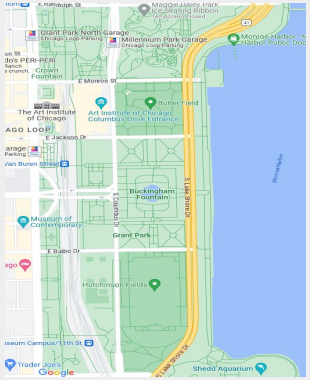
**Actual flight hours:** Over 200 hours
**Special Weather Condition:** 20 hours in adverse weather conditions, including rain, strong winds
**Simulated flight hours:** 10
**Crash history:** One drone crash in windy weather
**Certification:** Part 107

**Mission:** Photography
**Model:**
**Flight hours:** 50
**Crash history:** no crashes
**No. of successful flights:** 70
**Equipment:** High-resolution camera.
Obstacle avoidance sensor.



**Air traffic:** Light
**Human traffic:** Moderate
**Flight conditions:** Low clouds
Potential for rain showers or gusty winds. Wind speed is moderate, around 10-15 knots (approximately 11.5-17 mph)
**Physical area:** Hight trees

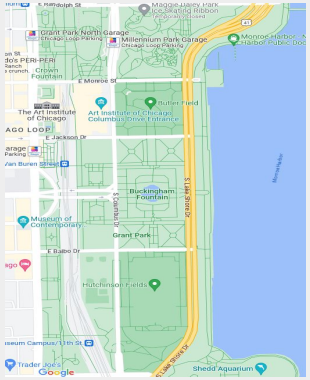
At a lively 60th birthday celebration for their best friend, attended by 100 guests on a scenic farm, a skilled drone photographer was invited to capture precious moments and create lasting memories. However, the presence of tall trees and low-hanging clouds posed challenges for the pilot to maintain visual line-of-sight (VLOS) during the flight.

**Integrated system's decision:** The system sent an alert - Important Safety Advisory - Visual Line-of-Sight Flight may be lost due to terrain, pilot experience, and weather conditions.

**Sky Master**

**Actual flight hours:** Over 200 hours
**Special Weather Condition:** 20 hours in adverse weather conditions, including rain, strong winds
**Simulated flight hours:** 10
**Crash history:** One drone crash in windy weather
**Certification:** Part 107

**Mission:** Photography
**Model:**
**Flight hours:** 50
**Crash history:** no crashes
**No. of successful flights:** 70
**Equipment:** High-resolution camera.
Obstacle avoidance sensor.



**Air traffic:** Light
**Human traffic:** Moderate
**Flight conditions:** Low clouds
Potential for rain showers or gusty winds. Wind speed is moderate, around 10-15 knots (approximately 11.5-17 mph)
**Physical area:** Hight trees

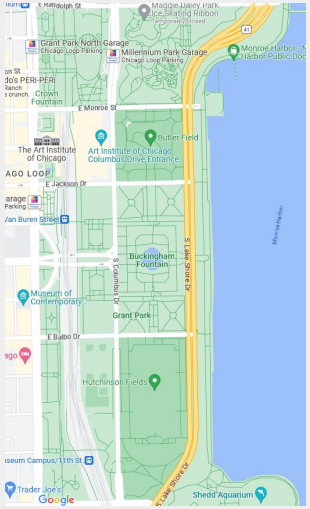
At a lively 60th birthday celebration for their best friend, attended by 100 guests on a scenic farm, a skilled drone photographer was invited to capture precious moments and create lasting memories. However, the presence of tall trees and low-hanging clouds posed challenges for the pilot to maintain visual line-of-sight (VLOS) during the flight.

**Integrated system's decision:** flight denied due to an important safety advisory - Visual Line-of-Sight Flight, based on terrain, pilot experience, and weather conditions.

**Novice Flyer**

**Actual flight hours:** 100
**Special Weather Cond:** 20 hours  in mild weather conditions and light rain
**Simulated flight hours:** 50
**Crash history:** no crashes
**Certification:** Part 107
Typically operates in less complex environments, such as suburban areas with open spaces.

