

Recall Navier-Stokes

$$\frac{\partial \vec{V}}{\partial t} + \vec{V} \cdot \nabla \vec{V} = -\frac{\nabla p}{\rho} + \nu \nabla^2 \vec{V}$$

LHS - Acceleration terms,  
first term in LHS is th.  
unstirred term and th  
second term is th  
convection acceleration,  
represents how velocity  
changes as one point of  
fluid moves from one  
place to another. grad  
bar of PSS is gradient  
of pressure, second term  
represents the viscosity  
of the fluid. A small

that the fluid is  
 inviscid, i.e. there  
 are no viscosity  
 effects. Another assumption  
 is that the density  
 is constant. The  
 $(\vec{v}, \nabla) \vec{v}$  term makes the  
 flow non-linear. If  
 viscosity = 0 then we  
 have, either

$$\frac{\partial \vec{v}}{\partial t} + (\vec{v}, \nabla) \vec{v} = - \frac{\nabla p}{\rho}.$$

PFB's underlying equations  
 numerically to get to

velocity field and its associated pressure. CFD is used for vastly different phenomena.

### Basic ingredients of CFD

#### 1 - The mathematical model

Given set of partial differential equations and a set of boundary / initial conditions.

Models target applications in incompressible flow, inviscid, turbulent, 2D or 3D. The model always has assumptions

12 - Discretization methods

Method for approximating  
of the PDEs by a system  
of algebraic equations

$$G(\mathbf{u}(x)) = \mathbf{f}(x)$$

$$G + x = b$$

- \* finite differences } big
  - \* finite volume } 3
  - \* finite elements }
  - \* spectral methods
  - a Bounding element method
- Two aspects of discretization

Geometry & Mesh

G Model - All mathematical operators  
of be transformed into  
arithmetic operators on  
the grid.

3 Analyse the numerical scheme

The numerical scheme  
must satisfy a number of  
conditions to be accepted  
: consistency, stability,  
convergence, accuracy.

4 Solve

Other grid point values &  
all the flux values

→ time dependent  $\rightarrow$  ODE  
 $\Rightarrow$  Stiff - Algebraic  
System

+ does integrations  
+ linear solves

GM  
GPost-processing, with

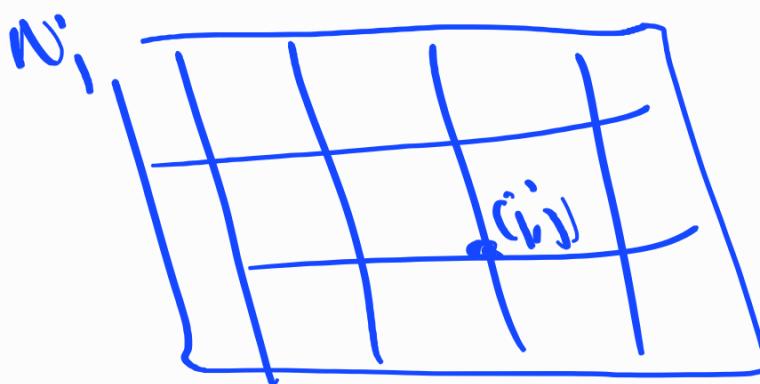
Lecture 2

The finite difference method

5 Approximate derivative

get from Taylor expansion

5 Step 1, define grid



- Two families  
of sites.

Ni are family A  
and Nj are family B

not blessed. Families diffuse  
only blessed over. Standard  
dissemination scheme.

For each node we have  
an unknown value of  
the field variable.

which depends on the  
neighborhood of nodes  
provided in algebraic  
expression.

# Definition of a derivative

$$\frac{dy}{dx} = \lim_{\Delta x \rightarrow 0} \frac{u(x_i + \Delta x) - u(x_i)}{\Delta x}$$

Geometrical interpretation

Slope of tangent to curve  $u(x)$

- Backward difference
- forward difference
- central difference, approximating derivative every,  $x_i, x_{i+1}$ , some approximations are better than others, qualify

of information improves as  
 $\Delta x \rightarrow 0$ .

Finite difference approximation:

Assume  $\Delta x$  uniform

Backward difference.

$$\frac{\partial y}{\partial x} \approx \frac{u(x_i) - u(x_{i-1})}{\Delta x}$$

Forward difference

$$\frac{\partial y}{\partial x} \approx \frac{u(x_{i+1}) - u(x_i)}{\Delta x}$$

Central difference

$$\frac{\partial y}{\partial x} \approx \frac{u(x_{i+1}) - u(x_{i-1})}{2\Delta x}$$

Taylor expand  $u(x)$  near  $x_i$ :

$$u(x) = u(x_i) + (x-x_i) \frac{\partial u}{\partial x} \Big|_i + \dots + \frac{(x-x_i)^n}{n!} \frac{\partial^n u}{\partial x^n} \Big|_i + \dots$$

$x \leftarrow x_{i+1}$   
 $\leftarrow x_i$ . Get  $u(x_{i+1})$  in

terms of  $u(x_i)$  and its derivatives.

$$\frac{\partial u}{\partial x} \Big|_i = \frac{u(x_{i+1}) - u(x_i)}{x_{i+1} - x_i}$$

$$- \frac{(x_{i+1} - x_i)}{2} \frac{\partial^2 u}{\partial x^2} \Big|_i - \frac{(x_{i+1} - x_i)}{3!} \frac{\partial^3 u}{\partial x^3} \Big|_i - \dots$$

If  $x_{i+1} - x_i$  is small, higher

order terms can be neglected.

