# GENERATING MINIMAL MODELS FOR GEOMETRIC THEORIES

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## Abstract

This paper describes a method, referred to as the chase, for generating minimal models for a geometric theory. A minimal model for a theory is a model for which there exists a homomorphism to any other model that can satisfy the theory. These models are useful in solutions to problems in many practical applications, including firewall configuration examination and access control evaluation. Also described is a Haskell implementation of the chase and its development process and design decisions.

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# 1 Introduction

Introductory text...

#### 1.1 Goals

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#### 1.2 The Chase

Aliquam vulputate mi non metus lacinia rutrum. In hac habitasse platea dictumst. Quisque magna nisi, lacinia quis molestie in, varius eu diam. Nullam tristique porta ante, malesuada egestas purus viverra nec. Nulla vestibulum pretium massa id mattis. Donec ut velit urna. Suspendisse potenti. Vivamus vitae consectetur quam. Mauris non ante mauris. Nulla id lectus ut velit mollis convallis vel non leo. Integer ac pulvinar nisl. Maecenas posuere fringilla consectetur.

# 2 Technical Background

In this paper, possibly ambiguous or uncommon notation will be used and thusly must be clearly defined. Also, topics that are necessary prerequisites will be summarized.

#### 2.1 Models

A  $model \ \mathbb{M}$  is a construct that consists of:

- a set, referenced as |M|, called the *universe* or *domain* of M
- a set of pairings of a *predicate* and a non-negative integral arity
- for each predicate R with arity k, a relation  $R_k^{\mathbb{M}} \subseteq |\mathbb{M}|$

It is important to distinguish the predicate, which is just a symbol, from the relation that it refers to when paired with its arity. The relation itself is a set of tuples of elements from the universe.

## 2.2 First-order Logic

First-order logic, also called *predicate logic*, is a formal logic system that is an extension of propositional logic. For our purposes, this logic system will not contain any constant symbols or function symbols, which are commonly included in first-order and propositional logic.

A first-order logic formula is defined inductively by

- if R is a relation symbol of arity k and each of  $t_0, \ldots, t_{k-1}$  is a variable, then  $R[t_0, \ldots, t_{k-1}]$  is a formula, specifically an atomic formula
- $\bullet \ \top$  and  $\bot$  are formulæ
- if  $\alpha$  is a formula then  $(\neg \alpha)$  is a formula
- if  $\alpha$  and  $\beta$  are formulæ then  $(\alpha \wedge \beta)$  is a formula
- if  $\alpha$  and  $\beta$  are formulæ then  $(\alpha \vee \beta)$  is a formula
- if  $\alpha$  and  $\beta$  are formulæ then  $(\alpha \to \beta)$  is a formula

- if  $\alpha$  is a formula and x is a variable then  $(\forall x : \alpha)$  is a formula
- if  $\alpha$  is a formula and  $\vec{x}$  is a set of variables of size k then  $(\forall \vec{x} : \alpha)$  is  $(\forall x_0 \dots \forall x_{k-1} : \alpha)$
- if  $\alpha$  is a formula and x is a variable then  $(\exists x : \alpha)$  is a formula
- if  $\alpha$  is a formula and  $\vec{x}$  is a set of variables of size k then  $(\exists \vec{x} : \alpha)$  is  $(\exists x_0 \dots \exists x_{k-1} : \alpha)$

#### 2.3 Positive Existential Form

Formulas in *positive existential form* are constrained to using only conjunctions ( $\wedge$ ), disjunctions ( $\vee$ ), existential quantifications ( $\exists$ ), tautologies ( $\top$ ), contradictions ( $\bot$ ), and relations to construct logic expressions.

