

MQP TITLE

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Abstract

This paper describes a method, referred to as the chase, for generating minimal models for a geometric theory. A minimal model for a theory is a model for which there exists a homomorphism to any other model that can satisfy the theory. These models are useful in solutions to problems in many practical applications, including firewall configuration examination and access control evaluation. Also described is a Haskell implementation of the chase and its development process and design decisions.

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1 Introduction

Introductory text...

1.1 Goals

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1.2 The Chase

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2 Technical Background

In this paper, possibly ambiguous or uncommon notation will be used and thusly must be clearly defined. Also, topics that are necessary prerequisites will be summarized.

2.1 Models

A *model* \mathbb{M} is a construct that consists of:

- a set, referenced as $|\mathbb{M}|$, called the *universe* or *domain* of \mathbb{M}
- a set of pairings of a *predicate* and a non-negative integral arity
- for each predicate R with arity k , a relation $R_k^{\mathbb{M}} \subseteq |\mathbb{M}|$

It is important to distinguish the predicate, which is just a symbol, from the relation that it refers to when paired with its arity. The relation itself is a set of tuples of elements from the universe.

2.2 First-order Logic

First-order logic, also called *predicate logic*, is a formula logic system that is an extension of propositional logic. For our purposes, this logic system will not contain any constant symbols or function symbols, which are commonly included in first-order and propositional logic.

A first-order logic formula is defined inductively by

- if R is a relation symbol of arity k and each of t_0, \dots, t_{k-1} is a variable, then $R[t_0, \dots, t_{k-1}]$ is a formula, specifically an *atomic formula*
- \top and \perp are formulæ
- if α is a formula then $(\neg\alpha)$ is a formula
- if α and β are formulæ then $(\alpha \wedge \beta)$ is a formula
- if α and β are formulæ then $(\alpha \vee \beta)$ is a formula
- if α and β are formulæ then $(\alpha \rightarrow \beta)$ is a formula

- if α is a formula and x is a variable then $(\forall x : \alpha)$ is a formula
- if α is a formula and \vec{x} is a set of variables of size k then $(\forall \vec{x} : \alpha)$ is $(\forall x_0 \dots \forall x_{k-1} : \alpha)$
- if α is a formula and x is a variable then $(\exists x : \alpha)$ is a formula
- if α is a formula and \vec{x} is a set of variables of size k then $(\exists \vec{x} : \alpha)$ is $(\exists x_0 \dots \exists x_{k-1} : \alpha)$

2.3 Geometric Logic

Geometric logic is first-order logic with constraints on the shape of the expression. Geometric logic formulæ are implicitly universally quantified first-order logic expressions of the form

$$A_0 \wedge \dots \wedge A_n \rightarrow E_0 \vee \dots \vee E_m$$

where $A_0 \dots A_n$ are atomics, $E_0 \dots E_m$ are first-order logic expressions of the form $\exists_{x_0 \dots x_k} A_0 \wedge \dots \wedge \exists_{x_0 \dots x_p} A_y$, and n, m, k, p , and y are integers greater than or equal to 0. A set of geometric logic formulæ is called a *geometric theory*.

explain why GL is useful to us

2.4 Variable Binding

The set of free variables in a formula is defined inductively as follows

- any variable occurrence in an atomic formula is a free variable
- the free variables in \top and \perp are \emptyset
- the free variables in $\neg\alpha$ are the free variables in α
- the free variables in $\alpha \wedge \beta$ are the union of the set of free variables in α with the set of free variables in β
- the free variables in $\alpha \vee \beta$ are the union of the set of free variables in α with the set of free variables in β
- the free variables in $\alpha \rightarrow \beta$ are the union of the set of free variables in α with the set of free variables in β
- the free variables in $\forall x : \alpha$ are the free variables in α that are not x

- the free variables in $\exists x : \alpha$ are the free variables in α that are not x

A *sentence* is a formula with an empty set of free variables.