Then we get the forward differences approximation of order  $O(\Delta x)$ , truncation errors. As  $\Delta x \rightarrow 0$ , error  $\rightarrow 0$  and the approximation error converges. Similar results for forward and central, although the error for central difference is  $\Delta x^2$ .

### Lecture 3

#### Definition

The power of  $\Delta x$  with which the truncation error  $\rightarrow 0$  is

called the order of accuracy  
of the finite difference approx.

FD, BD Both are first order  
accurate to  $O(\Delta x)$   
CD accurate to  $O(\Delta x^2)$ .

FD, BD are one-sided.

(Consider 1D domain  $(0, 1)$ )

" Mesh points

$$\Delta x = 0.1$$

1st order approximation  $O(\Delta x)$   
 $\approx O(10^{-1})$

2nd order approximation  $O(\Delta x^2) \approx O(10^{-2})$

You need more mesh points

If you want to use one-sided  
difference methods,

Notes

First order finite difference  
can be considered a central  
difference w.r.t a midpoint

$$\left. \frac{\partial u}{\partial x} \right|_{i+\frac{1}{2}} = \frac{u_{i+1} - u_i}{\Delta x} + O(\Delta x^2)$$

$$\left. \frac{\partial u}{\partial x} \right|_{i-\frac{1}{2}} = \frac{u_i - u_{i-1}}{\Delta x} + O(\Delta x^2)$$

gained an order of accuracy  
using the same formulae  
but considering more  
points.

$$\frac{\partial \vec{v}}{\partial x} + (\vec{V} \cdot \vec{\nabla}) \vec{v} = - \frac{\nabla P + \nabla J^2}{\rho} \vec{v}$$

\* Convective terms appear  
as a second order derivative

\* Convective fluxes appear  
as first order derivatives

Numerical modelling assumptions

1) Model equation tells  
us about a system of PDEs when  
high spatial derivative is  
second order and  
this is 1st order.

Different discretisation  
may be appropriate to  
the physical process.

Lecture 4 (I should set

for lessons 1-4 in  
the code).

## 0 1d, linear convection

$$\frac{\partial \bar{u}}{\partial t} + C \frac{\partial \bar{u}}{\partial x} = 0, \quad u(x_0) = u_0(x)$$
$$u(x,t) = u_0(x-ct)$$

Behaves similarly to a wave propagator. Relationship between convection and wave propagator. Space-time discretization i.e. width in  $x$   
 $\Delta x$ , width in  $t$   
 $\Delta t$ .

1 Numerical scheme FD in  $t$   
BD in  $x$

Possibilities

$$\frac{u_i - u_i}{\Delta t} + c \frac{u_i - u_{i-1}}{\Delta x} = 0$$

$$\Rightarrow u_i^{n+1} = u_i^n - \frac{\Delta t}{\Delta x} (c(u_i^n - u_{i-1}^n))$$

This function gives the function forward in time  
So you need an I.C.

I.C.  $u=2$  at  $0.5 \leq x \leq 1$

$u=1$  at  $x=0, x=2$

$u=1$  everywhere else.

Code this. Pseudocode is available in the lecture series.

## (2) 1D convection

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = 0$$

Inviscid Burger

$\frac{\partial u}{\partial x} + u \frac{\partial x}{\partial t} = 0$ , equation

can generate discontinuities between  
for smooth initial conditions

Discretization: FD in  $x$   
BD in  $t$

$$\frac{u_i^{n+1} - u_i^n}{\Delta t} + u_i^n \frac{u_i^n - u_{i-1}^n}{\Delta x} = 0$$

$$u_i^{n+1} = u_i^n - u_i^n \frac{\Delta t}{\Delta x} (u_i^n - u_{i-1}^n)$$

I.I  $u=2 @ 0.5 \leq x \leq 1$

$u=1$  everywhere else

$u=1$  at  $0, 2$

Cold start

Second Order derivatives

use approximation of  $\frac{\partial^2 u}{\partial x^2}$   
at 2 locations

Eg central difference of

2nd order: Combin FD & BN  
for 1st derivative, Taylor

$$u_i^{n+1} = u_i^n + \Delta x \frac{\partial u}{\partial x}|_i + \frac{\Delta x^2}{2} \frac{\partial^2 u}{\partial x^2}|_i + \dots$$

$$u_{i-1}^n = u_i^n - \Delta x \frac{\partial u}{\partial x}|_i + \frac{\Delta x^2}{2} \frac{\partial^2 u}{\partial x^2}|_i + \dots$$