# 2.4 Geometric Logic

Geometric logic is first-order logic with constraints on the shape of the expression. Geometric logic formulæ are implicitly universally quantified first-order logic expressions of the form

$$A_0 \wedge \ldots \wedge A_n \to E_0 \vee \ldots \vee E_m$$

where  $A_0 
ldots A_n$  are atomics,  $E_0 
ldots E_m$  are first-order logic expressions of the form  $\exists_{x_0 
ldots x_k} A_0 \land \dots \land \exists_{x_0 
ldots x_p} A_y$ , and n, m, k, p, and y are integers greater than or equal to 0. A set of geometric logic formulæ is called a *geometric theory*.

explain why GL is useful to us

# 2.5 Variable Binding

The set of free variables in a formula is defined inductively as follows

- any variable occurance in an atomic formula is a free variable
- the free variables in  $\top$  and  $\bot$  are  $\emptyset$
- the free variables in  $\neg \alpha$  are the free variables in  $\alpha$
- the free variables in  $\alpha \wedge \beta$  are the union of the set of free variables in  $\alpha$  with the set of free variables in  $\beta$

- the free variables in  $\alpha \vee \beta$  are the union of the set of free variables in  $\alpha$  with the set of free variables in  $\beta$
- the free variables in  $\alpha \to \beta$  are the union of the set of free variables in  $\alpha$  with the set of free variables in  $\beta$
- the free variables in  $\forall x : \alpha$  are the free variables in  $\alpha$  that are not x
- the free variables in  $\exists x : \alpha$  are the free variables in  $\alpha$  that are not x

A *sentence* is a formula with an empty set of free variables.

#### 2.6 Environment

An environment for a model M is a function from a variable to an element in  $|\mathbb{M}|$ . The syntax  $l_{[v \mapsto v']}$  defines an environment l'(x) that returns v' when x = v and returns l(x) otherwise.

# 2.7 Satisfiability

A model M is said to satisfy a formula  $\sigma$  in an environment l when

- $\sigma$  is a relation symbol R and  $R[l(a_0), \ldots, l(a_n)] \in \mathbb{M}$  where a is a set of variables
- $\sigma$  is of the form  $\neg \alpha$  and  $\mathbb{M} \not\models_l \alpha$
- $\sigma$  is of the form  $\alpha \wedge \beta$  and both  $\mathbb{M} \models_l \alpha$  and  $\mathbb{M} \models_l \beta$
- $\sigma$  is of the form  $\alpha \vee \beta$  and either  $\mathbb{M} \models_l \alpha$  or  $\mathbb{M} \models_l \beta$
- $\sigma$  is of the form  $\alpha \to \beta$  and either  $\mathbb{M} \not\models_l \alpha$  or  $\mathbb{M} \models_l \beta$
- $\sigma$  is of the form  $\forall x : \alpha$  and for every  $x' \in |\mathbb{M}|$ ,  $\mathbb{M} \models_{l[x \mapsto x']} \alpha$
- $\sigma$  is of the form  $\exists x : \alpha$  and for at least one  $x' \in |\mathbb{M}|$ ,  $\mathbb{M} \models_{l[x \mapsto x']} \alpha$

This is denoted as  $\mathbb{M} \models_l \sigma$  and read " $\sigma$  is true in  $\mathbb{M}$ ". The notation  $\mathbb{M} \models \sigma$  (no environment specification) means that either, under any environment l,  $\mathbb{M} \models_l \sigma$ .

A model M satisfies a set of formulæ  $\Sigma$  if for every  $\sigma$  such that  $\sigma \in \Sigma$ ,  $\mathbb{M} \models \sigma$ . This is denoted as  $\mathbb{M} \models \Sigma$  and read "M is a model of  $\Sigma$ ".

#### 2.8 Entailment

A set of formula  $\Sigma$  is said to *entail* a formula  $\sigma$  ( $\Sigma \models \sigma$ ) if the set of all models satisfied by  $\Sigma$  is a subset of the set of all models satisfied by  $\sigma$ .

The notation used for satisfiability and entailment is very similar, in that the operator used ( $\models$ ) is the same, but they can be distinguished by the type of left operand.