2.5 Environment

An *environment* for a model \mathbb{M} is a function from a variable to an element in $|\mathbb{M}|$. The syntax $l_{[v \mapsto v']}$ defines an environment $l'(x)$ that returns v' when $x = v$ and returns $l(x)$ otherwise.

2.6 Satisfiability

A model \mathbb{M} is said to satisfy a formula σ in an environment l when

- σ is a relation symbol R and $R[l(a_0), \dots, l(a_n)] \in \mathbb{M}$ where a is a set of variables
- σ is of the form $\neg\alpha$ and $\mathbb{M} \not\models_l \alpha$
- σ is of the form $\alpha \wedge \beta$ and both $\mathbb{M} \models_l \alpha$ and $\mathbb{M} \models_l \beta$
- σ is of the form $\alpha \vee \beta$ and either $\mathbb{M} \models_l \alpha$ or $\mathbb{M} \models_l \beta$
- σ is of the form $\alpha \rightarrow \beta$ and either $\mathbb{M} \not\models_l \alpha$ or $\mathbb{M} \models_l \beta$
- σ is of the form $\forall x : \alpha$ and for every $x' \in |\mathbb{M}|$, $\mathbb{M} \models_{l[x \mapsto x']} \alpha$
- σ is of the form $\exists x : \alpha$ and for at least one $x' \in |\mathbb{M}|$, $\mathbb{M} \models_{l[x \mapsto x']} \alpha$

This is denoted as $\mathbb{M} \models_l \sigma$ and read "σ is true in \mathbb{M} ". The notation $\mathbb{M} \models \sigma$ (no environment specification) means that either, under any environment l , $\mathbb{M} \models_l \sigma$.

A model \mathbb{M} satisfies a set of formulæ Σ if for every σ such that $\sigma \in \Sigma$, $\mathbb{M} \models \sigma$. This is denoted as $\mathbb{M} \models \Sigma$ and read "M is a model of Σ ".

2.7 Entailment

A set of formulæ Σ is said to *entail* a formula σ ($\Sigma \models \sigma$) if the set of all models satisfied by Σ is a subset of the set of all models satisfied by σ .

The notation used for satisfiability and entailment is very similar, in that the operator used (\models) is the same, but they can be distinguished by the type of left operand.

2.8 Homomorphisms

A *homomorphism* from \mathbb{A} to \mathbb{B} is a function $h : |\mathbb{A}| \rightarrow |\mathbb{B}|$ such that, for each relation symbol R and tuple $\langle a_0, \dots, a_n \rangle$ where $a \subseteq |\mathbb{A}|$, $\langle a_0, \dots, a_n \rangle \in R^{\mathbb{A}}$ implies $\langle h(a_0), \dots, h(a_n) \rangle \in R^{\mathbb{B}}$.

A homomorphism h is also a *strong homomorphism* if, for each relation symbol R and tuple $\langle a_0, \dots, a_n \rangle$ where $a \subseteq |\mathbb{A}|$, $\langle a_0, \dots, a_n \rangle \in R^{\mathbb{A}}$ if and only if $\langle h(a_0), \dots, h(a_n) \rangle \in R^{\mathbb{B}}$.

The notation $\mathbb{M} \preceq \mathbb{N}$ means that there exists a homomorphism $h : \mathbb{M} \rightarrow \mathbb{N}$. The identity function is a homomorphism from any model \mathbb{M} to itself. Homomorphisms are transitive, so $\mathbb{A} \preceq \mathbb{B} \wedge \mathbb{B} \preceq \mathbb{C}$ implies $\mathbb{A} \preceq \mathbb{C}$. However, $\mathbb{M} \preceq \mathbb{N} \wedge \mathbb{N} \preceq \mathbb{M}$ does not imply that $\mathbb{M} = \mathbb{N}$.

Given models \mathbb{M} and \mathbb{N} where $\mathbb{M} \preceq \mathbb{N}$ and a formula in positive-existential form ¹ σ , if $\mathbb{M} \models \sigma$ then $\mathbb{N} \models \sigma$.