Add

Isolate second deriv

$$\frac{\partial^2 u}{\partial x^2}|_i = \frac{u_{i+1}^n - 2u_i^n + u_{i-1}^n}{\Delta x^2} - \dots$$

### 3 - 1D Diffusion (Heat equation)

$$\frac{\partial u}{\partial t} = V \frac{\partial^2 u}{\partial x^2}, \text{ solution becomes } v \text{ constant}$$

typically  $u = e^{i(kx - \omega t)}$ ,  $iw = \sqrt{k^2}$

$$\Rightarrow u = U e^{i k x - \frac{1}{2} k^2 t} + \text{exponential damping}$$

Discretisation, physics of diffusion  
in isotropic the FD method is

approximate is (1)

$$\begin{cases} D \rightarrow t \\ D \rightarrow x \end{cases}$$

$$\frac{u_i^{n+1} - u_i^n}{\Delta t} = \frac{\sqrt{D} (u_{i+1}^n - 2u_i^n + u_{i-1}^n)}{\Delta x^2}$$

$$u_i^{n+1} = u_i^n + \sqrt{\frac{\Delta t}{D}} (u_{i+1}^n - 2u_i^n + u_{i-1}^n)$$

Same IC, BC as prev

$$u(x) \text{ if } 0.5 \leq x \leq 1$$

elsewhere

+ Burger's equation

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = \sqrt{\frac{\partial^2 u}{\partial x^2}}$$

$$\frac{u_i^{n+1} - u_i^n}{\Delta t} + u_i^n \frac{u_i^n - u_{i-1}^n}{\Delta x} = \sqrt{\frac{u_{i+1}^n + 2u_i^n - u_{i-1}^n}{\Delta x^2}}$$

$$u_i^{n+1} = u_i^n - u_i^n \frac{\Delta t}{\Delta x} (u_i^n - u_{i-1}^n) + \sqrt{\frac{\Delta t}{\Delta x^2}}$$

$$(u_{i+1}^n - 2u_i^n + u_{i-1}^n)$$

IC

$$u = -2v \frac{\partial \phi}{\partial x} + 4$$

$$\boxed{t=0}$$

$$\phi = \exp\left(\frac{-x^2}{4v}\right) + \exp\left(\frac{-(x-2\pi)^2}{4v}\right)$$

$$\text{BC}, \quad u(0,t) = u(2\pi,t)$$

Analytical solution

$$u = -2v \frac{\partial \phi}{\partial x} + 4$$

$$\phi = \exp\left(\frac{-(x-4t)^2}{4v(t+1)}\right) + \exp\left(\frac{-(x-4t-2\pi)^2}{4v(t+1)}\right)$$

Big pseudo-code available in video

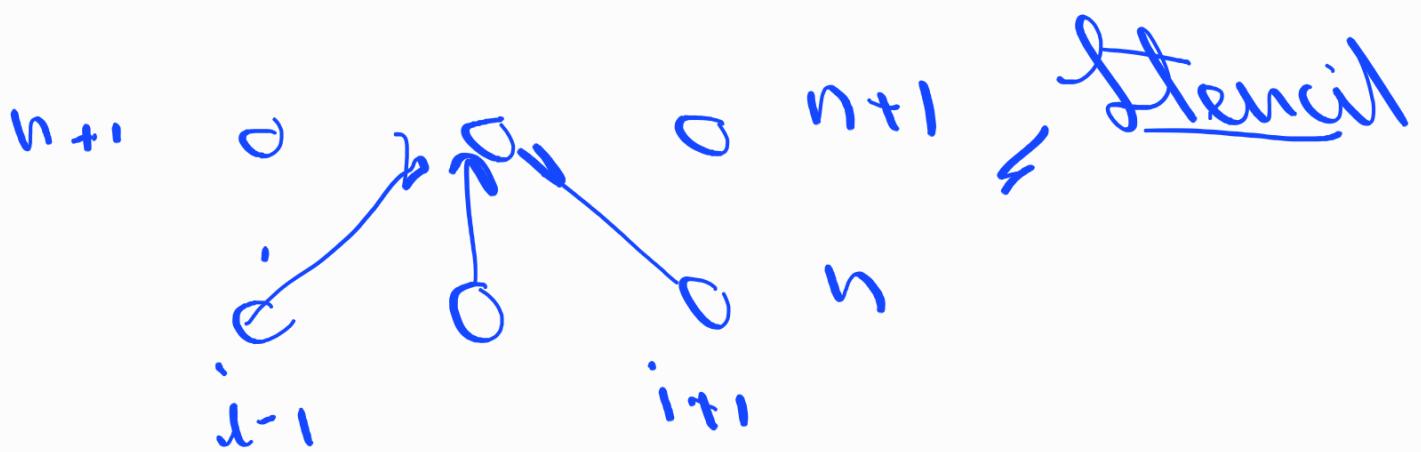
Lecture 5

Moving to 2D

Recalling 1D diffusion, FD in time  
and col in space, which  
gives only one unknown  
so computed values depend only  
on the past history

Start a solution, IC and 2 BC

A formulation of a continuous  
equation into a FD eqn. that  
expresses an unknown is called  
an explicit method



Suppose  $t = n+4$ . The unknown

At the boundaries do not  
get into the unknown  
ever, contrary to the  
physics.

