

GUANGZHI TANG

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RESEARCH INTERESTS

Neurorobotics, Spiking Neural Networks, Neuromorphic Computing

RESEARCH EXPERIENCE

Rutgers University

Computational Brain Lab

May 2016 - Present

Graduate Research Assistant

- Developing a brain mimicking robotic navigation system. The system follows the same structure with the brain's spatial system inside and surrounding the hippocampal formation found by experimental studies. Only biologically constrained computational components are used to pursue a biologically plausible implementation.
- Developed a spiking neural network model to drive a mobile robot to move in a simulated double-T maze. The model gave assumptions on place cell's remapping activities and border cell's mapping functionalities. This was the first model for the brain's spatial system fully using spiking neurons and bio-constrained components to transfer and manipulate information from sensory inputs to motor control.
- Developed a spiking neural network model of head direction cells to correct the head direction representation from dead reckoning errors. The model used Bayesian inference to combine visual cues from border cells and self-motion cues from head direction cells to generate more accurate head direction representation. This was the first model for head direction cell cue integration using a Bayesian inference approach.

Nanjing University

Reasoning and Learning Research Group

Sep 2013 - May 2015

Undergraduate Research Assistant

- Developed an adaptive algorithm to play Texas Holdem poker with different type of players. The algorithm used online learning and sampling with game theory approach, and outperformed many other online methods in the field of imperfect information extensive games.

Baidu, Inc.

Search Ranking Team, Mobile Search Group

Jul 2014 - Sep 2014

Research & Development Intern

- Developed methods to find search query correlations in huge amounts of daily mobile search raw data using Hadoop cluster. Developed personalized search ranking recommendation algorithms for users with different searching habits.

EDUCATION

Rutgers University

Ph.D student, Computer Science

Research Affiliation: Computational Brain Lab, CBIM

Research Advisor: Prof. Konstantinos Michmizos

New Brunswick, NJ

Sep 2017 - Present

Rutgers University

M.Sc, Computer Science

Overall GPA: 3.87

Thesis Advisor: Prof. Konstantinos Michmizos

Thesis Title: Gridbot: Towards a Neuroinspired Navigation System for Robot Planning

New Brunswick, NJ

Sep 2015 - May 2017

Nanjing University
B.Sc, Computer Science
Overall GPA: 3.1
National Talented Program of China

Nanjing, China
Sep 2011 - May 2015

PUBLICATIONS

Peer-reviewed Publications

- **Tang G**, Michmizos K. *Gridbot: An autonomous robot controlled by a Spiking Neural Network mimicking the brain's navigational system*. International Conference on Neuromorphic Systems, Knoxville, TN, 2018.
- **Tang G**, Michmizos K. *Gridbot: A Spiking Neural Network Model of the Brain's Navigation System for Autonomous Robots*. Neuro Inspired Computational Elements Workshop, Portland, OR, 2018.
- **Tang G**, Michmizos K. *Gridbot: Spike-Based Head Direction Cells Employing Bayesian Inference*. Neuro Inspired Computational Elements Workshop, San Jose, CA, 2017.
- **Tang G**, Michmizos K. *NeuroRobotics: A Spiking Neural Network Model of the Brain's Spatial Navigation System for Autonomous Robots*. Conference on Cognitive Computational Neuroscience, New York, NY, 2017.

Theses

- **Tang G**. *Gridbot: Towards a Neuroinspired Navigation System for Robot Planning*. Master's thesis, Rutgers University, New Brunswick, NJ, 2017.
- **Tang G**. *Fast Online Learning in Imperfect Information Extensive Games*. Bachelor's thesis, Nanjing University, Nanjing, China, 2015.

HONORS & AWARDS

Microsoft & IEEE Young Fellow Scholarship Award	MSRA, 2014
Scholarship of the National Talented Program	Chinese Ministry of Education, 2013, 2014

EXTRA CURRICULAR ACTIVITIES

Member, Rutgers University Cycling Team	2015-Present
Vice President, Nanjing University Cycling Association	2013-2015
Certification for First Aid and CPR	2016-Present