PCA Application (canadian cities dataset)

Data set / Download link

The data set of canadian cities was downloaded from this location:

https://simplemaps.com/data/canada-cities

```
In [77]: import numpy as np
    import pandas as pd
    import matplotlib.pyplot as plt

In [78]: # data set
    fname = './data/maps/simplemaps_canadacities_basicv1.8/canadacities.csv'

# Load data set into data frame
    dframe = pd.read_csv(fname)
    dframe.head(5)
```

city	city_ascii	province_id	province_name	iat	g	population	uells
city	city accii	province id	province_name	lat	Ina	population	done

Out[78]:

0	Toronto	Toronto	ON	Ontario	43.7417	-79.3733	5647656.0	442



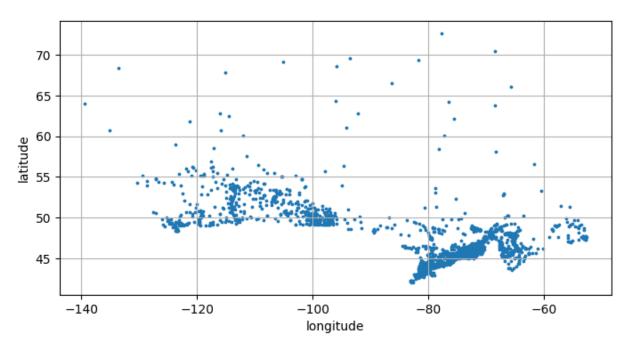
2	Vancouver	Vancouver	ВС	British Columbia	49.2500	-123.1000	2426160.0	574!
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3	Calgary	Calgary	AB	Alberta	51.0500	-114.0667	1306784.0	1597
4	Edmonton	Edmonton	AB	Alberta	53.5344	-113.4903	1151635.0	1320

For a demonstration of how to use PCA for data analysis only the columns on latitude (lat) and longitude (lng) are required.

These are extracted first.

```
In [79]: df_lon_lat = dframe.loc[:, ['lng', 'lat']]
         df_lon_lat.head(3)
Out[79]:
                  Ing
                          lat
             -79.3733 43.7417
             -73.5617 45.5089
         2 -123.1000 49.2500
In [80]: # the same data but this time as a ndarray
         lon_lat = df_lon_lat.values[:, :]
         print(f"lon_lat.shape : {lon_lat.shape}")
        lon_lat.shape : (1737, 2)
In [81]: fig1 = plt.figure(1, figsize=[8, 4])
         ax_f1 = fig1.add_subplot(1, 1, 1)
         ax_f1.scatter(lon_lat[:,0], lon_lat[:,1], s=3)
         ax_f1.grid(True)
         ax_f1.set_xlabel('longitude')
         ax_f1.set_ylabel('latitude');
Out[81]: Text(0, 0.5, 'latitude')
```



```
In [82]: lon = lon_lat[:,0]
         lat = lon_lat[:,1]
         mean_lon = np.mean(lon)
         mean_lat = np.mean(lat)
         mean_lon_lat = np.mean(lon * lat)
         mean_lon_lon = np.mean(lon * lon)
         mean_lat_lat = np.mean(lat * lat)
         x11 = mean_lon_lon - mean_lon**2
         x22 = mean_lat_lat - mean_lat**2
         x12 = mean_lon_lat - mean_lon * mean_lat
         x21 = x12
         print(f"entries of covariance matrix")
         print(f"x11 : {x11}")
         print(f"x22 : {x22}")
         print(f"x12 : {x12}")
         print(f"x21 : {x21}")
        entries of covariance matrix
```