In an explicit formula the  
BCs being defined the  
computations at one step.

How can we have a  
solver that involves  
the BCs at every time  
step?

→ BD approximation for  
the derivative i.e

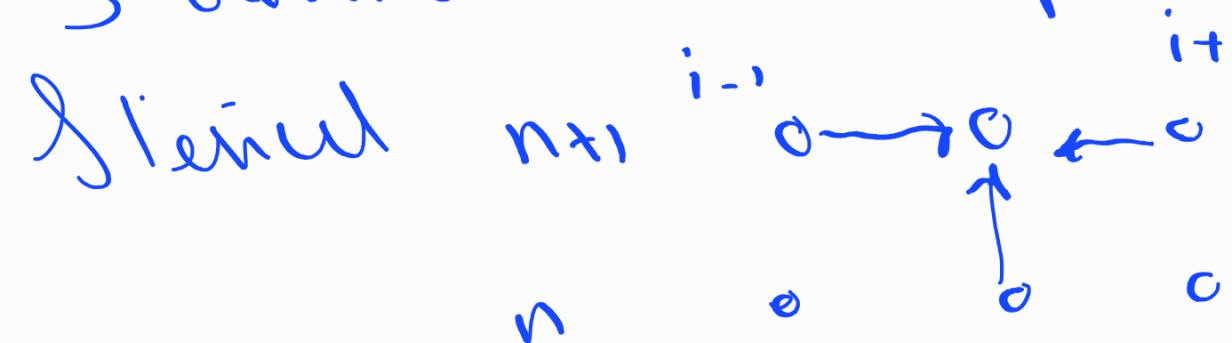
$$\frac{e_i^{n+1} - e_i^n}{\Delta t}$$

$$= e_i^{n+1} - e_i^{n+1} = e_i^{n+1} - e_i^{n-1}$$

$\sqrt{Dx^2 + 2Dt}$

$Dx$

3 unknowns in implicit shear



Need a set of coupled FD equations formed by writing of formulas for all points. Three per unknown at left.

$$\frac{\sqrt{Dt}}{Dx^2} u_{i+1}^{n+1} - \left(1 + \frac{2\sqrt{Dt}}{Dx^2}\right) u_i^n + \frac{\sqrt{Dt}}{Dx^2} u_{i-1}^{n+1} \quad * \text{Key}$$

$$- \frac{\sqrt{Dt}}{Dx^2} u_{i+1}^{n+1} = - u_i^n$$

↳ linear system of equations  
in tridiagonal matrix

Implicit, formulates which  
variables more than one  
unknown as an implicit  
method, lends up tridiagonal

### Crank - Nicolson method

→ Average of explicit and  
implicit scheme, for 1D diffus

$$M_i^{n+1} = M_i^n + \frac{1}{2} \frac{\nu \Delta t}{\Delta x^2} (M_{i+1}^{n+1} - 2u_i^{n+1} + M_{i-1}^{n+1}) \\ + \frac{1}{2} \frac{\nu \Delta t}{\Delta x^2} (M_{i+1}^n - 2u_i^n + M_{i-1}^n)$$

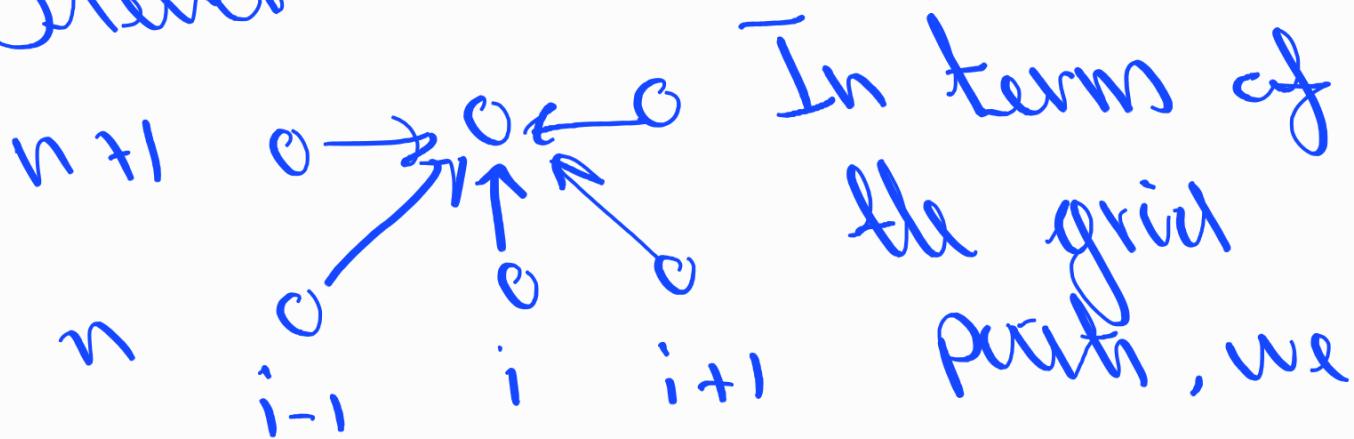
2nd order in time and space.  
Implicit → tridiagonal system  
to solve