# 2.9 Homomorphisms

A homomorphism from  $\mathbb{A}$  to  $\mathbb{B}$  is a function  $h: |\mathbb{A}| \to |\mathbb{B}|$  such that, for each relation symbol R and tuple  $\langle a_0, \ldots, a_n \rangle$  where  $a \subseteq |\mathbb{A}|, \langle a_0, \ldots, a_n \rangle \in R^{\mathbb{A}}$  implies  $\langle h(a_0), \ldots, h(a_n) \rangle \in R^{\mathbb{B}}$ .

A homomorphism h is also a strong homomorphism if, for each relation symbol R and tuple  $\langle a_0, \ldots, a_n \rangle$  where  $a \subseteq |\mathbb{A}|, \langle a_0, \ldots, a_n \rangle \in R^{\mathbb{A}}$  if and only if  $\langle h(a_0), \ldots, h(a_n) \rangle \in R^{\mathbb{B}}$ .

The notation  $\mathbb{M} \leq \mathbb{N}$  means that there exists a homomorphism  $h : \mathbb{M} \to \mathbb{N}$ . The identity function is a homomorphism from any model  $\mathbb{M}$  to itself. Homomorphisms are transitive, so  $\mathbb{A} \leq \mathbb{B} \wedge \mathbb{B} \leq \mathbb{C}$  implies  $\mathbb{A} \leq \mathbb{C}$ . However,  $\mathbb{M} \leq \mathbb{N} \wedge \mathbb{N} \leq \mathbb{M}$  does not imply that  $\mathbb{M} = \mathbb{N}$ .

Given models  $\mathbb{M}$  and  $\mathbb{N}$  where  $\mathbb{M} \leq \mathbb{N}$  and a formula in positive-existential form  $\sigma$ , if  $\mathbb{M} \models \sigma$  then  $\mathbb{N} \models \sigma$ .

An *isomorphism* is a homomorphism  $h : \mathbb{A} \to \mathbb{B}$  where h is 1:1 and onto and the inverse function  $h^{-1} : \mathbb{B} \to \mathbb{A}$  is a homomorphism.

#### 2.10 Minimal Models

Minimal models, also called *universal* models, are models for a theory with the special property that there exists a homomorphism from the minimal model to any other model satisfied by the theory. Minimal models have no unnecessary entities or relations and thus display the least amount of constraint necessary to satisfy the theory for which they are minimal.

More than one minimal model may exist for a given theory, and not every theory must have a minimal model. **give examples** 

<sup>&</sup>lt;sup>1</sup>geometric formulæ are implications of positive-existential formulæ

# 3 The Chase

The *chase* is a function that, when given a gemoetric theory, will generate a set of jointly minimal models for that theory. More specifically, if U is the set of all models obtained from an execution of the chase over a geometric theory T, for any model  $\mathbb{M}$  such that  $\mathbb{M} \models T$ , there is a homomorphism from some  $u \in U$  to  $\mathbb{M}$ .

There are three types of runs of the chase:

- a non-empty result in finite time
- an empty result in finite time
- an infinite run, with possible return dependent on implementation

# 3.1 Algorithm

Recall that geometric formulæ are of the form

$$\forall (free(F_L) \cup free(F_R)) : F_L \rightarrow F_R$$

where free is the function that calculates all free variables for a given formula and all F are first-order logic formulæ in positive existential form.

Geometric logic formulas are used by the chase because they have the useful property in that adding any relations or domain members to a model that satisfies a geometric logic formula will never cause the formula to no longer be satisfied. This is particularly helpful when trying to create a model that satisfies all formulas in a geometric theory.