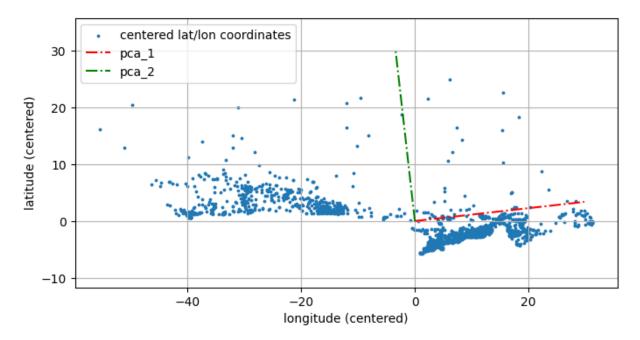
entries of covariance matrix x11 : 358.09345445689814 x22 : 13.044417240758321 x12 : -39.52986920519061 x21 : -39.52986920519061

```
In [83]: # centered data set
lon_c = lon - mean_lon
lat_c = lat - mean_lat

# build a centered data matrix (will be used later in this notebook)
lonlat_c = np.column_stack((lon_c, lat_c))

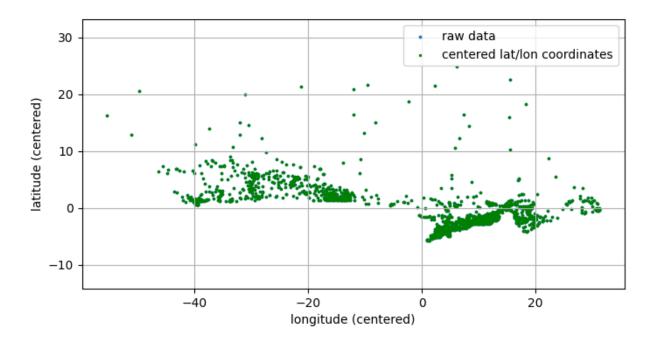
x11 = np.mean(lon_c * lon_c)
x22 = np.mean(lat_c * lat_c)
x12 = np.mean(lon_c * lat_c)
```

```
print(f"x11 : {x11}")
         print(f"x22 : {x22}")
         print(f"x12 : {x12}")
        x11 : 358.0934544568978
        x22 : 13.044417240759058
        x12 : -39.529869205191034
In [84]: # create covariance matrix and compute the eigen decomposition
         Xmat = np.array([[x11, x12], [x12, x22]])
         eigen_values, Vmat_t = np.linalg.eig(Xmat)
         print(f"eigen_values :\n{eigen_values}\n")
         print(f"Vmat_t
                              :\n{Vmat t}\n")
        eigen_values :
        [362.56419025 8.57368145]
        Vmat_t
        [[ 0.99366517  0.11238121]
         [-0.11238121 0.99366517]]
In [85]: fig2 = plt.figure(2, figsize=[8, 4])
         ax_f2 = fig2.add_subplot(1, 1, 1)
         # must preserve aspect ratio if orthogonal eigenvectors are displayed correctly ...
         ax_f2.axis('equal')
         ax_f2.scatter(lon_c, lat_c, s=3, label='centered lat/lon coordinates')
         ax_{2.plot([0, 30*Vmat_t[0, 0]], [0, 30*Vmat_t[0, 1]], c='r', linestyle='-.', label}
         ax_{f2.plot([0, 30*Vmat_t[1, 0]], [0, 30*Vmat_t[1, 1]], c='g', linestyle='-.', label}
         ax_f2.legend()
         ax_f2.grid(True)
         ax_f2.set_xlabel('longitude (centered)')
         ax_f2.set_ylabel('latitude (centered)');
Out[85]: Text(0, 0.5, 'latitude (centered)')
```



```
In [86]: # projections on pca1
         proj_pca1 = lonlat_c @ (Vmat_t[0, :]).T
         pca1 = np.column_stack((proj_pca1, proj_pca1)) * Vmat_t[0, :]
         proj_pca2 = lonlat_c @ (Vmat_t[1, :]).T
         pca2 = np.column_stack((proj_pca2, proj_pca2)) * Vmat_t[1, :]
In [87]: result = pca1 + pca2
In [88]: fig3 = plt.figure(3, figsize=[8, 4])
         ax_f3 = fig3.add_subplot(1, 1, 1)
         # must preserve aspect ratio if orthogonal eigenvectors are displayed correctly ...
         ax_f3.axis('equal')
         ax_f3.scatter(lon_c, lat_c, s=3, label='raw data')
         ax_f3.scatter(result[:, 0], result[:, 1], s=2, label='centered lat/lon coordinates'
         ax_f3.legend()
         ax_f3.grid(True)
         ax_f3.set_xlabel('longitude (centered)')
         ax_f3.set_ylabel('latitude (centered)');
```

Out[88]: Text(0, 0.5, 'latitude (centered)')



In []: