



Michael Deistler

Curriculum Vitae

Education

- since 2017 **Elite Master of Science in Neuroengineering**, *Technical University of Munich*, Munich.
Specialized in Computational Neuroscience
- 2017 **Semester abroad**, *KTH Royal Institute of Technology*, Stockholm, *German Grade – 1.3, American GPA – 3.7.*
- 2013–2017 **Bachelor of Science in Electrical and Information Engineering**, *Technical University of Munich*, Munich, *German Grade – 1.2, American GPA – 3.8.*
Degree with Honours
- 2013 **Abitur / Highschool Degree**, *Gymnasium Landau a. d. Isar*, *German Grade – 1.1, American GPA – 3.9.*

Bachelor Thesis

- Title *Temporal Interpolation of Grayscale Frames using Event Data from the DAVIS240*
- Supervisors Professor Eckehard Steinbach & PhD Christoph Bachhuber
- Description Dynamic Vision Sensors are a neuromorphic camera technology recording event data on an almost continuous time-scale. Additional to this data, the DAVIS240 also records traditional frame-based videos. This thesis explored the fusion of this data in order to create super slow-motion videos.

Experience

- 2018 **Six Week Research Project**, UNIVERSITY OF EDINBURGH, CHAIR FOR COMPUTATIONAL NEUROSCIENCE, Edinburgh, Supervisors: PhD. Matthias H. Hennig, Martino Sorbaro.
- Worked with biologically plausible Neural Network architectures
 - No further information due to upcoming publication possible
- 2017–2018 **Working Student**, BRAINLAB AG, Munich, Platforms Department.
- Implementation of a Script for automatic Bootcycle Tests
 - Electrical Circuit Design

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Date of Birth: 11. August 1995

- 2014-2018 **Research Assistant**, CHAIRS OF 'HUMAN-MACHINE-COMMUNICATION', 'SIGNAL PROCESSING METHODS' AND 'INTEGRATED SYSTEMS', Munich.
Teaching of classes to undergraduates throughout several semesters. The courses were:
- Digital Circuits
 - Stochastic Signals
 - Signal Representation
- 2016 **Six Month Internship**, BMW, CENTER FOR AUTONOMOUS DRIVING, Munich.
- Development of an Algorithm for movement compensation
 - OpenCL Parallelization of a Particle Filter for environment capturing
 - Integration of the software components in ROS
- 2015 **Eleven Week Internship**, GERMAN AEROSPACE CENTER, CENTER FOR COMMUNICATION AND NAVIGATION, Munich.
- Measure Propagation Conditions of Radio Signals
 - Create a GUI for data Visualization of an IMU (Inertial Measurement Unit)
- 2013-2014 **Participation in the AdvElsor Program**, TECHNICAL UNIVERSITY OF MUNICH, Munich.
Soft-Skill program offered by the TU Munich. Additionally, gained hands-on experience by building a rotor display in a group of ten people.

Programming Languages

- PYTHON **Advanced**, *Course project in Deep Learning; Research Project in Edinburgh.*
- MATLAB **Advanced**, *Nine-week working experience at DLR; Bachelor Thesis.*
- C++ **Intermediate**, *Self studies; Five-month working experience at BMW.*
- C **Intermediate**, *University course.*
- JAVA **Basic**, *Two-year education in highschool.*

Languages

- German **Mother tongue**
- English **Very Good**
- French **Basic**
- Swedish **Basic**