## 3.2 Examples

4 An Extended Application: Cryptographic Protocol Analysis

- 5 Haskell Chase Implementation
- 5.1 Future Considerations

# A Table of Syntax

syntax	definition
$f^{-1}$	the inverse function of $f$
$R[a_0, a_1, a_2]$	a relation of: relation symbol $R$ , arity 3, and tuple $\langle a_0, a_1, a_2 \rangle$
Τ	a tautological formula; one that will always hold
	a contradictory formula; one that will never hold
$\neg \alpha$	$\alpha$ does not hold
$\alpha \wedge \beta$	both $\alpha$ and $\beta$ hold
$\alpha \vee \beta$	either $\alpha$ or $\beta$ hold
$\alpha \to \beta$	either $\alpha$ does not hold or $\beta$ holds
$\forall x: \alpha$	for each element of the domain as $x$ , $\alpha$ holds
$\forall \vec{x}: \alpha$	for each $x_i \in x$ , $\forall x_i : \alpha$ holds
$\exists x : \alpha$	for each at least one element of the domain as $x$ , $\alpha$ holds
$\exists \vec{x}: \alpha$	for each $x_i \in x$ , $\exists x_i : \alpha$ holds
$l[x \mapsto y]$	the environment $l$ with variable $x$ mapped to domain member $y$
$\mathbb{M} \models_{l} \sigma$	$\mathbb{M}$ is a model of $\sigma$ under environment $l$
$\mathbb{M} \models \sigma$	$\mathbb{M} \models_l \sigma \text{ given any environment } l$
$\mathbb{M} \models_l \Sigma$	for each $\sigma \in \Sigma$ , $\mathbb{M} \models_l \sigma$
$\mathbb{M} \models \Sigma$	for each $\sigma \in \Sigma$ , $\mathbb{M} \models \sigma$
$\Sigma \models \sigma$	$\Sigma$ entails $\sigma$
$\mathbb{M} \preceq \mathbb{N}$	there exists a homomorphism $h:  \mathbb{M}  \to  \mathbb{N} $