We noted before that

$\frac{u_i^{n+1} - u_i^n}{\Delta t}$  will be an apprx  
for a midpoint.  
 $u_{i+\frac{1}{2}}^n$

Mixed

In terms of  
the grid  
path, we



have a central difference  
representation of  $\frac{\partial u}{\partial t}$  at A  
and the average diffn at  
the side point A.

Lesson 6

To extend 1D to 2D

JYH CP373 Assignment  
Partial difference.

G Building a 2D grid  
defining by the path

$$x_i = x_0 + i\Delta x, \quad y = y_0 + \Delta y \cdot j$$

$$M_{ij} = M(x_i, y_j)$$

Point  $(i+1, j+1)$ , TS in 2D

$$\begin{aligned} M_{i+1, j+1} &= M_{ij} + \left( \Delta x \frac{\partial}{\partial x} + \Delta y \frac{\partial}{\partial y} \right) u_{ij} \\ &\quad + \frac{1}{2} \left( \Delta x \frac{\partial^2}{\partial x^2} + \Delta y \frac{\partial^2}{\partial y^2} \right) u_{ij}^2 \\ &\quad + \dots \end{aligned}$$

Weder

FD at x

$$\left| \frac{\partial u}{\partial x} \right|_{ij} = \frac{M_{i+1,j} - M_{i,j}}{\Delta x} + O(\Delta x)$$

$$\left| \frac{\partial u}{\partial y} \right|_{ij} = \frac{M_{i,j+1} - M_{i,j}}{\Delta y} + O(\Delta x)$$

$u_{ij}$   $u_{ij}$

CH

$$\frac{\partial u}{\partial x}_{ij} = \frac{u_{i+1,j} - u_{i-1,j}}{2\Delta x} + c(\Delta x^2)$$

2nd order  
(D)

$$\frac{u_{i+1,j} - 2u_{ij} + u_{i-1,j}}{\Delta x^2}$$

2D form unverallg.

$$\frac{\partial u}{\partial t} + (\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y}) = 0$$

$$\frac{u_{ij}^{n+1} - u_{ij}^n}{\Delta t} + c \frac{u_{ij}^n - u_{i-1,j}^n}{\Delta x} + c \frac{u_{ij}^n - u_{ij-1}^n}{\Delta y}$$

$$\Rightarrow u_{ij}^{n+1} = u_{ij}^n - \frac{c\Delta t}{\Delta x} (u_{ij}^n - u_{i-1,j}^n) - \frac{c\Delta t}{\Delta y} (u_{ij}^n - u_{ij-1}^n)$$

$$1. \quad M=2 \quad 0.5 \leq x \leq 1, \quad 0.5 \leq y \leq 1$$

$M=1$   $\rho$  permanenter Wert

$u=1$

## 2D convection

$$u_x + u u_x + v u_y = 0$$

$$v_x + u v_x + v v_y = 0$$

$$\begin{cases} \#1 \\ \frac{u_{ij}^{n+1} - u_{ij}^n}{\Delta t} + u_{ij} \frac{u_{ij}^n - u_{i+1,j}}{\Delta x} + v_{ij} \frac{u_{ij}^n - u_{ij-1}}{\Delta y} = 0 \\ \#2 \\ \frac{v_{ij}^{n+1} - v_{ij}^n}{\Delta t} + v_{ij} \frac{v_{ij}^n - v_{i-1,j}}{\Delta x} + v_{ij} \frac{v_{ij}^n - v_{ij-1}}{\Delta y} = 0 \end{cases}$$

#1

$$u_{ij}^{n+1} = u_{ij}^n - \Delta t \left( u_{ij} \frac{u_{ij}^n - u_{i-1,j}}{\Delta x} + v_{ij} \frac{u_{ij}^n - u_{ij-1}}{\Delta y} \right)$$

$$v_{ij}^{n+1} = v_{ij}^n - \Delta t \left( u_{ij} \frac{v_{ij}^n - v_{i-1,j}}{\Delta x} + v_{ij} \frac{v_{ij}^n - v_{ij-1}}{\Delta y} \right)$$

Solve IC and boundary conditions.

