

ECE597ML-697ML: Kernel Trick

Mario Parente

Big Picture: So Far

- ▶ Cost function paradigm for supervised machine learning
 - ▶ Input \mathbf{x}
 - ▶ Output \mathbf{y}
 - ▶ Find $h_{\boldsymbol{\theta}}(\mathbf{x})$ such that $h_{\boldsymbol{\theta}}(\mathbf{x}^{(i)}) \approx y^{(i)}$
 - ▶ Cost function $J(\boldsymbol{\theta})$
 - ▶ Regularization to avoid overfitting

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 - ▶ Find $h_{\theta}(\mathbf{x})$ such that $h_{\theta}(\mathbf{x}^{(i)}) \approx y^{(i)}$
 - ▶ Cost function $J(\theta)$
 - ▶ Regularization to avoid overfitting
- ▶ Everything so far has been based on **linear models**
$$h_{\theta}(\mathbf{x}) = g(\theta^T \mathbf{x})$$

Kernel-Trick Motivation

- ▶ But what we really want are flexible non-linear classifiers!
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 - ▶ Kernel trick!
- ▶ Wait... feature expansions already allow non-linear learning...

$$(x_1, x_2) \mapsto (1, x_1, x_2, x_1^2, x_2^2, x_1x_2)$$

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- ▶ We would like something more “automatic”
- ▶ We don't want to expand our datasets to many times their original size
- ▶ **Kernel trick:** non-linear feature expansions in implicit way way
 - ▶ Computationally efficient
 - ▶ Don't actually do expansion

Kernel Trick Starting Point

Assumption (*): $\theta = \sum_{i=1}^m \alpha_i \mathbf{x}^{(i)}$ for some $\alpha_1, \dots, \alpha_m$

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- ▶ θ in **span** of feature vectors
- ▶ We'll discuss later how to find $\alpha_1, \dots, \alpha_m$

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- ▶ Predictions only depend on training data through kernel function! (dot products)

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- ▶ How to find $\alpha = (\alpha_1, \dots, \alpha_m)$? Minimize $J(\alpha)$. (More later)
- ▶ Note: (*) only needs to hold for θ that minimizes $J(\theta)$

Takeaway

$$h_{\theta}(\mathbf{x}) = \sum_{i=1}^m \alpha_i K(\mathbf{x}^{(i)}, \mathbf{x})$$

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Concrete Example: “Kernelized” Linear Regression

- **Observation:** can rewrite linear regression as a *different* linear regression model:

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- Map \mathbf{x} to new “feature vector” $k(\mathbf{x})$ (= kernel evaluation between \mathbf{x} and each training feature vector).
- What happens to original data matrix X under this mapping? (Recall: i th row of X is i th feature vector $\mathbf{x}^{(i)}$.)

- We get a new “data matrix” K , whose i th row holds dot products between $\mathbf{x}^{(i)}$ and each *other* training point:

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- ▶ **Demo**
- ▶ Note: this equivalence is only exact **without regularization**. In practice: use a different optimization method to find α to minimize $J(\alpha)$

Linear Models

Same reasoning applies more generally to any linear model of this form:

$$h_{\boldsymbol{\theta}}(\mathbf{x}) = g(\boldsymbol{\theta}^T \mathbf{x})$$
$$J(\boldsymbol{\theta}) = \sum_{k=1}^m \text{cost}(\boldsymbol{\theta}^T \mathbf{x}^{(k)}, y^{(k)})$$

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- ▶ Can fit model by substituting kernel matrix for data matrix.

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- ▶ To solve the learning problem and make predictions, we only need to be able to compute $K(\mathbf{x}, \mathbf{z}) = \phi(\mathbf{x})^T \phi(\mathbf{z})$. This is called the **kernel** corresponding to ϕ .

Example: Polynomial Kernel

Important trick: we can often compute kernel without actually doing the expansion

$$K(\mathbf{x}, \mathbf{z}) = (\mathbf{x}^T \mathbf{z})^2$$

Claim: this is the kernel corresponding to $\phi(\mathbf{x}) = \begin{bmatrix} x_1x_1 \\ x_1x_2 \\ x_2x_1 \\ x_2x_2 \end{bmatrix}$

Exercise: verify this on board

More Polynomial Kernels

Claim: these two are equivalent

$$\phi(\mathbf{x}) = \begin{bmatrix} 1 \\ \sqrt{2}x_1 \\ \sqrt{2}x_2 \\ x_1x_1 \\ x_1x_2 \\ x_2x_1 \\ x_2x_2 \end{bmatrix} \quad K(\mathbf{x}, \mathbf{z}) = (\mathbf{x}^T \mathbf{z} + 1)^2$$

- Complexity of computing $\phi(\mathbf{x})^T \phi(\mathbf{z})$?
- Complexity of computing $\mathbf{x}^T \mathbf{z}$?
- Complexity of computing $(\mathbf{x}^T \mathbf{z} + 1)^2$?

Polynomial Kernel: Significance

- ▶ Compute $\phi(\mathbf{x})^T \phi(\mathbf{z})$: $O(n^2)$
- ▶ Compute $\mathbf{x}^T \mathbf{z}$: $O(n)$
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If using *kernel trick*, can implement a non-linear feature expansion at no additional cost

Even More Polynomial Kernels

$$K(\mathbf{x}, \mathbf{z}) = (\mathbf{x}^T \mathbf{z} + 1)^d$$

Corresponds to ϕ that takes all products of up to d original features
 $O(n)$ time to compute kernel instead of $O(n^d)$

Gaussian Kernel

$$K(\mathbf{x}, \mathbf{z}) = \exp(-\gamma \|\mathbf{x} - \mathbf{z}\|^2)$$

- ▶ Highly flexible, non-linear kernel
- ▶ Corresponds to **infinite dimensional** ϕ (cannot implement feature mapping, but can still use kernel)
- ▶ Demos
 - ▶ Gaussian kernel intuition: similarity function
 - ▶ Linear regression

A Word on Regularization

- Suppose we want to combine feature expansion with regularization

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(derivation next slide)

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- ▶ This is *not* the same as penalizing $\|\boldsymbol{\alpha}\|^2$
 - ▶ Tip: use regularization with kernelized linear models
 - ▶ Tip: Use a custom optimizer for to minimize $J(\boldsymbol{\alpha})$

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Derivation of regularization term:

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Practical Tips

- ▶ Use **support vector machines** (SVMs) for kernelized classification
 - ▶ Like logistic regression, with *slightly* different loss function. (Derivation based on geometric principles, but end point the same.)
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- ▶ Use **kernel ridge regression** or **support vector regression** for kernelized regression
- ▶ Use Gaussian kernels
- ▶ Use regularization with kernels
- ▶ How to select λ and γ ?

Practical Tips

- ▶ Use **support vector machines** (SVMs) for kernelized classification
 - ▶ Like logistic regression, with *slightly* different loss function. (Derivation based on geometric principles, but end point the same.)
 - ▶ More efficient than logistic regression when used with kernels (many α_i values are **zero**)
- ▶ Use **kernel ridge regression** or **support vector regression** for kernelized regression
- ▶ Use Gaussian kernels
- ▶ Use regularization with kernels
- ▶ How to select λ and γ ? Cross-validation!

Demos

- ▶ Kernel logistic regression
- ▶ SVM loss
- ▶ SVM classification