

GENERATING MINIMAL MODELS FOR GEOMETRIC THEORIES

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Abstract

This paper describes a method, referred to as the chase, for generating jointly minimal models for a geometric theory. A minimal model for a theory is a model for which there exists a homomorphism to any other model that can satisfy the theory. These models are useful in solutions to problems in many practical applications, including but not limited to firewall configuration examination, protocol analysis, and access control evaluation. Also described is a Haskell implementation of the chase and its development process and design decisions.

Table of Contents

1	Introduction	1
1.1	Goals	1
1.2	The Chase	1
2	Technical Background	2
2.1	Models	2
2.2	First-order Logic	2
2.3	Positive Existential Form	3
2.4	Geometric Logic	3
2.5	Variable Binding	3
2.6	Environment	4
2.7	Satisfiability	4
2.8	Entailment	5
2.9	Homomorphisms	5
2.10	Minimal Models	5
3	The Chase	6
3.1	Algorithm	6
3.2	Examples	6
4	Haskell Chase Implementation	8
4.1	Operation	8
4.2	I/O, Tracing, Options	9
4.3	Future Considerations	9
5	An Extended Application:	

Cryptographic Protocol Analysis	10
A Table of Syntax	11
B Chase code	12
References	14

1 Introduction

Introductory text...

1.1 Goals

1.2 The Chase

2 Technical Background

In this paper, possibly ambiguous or uncommon notation will be used and thusly must be clearly defined. Also, topics that are necessary prerequisites will be summarized.

2.1 Models

A *model* \mathbb{M} is a construct that consists of:

- a set, referenced as $|\mathbb{M}|$, called the *universe* or *domain* of \mathbb{M}
- a set of pairings of a *predicate* and a non-negative integral arity
- for each predicate R with arity k , a relation $R_k^{\mathbb{M}} \subseteq |\mathbb{M}|$

It is important to distinguish the predicate, which is just a symbol, from the relation that it refers to when paired with its arity. The relation itself is a set of tuples of elements from the universe.

2.2 First-order Logic

First-order logic, also called *predicate logic*, is a formal logic system that is an extension of propositional logic. For our purposes, this logic system will not contain any constant symbols or function symbols, which are commonly included in first-order and propositional logic. We will see that these can be removed without loss of generality.

A first-order logic formula is defined inductively by

- if R is a relation symbol of arity k and each of t_0, \dots, t_{k-1} is a variable, then $R[t_0, \dots, t_{k-1}]$ is a formula, specifically an *atomic formula*
- if ρ and τ are variables, then $\rho = \tau$ is a formula
- \top and \perp are formulæ
- if α is a formula, then $(\neg\alpha)$ is a formula
- if α and β are formulæ, then $(\alpha \wedge \beta)$ is a formula
- if α and β are formulæ, then $(\alpha \vee \beta)$ is a formula
- if α and β are formulæ, then $(\alpha \rightarrow \beta)$ is a formula
- if α is a formula and x is a variable, then $(\forall x : \alpha)$ is a formula

- if α is a formula and \vec{x} is a set of variables of size k , then $(\forall \vec{x} : \alpha)$ is $(\forall x_0 \dots \forall x_{k-1} : \alpha)$
- if α is a formula and x is a variable, then $(\exists x : \alpha)$ is a formula
- if α is a formula and \vec{x} is a set of variables of size k , then $(\exists \vec{x} : \alpha)$ is $(\exists x_0 \dots \exists x_{k-1} : \alpha)$

A shorthand notation may sometimes be used which omits either the left or right side of an implication and implies a tautology ($\top \rightarrow \sigma$) and a contradiction ($\sigma \rightarrow \perp$) respectively.

Examples of first-order logic formulæ

$$\begin{array}{ll}
\text{reflexivity} & \rightarrow R[x, x] \\
\text{symmetry} & R[x, y] \rightarrow R[y, x] \\
\text{transitivity} & R[x, y] \wedge R[y, z] \rightarrow R[x, z] \\
& \forall r, u : R[r, r, r] \vee Q[u]
\end{array}$$

2.3 Positive Existential Form

Formulæ in *positive existential form* are constrained to using only conjunctions (\wedge), disjunctions (\vee), existential quantifications (\exists), tautologies (\top), contradictions (\perp), equalities, and relations to construct logic expressions.