## 2D Diffusion

$$M_t = V(u_{xx} + u_{yy})$$

$$\frac{u_{ij}^{n+1} - u_{ij}^n}{\Delta t} = V \left( \frac{u_{i+1,j}^n - 2u_{ij}^n + u_{i-1,j}^n}{\Delta x^2} \right)$$

$$+ V \left( \frac{v_{i+1,j}^n - 2v_{ij}^n + v_{i-1,j}^n}{\Delta y^2} \right)$$

$$= 1$$

$$u_{ij}^{n+1} = u_{ij}^n + \Delta t \left( V \left( \frac{u_{i+1,j}^n - 2u_{ij}^n + u_{i-1,j}^n}{\Delta x^2} \right) \right)$$

$$+ V \left( \frac{v_{i+1,j}^n - 2v_{ij}^n + v_{i-1,j}^n}{\Delta y^2} \right)$$

## ① 2D Burgers

$$1 - u_t + uu_x + vu_y = V(u_{xx} + u_{yy})$$

$$2 - v_t + uv_x + vv_y = V(v_{xx} + v_{yy})$$

Dissipative

$$1. \frac{\underline{u}_{ij}^{n+1} - \underline{u}_{ij}^n}{\Delta t} + u_{ij} \frac{\underline{u}_{ij}^n - \underline{u}_{i-1,j}^n}{\Delta x} + v_{ij} \frac{\underline{u}_{ij}^n - \underline{u}_{ij-1}^n}{\Delta y}$$

$$= \underline{v} \left( \frac{\underline{u}_{i+1,j}^n - 2\underline{u}_{ij}^n - \underline{u}_{i-1,j}^n}{\Delta x^2} + \frac{\underline{u}_{ij+1}^n - 2\underline{u}_{ij}^n + \underline{u}_{ij-1}^n}{\Delta y^2} \right)$$

$$2. \frac{\underline{v}_{ij}^{n+1} - \underline{v}_{ij}^n}{\Delta t} + u_{ij} \frac{\underline{v}_{ij}^n - \underline{v}_{i-1,j}^n}{\Delta x} + v_{ij} \frac{\underline{v}_{ij}^n - \underline{v}_{ij-1}^n}{\Delta y}$$

$$= \underline{v} \left( \frac{\underline{v}_{i+1,j}^n - 2\underline{v}_{ij}^n - \underline{v}_{i-1,j}^n}{\Delta x^2} + \frac{\underline{v}_{ij+1}^n - 2\underline{v}_{ij}^n + \underline{v}_{ij-1}^n}{\Delta y^2} \right)$$

## Lecture 11

$$\text{NS: } \nabla \cdot \vec{u} = 0, \quad \frac{d\vec{u}}{dt} + (\vec{u} \cdot \nabla) \vec{u} = -\frac{1}{\rho} \nabla p + \vec{w} \vec{u}$$

① Mass conservation for  $\vec{u}$ ,  
 but there is no obvious  
 way to compute velocity  
 and pressure. When compressible  
 we have this.

In 2D

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + V \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} = -\frac{1}{\rho} \frac{\partial p}{\partial y} + V \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right)$$

Multiply both equations by  $\frac{\partial}{\partial x}$ , then  
by  $\frac{\partial}{\partial y}$  and add

$$\begin{aligned} & \frac{\partial}{\partial t} \left( \frac{\partial u}{\partial x} \right) + \frac{\partial u}{\partial x} \frac{\partial^2 u}{\partial x^2} + u \frac{\partial^2 u}{\partial x^2} + \frac{\partial v}{\partial x} \frac{\partial u}{\partial y} + v \frac{\partial^2 u}{\partial x \partial y} \\ &= -\frac{1}{\rho} \frac{\partial^2 p}{\partial x^2} + V \frac{\partial}{\partial x} (\nabla^2 u) \end{aligned}$$

$$\begin{aligned} & \frac{\partial}{\partial t} \left( \frac{\partial v}{\partial y} \right) + \frac{\partial u}{\partial y} \frac{\partial^2 v}{\partial y^2} + u \frac{\partial^2 v}{\partial y^2} + \frac{\partial v}{\partial y} \frac{\partial v}{\partial x} + v \frac{\partial^2 v}{\partial y^2} \\ &= -\frac{1}{\rho} \frac{\partial^2 p}{\partial y^2} + V \frac{\partial}{\partial y} (\nabla^2 v) \end{aligned}$$

Add them element wise, so the final terms

$$\frac{\partial}{\partial t} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \left( \frac{\partial u}{\partial x} \right)^2 + \frac{\partial u}{\partial y} \frac{\partial v}{\partial x} + u \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial x \partial y} \right)$$

$$+ \frac{\partial v}{\partial x} \frac{\partial u}{\partial y} + \left( \frac{\partial v}{\partial y} \right) \rightarrow v \frac{\partial u}{\partial xy} + v \frac{\partial u}{\partial y^2}$$

$$= \frac{\partial}{\partial t} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \left( \frac{\partial u}{\partial x} \right)^2 + \frac{\partial u}{\partial y} \frac{\partial v}{\partial x} + u \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \\ + \left( \frac{\partial v}{\partial y} \right)^2 + v \frac{\partial}{\partial y} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right), \text{ bnd } \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$\Rightarrow \boxed{\left( \frac{\partial u}{\partial x} \right)^2 + 2 \frac{\partial u}{\partial y} \frac{\partial v}{\partial x} + \left( \frac{\partial v}{\partial y} \right)^2}$$

