le 14 * 3600$ node i must be served after 12 : 00PM and before 14 : 00PM
- **2** $Time_i isnotin\{(0,7.5*360001), (13*3600, 24*60*60-1)\}$
- **3** $Time_{end_i} \le 16 * 3600$

Modelling Capacity in VRP

Capacity can be modelled in VRP very similar to time

Thank You!