Though formulæ in positive existential form may at first appear to be quite restrictive, there exists some simple logical tricks to allow more expressiveness. Negation of a relation R with arity k can be implemented by assuming another relation R' with arity k , adding two formulæ to the theory of the form $R \wedge R' \rightarrow \perp$ and $\top \rightarrow R \vee R'$, and using R' where $\neg R$ would be used.

2.4 Geometric Logic

Geometric logic formulæ are implicitly universally quantified implications of positive existential formulæ. A set of geometric logic formulæ is called a *geometric theory*.

2.5 Variable Binding

The set of free variables in a formula is defined inductively as follows

- any variable occurrence in an atomic formula is a free variable
- the free variables in \top and \perp are \emptyset
- the free variables in $\rho = \tau$ are $\{\rho, \tau\}$

- the free variables in $\neg\alpha$ are the free variables in α
- the free variables in $\alpha \wedge \beta$ are the union of the set of free variables in α with the set of free variables in β
- the free variables in $\alpha \vee \beta$ are the union of the set of free variables in α with the set of free variables in β
- the free variables in $\alpha \rightarrow \beta$ are the union of the set of free variables in α with the set of free variables in β
- the free variables in $\forall x : \alpha$ are the free variables in α that are not x
- the free variables in $\exists x : \alpha$ are the free variables in α that are not x

A *sentence* is a formula with an empty set of free variables.

2.6 Environment

An *environment* for a model \mathbb{M} is a function from a variable to an element in $|\mathbb{M}|$. The syntax $\lambda_{[v \mapsto v']}$ defines an environment $\lambda'(x)$ that returns v' when $x = v$ and returns $\lambda(x)$ otherwise.

2.7 Satisfiability

A model \mathbb{M} is said to satisfy a formula σ in an environment l when

- σ is a relation symbol R and $R[l(a_0), \dots, l(a_n)] \in \mathbb{M}$ where a is a set of variables
- σ is of the form $\neg\alpha$ and $\mathbb{M} \not\models_l \alpha$
- σ is of the form $\alpha \wedge \beta$ and both $\mathbb{M} \models_l \alpha$ and $\mathbb{M} \models_l \beta$
- σ is of the form $\alpha \vee \beta$ and either $\mathbb{M} \models_l \alpha$ or $\mathbb{M} \models_l \beta$
- σ is of the form $\alpha \rightarrow \beta$ and either $\mathbb{M} \not\models_l \alpha$ or $\mathbb{M} \models_l \beta$
- σ is of the form $\forall x : \alpha$ and for every $x' \in |\mathbb{M}|$, $\mathbb{M} \models_{l[x \mapsto x']} \alpha$
- σ is of the form $\exists x : \alpha$ and for at least one $x' \in |\mathbb{M}|$, $\mathbb{M} \models_{l[x \mapsto x']} \alpha$

This is denoted as $\mathbb{M} \models_l \sigma$ and read ” σ is true in \mathbb{M} ”. The notation $\mathbb{M} \models \sigma$ (no environment specification) means that either, under any environment l , $\mathbb{M} \models_l \sigma$.

A model \mathbb{M} satisfies a set of formulæ Σ if for every σ such that $\sigma \in \Sigma$, $\mathbb{M} \models \sigma$. This is denoted as $\mathbb{M} \models \Sigma$ and read ” \mathbb{M} is a model of Σ ”.

2.8 Entailment

A set of formulae Σ is said to *entail* a formula σ ($\Sigma \models \sigma$) if the set of all models satisfied by Σ is a subset of the set of all models satisfied by σ .

The notation used for satisfiability and entailment is very similar, in that the operator used (\models) is the same, but they can be distinguished by the type of left operand.

2.9 Homomorphisms

A *homomorphism* from \mathbb{A} to \mathbb{B} is a function $h : |\mathbb{A}| \rightarrow |\mathbb{B}|$ such that, for each relation symbol R and tuple $\langle a_0, \dots, a_n \rangle$ where $a \subseteq |\mathbb{A}|$, $\langle a_0, \dots, a_n \rangle \in R^{\mathbb{A}}$ implies $\langle h(a_0), \dots, h(a_n) \rangle \in R^{\mathbb{B}}$.