RHS

$$-\frac{1}{\rho} \left( \frac{\partial^2 p}{\partial x^2} + \frac{\partial^2 p}{\partial y^2} \right) + v \left[ \frac{\partial}{\partial x} \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) \right. \\ \left. + \frac{\partial}{\partial y} \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) \right]$$

$$\frac{\partial^3 u}{\partial x^3} + \frac{\partial^3 u}{\partial x \partial y^2} + \frac{\partial^3 v}{\partial x^2 \partial y} + \frac{\partial^3 v}{\partial y^3}$$

$$\Rightarrow \frac{\partial^2}{\partial x^2} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \frac{\partial^2}{\partial y^2} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)$$

With symmetry

Stokes equations

$$-\frac{1}{\rho} \left( \frac{\partial^2 p}{\partial x^2} + \frac{\partial^2 p}{\partial y^2} \right) = \left( \frac{\partial u}{\partial x} \right)^2 + 2 \frac{\partial u}{\partial y} \frac{\partial v}{\partial x} + \left( \frac{\partial v}{\partial y} \right)^2$$

Roughly equation of following type

$$\nabla^2 p = f \Rightarrow \text{Poisson equation for}$$

pressure, mass still constant,  
is satisfied. Discretization

Second order central stiff

$$\frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \nabla \vec{u} = -\frac{1}{\rho} \nabla p + \nu \nabla^2 \vec{u}$$

discretize in time: forward euler in  
time, explicit.

$$\vec{u}^{n+1} = \vec{u}^n + \Delta t \left\{ -\vec{u}^n \cdot \nabla \vec{u}^n - \frac{1}{\rho} \nabla p^n + \nu \nabla^2 \vec{u}^n \right\}$$

$$\nabla \cdot \vec{u}^{n+1} = \nabla \cdot \vec{u}^n + \Delta t \left\{ -D(\vec{u}^n \cdot \nabla \vec{u}^n) \right\}$$

$$-\frac{1}{\rho} \nabla^2 p^{n+1} + \nu \nabla^2 (\nabla \cdot \vec{u}^n)$$

In the numerical scheme  
 we want  $\nabla \cdot \vec{u}^{n+1} = 0$ . But  
 we may have  $\nabla \cdot \vec{u}^n \neq 0$ .  
 (fracture step?)

Form equations for  $p$  at time  $n+1$

$$\nabla^2 p^{n+1} = \rho \frac{\nabla \cdot \vec{u}^n}{\Delta t} + \left\{ -\rho \nabla \cdot (\vec{u}^n \cdot \nabla \vec{u}^n) + \mu \nabla^2 (\nabla \cdot \vec{u}^n) \right\}$$

Third of velocity obtained from  
 Navier - Stokes on an intermediate  
 step in  $u^{n+0.5}$  and  $\nabla \cdot \vec{u}^{n+\frac{1}{2}} \neq 0$   
 (Need to calculate a pressure  
 $p^{n+1}$  such that continuity holds)

## Lecture 12

④ Laplace equation  $\frac{\partial^2 p}{\partial x^2} + \frac{\partial^2 p}{\partial y^2} = 0$

Divergence second order finite difference

$$\frac{P_{i+1,j}^n + 2P_{i,j}^n + P_{i-1,j}^n}{\Delta x^2} + \frac{P_{i,j+1}^n - 2P_{i,j}^n + P_{i,j-1}^n}{\Delta y^2} = 0$$

Transpose  $P_{ij}^n$

$$P_{ij} = \frac{\Delta y^2 (P_{i+1,j}^n + P_{i-1,j}^n) + \Delta x^2 (P_{i,j+1}^n + P_{i,j-1}^n)}{2(\Delta x^2 + \Delta y^2)}$$

IC  $\Rightarrow p=0$  everywhere in  $(0,2) \times (0,1)$

BC  $\Rightarrow p=0$  at  $x=0$

$p=y$  at  $x=2$

$\frac{\partial p}{\partial y}=0$  at  $y=0, 1$

Analytical solution

$$p(x,y) = \frac{x}{4} - 4 \sum_{n=1}^{\infty} \frac{\sinh(n\pi x) \cosh(n\pi y)}{(n\pi)^2 \sinh(2\pi n)}$$

- ① 5 point stencil, typical for  
Differences, differs in notation  
⇒ has to be what different  
to match physics
- ② And also can easily used when  
for Laplace operator.
- ③ Needs setting for steady state,  
to we used tri-diagonal -  
(pencil Jacobi method).