**Mission:** Delivery
**Model:**
**Flight hours:** 5,000




**Air traffic:** Moderate
**Human traffic:** Light
**Flight conditions:** Potential wind tunnels and areas of turbulence
Wind coming from the northwest at 12 knots (approx.14 miles per hour).
Wind speed is expected to increase to 15 knots (approximately 17 miles per hour) in next two hours.
**Physical area:** Sky scrapers

DroneSwift recently experienced significant growth in Metropolis city. Due to a surge in purchases, the organization decided to elevate the skill level of their young drone pilots. Novice Flyer has been entrusted with delivering an urgent package to a customer located in the heart of Downtown Metropolis, a bustling city renowned for its iconic skyscrapers and modern architecture. The delivery address is nestled within a dense cluster of tall buildings, forming what is commonly referred to as an 'urban canyon.' Novice Flyer eagerly embraced the challenge and began planning his flight. However, his limited experience in a large city led him to overlook fast-changing conditions and the possibility of encountering an urban canyon.

**Integrated system's decision:** flight denied based on the weather conditions, prompting the pilot to come up with a new plan.

## PILOT

**Actual flight hours:** Few

**Simulated hours:** Some

**Adverse Flight Exp.:** Very little weather experience

**Crash history:** None

**Certification:** Part 107

## DRONE

**Flight history:** Few flights and few successful flights. Two prior crashes

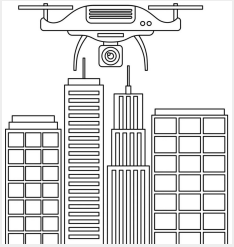
**Maintenance, repairs:** Repaired after crashes. Little regular maintenance.

**Make/Model history:** Self-built drone from online instructions. Of medium size, heavy build

**Available sensors:** Standard

**Communication method/quality:** Standard

**Software:** Standard



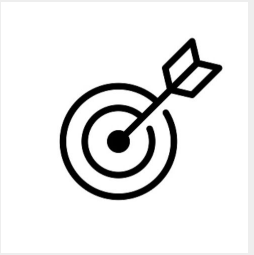
## CONDITIONS

**Air traffic:**
A few other drones flying nearby in the park

**Human traffic:**
Small crowds nearby

**Weather conditions:**
Light wind gusts, patchy clouds

**Physical area:**
A few trees, not many buildings



## MISSION

**Purpose:** Getting videos of a wedding in an urban park

**Complexity level:** Simple, few waypoints, some people nearby

**Flight rules:** Limited area and low maximum height. Line of Sight only

**Prior Simulations of this flight:** Many

## PILOT

**Actual flight hours:** Many

**Simulated hours:** Lots

**Adverse Flight Exp.:** Lots of weather experience

**Crash history:** A few

**Certification:** Part 107

## DRONE

**Flight history:** Moderate number of flight hours. No previous crashes

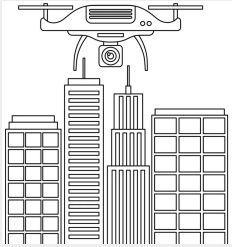
**Maintenance, repairs:** Regular maintenance

**Make/Model history:** Standard large drone, often used for commercial filming purposes

**Available sensors:** Standard

**Communication method/quality:** Standard

**Software:** Standard



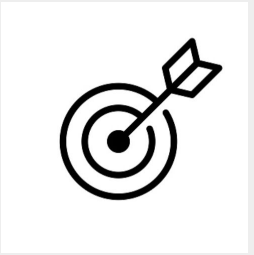
## CONDITIONS

**Air traffic:**
Heavy air traffic in a city

**Human traffic:**
Normal traffic for an urban area.

**Weather conditions:**
High winds, especially when flying between buildings

**Physical area:**
Many buildings and trees



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Simple, few waypoints, some people nearby

**Flight rules:**
Limited area and low maximum height. Line of Sight only

**Prior Simulations of this flight:** Many

**Actual flight hours:** Few.

**Simulated hours:** Some.

**Adverse Flight Exp.:** Very little weather experience.

**Crash history:** None.

**Certification:** Part 107.

**Flight history:** Few flights and few successful flights. Two prior crashes.

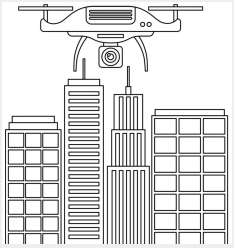
**Maintenance, repairs:** Repaired after crashes. Little regular maintenance.

**Make/Model history:** Self-built drone from online instructions. Of medium size, heavy build.

**Available sensors:** Standard.

**Communication method/quality:** Standard.

**Software:** Standard.



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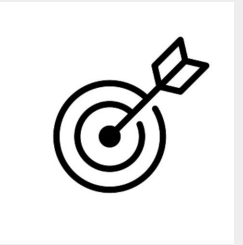

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