A homomorphism h is also a *strong homomorphism* if, for each relation symbol R and tuple $\langle a_0, \dots, a_n \rangle$ where $a \subseteq |\mathbb{A}|$, $\langle a_0, \dots, a_n \rangle \in R^{\mathbb{A}}$ if and only if $\langle h(a_0), \dots, h(a_n) \rangle \in R^{\mathbb{B}}$.

The notation $\mathbb{M} \preceq \mathbb{N}$ means that there exists a homomorphism $h : \mathbb{M} \rightarrow \mathbb{N}$. The identity function is a homomorphism from any model \mathbb{M} to itself. Homomorphisms are transitive, so $\mathbb{A} \preceq \mathbb{B} \wedge \mathbb{B} \preceq \mathbb{C}$ implies $\mathbb{A} \preceq \mathbb{C}$. However, $\mathbb{M} \preceq \mathbb{N} \wedge \mathbb{N} \preceq \mathbb{M}$ does not imply that $\mathbb{M} = \mathbb{N}$.

Given models \mathbb{M} and \mathbb{N} where $\mathbb{M} \preceq \mathbb{N}$ and a formula in positive-existential form ¹ σ , if $\mathbb{M} \models \sigma$ then $\mathbb{N} \models \sigma$.

A homomorphism $h : \mathbb{A} \rightarrow \mathbb{B}$ is also an *isomorphism* when h is 1:1 and onto and the inverse function $h^{-1} : \mathbb{B} \rightarrow \mathbb{A}$ is a homomorphism.

2.10 Minimal Models

Minimal models, also called *universal* models, are models for a theory with the special property that there exists a homomorphism from the minimal model to any other model satisfied by the theory. Minimal models have no unnecessary entities or relations and thus display the least amount of constraint necessary to satisfy the theory for which they are minimal.

More than one minimal model may exist for a given theory, and not every theory must have a minimal model. **give examples.**

A set of models M is said to be *jointly minimal* for a set of formulae Σ when every model μ such that $\mu \models \Sigma$ has a homomorphism from a model $m \in M$ to μ .

¹geometric formulae are implications of positive-existential formulae

3 The Chase

talk about chase as nondeterministic algorithm or deterministic implementation algorithm? or both...

The *chase* is a function that, when given a geometric theory, will generate a set of jointly minimal models for that theory. More specifically, if U is the set of all models obtained from an execution of the chase over a geometric theory T , for any model \mathbb{M} such that $\mathbb{M} \models T$, there is a homomorphism from some $u \in U$ to \mathbb{M} .

There are three types of runs of the chase:

- a non-empty result in finite time
- an empty result in finite time
- an infinite run, with possible return dependent on implementation

Recall that geometric formulæ are of the form

$$\forall (free(F_L) \cup free(F_R)) : F_L \rightarrow F_R$$

where *free* is the function that returns the set of all free variables for a given formula and all F are first-order logic formulæ in positive existential form. Also recall that a geometric formula's implication is implicitly universally quantified over all free variables.

Geometric logic formulæ are used by the chase because they have the useful property where adding any relations or domain members to a model that satisfies a geometric logic formula will never cause the formula to no longer be satisfied. This is particularly helpful when trying to create a model that satisfies all formulæ in a geometric theory.

3.1 Algorithm

3.2 Examples

Define Σ as the following geometric theory

$$\top \rightarrow \exists y, z : R[y, z] \tag{1}$$

$$R[x, w] \rightarrow (\exists y : Q[x, y]) \vee (\exists z : P[x, z]) \tag{2}$$

$$Q[u, v] \rightarrow (\exists z : R[u, z]) \vee (\exists z : R[z, w]) \tag{3}$$

$$P[u, v] \rightarrow \perp \tag{4}$$

The following three chase runs show the different types of results depending on which disjunct the algorithm attempts to satisfy when a disjunction is encountered

A non-empty result in finite time:

$$\begin{array}{lcl} \emptyset & \mapsto & \{ \quad a, b \quad \mid \quad R[a, b] \quad \} \\ & \mapsto & \{ \quad a, b, c \quad \mid \quad R[a, b], Q[a, c] \quad \} \end{array}$$