An *isomorphism* is a homomorphism $h : \mathbb{A} \rightarrow \mathbb{B}$ where h is 1:1 and onto and the inverse function $h^{-1} : \mathbb{B} \rightarrow \mathbb{A}$ is a homomorphism.

2.9 Minimal Models

Minimal models, also called *universal* models, are models for a theory with the special property that there exists a homomorphism from the minimal model to any other model satisfied by the theory. Minimal models have no unnecessary entities or relations and thus display the least amount of constraint necessary to satisfy the theory for which they are minimal.

More than one minimal model may exist for a given theory, and not every theory must have a minimal model. **give examples**

¹geometric formulæ are implications of positive-existential formulæ

3 The Chase

The *chase* is a function that, when given a geometric theory, will generate all minimal models for that theory.

There are three types of runs of the chase:

- a non-empty result in finite time
- an empty result in finite time
- an infinite run, with possible return dependent on implementation

3.1 Algorithm

Recall that geometric formulæ are of the form

$$\bigwedge A \rightarrow \bigvee \bigwedge \exists \vec{x} A$$

where A is an atomic formula and all sets can be zero-length.

3.2 Applications

4 Haskell Chase Implementation

A Table of Syntax

syntax	definition
f^{-1}	the inverse function of f
$R[a_0, a_1, a_2]$	a <i>relation</i> of: relation symbol R , arity 3, and tuple $\langle a_0, a_1, a_2 \rangle$
\top	a <i>tautological formula</i> ; one that will always hold
\perp	a <i>contradictory formula</i> ; one that will never hold
$\neg\alpha$	α does not hold
$\alpha \wedge \beta$	both α and β hold
$\alpha \vee \beta$	either α or β hold
$\alpha \rightarrow \beta$	either α does not hold or β holds
$\forall x : \alpha$	for each element of the domain as x , α holds
$\forall \vec{x} : \alpha$	for each $x_i \in x$, $\forall x_i : \alpha$ holds
$\exists x : \alpha$	for each at least one element of the domain as x , α holds
$\exists \vec{x} : \alpha$	for each $x_i \in x$, $\exists x_i : \alpha$ holds
$l[x \mapsto y]$	the environment l with variable x mapped to domain member y
$\mathbb{M} \models_l \sigma$	\mathbb{M} is a <i>model of</i> σ under environment l
$\mathbb{M} \models \sigma$	$\mathbb{M} \models_l \sigma$ given any environment l
$\mathbb{M} \models_l \Sigma$	for each $\sigma \in \Sigma$, $\mathbb{M} \models_l \sigma$
$\mathbb{M} \models \Sigma$	for each $\sigma \in \Sigma$, $\mathbb{M} \models \sigma$
$\Sigma \models \sigma$	Σ <i>entails</i> σ
$\mathbb{M} \preceq \mathbb{N}$	there exists a <i>homomorphism</i> $h : \mathbb{M} \rightarrow \mathbb{N} $

