```
function [error] = Calibration
simuParam = [92.1597 84.4488 0 305.4001 111.1565 0 604.8652;
             27.055 122.037 0 -56.4357 320.0625 0 604.8652;
             -119.2146 37.5882 0 -248.9644 208.9060 0 604.8652;
             -119.2146 -37.5882 0 -248.9644 -208.9060 0 604.8652;
             27.055 -122.037 0 -56.4357 -320.0625 0 604.8652;
             92.1597 -84.4488 0 305.4001 -111.1565 0 604.8652];
realParam = [96.6610, 81.7602, 1.0684, 305.2599, 115.0695, 2.6210,
 604.4299;
        22.2476, 125.2511, 0.5530, 55.2814, 322.9819, 4.2181,
 607.2473;
        -122.4519, 36.6453, 4.3547, -244.7954, 208.0087, 3.9365,
 600.4441;
        -120.6859, -34.4565, -4.9014, -252.5755, -211.8783, -3.0128,
 605.9031;
        24.7769, -125.0489, -4.8473, -53.9678, -320.6115, 4.3181,
 604.5251;
        91.3462 -80.9866 0.2515 302.4266 -109.4351 3.3812 600.0616];
IdentifiedValues=lsqnonlin(@costFunction,simuParam);
error = IdentifiedValues - realParam;
end
Local minimum possible.
```

lsqnonlin stopped because the size of the current step is less than the default value of the step size tolerance.

```
ans =
```

```
0.0003
        0.0000
                 -0.0005
                          0.0011
                                   0.0005
                                           -0.0018
                                                     0.0014
                -0.0000
                        -0.0002
-0.0001
        -0.0001
                                  0.0001
                                           -0.0005
                                                     0.0004
0.0007
        -0.0002
                -0.0023
                        0.0024
                                  0.0007 -0.0024
                                                     0.0002
0.0001
        -0.0004
                 -0.0005
                        0.0004 -0.0001
                                           0.0006
                                                   -0.0010
-0.0002
        -0.0002
                 -0.0001
                          -0.0000
                                  -0.0001
                                            0.0001
                                                   -0.0003
0.0003
        0.0001 -0.0004
                        0.0011
                                  0.0003
                                           -0.0018
                                                    0.0014
```

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