An empty result in finite time:

$$\begin{array}{lcl} \emptyset & \mapsto & \{ \quad a, b \quad \mid \quad R[a, b] \quad \} \\ & \mapsto & \{ \quad a, b, c \quad \mid \quad R[a, b], P[a, c] \quad \} \\ & \mapsto & \{ \quad a, b, c \quad \mid \quad R[a, b], P[a, c], \perp \quad \} \\ & \mapsto & \varepsilon \end{array}$$

An infinite run:

$$\begin{array}{lcl} \emptyset & \mapsto & \{ \quad a, b \quad \mid \quad R[a, b] \quad \} \\ & \mapsto & \{ \quad a, b, c \quad \mid \quad R[a, b], Q[a, c] \quad \} \\ & \mapsto & \{ \quad a, b, c, d \quad \mid \quad R[a, b], Q[a, c], R[d, c] \quad \} \\ & \mapsto & \{ \quad a, b, c, d, e \quad \mid \quad R[a, b], Q[a, c], R[d, c], Q[d, e] \quad \} \\ & \mapsto & \{ \quad a, b, c, d, e, f \quad \mid \quad R[a, b], Q[a, c], R[d, c], Q[d, e], R[f, e] \quad \} \\ & \mapsto & \dots \end{array}$$

4 Haskell Chase Implementation

The goal of the implementation of the chase is to deterministically find all possible outcomes of the chase. It does this by forking and taking all paths when encountering a disjunct rather than nondeterministically choosing one disjunct to satisfy.

The results from the attempts to satisfy each disjunct are returned as a list. The returned list will not contain an entry for runs that return no model, and will merge lists returned from runs that themselves encountered a disjunct. The lazy evaluation of Haskell allows a user to access members of the returned list even though some chase runs have not returned a value.

Appendix B contains the chase-running portions of the implementation.

4.1 Operation

The first step of the chase implementation is to verify that each formula of the given theory is an implication of positive-existential formulæ. If a formula φ is not an implication, but is in positive-existential form, it is replaced with $\top \rightarrow \varphi$.

After the input verification and coercion step, the *chase* function begins processing a *pending* list, which is initially populated with a single model that has an empty domain and no facts. In the special case where *chase* is run on an empty list, an empty list of models is returned.

For each *pending* model, each formula is evaluated to see if it holds in the model for all bindings. If a binding is found that does not satisfy the model, the model and binding in which the formula did not hold is passed to the *chaseSatisfy* function, along with the formula that needs to be satisfied. The list of models returned from *chaseSatisfy* is merged into the *pending* list, and the result of running *chase* on the new *pending* list is returned. If, however, the model holds for all formulæ in the theory and all possible associated bindings, it is concatenated with the result of running the chase on the rest of the models in the *pending* list.

The *chaseSatisfy* function performs a pattern match on the type of formula given. Assuming *chaseSatisfy* is given a model \mathbb{M} , a binding λ , and a formula φ , *chaseSatisfy*

will behave as outlined in the following algorithm.

```

return switch  $\varphi$  do
| case  $\top$  return a list containing  $\mathbb{M}$ 
| case  $\perp$  return an empty list
| case  $\rho = \tau$  return a list containing the model returned by applying the quotient
|   function to  $\mathbb{M}$ 
| case  $\alpha \vee \beta$  return (result of recursion on  $\alpha$ )  $\cup$  (result of recursion on  $\beta$ )
| case  $\alpha \wedge \beta$ 
|   | create an empty list  $r$ 
|   | foreach model  $m$  in the result of recursion on  $\alpha$  do
|   |   | union  $r$  with the result of recursion on  $\beta$ 
|   | return  $r$ 
| case  $\alpha \rightarrow \beta$ 
|   | if  $\mathbb{M}_\lambda \models \alpha$  then return the result of recursion on  $\beta$ 
|   | else return an empty list
| case  $R[\vec{x}]$ 
|   | define a new model  $\mathbb{N}$  where  $|\mathbb{N}| = |\mathbb{M}|$ 
|   | add a new element  $\omega$  to  $|\mathbb{N}|$ 
|   | forall the  $P_{\mathbb{M}}$  do  $P_{\mathbb{N}} = P_{\mathbb{M}}$ 
|   | define  $R_{\mathbb{N}}[x_0 \dots x_n]$  as  $R_{\mathbb{M}}[\lambda(x_0) \dots \lambda(x_n)]$ 
|   | foreach  $v \in \vec{x}$  do
|   |   | if  $v \notin \lambda$  then  $\lambda$  becomes  $\lambda_{v \mapsto \omega}$ 
|   | return a list containing  $\mathbb{N}$ 
| case  $\exists \vec{x} : \alpha$ 
|   | if  $\vec{x} = \emptyset$  then recurse on  $\alpha$ 
|   | if  $|\mathbb{M}| \neq \emptyset$  and  $\exists v' \in |\mathbb{M}| : (\lambda' = \lambda_{x_0 \mapsto v'} \text{ and } \mathbb{M} \models_{\lambda'} \alpha)$  then
|   |   | return a list containing  $\mathbb{M}$ 
|   | else
|   |   | define a new model  $\mathbb{N}$  where  $|\mathbb{N}| = |\mathbb{M}|$ 
|   |   | add an element  $\omega$  to  $|\mathbb{N}|$  such that  $\omega \notin |\mathbb{N}|$ 
|   |   | forall the  $R_{\mathbb{M}}$  do  $R_{\mathbb{N}} = R_{\mathbb{M}}$ 
|   |   | define  $\kappa = \lambda_{x_0 \mapsto \omega}$ 
|   |   | return the result of recursion using model  $\mathbb{N}$  and binding  $\kappa$  on
|   |   |  $\exists \{x_1 \dots x_n\} : \alpha$ 