B Chase code

```

1  module Chase where
2  import Parser
3  import Helpers
4  import Debug.Trace
5  import Data.List
6
7  chaseVerify :: [Formula] -> [Formula]
8  — verifies that each formula is in positive existential form and performs some
9  — normalization on implied/constant implications
10 chaseVerify formulae =
11   let isNotPEF = not.isPEF in
12   map (\f -> case f of
13     Implication a b ->
14       if isNotPEF a || isNotPEF b then error ("implication must be in positive existential form")
15       else f
16     - ->
17       if isNotPEF f then error ("formula must be in positive existential form:" ++ showFormula f)
18       else (Implication Tautology f)
19   ) formulae
20
21 chase :: [Formula] -> [Model]
22 — runs the chase algorithm on a given theory and returns a list of models that
23 — satisfy it
24 chase formulae = chase' (chaseVerify formulae) ([], [(mkModel [] [])])
25
26 chase' :: [Formula] -> ([Model], [Model]) -> [Model]
27 — used by the chase function to hide the model identity argument
28 chase' formulae (done, []) = done
29 chase' formulae (done, pending) =
30   let self = chase' formulae in
31   let (p:ending) = pending in
32   trace ("running chase on " ++ show (done, pending)) $
33   if all (\f -> holds p (UniversalQuantifier (freeVariables f) f)) formulae then
34     trace ("all formulae in theory hold for model " ++ showModel p) $
35     trace ("moving model into done list") $
36     self (union done [p], ending)
37   else
38     let possiblySatisfiedModels = attemptToSatisfyFirstFailure p formulae in
39     trace ("at least one formula does not hold for model " ++ showModel p) $
40     trace ("unioning " ++ show ending ++ " with " ++ show possiblySatisfiedModels) $
41     self (done, union ending possiblySatisfiedModels)
42
43 attemptToSatisfyFirstFailure :: Model -> [Formula] -> [Model]
44 — checks if each formula holds, sequentially, until one does not, then tries
45 — to satisfy that formula
46 attemptToSatisfyFirstFailure model (f:formulae) =
47   let self = attemptToSatisfyFirstFailure model in
48   if holds model (UniversalQuantifier (freeVariables f) f) then self formulae
49   else attemptToSatisfy model f
50
51 attemptToSatisfy :: Model -> Formula -> [Model]
52 — returns a model that is altered so that the given formula will hold
53 attemptToSatisfy model formula =
54   let f' = UniversalQuantifier (freeVariables formula) formula in
55   trace ("attempting to satisfy " ++ showFormula formula ++ ")") $
56   attemptToSatisfy' model [] f'
57
58 attemptToSatisfy' :: Model -> Environment -> Formula -> [Model]
59 — hides the environment identity in the 'attemptToSatisfy' function arguments

```

```

60 attemptToSatisfy' model env formula =
61   let (domain,relations) = model in
62   let domainSize = length domain in
63   let self = attemptToSatisfy' model in
64   — trace (" attempting to satisfy (" ++ showFormula formula ++ ") with env " ++ show env)
65   case formula of
66     Tautology -> [model]
67     Contradiction -> []
68     Or a b -> union (self env a) (self env b)
69     And a b -> concatMap (\m -> attemptToSatisfy' m env b) (self env a)
70     Implication a b -> if holds' model env a then self env b else []
71     Atomic predicate vars ->
72       let newRelation = mkRelation predicate (length vars) [genNewRelationArgs env vars (fr
73       let newModel = mkModel (mkDomain domainSize) (mergeRelation newRelation relations) in
74       trace (" adding new relation: " ++ show newRelation) $
75       [newModel]
76     ExistentialQuantifier [] f -> self env f
77     ExistentialQuantifier (v:vs) f ->
78       let f' = ExistentialQuantifier vs f in
79       let nextDomainElement = fromIntegral $ (length domain) + 1 in
80       if any (\v' -> holds' model (hashSet env v v') f') domain then
81         trace (" " ++ showFormula formula ++ " already holds") $
82         [model]
83       else
84         trace (" adding new domain element " ++ show nextDomainElement ++ " for variable
85         attemptToSatisfy' (mkDomain nextDomainElement,relations) (hashSet env v nextDomain
86     UniversalQuantifier [] f -> self env f
87     UniversalQuantifier (v:vs) f ->
88       let f' = UniversalQuantifier vs f in
89       concatMap (\v' -> self (hashSet env v v') f') domain
90     - -> error ("formula not in positive existential form: " ++ showFormula formula)
91
92 genNewRelationArgs :: Environment -> [Variable] -> DomainElement -> [DomainElement]
93 — for each Variable in the given list of Variables, retrieves the value
94 — assigned to it in the given environment, or the next domain element if it
95 — does not exist
96 genNewRelationArgs env [] domainSize = []
97 genNewRelationArgs env (v:ars) domainSize =
98   let self = genNewRelationArgs env in
99   case lookup v env of
100     Just v' -> v' : (self ars domainSize)
101     - -> (domainSize+1) : (self ars (domainSize+1))

```

References

- [1] A Cottrell, *Word Processors: Stupid and Inefficient*,
www.ecn.wfu.edu/~cottrell/wp.html