### B Chase code

```
1 module Chase where
    import Parser
 3
    import Helpers
    import Debug. Trace
   import Data. List
    chaseVerify :: [Formula] -> [Formula]
    - verifies that each formula is in positive existential form and performs some
9
   -- normilization on implied/constant implications
10
    chaseVerify formulae =
       let isNotPEF = not.isPEF in
11
12
       \operatorname{map} (\f -> \operatorname{case} f \operatorname{of}
13
           Implication a b ->
              if isNotPEF a || isNotPEF b then error ("implication_must_be_in_positive_existential_
14
15
16
              if isNotPEF f then error ("formula_must_be_in_positive_existential_form:_" ++ showFor
17
              else (Implication Tautology f)
19
       ) formulae
20
21
   chase :: [Formula] -> [Model]
   - runs the chase algorithm on a given theory and returns a list of models that
22
23
   -- satisfy it
    chase formulae = chase' (chaseVerify formulae) ([],[(mkModel [] [])])
25
    chase' :: [Formula] -> ([Model], [Model]) -> [Model]
26
    - used by the chase function to hide the model identity argument
28
    chase' formulae (done,[]) = done
29
    chase 'formulae (done, pending) =
       let self = chase' formulae in
30
31
       let (p:ending) = pending in
       trace ("running_chase_on_" ++ show (done, pending)) $
32
       if all (\f \rightarrow \text{holds p (UniversalQuantifier (freeVariables f) f)}) formulae then
33
34
           trace ("__all_formulae_in_theory_hold_for_model_" ++ showModel p) $
35
           trace ("__moving_model_into_done_list") $
36
           self (union done [p], ending)
37
           \textbf{let} \hspace{0.1cm} \textbf{possibly} Satisfied Models \hspace{0.1cm} = \hspace{0.1cm} \textbf{attempt} To Satisfy First Failure \hspace{0.1cm} \textbf{p} \hspace{0.1cm} \textbf{formulae} \hspace{0.1cm} \textbf{in}
38
           trace ("__at_least_one_formula_does_not_hold_for_model_" ++ showModel p) $ trace ("_uunioning_" ++ show ending ++ "_with_[" ++ intercalate ",_" (map showModel poss
39
           self (done, union ending possibly Satisfied Models)
41
42
    attemptToSatisfyFirstFailure :: Model -> [Formula] -> [Model]
43
    - checks if each formula holds, sequentially, until one does not, then tries
44
    -- to satisfy that formula
45
46
    attemptToSatisfyFirstFailure model (f:ormulae) =
47
       let self = attemptToSatisfyFirstFailure model in
       if holds model (Universal Quantifier (free Variables f) f) then self ormulae
48
49
       {\bf else} \ {\bf attemptToSatisfy} \ {\bf model} \ {\bf f}
50
    51
52
    attemptToSatisfy model formula =
       let f' = UniversalQuantifier (freeVariables formula) formula in
54
       trace ("__attempting_to_satisfy_(" ++ showFormula formula ++ ")") $
55
       attemptToSatisfy ' model [] f'
57
    attemptToSatisfy' :: Model -> Environment -> Formula -> [Model]
   - hides the environment identity in the 'attempt To Satisfy' function arguments
```

```
60
     attemptToSatisfy' model env formula =
 61
         let (domain, relations) = model in
         let domainSize = length domain in
 63
         let self = attemptToSatisfy ' model in
         -- trace \ (" \ attempting \ to \ satisfy \ (" ++ showFormula \ formula \ ++ ") \ with \ env " ++ show \ env)
 64
         case formula of
 65
 66
             Tautology -> [model]
 67
             Contradiction -> []
             Or a b -> union (self env a) (self env b)
 68
             And a b -> concatMap (\m -> attemptToSatisfy' m env b) (self env a) Implication a b -> if holds' model env a then self env b else []
 69
 70
 71
             Atomic predicate vars ->
                 let newRelation = mkRelation predicate (length vars) [genNewRelationArgs env vars (fr
 72
 73
                 let newModel = mkModel (mkDomain domainSize) (mergeRelation newRelation relations) in
                 trace ("____adding_new_relation:_" ++ show newRelation) $
 74
 75
                 [newModel]
             Existential Quantifier [] f \rightarrow self env f Existential Quantifier (v:vs) f \rightarrow
 76
 77
 78
                 let f' = Existential Quantifier vs f in
                 let nextDomainElement = fromIntegral $ (length domain) + 1 in
if any (\v' -> holds' model (hashSet env v v') f') domain then
    trace ("----" ++ showFormula formula ++ "-already-holds") $
 79
 80
 81
                     [model]
 82
 83
                     trace ("____adding_new_domain_element_" ++ show nextDomainElement ++ "_for_variabl
 84
             attemptToSatisfy' (mkDomain nextDomainElement, relations) (hashSet env v nextDomainUniversalQuantifier [] f -> self env f UniversalQuantifier (v:vs) f ->
 85
 86
 87
 88
                 let f' = UniversalQuantifier vs f in
             concatMap (\v' -> self (hashSet env v v') f') domain
- > error ("formula_not_in_positive_existential_form:_" ++ showFormula formula)
 89
 90
 91
     genNewRelationArgs \ :: \ Environment \ -> \ [\,Variable\,] \ -> \ DomainElement\, -> \ [\,DomainElement\,]
 92
     — for each Variable in the given list of Variables, retrieves the value
93
         assigned to it in the given environment, or the next domain element if it
 95
         does not exist
     genNewRelationArgs env [] domainSize = []
 96
     genNewRelationArgs env (v:ars) domainSize =
         let self = genNewRelationArgs env in
 98
99
         case lookup v env of
             Just v' -> v' : (self ars domainSize)
100
101
             - -> (domainSize+1) : (self ars (domainSize+1))
```

# References

 $[1] \ \ A \ \ Cottrell, \ Word \ Processors: \ Stupid \ and \ Inefficient, \\ \text{www.ecn.wfu.edu/~cottrell/wp.html}$