```

4.2 I/O, Tracing, Options

4.3 Future Considerations

5 An Extended Application: Cryptographic Protocol Analysis

A Table of Syntax

syntax	definition
f^{-1}	the inverse function of f
$R[a_0, a_1, a_2]$	a <i>relation</i> of: relation symbol R , arity 3, and tuple $\langle a_0, a_1, a_2 \rangle$
\top	a <i>tautological formula</i> ; one that will always hold
\perp	a <i>contradictory formula</i> ; one that will never hold
$\rho = \tau$	given assumed environment λ , $\lambda(\rho) = \lambda(\tau)$
$\neg\alpha$	α does not hold
$\alpha \wedge \beta$	both α and β hold
$\alpha \vee \beta$	either α or β hold
$\alpha \rightarrow \beta$	either α does not hold or β holds
$\forall x : \alpha$	for each element of the domain as x , α holds
$\forall \vec{x} : \alpha$	for each $x_i \in x$, $\forall x_i : \alpha$ holds
$\exists x : \alpha$	for each at least one element of the domain as x , α holds
$\exists \vec{x} : \alpha$	for each $x_i \in x$, $\exists x_i : \alpha$ holds
$\lambda[x \mapsto y]$	the environment λ with variable x mapped to domain member y
$\mathbb{M} \models_l \sigma$	\mathbb{M} is a <i>model of</i> σ under environment l
$\mathbb{M} \models \sigma$	$\mathbb{M} \models_l \sigma$ given any environment l
$\mathbb{M} \models_l \Sigma$	for each $\sigma \in \Sigma$, $\mathbb{M} \models_l \sigma$
$\mathbb{M} \models \Sigma$	for each $\sigma \in \Sigma$, $\mathbb{M} \models \sigma$
$\Sigma \models \sigma$	Σ <i>entails</i> σ
$\mathbb{M} \preceq \mathbb{N}$	there exists a <i>homomorphism</i> $h : \mathbb{M} \rightarrow \mathbb{N} $

