

ECE 373 Assignment #3

Spring 2019

Part 1: Digging for Details

One of the tasks of a device driver developer is to gather information about the hardware to be controlled – e.g. what I/O ports are connected to which pins, how many microseconds it takes to reset the chip, or what bit pattern is needed to enable a temperature sensor. In the past, we had to dig around in dark shelves for thick paperback device handbooks – you can probably still find some of these around the Engineering labs and offices. Nowadays, though, the internet is often a great resource for much of this information. These questions will require you to do some searching online for useful device information.

1. Atomic Motherboards (go boom)

The computer box we're using in the lab is an AIMB-212 from Advantech. Since the box is locked down, you can't look at the insides to see what it has, so you need some product information. Use the internet to find a datasheet, a User Manual, or some other documentation for this little computer. Download it for your reference, and review it.

- a) what is the audio device?
- b) what device is the GPIO connected to?
- c) how many network (LAN) devices are on the motherboard and what are they?
- d) how many total serial ports does the box support, inside and out?

2. Network Noodling

Since the experimental boxes are not connected to the university network, the network devices are going unused (one port is plugged into the CAT network, but that's only for us to rebuild the boxes if Atomic lives up to its name – it can be disconnected). Later in this assignment we will explore how to play with them, but first we need some information about how they work. Find the datasheet for the LAN device connected through PCIe (**not through the integrated chip's LCI**), and download it for your reference. The Pin Interface chapter tells how to physically connect to the chip. The Driver Programming Interface chapter tells about the memory-mapped registers – what are their addresses and what bit patterns are used to do things. From the datasheet:

- a) What pins control the LEDs?
- b) What address offset is the Device Control Register?
- c) What bit in the Device Control Register will force a reset of the network chip?

3. Winken, Blinken, and Nod

Without any other wires or connectors needed, we can use the LEDs on the network devices as our little toys. There are many ways to set up the LEDs for blinking and for indicating various states in the chip, so the description is spread across several pages.

- a) What register (name and address) controls the LEDs?
- b) What bit pattern should you use to turn off LED1?
- c) What bit pattern should you use to make LED2 blink?

4. EIEIO

The Super I/O chip is designed to be responsible for handling many different duties in a standard PC computer. It is a pretty standard design, but a data sheet is still needed, especially if you want to know how to control the GPIO pins.

- a) what company makes the Super I/O chip in this box?
- b) can you find the datasheet on the web?
- c) where/how can you find this chip's datasheet if you aren't able to find it with a standard web search?

Part 2: Make it Blink

It's time to start driving hardware. Here we put together what you've just found with your code from Homework Assignment #2 and information from the PCI lecture. Roll all that together and we can start blinking LED's on our Atomic boxes in the lab, or in your own VM's.

Note: This part of the assignment can be done on the Atom lab machines to use their real hardware, or in your own laptop/VM, as long as you have an e1000/e1000e type virtual network device. If you are using a VM that doesn't have actual LEDs to watch, you can try using the ledmon user program that tries to watch the virtual LEDs for you: <http://web.cecs.pdx.edu/~sln/ece373/ledmon>

5. Confirmation the char device works:

The first part of this assignment deals with getting the character device framework running. Use your kernel code and userspace program from Homework #2. Make sure you can open the character device, read from it, and write to it. At this point, it should still read from and write to the syscall_var integer.

6. Register a PCI driver:

The next piece is to register the PCI device. You'll need to look at `lspci` to find the device ID for the device in question (hint: **`lspci -n`** is more helpful for this...).

Attach the device by implementing the `.probe()` function callback for PCI devices. Make sure to map the BAR for register access, and store the physical address of the BAR for use later.

It's highly recommended to refer to code we looked at in class to figure out what to do here...and there isn't much needed to be done (double hint: the `e1000e` driver isn't a bad place to peek). Don't forget to properly clean up the device with a `.remove()` routine.

You'll also need to figure out which header file to include. It's a good idea to look at the header where the various `pci_request_*` calls are defined, using that helpful web tool we keep referring to.

Finally, hook up the PCI driver into your `init_module()` routine, and subsequent unregister in your `exit_module()`. What happens in `dmesg` when you load your driver? **NOTE: Make sure to unbind `e1000e` before doing this! Otherwise your driver will get loaded but not have any device to connect to because the `e1000e` driver has already claimed it. Refer to lecture notes on how to bind/unbind.**

7. Hook up file operations

Now you have a nice and shiny PCI driver that loads and does nothing. Let's do something with it:

Modify your `read()` implementation so it will read the LED register, using the register information you found above in problem 3. Return the value of the register to the supplied userspace buffer (remember `copy_to_user?`).

Modify your `write()` implementation so it will write the LED register with the value supplied in the `write()` system call. Make sure to at least verify the data is somewhat valid...(make sure it's a 32-bit number).

8. The Home stretch!

Now your device driver is hooked up and ready to accept inputs. First unbind the device from the `e1000e` driver. Modify your tiny C program in userspace that opens the character device you created (it's ok to hard-code your `/dev` file here), and have it read the current value of the LED register and display it. Then have your C program write a value to make LED0 turn on. After writing the value, read the value back out and display it. Sleep for 2 seconds, and write a value to disable the LED. Remove your driver, then bind the device back to `e1000e`.

You are done. Phew!

Make sure your module unloads successfully, and properly cleans up ALL resources you allocated in the driver (`chardev`, `dev_t`, `pci` resources, etc.).

What to turn in:

1. Answers to the questions in Part 1
2. All code/scripts you used in this assignment. This include source code to any kernel modules, userspace programs, makefiles, and any scripts that you used to automate any part of the build process.
3. A typescript of you binding and unbinding the e1000e driver, and your userspace program running through part 8 of this assignment.

Turn these materials in before or at the start of class on **Wednesday, 01-May-2019**.