④ Poins equidistant  $\frac{\partial^2 p}{\partial x^2} + \frac{\partial^2 p}{\partial y^2} = b$

$$\frac{P_{i+1,j} - 2P_{ij} + P_{i-1,j}}{\Delta x^2} + \frac{P_{i,j+1} - 2P_{ij} + P_{i,j-1}}{\Delta y^2} = b_{ij}$$

$$= b_{ij}$$

$$\Rightarrow P_{ij}^n = (P_{i+1,j}^n + P_{i-1,j}^n) \Delta y^2 + (P_{i,j+1}^n + P_{i,j-1}^n) \Delta x^2$$

$$-b_{ij} \Delta x^2 \Delta y^2$$

$$2(\Delta x^2 + \Delta y^2)$$

Lc  $\rho=0 \quad \forall x, y \in (0,2) \times (0,1)$

BC  $\rho=0 @ x=0, z \text{ and } y=0, 1$

$b_{ij} = 100 @ i = \frac{n_x}{4}, j = \frac{ny}{4}$

$b_{ij} = -100 @ i = \frac{3}{4}n_x, j = \frac{3}{4}ny$

$b_{ij} = 0 \text{ else.}$

ii. Navier-Stokes (cavity, (Basilijff),  
Burgers)

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + V \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$
$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} = -\frac{1}{\rho} \frac{\partial p}{\partial y} + V \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right)$$

$$\frac{\partial^2 p}{\partial x^2} + \frac{\partial^2 p}{\partial y^2} = -P \left( \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} \frac{\partial v}{\partial x} + \frac{\partial v}{\partial x} \frac{\partial v}{\partial y} \right)$$

$$+ \rho \frac{\partial}{\partial t} \left( \frac{u^n}{\partial x} + \frac{v^n}{\partial y} \right)$$

Drei Gleichungen

$$\begin{aligned} & \frac{u_{i,j}^{n+1} - u_{i,j}^n}{\Delta t} + u_{i,j}^n \frac{u_{i,j}^n - u_{i,j-1}^n}{\Delta x} + v_{i,j}^n \frac{u_{i,j}^n - u_{i,j+1}^n}{\Delta y} \\ &= -\frac{1}{\rho} \frac{p_{i+1,j}^n - p_{i-1,j}^n}{2\Delta x} + V \left( \frac{u_{i,j+1}^n - 2u_{i,j}^n + u_{i,j-1}^n}{\Delta x^2} \right. \\ & \quad \left. + \frac{u_{i,j+1}^n - 2u_{i,j}^n + u_{i,j-1}^n}{\Delta y^2} \right) \end{aligned}$$

$$\begin{aligned} & \frac{p_{i+1,j}^n - 2p_{i,j}^n + p_{i-1,j}^n}{\Delta x^2} + \frac{p_{i,j+1}^n - 2p_{i,j}^n + 2p_{i,j-1}^n}{\Delta y^2} \\ &= -\rho \left[ \left( \frac{u_{i,j+1}^n - u_{i,j-1}^n}{2\Delta x} \right)^2 + \left( \frac{u_{i,j+1}^n - u_{i,j-1}^n}{\Delta y} \right) \left( \frac{v_{i,j+1}^n - v_{i,j-1}^n}{2\Delta x} \right) \right. \\ & \quad \left. + \left( \frac{v_{i,j+1}^n - v_{i,j-1}^n}{2\Delta y} \right)^2 \right] + \end{aligned}$$

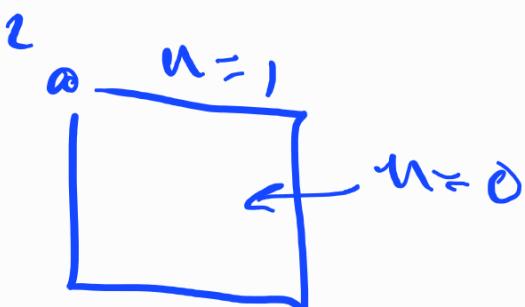
$$P = \frac{1}{\rho} (u_{i,j+1}^n - u_{i,j-1}^n) \cdot (v_{i,j+1}^n - v_{i,j-1}^n)$$

$$\frac{1}{\Delta t} \left( \frac{v_{ij} - v_{ij-1}}{2\Delta x} + \frac{v_{ij+1} - v_{ij-1}}{2\Delta y} \right)$$

Transpos  $u_i^{n+1}, v_i^{n+1}$ ,  $p_i^n$

IC  $u, v, p = 0$

BC  $u=1$  at  $y=2$ ,  $u, v=0$   $x=0, 2$   
 $y=0$



$p \approx 0$  at  $y=2$

$\frac{dp}{dy} = 0$  at  $y=0$

$\frac{\partial p}{\partial x} = 0$  at  $x=0, 2$ ,

(Basically Penjain and 2n)  
 Burger's.

⑩ same as 11 but F is in  
 algorithm for u  
 IC  $u, v, p = 0$  everywhere

TSC er, v, p percentile ab 0,2

$U, V = 0$  @  $y = 0, 2$

$\frac{dP}{dy} = 0$  @  $y = 0, 2$