B Chase code

TODO: make the long lines short so they fit

```

1  module Chase where
2  import Parser
3  import Helpers
4  import Debug.Trace
5  import Data.List
6
7  chaseVerify :: Formula -> Formula
8  — verifies that a formula is in positive existential form and performs some
9  — normalization on implied/constant implications
10 chaseVerify formula =
11   let isNotPEF = not.isPEF in
12   case formula of
13     Implication a b ->
14       if isNotPEF a || isNotPEF b then
15         error ("implication must be in positive existential form:" ++ showFormula formula)
16       else formula
17   - ->
18     if isNotPEF formula then
19       error ("formula must be in positive existential form:" ++ showFormula formula)
20     else (Implication Tautology formula)
21
22 chase :: [Formula] -> [Model]
23 — a wrapper for the chase' function to hide the model identity and theory
24 — manipulation
25 chase formulae = chase' (map chaseVerify formulae) [([] , [])]
26
27 chase' :: [Formula] -> [Model] -> [Model]
28 — runs the chase algorithm on a given theory, manipulating the given list of
29 — models, and returning a list of models that satisfy the theory
30 chase' formulae [] = []
31 chase' formulae pending@(m:rest) =
32   let self = chase' formulae in
33   trace ("running chase on" ++ show pending) $
34   case findFirstFailure m formulae of
35     Just newPending ->
36       trace ("at least one formula does not hold for model" ++ showModel m) $
37       trace ("unioning" ++ show rest ++ " with" ++ intercalate ", " (map showModel newPending)) $
38       self (union rest newPending)
39     Nothing -> — represents no failures
40       trace ("all formulae in theory hold for model" ++ showModel m) $
41       trace ("moving model into done list") $
42       m : self rest
43
44 findFirstFailure :: Model -> [Formula] -> Maybe [Model]
45 —
46 findFirstFailure model [] = Nothing — no failure found
47 findFirstFailure model@(domain, relations) (f:ormulae) =
48   let self = findFirstFailure model in
49   let bindings = allBindings (freeVariables f) domain [] in
50   if holds' model (UniversalQuantifier (freeVariables f) f) then self ormulae
51   else Just $ findFirstBindingFailure model f bindings
52
53 findFirstBindingFailure :: Model -> Formula -> [Environment] -> [Model]
54 —
55 findFirstBindingFailure model formula (e:es) =
56   let self = findFirstBindingFailure model formula in
57   if holds' model e formula then self es
58   else
59     trace ("attempting to satisfy (" ++ showFormula formula ++ ") with env" ++ show e) $
60     chaseSatisfy model e formula

```



```

61
62 chaseSatisfy :: Model -> Environment -> Formula -> [Model]
63 ---
64 chaseSatisfy model env formula =
65   let (domain,relations) = model in
66   let domainSize = length domain in
67   let self = chaseSatisfy model in
68   case formula of
69     Tautology -> [model]
70     Contradiction -> []
71     Or a b -> union (self env a) (self env b)
72     And a b -> concatMap (\m -> chaseSatisfy m env b) (self env a)
73     Equality v1 v2 -> case (lookup v1 env,lookup v2 env) of
74       (Just v1, Just v2) -> [quotient model v1 v2]
75       _ -> error("Could not look up one of \" ++ variableName v2 ++ "\"_or_\" ++ variableName
76     Implication a b -> if holds' model env a then self env b else []
77     Atomic predicate vars ->
78       let newRelationArgs = genNewRelationArgs env vars (fromIntegral (length domain)) in
79       let newRelation = mkRelation predicate (length vars) [newRelationArgs] in
80       let newModel = mkModel (mkDomain domainSize) (mergeRelation newRelation relations) in
81       trace ("Adding new relation: " ++ show newRelation) $
82       [newModel]
83     ExistentialQuantifier [] f -> self env f
84     ExistentialQuantifier (v:vs) f ->
85       let f' = ExistentialQuantifier vs f in
86       let nextDomainElement = fromIntegral $ (length domain) + 1 in
87       if (domain /= []) && (any (\v' -> holds' model (hashSet env v v') f') domain) then
88         trace (" " ++ showFormula formula ++ " already holds") $
89         [model]
90       else
91         trace ("Adding new domain element " ++ show nextDomainElement ++ " for variable " ++
92         chaseSatisfy (mkDomain nextDomainElement,relations) (hashSet env v nextDomainElement) f
93         -> error ("formula not in positive existential form: " ++ showFormula formula)
94
95 genNewRelationArgs :: Environment -> [Variable] -> DomainElement -> [DomainElement]
96 --- for each Variable in the given list of Variables, retrieves the value
97 --- assigned to it in the given environment, or the next domain element if it
98 --- does not exist
99 genNewRelationArgs env [] domainSize = []
100 genNewRelationArgs env (v:vs) domainSize =
101   let self = genNewRelationArgs env vs in
102   case lookup v env of
103     Just v' -> v' : self domainSize
104     _ -> domainSize+1 : self (domainSize+1)

```

References

- [1] A Cottrell, *Word Processors: Stupid and Inefficient*,
www.ecn.wfu.edu/~cottrell/wp.html